# On the intersection of random rotations of a symmetric convex body 

Silouanos Brazitikos and Pantelis Stavrakakis


#### Abstract

Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. We provide general estimates for the volume and the radius of $C \cap U(C)$ where $U$ is a random orthogonal transformation of $\mathbb{R}^{n}$. In particular, we consider the case where $C$ is in the isotropic position or $C$ is the volume normalized $L_{q}$-centroid body $Z_{q}(\mu)$ of an isotropic log-concave measure $\mu$ on $\mathbb{R}^{n}$.


## 1 Introduction

A well-known principle in the asymptotic theory of convex bodies asserts that local statements describing the structure of lower dimensional sections and projections of a symmetric convex body $C$ in $\mathbb{R}^{n}$ can be "translated" to global statements about properties of $C$ and its orthogonal images $U(C)$. A number of results, including the global form of Dvoretzky theorem proved by V. Milman and Schechtman in [26], illustrate this point of view. The volume ratio theorem is another classical example of the parallelism between the global and the local asymptotic theory. Szarek and Tomczak-Jaegermann [32], generalizing previous work of Kashin [12] for the unit ball of $\ell_{1}^{n}$, proved that if $C$ is a symmetric convex body in $\mathbb{R}^{n}$ such that $B_{2}^{n} \subseteq C$ and $|C|=\alpha^{n}\left|B_{2}^{n}\right|$ for some $\alpha>1$ then, for every $1 \leqslant k \leqslant n$, a random subspace $F \in G_{n, k}$ satisfies with probability greater than $1-e^{-n}$

$$
B_{2}^{n} \cap F \subseteq C \cap F \subseteq(c \alpha)^{\frac{n}{n-k}} B_{2}^{n} \cap F
$$

where $c>0$ is an absolute constant. The global analogue of this statement is that, under the same hypothesis, there exists $U \in O(n)$ with the property

$$
B_{2}^{n} \subset C \cap U(C) \subset c \alpha^{2} B_{2}^{n}
$$

where $c>0$ is an absolute constant. In a few words, the fact that most of the $n / 2-$ dimensional sections of $C$ are $\alpha^{2}$-equivalent to a Euclidean ball can be translated to the global statement that intersecting $C$ with a random rotation $U(C)$ we obtain a convex body which is $\alpha^{2}$-equivalent to $B_{2}^{n}$.

In this note we consider the intersection of a symmetric convex body $C$ with $U(C)$, where $U \in O(n)$ is a random orthogonal transformation of $\mathbb{R}^{n}$, and we are
mainly interested in the expectation of the volume and the radius $R(C \cap U(C)):=$ $\max \left\{\|x\|_{2}: x \in C \cap U(C)\right\}$ of $C \cap U(C)$. One motivation for this work was to understand the way these two quantities depend on classical parameters of the body $C$; a second motivation was to understand better the regularity properties of the $L_{q}$-centroid bodies of isotropic log-concave measures. Naturally, our results are directed to these two questions. We write $\|\cdot\|_{C}$ for the norm induced by $C$ on $\mathbb{R}^{n}$ and we denote by $M:=M(C)$ and by $w(C)$ the expectation of this norm on the unit sphere and the mean width of $C$ respectively.

Starting with the volume, it is clear that $|C \cap U(C)| \leqslant 1$ for all $U$, and the example of the Euclidean ball $\overline{B_{2}^{n}}$ of volume 1 shows that, in full generality, one cannot expect anything better than this trivial upper bound. However, we will see that, under some natural condition on $C$, one can provide subexponential upper bounds for the expectation

$$
\mathbb{E}_{U}|C \cap U(C)|=\int_{O(n)}|C \cap U(C)| d \nu(U)
$$

where $\nu$ is the Haar measure on $O(n)$. Our starting point is a simple formula for this expectation; one has

$$
\begin{equation*}
\int_{O(n)}|C \cap U(C)| d \nu(U)=\int_{C} \sigma\left(S^{n-1} \cap \frac{1}{\|x\|_{2}} C\right) d x \tag{1.1}
\end{equation*}
$$

where $\sigma$ is the rotationally invariant probability measure on the unit sphere $S^{n-1}$. Therefore, one has to understand the behaviour of $\sigma\left(S^{n-1} \cap t C\right)$ for small values of $t$ or, equivalently, the behaviour of $\gamma_{n}(\alpha C)$ for $\alpha \simeq 1$ (see Lemma 4.1 below). A parameter which plays a key role in small ball probability estimates and is very much related to this question was introduced by Klartag and Vershynin in [18]: they defined $d(C)$ as follows:

$$
d(C):=\min \left\{-\log \sigma\left(\left\{x \in S^{n-1}:\|x\|_{C} \leqslant \frac{M(C)}{2}\right\}\right), n\right\}
$$

Using the $B$-theorem of Cordero-Erausquin, Fradelizi and Maurey [5], in Section 4 we obtain the following estimate.

Theorem 1.1. There exists an absolute constant $B_{0}>0$ such that if $C$ is a symmetric convex body of volume 1 in $\mathbb{R}^{n}$ with $\sqrt{n} M(C) \geqslant B_{0}$ then

$$
\begin{equation*}
\int_{O(n)}|C \cap U(C)| d \nu(U) \leqslant e^{-c d(C)} \tag{1.2}
\end{equation*}
$$

where $c>0$ is an absolute constant.
The condition $\sqrt{n} M(C) \geqslant B_{0}$ in Theorem 1.1 is rather natural; observe that if we express the volume of $C$ as an integral in polar coordinates and use Hölder's inequality then we get

$$
\begin{equation*}
\operatorname{vrad}(C) M(C) \geqslant 1 \tag{1.3}
\end{equation*}
$$

with equality if $C$ is a Euclidean ball. If $|C|=1$ then $\operatorname{vrad}(C):=\left(|C| /\left|B_{2}^{n}\right|\right)^{1 / n} \simeq$ $\sqrt{n}$ and hence the bodies for which $\operatorname{vrad}(C) M(C) \leqslant B_{0}$ form a rather restricted class.

The proof of Theorem 1.1 is given in Section 4. The general upper bound in (1.2) depends on the order of $d(C)$. We give some concrete applications in the case where $C$ is a (normalized) $\ell_{p}^{n}$-ball. We also discuss some classical positions of the body $C$ from this point of view. A case of interest is when the body is in the isotropic position (see Section 2 for the definition and background information). In this case, using the thin shell estimate (see e.g. [11]) we obtain an alternative bound.

Theorem 1.2. Let $K$ be an isotropic convex body in $\mathbb{R}^{n}$. Then, either $L_{K} \leqslant 1$ or

$$
\begin{equation*}
\int_{O(n)}|K \cap U(K)| d \nu(U) \leqslant c_{1} e^{-c_{2} \sqrt{n}} \tag{1.4}
\end{equation*}
$$

where $c_{1}, c_{2}>0$ are absolute constants.
In fact, one can obtain a similar sub-exponential estimate in Theorem 1.2 under the assumption $L_{K} \geqslant t$, for any $t>\sqrt{2 / \pi}$; this would only affect the constant $c_{2}$ (see Proposition 4.8 for a precise statement). Note also that the condition that is used in Theorem 1.2 is different from the one in Theorem 1.1; here, we require that the isotropic constant $L_{K}$ of $K$ is large enough: $L_{K} \geqslant 1$. It is a major open problem whether there exists an absolute constant $c_{0}>0$ such that $L_{K} \leqslant c_{0}$ for all isotropic convex bodies in any dimension; if this is true, and in particular if $c_{0}<1$, then the statement of Theorem 1.2 does not provide significant information.

In order to give lower bounds for $|C \cap U(C)|$ we use simple entropy estimates. In fact, our bounds are valid for every $U \in O(n)$. In Section 3 we show that, for every $\varrho>0$ and any $U \in O(n)$, one has

$$
\begin{equation*}
|C \cap U(C)| \geqslant\left[\min \left\{(4 \varrho)^{n / 2} N\left(C, \varrho \overline{B_{2}^{n}}\right),(4 / \varrho)^{n / 2} N\left(\varrho \overline{B_{2}^{n}}, C\right)\right\}\right]^{-2}, \tag{1.5}
\end{equation*}
$$

where $N(A, B)$ is the covering number of $A$ by $B$, i.e. the least number of translates of $B$ needed to cover $A$. Then, using known results on covering numbers, we obtain the following.

Theorem 1.3. Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. For any $U \in O(n)$ we have

$$
\begin{equation*}
|C \cap U(C)| \geqslant e^{-c n \min \left\{w^{2}(C) / n, n M^{2}(C)\right\}} \tag{1.6}
\end{equation*}
$$

where $c>0$ is an absolute constant. In particular, for any $1 \leqslant p \leqslant \infty$ and any $U \in O(n)$ we have

$$
\begin{equation*}
\left|\overline{B_{p}^{n}} \cap U\left(\overline{B_{p}^{n}}\right)\right| \geqslant e^{-c n}, \tag{1.7}
\end{equation*}
$$

where $c>0$ is an absolute constant and $\overline{B_{p}^{n}}$ is the "normalized" $\ell_{p}^{n}$-ball.

The dependence on $M(C)$ and $w(C)$ in Theorem 1.3 indicates that in order to obtain some non trivial information, we should consider some "good position" of the body $C$. We provide a number of results of this type: If $C$ is in $M$-position with constant $\beta$ then, for any $U \in O(n)$ we have $|C \cap U(C)| \geqslant e^{-2(\beta+1) n}$. Similarly, if $K$ is an isotropic symmetric convex body in $\mathbb{R}^{n}$ then

$$
\begin{equation*}
|K \cap U(K)| \geqslant\left(c L_{K}\right)^{-n} \tag{1.8}
\end{equation*}
$$

for every $U \in O(n)$, where $c \geqslant 4$ is an absolute constant.
In Section 5 we recall some known results from the local theory of normed spaces which lead to upper bounds for the radius of $C \cap U(C)$. It is well understood that if one has an upper bound for the radius of a random $k$-dimensional section $C \cap F$ of $C$ where $k \geqslant\left(1-c_{0}\right) n$ (for some small absolute constant $\left.c_{0} \in(0,1)\right)$ then the same bound holds true for the radius of a random intersection $C \cap U(C)$. There are several versions of this statement; we review the strongest and most recent ones (see [8], [33], [20]). In particular, combining these results with the low $M^{*}$-estimate, one gets the next very general fact, in the spirit of [26, Theorem 2.2] and most probably known to experts: a random $U \in O(n)$ satisfies

$$
R(C \cap U(C)) \leqslant c w(C)
$$

with probability greater than $1-e^{-n}$, where $c>0$ is an absolute constant.
In the last section of this article we apply the previous results to the $L_{q}$-centroid bodies $Z_{q}(\mu)$ of an isotropic log-concave measure $\mu$ on $\mathbb{R}^{n}$. Recall that, if $\mu$ is a log-concave probability measure on $\mathbb{R}^{n}$ and $q \geqslant 1$ then the $L_{q}$-centroid body $Z_{q}(\mu)$ of $\mu$ is the symmetric convex body with support function

$$
\begin{equation*}
h_{Z_{q}(\mu)}(y):=\left(\int_{\mathbb{R}^{n}}|\langle x, y\rangle|^{q} d \mu(x)\right)^{1 / q} \tag{1.9}
\end{equation*}
$$

The study of random rotations of $Z_{q}(\mu)$ proved to be useful in recent works on the thin shell conjecture. The following fact plays a key role in the article of Klartag and E. Milman [17] which introduces a regularization step for the study of this problem and strengthens the small ball estimates of [11]: if $2 \leqslant q \leqslant \sqrt{n}$ then a random $U \in O(n)$ satisfies

$$
Z_{q}(\mu)+U\left(Z_{q}(\mu)\right) \supseteq c \sqrt{q} B_{2}^{n}
$$

with probability greater than $1-e^{-c n}$. Using the results of Section 5 and the estimates of [9] on the inradius of random proportional projections of $Z_{q}(\mu)$ we provide a second proof. In a similar way one can prove an analogous inner regularization result for the polar body $Z_{q}^{\circ}(\mu)$; this is actually simpler. The precise statement, in the spirit of this note, is as follows.

Theorem 1.4. Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$. For any $q \leqslant \sqrt{n}$, a random $U \in O(n)$ satisfies

$$
\overline{Z_{q}^{\circ}}(\mu) \cap U\left(\overline{Z_{q}^{\circ}}(\mu)\right) \subseteq c \sqrt{n} B_{2}^{n} \quad \text { and } \quad \overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right) \subseteq c \sqrt{n} B_{2}^{n}
$$

with probability greater than $1-2 e^{-n}$.

In the case of $Z_{q}(\mu)$, Theorem 1.1 leads to the following estimate: Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$ and let $2 \leqslant q \leqslant \sqrt{n}$. If $\sqrt{q} M\left(Z_{q}(\mu)\right) \geqslant B_{1}$ then

$$
\begin{equation*}
\int_{O(n)}\left|\overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right)\right| d \nu(U) \leqslant e^{-c_{1} n / q} \tag{1.10}
\end{equation*}
$$

where $B_{1}, c_{1}>0$ are absolute constants. The question to give an upper bound for $M\left(Z_{q}(\mu)\right)$ is naturally related to the necessary condition for (1.10). This was one of the main objects of study in [9], where a partial non-trivial upper bound was obtained: for every $1 \leqslant q \leqslant n^{3 / 7}$ one has $M\left(Z_{q}(\mu)\right) \leqslant C(\log q)^{5 / 6} / \sqrt[6]{q}$.

## 2 Notation and background material

We work in $\mathbb{R}^{n}$, which is equipped with a Euclidean structure $\langle\cdot, \cdot\rangle$. We denote the corresponding Euclidean norm by $\|\cdot\|_{2}$, and write $B_{2}^{n}$ for the Euclidean unit ball, and $S^{n-1}$ for the unit sphere. Volume is denoted by $|\cdot|$. The volume $\omega_{n}$ of $B_{2}^{n}$ is equal to $\pi^{n / 2} / \Gamma\left(\frac{n}{2}+1\right)$; from Stirling's formula we see that $\omega_{n}^{1 / n} \simeq 1 / \sqrt{n}$. We write $\sigma$ for the rotationally invariant probability measure on $S^{n-1}$ and denote the Haar measure on $O(n)$ by $\nu$. The Grassmann manifold $G_{n, k}$ of $k$-dimensional subspaces of $\mathbb{R}^{n}$ is equipped with the Haar probability measure $\nu_{n, k}$. Let $1 \leqslant k \leqslant n$ and $F \in G_{n, k}$. We will denote the orthogonal projection from $\mathbb{R}^{n}$ onto $F$ by $P_{F}$. We also define $B_{F}:=B_{2}^{n} \cap F$ and $S_{F}:=S^{n-1} \cap F$.

The letters $c, c^{\prime}, c_{1}, c_{2}$ etc. denote absolute positive constants whose value may change from line to line. Whenever we write $a \simeq b$, we mean that there exist absolute constants $c_{1}, c_{2}>0$ such that $c_{1} a \leqslant b \leqslant c_{2} a$.

Basic references for the theory of convex bodies and the asymptotic theory of finite dimensional normed spaces are the classical books of Schneider [31], Milman and Schechtman [25] and Pisier [30].
Symmetric convex bodies. A convex body in $\mathbb{R}^{n}$ is a compact convex set $C \subset \mathbb{R}^{n}$ with non-empty interior. In this article we discuss symmetric convex bodies, namely convex bodies $C$ with the property that $x \in C$ if and only if $-x \in C$. The volume radius of $C$ is the quantity $\operatorname{vrad}(C)=\left(|C| /\left|B_{2}^{n}\right|\right)^{1 / n}$. The support function of $C$ is defined by $h_{C}(y):=\max \{\langle x, y\rangle: x \in C\}$, and the mean width of $C$ is the average

$$
\begin{equation*}
w(C):=\int_{S^{n-1}} h_{C}(\theta) d \sigma(\theta) \tag{2.1}
\end{equation*}
$$

of $h_{C}$ on $S^{n-1}$. The radius $R(C)$ of $C$ is the smallest $R>0$ such that $C \subseteq R B_{2}^{n}$ and the inradius $r(C)$ of $C$ is the largest $r>0$ for which $r B_{2}^{n} \subseteq C$.

The polar body $C^{\circ}$ of a symmetric convex body $C$ in $\mathbb{R}^{n}$ is defined by

$$
\begin{equation*}
C^{\circ}:=\left\{y \in \mathbb{R}^{n}:\langle x, y\rangle \leqslant 1 \text { for all } x \in C\right\} . \tag{2.2}
\end{equation*}
$$

The Blaschke-Santaló inequality states that $|C|\left|C^{\circ}\right| \leqslant \omega_{n}^{2}$, with equality if and only if $C$ is an ellipsoid. The reverse Santaló inequality of Bourgain and V. Milman [3]
states that there exists an absolute constant $c>0$ such that, conversely,

$$
\begin{equation*}
\left(|C|\left|C^{\circ}\right|\right)^{1 / n} \geqslant c / n \tag{2.3}
\end{equation*}
$$

where $c>0$ is an absolute constant.
Every symmetric convex body $C \subset \mathbb{R}^{n}$ induces a norm to $\mathbb{R}^{n}$, given by $\|x\|_{C}=$ $\min \{t \geqslant 0: x \in t C\}$. Then, the dual norm $\|\cdot\|_{*}$ of $\|\cdot\|$, defined by

$$
\|y\|_{*}=\max \left\{|\langle x, y\rangle|:\|x\|_{C} \leqslant 1\right\}
$$

is the norm induced by $C^{\circ}$ to $\mathbb{R}^{n}$ : we have

$$
h_{C}(x)=\|x\|_{C^{\circ}}=\|x\|_{*}
$$

for all $x \in \mathbb{R}^{n}$. We also write $b:=b(C)$ for the smallest positive constant for which $\|x\|_{C} \leqslant b\|x\|_{2}$ for all $x \in \mathbb{R}^{n}$. Note that $b(C)=r(C)^{-1}$.

We will use some basic facts from the asymptotic theory of finite dimensional normed spaces. A parameter that plays a central role in the theory, and in this article, is the average

$$
\begin{equation*}
M(C):=\int_{S^{n-1}}\|\theta\|_{C} d \sigma(\theta) \tag{2.4}
\end{equation*}
$$

of $\|\cdot\|_{C}$ on $S^{n-1}$. Note that $M(C)=w\left(C^{\circ}\right)$ and that

$$
\begin{equation*}
M(C)^{-1} \leqslant \operatorname{vrad}(C) \leqslant w(C)=M\left(C^{\circ}\right) \tag{2.5}
\end{equation*}
$$

the left hand side inequality is easily checked if we express the volume of $C$ as an integral in polar coordinates and use Hölder's inequality, while the right hand side inequality is the classical Urysohn's inequality.

The critical dimension $k(C)$ of a symmetric convex body $C$ in $\mathbb{R}^{n}$ is the largest positive integer $k \leqslant n$ with the property that the measure $\nu_{n, k}$ of $F \in G_{n, k}$ for which we have $\frac{1}{2 M(C)} B_{F} \subseteq C \cap F \subseteq \frac{2}{M(C)} B_{F}$ is greater than $\frac{n}{n+k}$. This parameter was studied in [26] where it is shown that it is completely determined by the dimension, the parameter $M(C)$ and the inradius of $C$ : one always has

$$
\begin{equation*}
c_{1} n \frac{M(C)^{2}}{b(C)^{2}} \leqslant k(C) \leqslant c_{2} n \frac{M(C)^{2}}{b(C)^{2}}, \tag{2.6}
\end{equation*}
$$

where $c_{1}, c_{2}>0$ are absolute constants. We also define $k_{*}(C)=k\left(C^{\circ}\right)$. Note that $k_{*}(C) \simeq n \frac{w(C)^{2}}{R(C)^{2}}$. Generalizing the definition of $d(C)$ which was given in the introduction, for every $r>1$ we define

$$
d_{r}(C)=\min \left\{-\log \sigma\left(\left\{x \in S^{n-1}:\|x\|_{C} \leqslant \frac{M(C)}{r}\right\}\right), n\right\}
$$

Note that $d(C)=d_{2}(C)$. One can check (see [18]) that $d(C) \geqslant c k(C)$, where $c>0$ is an absolute constant.

Finally, we will need Milman's low $M^{*}$-estimate which states that there exists a function $\lambda:(1, \infty) \rightarrow \mathbb{R}^{+}$such that if $C$ is a symmetric convex body in $\mathbb{R}^{n}$, then a subspace $F \in G_{n, k}$ satisfies

$$
\begin{equation*}
R(C \cap F) \leqslant \lambda\left(\frac{n}{n-k}\right) w(C) \tag{2.7}
\end{equation*}
$$

with probability greater than $1-\exp \left(-c_{2}(n-k)\right)$, where $c_{1}, c_{2}>0$ are absolute constants. Milman's first proof of (2.7) appears in [21], and a second proof from [22] establishes $(2.7)$ with $\lambda(t)=c t$. Pajor and Tomczak-Jaegermann proved in [27] that the same statement holds true with $\lambda(t)=c \sqrt{t}$, which is the asymptotically best possible behavior. Finally, Gordon [10] proved a sharp form of the latter result; in particular, he showed that the value of the constant $c$ can be assumed asymptotically equal to 1 .

Given two convex bodies $C, L \subseteq \mathbb{R}^{n}$, we will write $C \simeq L$ if there exist absolute constants $c_{1}, c_{2}>0$ such that $c_{1} C \subseteq L \subseteq c_{2} C$. For notational convenience we write $\bar{C}$ for the homothetic image of volume 1 of a convex body $C \subseteq \mathbb{R}^{n}$, i.e. $\bar{C}:=|C|^{-1 / n} C$.
Log-concave probability measures. We denote by $\mathcal{P}_{n}$ the class of all Borel probability measures on $\mathbb{R}^{n}$ which are absolutely continuous with respect to the Lebesgue measure. The density of $\mu \in \mathcal{P}_{n}$ is denoted by $f_{\mu}$. We say that $\mu \in \mathcal{P}_{n}$ is centered and we write $\operatorname{bar}(\mu)=0$ if, for all $\theta \in S^{n-1}$,

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\langle x, \theta\rangle d \mu(x)=\int_{\mathbb{R}^{n}}\langle x, \theta\rangle f_{\mu}(x) d x=0 \tag{2.8}
\end{equation*}
$$

A measure $\mu$ on $\mathbb{R}^{n}$ is called log-concave if $\mu(\lambda A+(1-\lambda) B) \geqslant \mu(A)^{\lambda} \mu(B)^{1-\lambda}$ for all compact subsets $A$ and $B$ of $\mathbb{R}^{n}$ and all $\lambda \in(0,1)$. A function $f: \mathbb{R}^{n} \rightarrow[0, \infty)$ is called log-concave if its support $\{f>0\}$ is a convex set and the restriction of $\log f$ to it is concave. Borell has proved in [1] that if a probability measure $\mu$ is log-concave and $\mu(H)<1$ for every hyperplane $H$, then $\mu \in \mathcal{P}_{n}$ and its density $f_{\mu}$ is log-concave. Note that if $K$ is a convex body in $\mathbb{R}^{n}$ then the Brunn-Minkowski inequality implies that $\mathbf{1}_{K}$ is the density of a $\log$-concave measure.

If $\mu$ is a log-concave measure on $\mathbb{R}^{n}$ with density $f_{\mu}$, we define the isotropic constant of $\mu$ by

$$
\begin{equation*}
L_{\mu}:=\left(\frac{\sup _{x \in \mathbb{R}^{n}} f_{\mu}(x)}{\int_{\mathbb{R}^{n}} f_{\mu}(x) d x}\right)^{\frac{1}{n}}[\operatorname{det} \operatorname{Cov}(\mu)]^{\frac{1}{2 n}}, \tag{2.9}
\end{equation*}
$$

where $\operatorname{Cov}(\mu)$ is the covariance matrix of $\mu$ with entries

$$
\begin{equation*}
\operatorname{Cov}(\mu)_{i j}:=\frac{\int_{\mathbb{R}^{n}} x_{i} x_{j} f_{\mu}(x) d x}{\int_{\mathbb{R}^{n}} f_{\mu}(x) d x}-\frac{\int_{\mathbb{R}^{n}} x_{i} f_{\mu}(x) d x}{\int_{\mathbb{R}^{n}} f_{\mu}(x) d x} \frac{\int_{\mathbb{R}^{n}} x_{j} f_{\mu}(x) d x}{\int_{\mathbb{R}^{n}} f_{\mu}(x) d x} \tag{2.10}
\end{equation*}
$$

Note that $L_{\mu}$ is an affine invariant of $\mu$ and does not depend on the choice of the Euclidean structure. We say that a log-concave probability measure $\mu$ on $\mathbb{R}^{n}$ is isotropic if $\operatorname{bar}(\mu)=0$ and $\operatorname{Cov}(\mu)$ is the identity matrix.

A convex body $K$ in $\mathbb{R}^{n}$ is called isotropic if it has volume 1 , it is centered, i.e. its barycenter is at the origin, and if its inertia matrix is a multiple of the identity matrix: there exists a constant $L_{K}>0$ such that

$$
\begin{equation*}
\int_{K}\langle x, \theta\rangle^{2} d x=L_{K}^{2} \tag{2.11}
\end{equation*}
$$

for every $\theta$ in the Euclidean unit sphere $S^{n-1}$. Note that a centered convex body $K$ of volume 1 in $\mathbb{R}^{n}$ is isotropic, i.e. it satisfies (2.11), if and only if the logconcave probability measure $\mu_{K}$ with density $x \mapsto L_{K}^{n} \mathbf{1}_{K / L_{K}}(x)$ is isotropic. The hyperplane conjecture asks if there exists an absolute constant $C>0$ such that

$$
\begin{equation*}
L_{n}:=\max \left\{L_{K}: K \text { is isotropic in } \mathbb{R}^{n}\right\} \leqslant C \tag{2.12}
\end{equation*}
$$

for all $n \geqslant 1$. Bourgain proved in [2] that $L_{n} \leqslant c \sqrt[4]{n} \log n$, while Klartag [13] obtained the bound $L_{n} \leqslant c \sqrt[4]{n}$. A second proof of Klartag's bound appears in [16].

Let $\mu \in \mathcal{P}_{n}$. For every $1 \leqslant k \leqslant n-1$ and every $E \in G_{n, k}$, the marginal $\pi_{E} \mu$ of $\mu$ with respect to $E$ is the probability measure with density

$$
\begin{equation*}
f_{\pi_{E} \mu}(x)=\int_{x+E^{\perp}} f_{\mu}(y) d y \tag{2.13}
\end{equation*}
$$

It is easily checked that if $\mu$ is centered, isotropic or log-concave, then $\pi_{E} \mu$ is also centered, isotropic or log-concave, respectively.

Recall that, if $\mu$ is a log-concave probability measure on $\mathbb{R}^{n}$ and $q \geqslant 1$ then the $L_{q}$-centroid body $Z_{q}(\mu)$ of $\mu$ is the symmetric convex body with support function

$$
\begin{equation*}
h_{Z_{q}(\mu)}(y):=\left(\int_{\mathbb{R}^{n}}|\langle x, y\rangle|^{q} d \mu(x)\right)^{1 / q} . \tag{2.14}
\end{equation*}
$$

Observe that $\mu$ is isotropic if and only if it is centered and $Z_{2}(\mu)=B_{2}^{n}$. From Hölder's inequality it follows that $Z_{1}(\mu) \subseteq Z_{p}(\mu) \subseteq Z_{q}(\mu)$ for all $1 \leqslant p \leqslant q<\infty$. Conversely, using Borell's lemma (see [25, Appendix III]), one can check that

$$
\begin{equation*}
Z_{q}(\mu) \subseteq c \frac{q}{p} Z_{p}(\mu) \tag{2.15}
\end{equation*}
$$

for all $1 \leqslant p<q$. In particular, if $\mu$ is isotropic, then $R\left(Z_{q}(\mu)\right) \leqslant c q$. From [28] and [29] one knows that the " $q$-moments"

$$
\begin{equation*}
I_{q}(\mu):=\left(\int_{\mathbb{R}^{n}}\|x\|_{2}^{q} d x\right)^{1 / q}, \quad q \in(-n,+\infty) \backslash\{0\} \tag{2.16}
\end{equation*}
$$

of the Euclidean norm with respect to an isotropic log-concave probability measure $\mu$ on $\mathbb{R}^{n}$ are equivalent to $I_{2}(\mu)=\sqrt{n}$ as long as $|q| \leqslant \sqrt{n}$. Also, Paouris has proved in [28] that

$$
\begin{equation*}
w\left(Z_{q}(\mu)\right) \simeq \sqrt{q} \tag{2.17}
\end{equation*}
$$

for all $q \leqslant \sqrt{n}$ and

$$
\begin{equation*}
\left|Z_{q}(\mu)\right|^{1 / n} \leqslant c_{2} \sqrt{q / n} \tag{2.18}
\end{equation*}
$$

for all $2 \leqslant q \leqslant n$. On the other hand, in [16] Klartag and Milman prove that

$$
\begin{equation*}
\left|Z_{q}(\mu)\right|^{1 / n} \geqslant c_{3} \sqrt{q / n} \tag{2.19}
\end{equation*}
$$

for all $q \leqslant \sqrt{n}$, where $c_{3}>0$ is an absolute constant. This determines the volume radius of $Z_{q}(\mu)$ for all $q \leqslant \sqrt{n}$.

Finally, let us recall the thin-shell estimate, first obtained by Klartag in [14] and [15] (see also [7] and [6]). The currently best known result is due to Guédon and E. Milman [11]: If $\mu$ is an isotropic log-concave measure on $\mathbb{R}^{n}$ then

$$
\begin{equation*}
\mu\left(\left\{x \in \mathbb{R}^{n}:\left|\|x\|_{2}-\sqrt{n}\right| \geqslant t \sqrt{n}\right\}\right) \leqslant c_{1} \exp \left(-c_{2} \sqrt{n} \min \left(t^{3}, t\right)\right) \tag{2.20}
\end{equation*}
$$

for all $t \geqslant 0$, and (see [17])

$$
\begin{equation*}
\mu\left(\left\{x \in \mathbb{R}^{n}:\|x\|_{2} \leqslant \varepsilon \sqrt{n}\right\}\right) \leqslant(C \varepsilon)^{c_{2} \sqrt{n}} \tag{2.21}
\end{equation*}
$$

for all $0 \leqslant \varepsilon \leqslant 1 / c_{1}$, where $c_{1}, c_{2}>0$ are absolute constants.

## 3 Lower bounds for the volume

For the lower bound we use a simple argument which is based on entropy estimates. Recall that the covering number $N(A, B)$ of a body $A$ by a second body $B$ is the least integer $N$ for which there exist $N$ translates of $B$ whose union covers $A$. We need some standard estimates on covering numbers, that can be found e.g. in Pisier's book [30, Chapter 7]:

Fact 3.1. (i) If $C$ is a convex body and $L$ is a symmetric convex body in $\mathbb{R}^{n}$, then

$$
\begin{equation*}
2^{-n} \frac{|C+L|}{|L|} \leq N(C, L) \leq 2^{n} \frac{|C+L|}{|L|} \tag{3.1}
\end{equation*}
$$

(ii) If both $C$ and $L$ are symmetric, then

$$
\begin{equation*}
|C| \leq N(C, L)|C \cap L| \tag{3.2}
\end{equation*}
$$

Let $C$ be a symmetric convex body in $\mathbb{R}^{n}$. Using Fact 3.1 we can give a lower bound for $|C \cap U(C)|$ which is actually valid for every $U \in O(n)$. From (3.2) it follows that

$$
\begin{equation*}
1=|C| \leqslant N(C, U(C))|C \cap U(C)| . \tag{3.3}
\end{equation*}
$$

In order to estimate $N(C, U(C))$, for every $\varrho>0$ we write

$$
\begin{equation*}
N(C, U(C)) \leqslant N\left(C, \varrho \overline{B_{2}^{n}}\right) N\left(\varrho \overline{B_{2}^{n}}, U(C)\right)=N\left(C, \varrho \overline{B_{2}^{n}}\right) N\left(\varrho \overline{B_{2}^{n}}, C\right) \tag{3.4}
\end{equation*}
$$

On the other hand,

$$
\begin{equation*}
N\left(\varrho \overline{B_{2}^{n}}, C\right) \leqslant 2^{n}\left|\varrho \overline{B_{2}^{n}}+C\right| \leqslant(4 \varrho)^{n} N\left(C, \varrho \overline{B_{2}^{n}}\right), \tag{3.5}
\end{equation*}
$$

using (3.1) and the fact that $|C|=\left|\overline{B_{2}^{n}}\right|=1$. It follows that

$$
\begin{equation*}
N(C, U(C)) \leqslant(4 \varrho)^{n}\left[N\left(C, \varrho \overline{B_{2}^{n}}\right)\right]^{2}, \tag{3.6}
\end{equation*}
$$

and in a similar way we check that

$$
\begin{equation*}
N(C, U(C)) \leqslant(4 / \varrho)^{n}\left[N\left(\varrho \overline{B_{2}^{n}}, C\right)\right]^{2} \tag{3.7}
\end{equation*}
$$

Putting these estimates together, we get:
Lemma 3.2. Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. For every $\varrho>0$ and any $U \in O(n)$ one has

$$
\begin{equation*}
|C \cap U(C)| \geqslant\left[\min \left\{(4 \varrho)^{n / 2} N\left(C, \varrho \overline{B_{2}^{n}}\right),(4 / \varrho)^{n / 2} N\left(\varrho \overline{B_{2}^{n}}, C\right)\right\}\right]^{-2} \tag{3.8}
\end{equation*}
$$

One can estimate the covering numbers $N\left(C, \varrho \overline{B_{2}^{n}}\right)$ and $N\left(\varrho \overline{B_{2}^{n}}, C\right)$ using Sudakov's inequality and its dual (see e.g. [30]). Recall that $\overline{B_{2}^{n}} \simeq \sqrt{n} B_{2}^{n}$ and hence

$$
N\left(C, \varrho \overline{B_{2}^{n}}\right) \leqslant \exp \left(c_{1} w^{2}(C) / \varrho^{2}\right) \quad \text { and } \quad N\left(\varrho \overline{B_{2}^{n}}, C\right) \leqslant \exp \left(c_{1} \varrho^{2} n^{2} M^{2}(C)\right)
$$

where $c_{1}>0$ is an absolute constant. Choosing $\varrho=1$ in Lemma 3.2, we get

$$
\begin{equation*}
|C \cap U(C)| \geqslant \frac{1}{4^{n} \exp \left(\min \left\{2 c_{2} w^{2}(C), 2 c_{1} n^{2} M^{2}(C)\right\}\right)} . \tag{3.9}
\end{equation*}
$$

Taking into account the fact that $\min \{w(C) / \sqrt{n}, \sqrt{n} M(C)\} \geqslant c_{3}$ (which implies that $4^{n} \leqslant \exp \left(c_{4} n \min \left\{w^{2}(C) / n, n M^{2}(C)\right\}\right)$, we conclude the following.

Theorem 3.3. Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. For any $U \in O(n)$ we have

$$
\begin{equation*}
|C \cap U(C)| \geqslant e^{-c n \min \left\{w^{2}(C) / n, n M^{2}(C)\right\}} \tag{3.10}
\end{equation*}
$$

where $c>0$ is an absolute constant.
We may apply Theorem 3.3 to the normalized balls $\overline{B_{p}^{n}}, 1 \leqslant p \leqslant \infty$. The known estimates for $\left|B_{p}^{n}\right|$ imply that if $1 \leqslant p \leqslant 2$ then $\overline{B_{p}^{n}} \simeq n^{1 / p} B_{p}^{n}$. On the other hand, $\|x\|_{p} \leqslant n^{\frac{1}{p}-\frac{1}{2}}\|x\|_{2}$ and hence $M\left(B_{p}^{n}\right) \leqslant n^{\frac{1}{p}-\frac{1}{2}}$. Therefore,

$$
M\left(\overline{B_{p}^{n}}\right) \leqslant c n^{-\frac{1}{p}} M\left(B_{p}^{n}\right) \leqslant c / \sqrt{n}
$$

Moreover, if $2 \leqslant p \leqslant \infty$ and if $q$ is the conjugate exponent of $p$, then $\overline{B_{p}^{n}} \simeq n^{1 / p} B_{p}^{n}$ and hence

$$
w\left(\overline{B_{p}^{n}}\right) \leqslant c n^{\frac{1}{p}} w\left(B_{p}^{n}\right)=c n^{\frac{1}{p}} M\left(B_{q}^{n}\right) \leqslant c n^{\frac{1}{p}} n^{\frac{1}{q}-\frac{1}{2}}=c \sqrt{n} .
$$

Combining the above, we see that

$$
\min \left\{w^{2}\left(\overline{B_{p}^{n}}\right) / n, n M^{2}\left(\overline{B_{p}^{n}}\right)\right\} \leqslant c
$$

for all $1 \leqslant p \leqslant \infty$, where $c>0$ is an absolute constant. Theorem 3.3 gives:

Proposition 3.4. For any $1 \leqslant p \leqslant \infty$ and any $U \in O(n)$ we have

$$
\begin{equation*}
\left|\overline{B_{p}^{n}} \cap U\left(\overline{B_{p}^{n}}\right)\right| \geqslant e^{-c n}, \tag{3.11}
\end{equation*}
$$

where $c>0$ is an absolute constant.
A second application of Lemma 3.2 can be given in the case where $C$ is in $M$ position. Milman (see e.g. [23]) proved that there exists an absolute constant $\beta>0$ such that every symmetric convex body $C$ in $\mathbb{R}^{n}$ has a linear image $\tilde{C}$ of volume 1 which satisfies

$$
\begin{equation*}
\max \left\{N\left(\tilde{C}, \overline{B_{2}^{n}}\right), N\left(\overline{B_{2}^{n}}, \tilde{C}\right)\right\} \leqslant \exp (\beta n) \tag{3.12}
\end{equation*}
$$

We say that a convex body $C$ which satisfies this estimate is in $M$-position with constant $\beta$. Applying Lemma 3.2 we get:

Proposition 3.5. Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. If $C$ is in $M$-position with constant $\beta$ then, for any $U \in O(n)$ we have

$$
\begin{equation*}
|C \cap U(C)| \geqslant e^{-2(\beta+1) n} \tag{3.13}
\end{equation*}
$$

Next, assume that $K$ is in the isotropic position. We use the following lemma (see [4, Section 3.2]): If $K$ is an isotropic convex body in $\mathbb{R}^{n}$ then, for every $t>0$,

$$
\begin{equation*}
N\left(K, t \overline{B_{2}^{n}}\right) \leqslant \exp \left(\frac{c n L_{K}}{t}\right), \tag{3.14}
\end{equation*}
$$

where $c>0$ is an absolute constant. In particular,

$$
\begin{equation*}
N\left(K, L_{K} \bar{B}_{2}^{n}\right) \leqslant e^{c n} \tag{3.15}
\end{equation*}
$$

But then, from (3.6) we have

$$
\begin{equation*}
N(K, U(K)) \leqslant\left(4 L_{K} e^{2 c}\right)^{n} \tag{3.16}
\end{equation*}
$$

and Lemma 3.2 implies the following:
Proposition 3.6. Let $K$ be an isotropic symmetric convex body in $\mathbb{R}^{n}$. Then,

$$
\begin{equation*}
|K \cap U(K)| \geqslant\left(c_{1} L_{K}\right)^{-n} \tag{3.17}
\end{equation*}
$$

for every $U \in O(n)$, where $c_{1} \geqslant 4$ is an absolute constant.

## 4 Upper bounds for the volume

Our upper bounds for $\mathbb{E}_{U}|C \cap U(C)|$ will be based on Lemma 4.2. This follows from Fubini's theorem and the next fact (see e.g. [18]; in fact, both statements hold true for any star body $C$ in $\mathbb{R}^{n}$ ).

Lemma 4.1. If $A$ is a symmetric convex body in $\mathbb{R}^{n}$, then

$$
\frac{1}{2} \sigma\left(S^{n-1} \cap \frac{1}{2} A\right) \leqslant \gamma_{n}(\sqrt{n} A) \leqslant \sigma\left(S^{n-1} \cap 2 A\right)+e^{-c n}
$$

Lemma 4.2. Let $C$ be a symmetric convex body in $\mathbb{R}^{n}$. Then,

$$
\begin{equation*}
\int_{O(n)}|C \cap U(C)| d \nu(U) \leqslant 2 \int_{C} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} C\right) d x \tag{4.1}
\end{equation*}
$$

Proof. Using basic properties of the Haar measure $\nu$ on $O(n)$ we may express the expectation of $|C \cap U(C)|$ as follows:

$$
\begin{align*}
\int_{O(n)}|C \cap U(C)| d \nu(U) & =\int_{O(n)} \int_{\mathbb{R}^{n}} \chi_{C}(x) \chi_{C}(U x) d x d \nu(U)  \tag{3.8}\\
& =\int_{\mathbb{R}^{n}} \chi_{C}(x) \int_{O(n)} \chi_{C}(U x) d \nu(U) d x \\
& =\int_{C} \nu(\{U \in O(n): U x \in C\}) d x \\
& =\int_{C} \nu\left(\left\{U \in O(n):\|x\|_{2} U\left(x /\|x\|_{2}\right) \in C\right\}\right) d x \\
& =\int_{C} \sigma\left(\left\{\theta \in S^{n-1}: \theta \in \frac{1}{\|x\|_{2}} C\right\}\right) d x \\
& =\int_{C} \sigma\left(S^{n-1} \cap \frac{1}{\|x\|_{2}} C\right) d x
\end{align*}
$$

From Lemma 4.1 we get

$$
\begin{equation*}
\sigma\left(S^{n-1} \cap \frac{1}{\|x\|_{2}} C\right) \leqslant 2 \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} C\right) \tag{4.2}
\end{equation*}
$$

and the lemma follows.
A simple consequence of Lemma 4.2 is the next fact.
Proposition 4.3. There exists an absolute constant $\alpha_{0}>0$ such that if $C$ is a symmetric convex body of volume 1 in $\mathbb{R}^{n}$ then

$$
\begin{equation*}
\int_{O(n)}|C \cap U(C)| d \nu(U) \leqslant \gamma_{n}\left(\alpha_{0} C\right)+e^{-n} \tag{4.3}
\end{equation*}
$$

Proof. Let $\rho_{n}=e^{-1} \omega_{n}^{-1 / n}$. Then, we have

$$
\int_{C \cap \rho_{n} B_{2}^{n}} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} C\right) d x \leqslant\left|C \cap \rho_{n} B_{2}^{n}\right| \leqslant\left|\rho_{n} B_{2}^{n}\right|=e^{-n} .
$$

On the other hand, if $x \in C \backslash \rho_{n} B_{2}^{n}$ then

$$
\frac{2 \sqrt{n}}{\|x\|_{2}} \leqslant \frac{2 \sqrt{n}}{\rho_{n}}=2 e \sqrt{n} \omega_{n}^{1 / n}
$$

Therefore,

$$
\int_{C \backslash \rho_{n} B_{2}^{n}} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} C\right) d x \leqslant \gamma_{n}\left(\alpha_{0} C\right),
$$

where $\alpha_{0}=\sup _{n} 2 e \sqrt{n} \omega_{n}^{1 / n} \sim 2 e \sqrt{2 \pi e}$.
In view of Proposition 4.3 we need to control $\gamma_{n}(t C), t>0$. One way is to use the parameter $d_{r}(C)$. Recall that, for any $r>1$, we set

$$
d_{r}(C)=\min \left\{-\log \sigma\left(\left\{x \in S^{n-1}:\|x\|_{C} \leqslant \frac{M(C)}{r}\right\}\right), n\right\} .
$$

One of the main results in [18] is the following small ball probability estimate:
Theorem 4.4. For every $r>1$ and every $0<\varepsilon<\frac{1}{32 r^{2}}$ we have

$$
\begin{equation*}
\gamma_{n}(\varepsilon \sqrt{n} M(C) C) \leqslant\left(c_{1} \varepsilon\right)^{c_{2}(r) d_{r}(C)} \leqslant\left(c_{1} \varepsilon\right)^{c_{3}(r) k(C)} \tag{4.4}
\end{equation*}
$$

where $c_{1}>0$ is an absolute constant and $c_{2}(r), c_{3}(r) \simeq \frac{1}{\log (8 r)}$.
For completeness we sketch the proof of Theorem 4.4. The main tool is the $B$-theorem of Cordero-Erausquin, Fradelizi and Maurey [5]: if $C$ is a symmetric convex body in $\mathbb{R}^{n}$ then the function

$$
t \mapsto \gamma_{n}\left(e^{t} C\right)
$$

is log-concave on $\mathbb{R}$. This implies that $\gamma_{n}\left(a^{\lambda} b^{1-\lambda} C\right) \geqslant \gamma_{n}(a C)^{\lambda} \gamma_{n}(b C)^{1-\lambda}$ for all $a, b>0$ and $\lambda \in(0,1)$. We use this fact in the following way. Let $m=\operatorname{med}\left(\|\cdot\|_{C}\right)$ denote the median (or Lévy mean) of $\|\cdot\|_{C}$ on $S^{n-1}$. Markov's inequality shows that

$$
\frac{m}{2} \leqslant \int_{\left\{\theta:\|\theta\|_{C} \geqslant m\right\}}\|\theta\|_{C} d \sigma(\theta) \leqslant M(C) .
$$

It is also known that, conversely, $M(C) \leqslant c_{0} m$ for some absolute constant $c_{0}>0$, a fact that will be used in the end of the proof.

We set $D=m \sqrt{n} C$. According to Lemma 4.1 we have

$$
\begin{equation*}
\gamma_{n}(2 D) \geqslant \frac{1}{2} \sigma\left(S^{n-1} \cap m C\right) \geqslant \frac{1}{4} \tag{4.5}
\end{equation*}
$$

by the definition of the median. On the other hand, using Lemma 4.1 again, we have

$$
\begin{align*}
\gamma_{n}\left(\frac{1}{4 r} D\right) & \leqslant \sigma\left(S^{n-1} \cap \frac{m}{2 r} C\right)+e^{-c n}  \tag{4.6}\\
& =\sigma\left(\left\{\theta \in S^{n-1}:\|\theta\|_{C} \leqslant \frac{m}{2 r}\right\}\right)+e^{-c n} \\
& \leqslant \sigma\left(\left\{\theta \in S^{n-1}:\|\theta\|_{C} \leqslant \frac{M(C)}{r}\right\}\right)+e^{-c n} \\
& \leqslant 2 e^{-c_{1} d_{r}(C)}
\end{align*}
$$

where $c_{1}>0$ is a suitable absolute constant. We may assume that $0<\varepsilon<\frac{1}{32 r^{2}}$ and then we apply the $B$-theorem for the body $D$, with $a=\varepsilon, b=2$ and $\lambda=$ $\log (8 r) / \log \frac{2}{\varepsilon}$. This gives

$$
\begin{equation*}
\gamma_{n}(\varepsilon D)^{\frac{\log (8 r)}{\log (2 / \varepsilon)}} \gamma_{n}(2 D)^{1-\frac{\log (8 r)}{\log (2 r)}} \leqslant \gamma_{n}\left(\frac{1}{4 r} D\right) . \tag{4.7}
\end{equation*}
$$

Note that $\frac{\log (8 r)}{\log (2 / \varepsilon)}<\frac{1}{2}$, and hence $\gamma_{n}(2 D)^{1-\frac{\log (8 r)}{\log (2 / \varepsilon)}} \geqslant \frac{1}{2}$. Combining (4.5), (4.6) and (4.7) we see that

$$
\begin{equation*}
\gamma_{n}(\varepsilon D) \leqslant\left(4 e^{-c_{1} d_{r}(C)}\right)^{\frac{\log (2 / \varepsilon)}{\log (8 r)}} \leqslant\left(c_{2} \varepsilon\right)^{c_{3}(r) d_{r}(C)} \tag{4.8}
\end{equation*}
$$

where $c_{3}(r)=\frac{c_{3}}{\log (8 r)}$ for some absolute constant $c_{3}>0$. This proves (4.4).
Next, we combine Proposition 4.3 with Theorem 4.4.
Proposition 4.5. There exists an absolute constant $B_{0}>0$ such that if $r>1$ and $C$ is a symmetric convex body of volume 1 in $\mathbb{R}^{n}$ with $\sqrt{n} M(C) \geqslant B_{0} r^{2}$ then

$$
\begin{equation*}
\int_{O(n)}|C \cap U(C)| d \nu(U) \leqslant e^{-\frac{c}{\log (8 r)} d_{r}(C)} \tag{4.9}
\end{equation*}
$$

for all $r>1$, where $c>0$ is an absolute constant.
Proof. From Theorem 4.4 we know that if $0<\varepsilon<\frac{1}{c_{2} r^{2}}$ then

$$
\gamma_{n}(\varepsilon M(C) \sqrt{n} C) \leqslant\left(c_{1} \varepsilon\right)^{c_{2}(r) d_{r}(C)} .
$$

Let $\varepsilon=\frac{\alpha_{0}}{\sqrt{n} M(C)}$. If $\sqrt{n} M(C) \geqslant \max \left\{c_{1} e, c_{2} r^{2}\right\} \alpha_{0}$ then we get

$$
\gamma_{n}\left(\alpha_{0} C\right) \leqslant e^{-\frac{c_{3}}{\log (8 r)} d_{r}(C)}
$$

The result follows from Proposition 4.3.
Remark 4.6. An alternative estimate can be given in terms of the inradius $r$

$$
r(C)=\sup \left\{r>0: r B_{2}^{n} \subseteq C\right\}
$$

of the body $C$. One can use the next small ball probability estimate which is due to Latała and Oleszkiewicz [19] (the proof is based again on the $B$-theorem): Let $A$ be a symmetric convex body in $\mathbb{R}^{n}$ with inradius $r=r(A)$ and $\gamma_{n}(A) \leqslant 1 / 2$. For any $0 \leqslant \varepsilon \leqslant 1$ we have

$$
\begin{equation*}
\gamma_{n}(\varepsilon A) \leqslant(2 \varepsilon)^{r(A)^{2} / 4} \gamma_{n}(D) \tag{4.10}
\end{equation*}
$$

We use this result as follows: assume that $C$ is a symmetric convex body of volume 1 in $\mathbb{R}^{n}$ with $\sqrt{n} M(C) \geqslant B_{0}$ and $d(C) \geqslant B_{0}$. We check that $A=\frac{m \sqrt{n}}{8} C$ satisfies $\gamma_{n}(A) \leqslant \frac{1}{2}$, and hence, applying (4.10) for $A$, we see that if $0<\varepsilon<\frac{1}{2 e}$ then
$\gamma_{n}(\varepsilon A) \leqslant 2 e^{-r^{2}(A) / 4}$. Note that $\frac{\varepsilon m \sqrt{n}}{8}=\alpha_{0}$ if we choose $\varepsilon=\frac{8 \alpha_{0}}{\sqrt{n} m}$. If $\sqrt{n} m \geqslant 16 e \alpha_{0}$ then we get

$$
\gamma_{n}\left(\alpha_{0} C\right) \leqslant 2 e^{-r^{2}(A) / 4}=2 e^{-n m^{2} r^{2}(C)}
$$

From Proposition 4.3 we get $\mathbb{E}_{U}|C \cap U(C)| \leqslant \exp \left(-c n m^{2}(C) r^{2}(C)\right)$. However, note that $n m^{2}(C) r^{2}(C) \leqslant 4 n M^{2}(C) r^{2}(C) \simeq k(C) \leqslant c^{\prime} d(C)$.
Remark 4.7. Recall that for every symmetric convex body $C$ of volume 1 in $\mathbb{R}^{n}$ one has

$$
\sqrt{n} M(C) \geqslant \sqrt{n}\left(\frac{\left|B_{2}^{n}\right|}{|C|}\right)^{1 / n}=\sqrt{n} \omega_{n}^{1 / n} \sim \sqrt{2 \pi e}
$$

So, the condition $\sqrt{n} M(C) \geqslant B_{0}$ is not satisfied by those bodies for which

$$
M(C) \operatorname{vrad}(C) \simeq 1
$$

An example is given by the Euclidean ball $\overline{B_{2}^{n}}$ of volume 1. However, in this case one has $\left|\overline{B_{2}^{n}} \cap U\left(\overline{B_{2}^{n}}\right)\right|=1$ for all $U \in O(n)$. In other words, if one asks for a non-trivial (exponentially small) upper bound for the expectation of $|C \cap U(C)|$ then some condition is required. Thus, the condition $\sqrt{n} M(C) \geqslant B_{0}$ seems very natural.

In the example of the cube $Q_{n}=\left[-\frac{1}{2}, \frac{1}{2}\right]^{n}$ one has $\sqrt{n} M\left(Q_{n}\right) \simeq \sqrt{\log n}$ and hence Proposition 4.5 applies. However, it is easier to compute $\gamma_{n}\left(\alpha_{0} Q_{n}\right)$ directly and then to apply Proposition 4.3. If $\Phi(t)=\frac{1}{\sqrt{2 \pi}} \int_{-\infty}^{t} e^{-s^{2} / 2} d s$ is the distribution function of a standard normal random variable then one has

$$
\gamma_{n}\left(\alpha_{0} Q_{n}\right)=\left(2 \Phi\left(\alpha_{0} / 2\right)-1\right)^{n}=e^{-\delta_{0} n}
$$

where $\delta_{0}\left(\alpha_{0}\right)>0$ is defined by the equation $2 \Phi\left(\alpha_{0} / 2\right)-1=e^{-\delta_{0}}$. In [18] it is checked that $c_{1} n^{1-c_{1} r^{-2}} \leqslant d_{r}\left(Q_{n}\right) \leqslant c_{2} n^{1-c_{2} r^{-2}}$ for all $r>1$. Therefore, using Proposition 4.5 with $r \simeq \sqrt[4]{\log n}$, one would obtain the estimate

$$
\mathbb{E}_{U}\left(Q_{n} \cap U\left(Q_{n}\right)\right) \leqslant e^{-c n^{1-\delta}}
$$

for any $\delta>0$ and any $n \geqslant n_{0}(\delta)$. An analogous situation appears for any $2<$ $q<\infty$; one has $d_{c_{q}}\left(B_{q}^{n}\right) \geqslant C_{q} n$ for some constants $c_{q}, C_{q}>0$ depending only on $q$. This leads to an upper bound for $\mathbb{E}_{U}\left|\overline{B_{q}^{n}} \cap U\left(\overline{B_{q}^{n}}\right)\right|$ of the form $\exp \left(-n^{1-\delta}\right)$ for any $0<\delta<1$, at least when $q$ and $n$ are large enough. These bounds should be compared with the lower bound from Fact 3.4.

In the last section of this article we apply Proposition 4.5 to the centroid bodies $Z_{q}(\mu)$ of an isotropic log-concave measure $\mu$ on $\mathbb{R}^{n}$. The next proposition provides an alternative argument leading to an upper bound for $\mathbb{E}_{U}|K \cap U(K)|$ in the case where $K$ is an isotropic convex body in $\mathbb{R}^{n}$.

Proposition 4.8. Let $K$ be an isotropic convex body in $\mathbb{R}^{n}$. Assume that $L_{K}=$ $(1+\delta) \sqrt{2 / \pi}$ for some $\delta>0$. Then,

$$
\begin{equation*}
\int_{O(n)}|K \cap U(K)| d \nu(U) \leqslant c_{1} e^{-c_{2}(\delta) \sqrt{n}} \tag{4.11}
\end{equation*}
$$

where $c_{1}>0$ is an absolute constant and $c_{2}(\delta) \simeq \min \left\{1, \delta^{3}\right\}$.
Proof. Assume that $L_{K}>\sqrt{2 / \pi}$, and write $L_{K}=(1+\delta) \sqrt{2 / \pi}$ for some $\delta>0$. Let $\varepsilon \in(0,1)$ that will be suitably chosen depending on $\delta$. From the thin-shell estimate (2.20) we know that if

$$
\begin{equation*}
A:=\left\{x \in K:\left|\|x\|_{2}-\sqrt{n} L_{K}\right| \leqslant \varepsilon \sqrt{n} L_{K}\right\} \tag{4.12}
\end{equation*}
$$

then

$$
\begin{equation*}
|A| \geqslant 1-C_{1} \exp \left(-c_{2} \varepsilon^{3} \sqrt{n}\right) \tag{4.13}
\end{equation*}
$$

provided $n$ is large enough. Let $\rho=\varepsilon \sqrt{n} L_{K}$. If $K_{\rho}=K \cap \rho B_{2}^{n}$, from (4.13) we know that $\left|K_{\rho}\right| \leqslant C_{1} \exp \left(-c_{2} \varepsilon^{3} \sqrt{n}\right)$. Then,

$$
\begin{equation*}
\int_{K_{\rho}} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} K\right) d x \leqslant\left|K_{\rho}\right| \leqslant C_{1} \exp \left(-c_{2} \varepsilon^{3} \sqrt{n}\right) \tag{4.14}
\end{equation*}
$$

On the other hand,

$$
\begin{equation*}
\int_{K \backslash K_{\rho}} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} K\right) d x \leqslant\left|K \backslash K_{\rho}\right| \gamma_{n}\left(\frac{2}{(1-\varepsilon) L_{K}} K\right), \tag{4.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\gamma_{n}(a K) \leqslant\left(\frac{a}{\sqrt{2 \pi}}\right)^{n}|K| \tag{4.16}
\end{equation*}
$$

for every $a>0$, so

$$
\begin{align*}
\int_{K \backslash K_{\rho}} \gamma_{n}\left(\frac{2 \sqrt{n}}{\|x\|_{2}} K\right) d x & \leqslant\left(\frac{2}{(1-\varepsilon) \sqrt{2 \pi} L_{K}}\right)^{n}  \tag{4.17}\\
& =\left(\frac{1}{(1-\varepsilon)(1+\delta)}\right)^{n} \leqslant C_{2} e^{-c_{3} \min \{1, \delta\} n}
\end{align*}
$$

if we choose $\varepsilon<\min \{1, \delta\} / 3$. It follows that

$$
\begin{equation*}
\int_{O(n)}|K \cap U(K)| d \nu(U) \leqslant c_{1} e^{-c_{4}(\delta) \sqrt{n}} \tag{4.18}
\end{equation*}
$$

with $c_{4}(\delta) \simeq[\min \{1, \delta\}]^{3}$.

## 5 Upper bounds for the radius

Let $C$ be a symmetric convex body of volume 1 in $\mathbb{R}^{n}$. In this Section we briefly recall known arguments leading to an upper bound for the radius $R(C \cap U(C))$ of the intersection of $C$ with its random rotations $U(C)$.

Proposition 5.1. If $R(C \cap E) \leqslant r$ for all $E$ in a subset of $G_{n, n / 2}$ of measure greater than $1 / 2$ then there exists $U \in O(n)$ such that $R(C \cap U(C)) \leqslant \sqrt{2} r$.

Proof. We use a standard argument which goes back to Krivine (see [30] or [24]). From the assumption we know that there exists $E \in G_{n, n / 2}$ such that

$$
\begin{equation*}
\|y\|_{C} \geqslant \frac{1}{r}\|y\|_{2} \tag{5.1}
\end{equation*}
$$

for all $y \in E$ and all $y \in E^{\perp}$. We write $P_{1}=P_{E}$ and $P_{2}=P_{E^{\perp}}$. Then, we write $I=P_{1}+P_{2}$ and we define $U=P_{1}-P_{2} \in O(n)$. Let $x \in \mathbb{R}^{n}$. We write $x=x_{1}+x_{2}$, where $x_{1}=P_{1}(x)$ and $x_{2}=P_{2}(x)$. Then,

$$
\begin{aligned}
\left\|x_{1}+x_{2}\right\|_{C}+\left\|x_{1}-x_{2}\right\|_{C} & \geqslant 2 \max \left\{\left\|x_{1}\right\|_{C},\left\|x_{2}\right\|_{C}\right\} \geqslant \frac{2}{r} \max \left\{\left\|x_{1}\right\|_{2},\left\|x_{2}\right\|_{2}\right\} \\
& \geqslant \frac{\sqrt{2}}{r} \sqrt{\left\|x_{1}\right\|_{2}^{2}+\left\|x_{2}\right\|_{2}^{2}}=\frac{\sqrt{2}}{r}\|x\|_{2}
\end{aligned}
$$

This means that

$$
\begin{equation*}
\|x\|_{C}+\|x\|_{U^{-1}(C)} \geqslant \frac{\sqrt{2}}{r}\|x\|_{2} \tag{5.2}
\end{equation*}
$$

or equivalently, since $U=U^{*}$,

$$
\begin{equation*}
2 \operatorname{conv}\left(C^{\circ} \cup U\left(C^{\circ}\right)\right) \supseteq C^{\circ}+U\left(C^{\circ}\right) \supseteq \frac{\sqrt{2}}{r} B_{2}^{n} \tag{5.3}
\end{equation*}
$$

Taking polars we conclude the proof.
The next observation is that the existence of one e.g. $3 n / 4$-dimensional section with radius $r$ implies that random $n / 2$-dimensional sections have radius of the same order. Then, we may apply Proposition 5.1 to find $U \in O(n)$ with $R(C \cap U(C)) \leqslant$ $c_{3} r$.

Theorem 5.2. If $R(C \cap F) \leqslant r$ for some $F \in G_{n, 3 n / 4}$ then a random subspace $E \in G_{n, n / 2}$ satisfies

$$
R(C \cap E) \leqslant c_{1} r
$$

with probability greater than $1-e^{-c_{2} n}$.
Proof. This fact has been observed in [8], [33] and soon after, in a sharper form, in [20] where it was proved that if $C$ is a symmetric convex body in $\mathbb{R}^{n}$, and if $1 \leqslant k<m<n$ and $\mu=\frac{n-k}{n-m}$, then assuming that $R(C \cap F) \leqslant r$ for some $F \in G_{n, m}$ we have that a random subspace $E \in G_{n, k}$ satisfies

$$
R(C \cap E) \leqslant r\left(c_{2} \sqrt{\frac{n}{n-m}}\right)^{\frac{\mu}{\mu-1}}
$$

with probability greater than $1-2 e^{-(n-k) / 2}$, where $c_{2}>0$ is an absolute constant.

Assume that $R(C \cap F) \leqslant r$ for some $F \in G_{n, m}$, where $m=3 n / 4$. Applying the above with $k=n / 2$ (and $\mu=2$ ) we conclude the proof.

We can actually prove an analogue of Proposition 5.1 for a random $U \in O(n)$ using the next result of Vershynin and Rudelson [33]: There exist absolute constants $c_{0}, c_{1}>0$ with the following property: if $C$ and $D$ are two symmetric convex bodies in $\mathbb{R}^{n}$ which have sections of dimensions at least $k$ and $n-c_{0} k$ whose radius is bounded by 1 , then a random $U \in O(n)$ satisfies $R(C \cap U(D)) \leqslant c_{1}^{n / k}$ with probability greater than $1-e^{-n}$. We set $D=C$ and $k=n / 2$ to get the following.

Theorem 5.3. If

$$
r_{C}:=\min \left\{R(C \cap F): \operatorname{dim}(F)=\left\lceil\left(1-c_{0} / 2\right) n\right\rceil\right\}
$$

then $R(C \cap U(C)) \leqslant c_{2} r_{C}$ with probability greater than $1-e^{-n}$ with respect to $U \in O(n)$.

An immediate application of Theorem 5.3 is an estimate for $R(C \cap U(C))$ in terms of the mean width $w(C)$. By the low $M^{*}$-estimate (2.7) we know that $r_{C} \leqslant$ $c_{3} w(C)$. Thus, we have:

Proposition 5.4. Let $C$ be a symmetric convex body in $\mathbb{R}^{n}$. A random $U \in O(n)$ satisfies

$$
R(C \cap U(C)) \leqslant c w(C)
$$

with probability greater than $1-e^{-n}$, where $c>0$ is an absolute constant.

## 6 Applications to centroid bodies of log-concave measures

As an application of the results of the previous sections, we discuss the case of the centroid bodies $Z_{q}(\mu)$ of an isotropic log-concave measure $\mu$ on $\mathbb{R}^{n}$.

Starting with the volume, and in view of Proposition 4.5, we need a lower bound for $d\left(Z_{q}(\mu)\right)$. We will use the fact that

$$
d\left(Z_{q}(\mu)\right) \geqslant c_{1} k\left(Z_{q}(\mu)\right)=c_{1} k_{*}\left(Z_{q}^{\circ}(\mu)\right)
$$

Assuming that $2 \leqslant q \leqslant q_{*}(\mu)$ we have

$$
w\left(Z_{q}^{\circ}(\mu)\right)=M\left(Z_{q}(\mu)\right) \geqslant\left(\frac{\left|B_{2}^{n}\right|}{\left|Z_{q}(\mu)\right|}\right)^{1 / n} \geqslant \frac{c_{2}}{\sqrt{q}}
$$

while the inclusion $B_{2}^{n}=Z_{2}(\mu) \subseteq Z_{q}(\mu)$ implies that $R\left(Z_{q}^{\circ}(\mu)\right) \leqslant 1$. It follows that

$$
\begin{equation*}
d\left(Z_{q}(\mu)\right) \geqslant c_{1} k_{*}\left(Z_{q}^{\circ}(\mu)\right) \geqslant c_{4} n \frac{w^{2}\left(Z_{q}^{\circ}(\mu)\right)}{R^{2}\left(Z_{q}^{\circ}(\mu)\right)} \geqslant \frac{c_{5} n}{q} . \tag{6.1}
\end{equation*}
$$

It is convenient to normalize the volume, and consider $\overline{Z_{q}}(\mu)$ instead of $Z_{q}(\mu)$. Recall from Section 2 that if $q \leqslant \sqrt{n}$ then $\left|Z_{q}(\mu)\right|^{1 / n} \simeq \sqrt{q / n}$, and hence

$$
\overline{Z_{q}}(\mu) \simeq \sqrt{n / q} Z_{q}(\mu)
$$

Then,

$$
\begin{equation*}
M\left(\overline{Z_{q}}(\mu)\right) \simeq \sqrt{q / n} M\left(Z_{q}(\mu)\right) \tag{6.2}
\end{equation*}
$$

We can now apply Proposition 4.5.
Proposition 6.1. Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$ and let $2 \leqslant$ $q \leqslant \sqrt{n}$. If $\sqrt{q} M\left(Z_{q}(\mu)\right) \geqslant B_{1}$ then

$$
\begin{equation*}
\int_{O(n)}\left|\overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right)\right| d \nu(U) \leqslant e^{-c_{1} n / q} \tag{6.3}
\end{equation*}
$$

where $B_{1}, c_{1}>0$ are absolute constants.
On the other hand, from 2.17 we see that $w\left(\overline{Z_{q}}(\mu)\right) \simeq \sqrt{n / q} w\left(Z_{q}(\mu)\right) \simeq \sqrt{n}$. Therefore, Theorem 3.3 gives:

Proposition 6.2. Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$ and let $2 \leqslant$ $q \leqslant \sqrt{n}$. For any $U \in O(n)$ one has

$$
\begin{equation*}
\left|\overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right)\right| \geqslant e^{-c_{2} n} \tag{6.4}
\end{equation*}
$$

where $c_{2}>0$ is an absolute constant.
Next, we discuss the radius of $\overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right)$. Our main tool is a (simplified version of a) result from [9] about proportional projections of the centroid bodies.

Theorem 6.3. Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$. For every $0<$ $\varepsilon<1$ and any $q \leqslant \sqrt{\varepsilon n}$ we may find $k \geqslant(1-\varepsilon) n$ and $F \in G_{n, k}$ such that

$$
\begin{equation*}
P_{F}\left(Z_{q}(\mu)\right) \supseteq c_{1} \varepsilon^{2} \sqrt{q} B_{F}, \tag{6.5}
\end{equation*}
$$

where $c_{1}>0$ is an absolute constant.
Now, we can use Theorem 5.3 to give a lower bound for the radius of $Z_{q}(\mu) \cap$ $U\left(Z_{q}(\mu)\right)$ or $Z_{q}^{\circ}(\mu) \cap U\left(Z_{q}^{\circ}(\mu)\right)$ for a random $U \in O(n)$. Since the mean width of $Z_{q}(\mu), 2 \leqslant q \leqslant \sqrt{n}$, is known to be of the order of $\sqrt{q}$, we can use the low $M^{*}$-estimate to get that if $\varepsilon \in(0,1)$ and $k=(1-\varepsilon) n$, then a subspace $F \in G_{n, k}$ satisfies

$$
\begin{equation*}
R\left(Z_{q}(\mu) \cap F\right) \leqslant \frac{c_{2} \sqrt{q}}{\sqrt{\varepsilon}} \tag{6.6}
\end{equation*}
$$

with probability greater than $1-\exp \left(-c_{2} \varepsilon n\right)$, where $c_{1}, c_{2}>0$ are absolute constants. Applying this fact with $k=n / 2$ we see that the bodies $C=D=\frac{c_{3}}{\sqrt{q}} Z_{q}(\mu)$
have sections of dimensions at least $n / 2$ and $\left(1-c_{0} / 2\right) n$ whose radius is bounded by 1 (it suffices to choose $c_{3}>0$ small enough). Then, from Theorem 5.3 we get $R\left(Z_{q}(\mu) \cap U\left(Z_{q}(\mu)\right)\right) \leqslant c_{4} \sqrt{q}$ with probability greater than $1-e^{-n}$.

Similarly, from Theorem 6.3 we know that

$$
R\left(Z_{q}^{\circ}(\mu) \cap F\right) \leqslant \frac{c_{2}}{\varepsilon^{2} \sqrt{q}}
$$

for a random $F \in G_{n,(1-\varepsilon) n}$. Applying this fact with $k=n / 2$ we see that the bodies $C=D=c_{3} \sqrt{q} Z_{q}^{\circ}(\mu)$ have sections of dimensions at least $n / 2$ and ( $1-c_{0} / 2$ ) $n$ whose radius is bounded by 1 (it suffices to choose $c_{3}>0$ small enough). Then, from Theorem 5.3 we get $R\left(Z_{q}^{\circ}(\mu) \cap U\left(Z_{q}^{\circ}(\mu)\right)\right) \leqslant c_{4} / \sqrt{q}$ with probability greater than $1-e^{-n}$.

We summarize in the next theorem.
Theorem 6.4. Let $\mu$ be an isotropic log-concave measure on $\mathbb{R}^{n}$. For any $2 \leqslant q \leqslant$ $\sqrt{n}$, a random $U \in O(n)$ satisfies

$$
Z_{q}(\mu)+U\left(Z_{q}(\mu)\right) \supseteq c_{1} \sqrt{q} B_{2}^{n} \quad \text { and } \quad Z_{q}^{\circ}(\mu)+U\left(Z_{q}^{\circ}(\mu)\right) \supseteq \frac{c_{1}}{\sqrt{q}} B_{2}^{n}
$$

or equivalently,

$$
\overline{Z_{q}^{\circ}}(\mu) \cap U\left(\overline{Z_{q}^{\circ}}(\mu)\right) \subseteq c_{2} \sqrt{n} B_{2}^{n} \quad \text { and } \quad \overline{Z_{q}}(\mu) \cap U\left(\overline{Z_{q}}(\mu)\right) \subseteq c_{2} \sqrt{n} B_{2}^{n}
$$

with probability greater than $1-2 e^{-n}$.
Acknowledgment. We would like to thank the referee for comments and valuable suggestions on the presentation of the results of this article.

## References

[1] C. Borell, Convex measures on locally convex spaces, Ark. Mat. 12 (1974), 239-252.
[2] J. Bourgain, On the distribution of polynomials on high dimensional convex sets, Geom. Aspects of Funct. Analysis (Lindenstrauss-Milman eds.), Lecture Notes in Math. 1469 (1991), 127-137.
[3] J. Bourgain and V. D. Milman, New volume ratio properties for convex symmetric bodies in $\mathbb{R}^{n}$, Invent. Math. 88 (1987), 319-340.
[4] S. Brazitikos, A. Giannopoulos, P. Valettas and B-H. Vritsiou, Geometry of isotropic convex bodies, Mathematical Surveys and Monographs, Amer. Math. Society (to appear).
[5] D. Cordero-Erausquin, M. Fradelizi and B. Maurey, The (B)-conjecture for the Gaussian measure of dilates of symmetric convex sets and related problems, J. Funct. Anal. 214 (2004), 410-427.
[6] B. Fleury, Concentration in a thin Euclidean shell for log-concave measures, J. Funct. Anal. 259 (2010), 832-841.
[7] B. Fleury, O. Guédon and G. Paouris, A stability result for mean width of $L_{p^{-}}$ centroid bodies, Adv. Math. 214, 2 (2007), 865-877.
[8] A. Giannopoulos, V. D. Milman and A. Tsolomitis, Asymptotic formulas for the diameter of sections of symmetric convex bodies, Journal of Functional Analysis 223 (2005), 86-108.
[9] A. Giannopoulos, P. Stavrakakis, A. Tsolomitis and B-H. Vritsiou, Geometry of the $L_{q}$-centroid bodies of an isotropic log-concave measure, Trans. Amer. Math. Soc. (to appear).
[10] Y. Gordon, On Milman's inequality and random subspaces which escape through a mesh in $\mathbb{R}^{n}$, Lecture Notes in Mathematics 1317 (1988), 84-106.
[11] O. Guédon and E. Milman, Interpolating thin-shell and sharp large-deviation estimates for isotropic log-concave measures, Geom. Funct. Anal. 21 (2011), 1043-1068.
[12] B. S. Kashin, Sections of some finite-dimensional sets and classes of smooth functions, Izv. Akad. Nauk. SSSR Ser. Mat. 41 (1977), 334-351.
[13] B. Klartag, On convex perturbations with a bounded isotropic constant, Geom. Funct. Anal. 16 (2006), 1274-1290.
[14] B. Klartag, A central limit theorem for convex sets, Invent. Math. 168 (2007), 91-131.
[15] B. Klartag, Power-law estimates for the central limit theorem for convex sets, J. Funct. Anal. 245 (2007), 284-310.
[16] B. Klartag and E. Milman, Centroid Bodies and the Logarithmic Laplace Transform - A Unified Approach, J. Funct. Anal. 262 (2012), 10-34.
[17] B. Klartag and E. Milman, Inner regularization of log-concave measures and smallball estimates, in Geom. Aspects of Funct. Analysis (Klartag-Mendelson-Milman eds.), Lecture Notes in Math. 2050 (2012), 267-278.
[18] B. Klartag and R. Vershynin, Small ball probability and Dvoretzky theorem, Israel J. Math. 157 (2007), 193-207.
[19] R. Latała and K. Oleszkiewicz, Small ball probability estimates in terms of widths, Studia Math. 169 (2005), 305-314.
[20] A. E. Litvak, A. Pajor and N. Tomczak-Jaegermann, Diameters of Sections and Coverings of Convex Bodies, J. Funct. Anal. 231 (2006), 438-457.
[21] V. D. Milman, Geometrical inequalities and mixed volumes in the Local Theory of Banach spaces, Astérisque 131 (1985), 373-400.
[22] V. D. Milman, Random subspaces of proportional dimension of finite dimensional normed spaces: approach through the isoperimetric inequality, Lecture Notes in Mathematics 1166 (1985), 106-115.
[23] V. D. Milman, Isomorphic symmetrization and geometric inequalities, Lecture Notes in Mathematics 1317 (1988), 107-131.
[24] V. D. Milman, Some applications of duality relations, Lecture Notes in Mathematics 1469 (1991), 13-40.
[25] V. D. Milman and G. Schechtman, Asymptotic Theory of Finite Dimensional Normed Spaces, Lecture Notes in Mathematics 1200 (1986), Springer, Berlin.
[26] V. D. Milman and G. Schechtman, Global versus Local asymptotic theories of finitedimensional normed spaces, Duke Math. Journal 90 (1997), 73-93.
[27] A. Pajor and N. Tomczak-Jaegermann, Subspaces of small codimension of finite dimensional Banach spaces, Proc. Amer. Math. Soc. 97 (1986), 637-642.
[28] G. Paouris, Concentration of mass in convex bodies, Geometric and Functional Analysis 16 (2006), 1021-1049.
[29] G. Paouris, Small ball probability estimates for log-concave measures, Trans. Amer. Math. Soc. 364 (2012), 287-308.
[30] G. Pisier, The Volume of Convex Bodies and Banach Space Geometry, Cambridge Tracts in Mathematics 94 (1989).
[31] R. Schneider, Convex Bodies: The Brunn-Minkowski Theory, Encyclopedia of Mathematics and its Applications 44, Cambridge University Press, Cambridge (1993).
[32] S. J. Szarek and N. Tomczak-Jaegermann, On nearly Euclidean decompositions of some classes of Banach spaces, Compositio Math. 40 (1980), 367-385.
[33] R. Vershynin, Isoperimetry of waists and local versus global asymptotic convex geometries (with an appendix by M. Rudelson and R. Vershynin), Duke Mathematical Journal 131 (2006), 1-16.

Keywords: Convex bodies, log-concave probability measures, volume estimates, random rotations.
2010 MSC: Primary 52A23; Secondary 46B06, 52A40.

Silouanos Brazitikos: Department of Mathematics, University of Athens, Panepistimioupolis 15784 , Athens, Greece.
E-mail: silouanb@math.uoa.gr
Pantelis Stavrakakis: Department of Mathematics, University of Athens, Panepistimioupolis 15784 , Athens, Greece.
E-mail: pantstav@yahoo.gr

