On the Ψ_2-behavior of linear functionals on isotropic convex bodies

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Abstract

The slicing problem can be reduced to the study of isotropic convex bodies K with $\operatorname{diam}(K) \leq c\sqrt{n}L_K$, where L_K is the isotropic constant. We study the ψ_2-behavior of linear functionals on this class of bodies. It is proved that $\|\langle \cdot, \theta \rangle\|_{\psi_2} \leq CL_K$ for all θ in a subset U of S^{n-1} with measure $\sigma(U) \geq 1 - \exp(-c\sqrt{n})$. However, there exist isotropic convex bodies K with uniformly bounded geometric distance from the Euclidean ball, such that $\max_{\theta \in S^{n-1}} \|\langle \cdot, \theta \rangle\|_{\psi_2} \geq c\sqrt[4]{n}L_K$. In a different direction, we show that good average ψ_2-behavior of linear functionals on an isotropic convex body implies very strong dimension-dependent concentration of volume inside a ball of radius $r \simeq \sqrt{n}L_K$.

1 Introduction

Let K be a convex body in $\mathbb{R}^n$ with volume $|K| = 1$ and center of mass at the origin. Let $\alpha \in [1,2]$. For every bounded measurable function $f : K \to \mathbb{R}$, the α-Orlicz norm of f is defined by

$$
(1.1) \qquad \|f\|_{\psi_\alpha} = \inf \left\{ t > 0 : \int_K e^{|f/t|^\alpha} dx \leq 2 \right\}.
$$

It is not hard to check that $\|f\|_{\psi_\alpha} \simeq \sup\{q^{-1/\alpha}\|f\|_q : q \geq \alpha\}$. For every $x \in \mathbb{R}^n$ we consider the linear functional $f_x(y) = \langle y, x \rangle$. We say that x defines a ψ_α-direction for K with a constant $b > 0$ if

$$
(1.2) \qquad \|f_x\|_{\psi_\alpha} \leq b\|f_x\|_\alpha.
$$

Equivalently, if $\|f_x\|_q \leq cbq^{1/\alpha}\|f_x\|_\alpha$ for every $q \geq \alpha$, where $c > 0$ is an absolute constant. We say that K is a ψ_α-body with constant b if (1.2) holds for every x.

It is clear that if x defines a ψ_α-direction for K and if $T \in SL(n)$, then T^*x defines a ψ_α-direction (with the same constant) for $T(K)$. It follows that $T(K)$ is

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a ψ_α-body if K is a ψ_α-body. By Borell's lemma (see [17], Appendix III), there exists an absolute constant $C > 0$ with the following property: every convex body K is a ψ_1-body with constant C.

The study of ψ_2-directions for linear functionals on convex bodies is motivated by the well-known problem of the isotropic constant (see [13]). A convex body K in $\mathbb{R}^n$ is said to be isotropic if it has volume $|K| = 1$, center of mass at the origin, and there exists a constant $L_K > 0$ such that

$$(1.3) \qquad \int_K \langle y, \theta \rangle^2 dy = L_K^2$$

for every $\theta \in S^{n-1}$. Every convex body with center of mass at the origin has a linear image which is isotropic. Moreover, this image is unique up to orthogonal transformations; this shows that the *isotropic constant* L_K is well-defined for the linear class of K.

The isotropic constant is closely related to the slicing problem which asks if there exists an absolute constant $c > 0$ such that $\max_{\theta \in S^{n-1}} |K \cap \theta^\perp| \geq c$ for every convex body K of volume 1 in $\mathbb{R}^n$ with center of mass at the origin. Indeed, by Brunn's principle, for any convex body K in $\mathbb{R}^n$ and any $\theta \in S^{n-1}$ the function $t \mapsto |K \cap (\theta^\perp + t\theta)|$ is log-concave on its support, and this implies that

$$(1.4) \qquad \int_K \langle y, \theta \rangle^2 dy \simeq |K \cap \theta^\perp|^{-2}.$$

Using this relation one can check (see [13]) that an affirmative answer to the slicing problem is equivalent to the following statement: There exists an absolute constant $C > 0$ such that $L_K \leq C$ for every convex body K of volume 1 with center of mass at the origin.

One can easily see that $L_K = O(\sqrt{n})$ for every K. Uniform boundedness of L_K is known for some classes of bodies: unit balls of spaces with 1-unconditional basis, zonoids and their polars, etc. The best known general upper estimate is due to Bourgain [3] (see [15] for the not necessarily symmetric case): $L_K \leq c \sqrt[4]{n} \log n$, where $c > 0$ is an absolute constant. Bourgain's argument reduces the problem to the class of isotropic convex bodies K with circumradius $R(K) \leq c\sqrt{n}L_K$, where $c > 0$ is an absolute constant. The other main ingredient of the argument is the fact that every convex body is a ψ_1-body with a uniform constant. One can see from the proof that stronger information on the ψ_2-behavior of linear functionals on K, combined with Talagrand's majorizing measure theorem and Pisier's MM^*-estimate, would result in an $O(\log n)$ estimate for L_K. In fact, Bourgain [4] has recently shown that the isotropic constant of a ψ_2-body with constant b is bounded by $cb \log b$. In view of these observations, V. Milman asked the following question.

Question. Let K be an isotropic convex body in $\mathbb{R}^n$. Is it true that most $\theta \in S^{n-1}$ define a ψ_2-direction for K with a "good" constant (say, logarithmic in n)?

In fact, it is not known if there exists an absolute constant $C > 0$ such that every isotropic convex body has at least one ψ_2-direction with constant C. Bobkov

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and Nazarov (see [6] and [7]) have recently proved that if K is an isotropic 1-unconditional convex body, then $\|f_\theta\|_{\psi_2} \leq c\sqrt{n}\|\theta\|_\infty$ for every $\theta \in S^{n-1}$. In particular, the diagonal direction is a ψ_2-direction. Zonoids form a second class of convex bodies for which the existence of good ψ_2-directions can be established (see [16]). As for ψ_2-bodies, it is presently known that the unit balls of ℓ_q^n, $2 \leq q \leq \infty$ are ψ_2-bodies with a uniformly bounded constant C (see [5] and [8]).

The aim of this paper is to study the ψ_2-behavior of linear functionals on isotropic convex bodies K with $R(K) \leq \gamma\sqrt{n}L_K$ in terms of the parameter $\gamma > 0$. We call these "isotropic bodies with small diameter". Our general positive results are summarized in the following theorem.

Theorem A *Let K be an isotropic convex body in $\mathbb{R}^n$. If $K \subseteq (\gamma\sqrt{n}L_K)B_2^n$ for some $\gamma > 0$, then*

$$(1.5) \qquad \sigma\big(\theta \in S^{n-1} : \|f_\theta\|_{\psi_2} \geq c_1\gamma t L_K\big) \leq \exp(-c_2\sqrt{n}t^2/\gamma)$$

for every $t \geq 1$, where $c_1, c_2 > 0$ are absolute constants.

In other words, for a random direction $\theta \in S^{n-1}$, an isotropic convex body with small diameter satisfies

$$(1.6) \qquad \|\langle \cdot, \theta \rangle\|_{\psi_2} \leq C\gamma L_K.$$

However, the concentration estimate is rather weak (observe the $\sqrt{n}$-dependence in Theorem A) to be directly applicable to the slicing problem. It turns out that the positive result of Theorem A is optimal. One can construct an isotropic convex body K with small diameter, for which $\max_\theta \|f_\theta\|_{\psi_2} \simeq \sqrt[4]{n}L_K$. Surprisingly enough, the example may be given by a body whose geometric distance to the Euclidean ball is uniformly bounded.

Theorem B *There exists an isotropic convex body of revolution K in $\mathbb{R}^n$ with the following properties:*

$$(1.7) \qquad c_1\sqrt{n}B_2^n \subseteq K \subseteq c_2\sqrt{n}B_2^n$$

and

$$(1.8) \qquad \|\langle \cdot, e_n \rangle\|_{\psi_2} \geq c_3\sqrt[4]{n}$$

where $c_1, c_2, c_3 > 0$ are absolute constants.

Theorems A and B are proved in Sections 2 and 3 respectively. In Section 4 we discuss the relation of the ψ_2-behavior of linear functionals to a different question about the concentration of mass on isotropic convex bodies. Alesker [1] has proved that if K is isotropic, then the Euclidean norm $f(y) = \|y\|_2$ satisfies the ψ_2-estimate $\|f\|_{\psi_2} \leq c\|f\|_1 \leq c\sqrt{n}L_K$ where $c > 0$ is an absolute constant. This leads to the tail estimate

$$(1.9) \qquad \text{Prob}\left(\{y \in K : \|y\|_2 \geq c_1 t\sqrt{n}L_K\}\right) \leq 2\exp(-t^2)$$

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for every $t > 0$. Bobkov and Nazarov [6] have obtained a striking dimension-dependent result in the 1-unconditional case: There exists an absolute constant $c > 0$ such that if K is an isotropic 1-unconditional convex body in $\mathbb{R}^n$, then

$$(1.10) \qquad \text{Prob}\left(\left\{y \in K : \|y\|_2 \geq ct\sqrt{n}\right\}\right) \leq \exp\left(-t\sqrt{n}\right)$$

for every $t \geq 1$. This estimate is stronger than (1.9) for all $t \geq 1$. A question which arises naturally and was actually stated in [6] is whether such an inequality may hold in full generality. This question is studied in [17] where equivalent conditions are provided. The results of [17] were recently used in [10] to establish a positive answer for a non-unconditional case: the unit balls of the Schatten trace classes S_p^n, $1 \leq p \leq \infty$, of matrices on $\mathbb{R}^n$ or $\mathbb{C}^n$. Here we show that, in general, good average ψ_2-behavior of linear functionals implies a very strong dimension-dependent concentration.

Theorem C *Let K be an isotropic convex body in $\mathbb{R}^n$. Assume that*

$$(1.11) \qquad \int_{S^{n-1}} \|f_\theta\|_{\psi_2}\sigma(d\theta) \leq \gamma L_K$$

for some $\gamma > 0$. Then,

$$(1.12) \qquad \text{Prob}\left(\left\{y \in K : \|y\|_2 \geq c_1\gamma t\sqrt{n}L_K\right\}\right) \leq \exp\left(-c_2 t\sqrt{n}\right)$$

for every $t \geq 1$, where $c_1, c_2 > 0$ are absolute constants.

For the proof of Theorem C we study from an asymptotic point of view the family of L_q-centroid bodies of an isotropic convex body. In fact, this study was at the basis of our original proof of Theorem A. The possibility of giving the simpler proof in Section 2 was kindly pointed out to the author by G. Schechtman and B. Klartag. Nevertheless, the proof of Theorem C indicates that this line of thought has some interesting consequences.

Notation. We work in $\mathbb{R}^n$, which is equipped with a Euclidean structure $\langle \cdot, \cdot \rangle$. We denote by $\|\cdot\|_2$ the corresponding Euclidean norm, and write B_2^n for the Euclidean unit ball and S^{n-1} for the unit sphere. Volume is denoted by $|\cdot|$. We write σ for the rotationally invariant probability measure on S^{n-1} and ω_n for the volume of B_2^n.

A convex body is a compact convex subset K of $\mathbb{R}^n$ with non-empty interior. We say that K is symmetric (or centered) if $x \in K \Rightarrow -x \in K$. We say that K has centre of mass at the origin if $\int_K \langle x, \theta \rangle dx = 0$ for every $\theta \in S^{n-1}$.

The circumradius of K is the quantity $R(K) = \max\{\|x\|_2 : x \in K\}$, and the polar body K° of K is

$$(1.13) \qquad K^\circ := \{y \in \mathbb{R}^n : \langle x, y \rangle \leq 1 \text{ for all } x \in K\}.$$

Let V be a symmetric convex body in $\mathbb{R}^n$. The function $\|x\|_V = \inf\{\lambda > 0 : x \in \lambda V\}$ is a norm on $\mathbb{R}^n$, and the space $(\mathbb{R}^n, \|\cdot\|_V)$ will be denoted by X_V. The dual space of X_V is X_{V°.

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Whenever we write $a \simeq b$, we mean that there exist absolute constants $c_1, c_2 > 0$ such that $c_1 a \leq b \leq c_2 a$. The letters c, c', C, c_1, c_2 etc. denote absolute positive constants which may change from line to line. We refer to the books of Schneider [18] and Milman-Schechtman [14] for basic facts from the Brunn-Minkowski theory and the asymptotic theory of finite dimensional normed spaces. A classical reference for isotropic convex bodies and the slicing problem is the paper [13] of Milman and Pajor.

2   Isotropic convex bodies with small diameter

Let K be an isotropic convex body in $\mathbb{R}^n$. In this Section we assume that $K \subseteq (\gamma \sqrt{n} L_K) B_2^n$ (one can easily check that γ must exceed an absolute constant $c > 0$). If $\gamma \simeq 1$ we say that K is "an isotropic convex body with small diameter". Our aim is to show that a random $\theta \in S^{n-1}$ defines a ψ_2-direction with constant $C(\gamma)$. The precise statement is the following.

Theorem 2.1 *Let K be an isotropic convex body in $\mathbb{R}^n$. Assume that for some $\gamma > 0$ we have $K \subseteq (\gamma \sqrt{n} L_K) B_2^n$. Then,*

$$(2.1) \qquad \sigma(\theta \in S^{n-1} : \|f_\theta\|_{\psi_2} \geq c_1 \gamma t L_K) \leq \exp(-c_2 \sqrt{n} t^2 / \gamma)$$

for every $t \geq 1$, where $c_1, c_2 > 0$ are absolute constants.

The proof will be based on a well-known consequence of the spherical isoperimetric inequality (see [14]): Let $n \geq 4$. If $F : S^{n-1} \to \mathbb{R}$ is a Lipschitz continuous function with constant b_F, then

$$(2.2) \qquad \sigma(\theta \in S^{n-1} : F(\theta) \geq m_F + s) \leq \exp\left(-\frac{ns^2}{4b_F^2}\right)$$

for every $s > 0$, where m_F is the Lévy mean of F (the unique $m > 0$ for which $\sigma(\{F(\theta) \geq m\}) \geq 1/2$ and $\sigma(\{F(\theta) \leq m\}) \geq 1/2$).

Consider the function $F(\theta) = \|f_\theta\|_{\psi_2}$ on S^{n-1}. In the next two Claims we estimate the parameters b_F and m_F.

Claim 2.2 *We have $b_F \leq c_3 \sqrt{\gamma} \sqrt[4]{n} L_K$, where $c_3 > 0$ is an absolute constant.*

Proof. Let $\theta \in S^{n-1}$. From the definition of $\| \cdot \|_{\psi_\alpha}$ we check that

$$(2.3) \qquad \|f_\theta\|_{\psi_2}^2 \leq \|f_\theta\|_{\psi_1} \|f_\theta\|_\infty.$$

Since every $\theta \in S^{n-1}$ defines a ψ_1-direction with constant C and $\|f_\theta\|_\infty \leq R(K) \leq \gamma\sqrt{n}L_K$, we get

$$(2.4) \qquad \|f_\theta\|_{\psi_2}^2 \leq (CL_K)(\gamma\sqrt{n}L_K).$$

Then, the claim follows from the triangle inequality for $\|\cdot\|_{\psi_2}$. □

The next lemma will allow us to estimate m_F (a similar argument appears in [16]).

Lemma 2.3 *Let K be an isotropic convex body in $\mathbb{R}^n$ with $K \subseteq (\gamma\sqrt{n}L_K)B_2^n$. Then,*

$$(2.5) \qquad \int_{S^{n-1}} \int_K \exp\left(\frac{|\langle y,\theta\rangle|}{c_4\gamma L_K}\right)^2 dy\sigma(d\theta) \leq 2,$$

where $c_4 > 0$ is an absolute constant.

Proof. A direct computation shows that for every $p \geq 1$ and every $x \in \mathbb{R}^n$,

$$(2.6) \qquad \left(\int_{S^{n-1}} |\langle y,\theta\rangle|^p \sigma(d\theta)\right)^{1/p} \simeq \left(\frac{p}{p+n}\right)^{1/2} \|y\|_2.$$

Let $c_4 > 0$ be a constant to be determined. We have
$$(2.7)$$
$$\int_{S^{n-1}} \int_K \exp\left(\frac{|\langle y,\theta\rangle|}{c_4\gamma L_K}\right)^2 dy\sigma(d\theta) = 1 + \sum_{k=1}^{\infty} \frac{1}{k!c_4^{2k}\gamma^{2k}L_K^{2k}} \int_K \int_{S^{n-1}} |\langle y,\theta\rangle|^{2k}\sigma(d\theta)dy.$$

Using (2.6) we see that the right hand side of (2.7) is bounded by

$$(2.8) \qquad 1 + \sum_{k=1}^{\infty} \frac{1}{k!c_4^{2k}\gamma^{2k}L_K^{2k}} \left(\frac{2c_5k}{2k+n}\right)^k \int_K \|y\|_2^{2k}dy$$

where $c_5 > 0$ is an absolute constant. Since $\|y\|_2 \leq \gamma\sqrt{n}L_K$ for every $y \in K$, we get

$$(2.9) \qquad \int_{S^{n-1}} \int_K \exp\left(\frac{|\langle y,\theta\rangle|}{c_4\gamma L_K}\right)^2 dy\sigma(d\theta) \leq 1 + \sum_{k=1}^{\infty} \left(\frac{2ec_5^2n}{c_4^2(2k+n)}\right)^k \leq 2$$

if we choose $c_4 = 2\sqrt{e}c_5$. □

An application of Markov's inequality shows that, with probability greater than or equal to $1/2$, a vector $\theta \in S^{n-1}$ satisfies

$$(2.10) \qquad \frac{1}{(c_4\gamma L_K)^{2k}} \int_K |f_\theta(y)|^{2k}dx \leq k! \int_K \exp\left(\frac{|f_\theta(y)|}{c_4\gamma L_K}\right)^2 dx \leq 4k!.$$

Since $\|f_\theta\|_{\psi_2} \simeq \sup\left\{\frac{\|f_\theta\|_{2k}}{\sqrt{k}} : k \in \mathbb{N}\right\}$, we have

$$(2.11) \qquad \sigma\left(\{\theta \in S^{n-1} : \|f_\theta\|_{\psi_2} \leq c_6\gamma L_K\}\right) \geq 1/2$$

for some absolute constant $c_6 > 0$. This proves our second Claim.

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Claim 2.4 *We have $m_F \leq c_6 \gamma L_K$, where $c_6 > 0$ is an absolute constant.* $\square$

Proof of Theorem 2.1. We first observe that $\|f_\theta\|_{\psi_2} \geq c_7 \|f_\theta\|_2 = c_7 L_K$ for every $\theta \in S^{n-1}$, and hence,

$$(2.12) \qquad\qquad m_F \geq c_7 L_K,$$

where $c_7 > 0$ is an absolute constant. Let $t \geq 1$. We apply (2.2) with $s = t m_F$, and using (2.12), Claim 2.2 and Claim 2.4 we get

$$
\begin{aligned}
\sigma(\theta \in S^{n-1} : \|f_\theta\|_{\psi_2} \geq c_6 \gamma (1+t) L_K) &\leq \sigma(\theta \in S^{n-1} : \|f_\theta\|_{\psi_2} \geq (1+t) m_F) \\
&\leq \exp\left(-\frac{n t^2 m_F^2}{4 b_F^2}\right) \\
&\leq \exp\left(-\frac{c_7^2 n t^2 L_K^2}{4 c_3^2 \gamma \sqrt{n} L_K^2}\right) \\
&= \exp(-c_2 \sqrt{n} t^2 / \gamma),
\end{aligned}
$$

where $c_2 = c_7^2 / (4 c_3^2)$. Since $c_6 (1+t) \leq 2 c_6 t$, the result follows with $c_1 = 2 c_6$. $\square$

3 An example

In this Section we exhibit an example of an isotropic convex body K in $\mathbb{R}^n$ which has bounded geometric distance from the Euclidean unit ball but has the worst possible ψ_2-behavior. One can build such an example inside the class of bodies of revolution.

Lemma 3.1 *There exist $a \simeq \sqrt{n}$ and $b \simeq 1/\sqrt{n}$ such that the symmetric convex body*

$$(3.1) \qquad\qquad C = \{y = (x,t) : |t| \leq a, \|x\|_2 \leq a - b|t|\}$$

has volume 1 and satisfies

$$(3.2) \qquad\qquad c_1 \leq \int_C \langle y, \theta \rangle^2 dy \leq c_2$$

for every $\theta \in S^{n-1}$, where $c_1, c_2 > 0$ are absolute constants.

Proof. Let r_{n-1} be the solution of the equation $\omega_{n-1} r^{n-1} = 1$, and consider the body

$$(3.3) \qquad C_1 = \{(x,t) : |t| \leq r_{n-1}, \|x\|_2 \leq r_{n-1} - |t|/\sqrt{n}\}.$$

Since $r_{n-1} \simeq \sqrt{n}$, we easily check that
(3.4)

$$
|C_1| = 2\omega_{n-1} \int_0^{r_{n-1}} \left(r_{n-1} - \frac{t}{\sqrt{n}}\right)^{n-1} dt = 2\omega_{n-1} r_{n-1}^n \sqrt{n} \frac{1 - \left(1 - \frac{1}{\sqrt{n}}\right)^n}{n} \simeq 1.
$$

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Therefore, we may find $s > 0$ with $s^n \simeq 1$ such that $C := sC_1$ has volume 1. It is clear that C can be written in the form (3.1), with $a = sr_{n-1} \simeq \sqrt{n}$ and $b = 1/\sqrt{n}$. Also, C is symmetric with respect to the coordinate subspaces, and hence, (3.2) will hold for every $\theta \in S^{n-1}$ provided that

$$(3.5) \qquad c_1 \leq \int_C \langle y, e_j \rangle^2 dy \leq c_2.$$

From (1.4) it is enough to check that

$$(3.6) \qquad c_3 \leq |C \cap e_j^{\perp}| \leq c_4$$

for every $j = 1, \ldots, n$. Let $j \leq n - 1$. Then,

$$
\begin{aligned}
|C_1 \cap e_j^{\perp}| &= 2\omega_{n-2} \int_0^{r_{n-1}} \left(r_{n-1} - \frac{t}{\sqrt{n}} \right)^{n-2} dt \\
&\leq 2\omega_{n-2} \left(\int_0^{r_{n-1}} \left(r_{n-1} - \frac{t}{\sqrt{n}} \right)^{n-1} dt \right)^{\frac{n-2}{n-1}} \sqrt[n-1]{r_{n-1}} \\
&= 2\omega_{n-2} \left(\frac{|C_1|}{\omega_{n-1}} \right)^{\frac{n-2}{n-1}} \sqrt[n-1]{r_{n-1}} \leq c_5 \sqrt[n-1]{r_{n-1}} \simeq 1.
\end{aligned}
$$

For the lower bound we observe that

$$
\begin{aligned}
|C_1 \cap e_j^{\perp}| &= 2\omega_{n-2} \int_0^{r_{n-1}} \left(r_{n-1} - \frac{t}{\sqrt{n}} \right)^{n-2} dt \\
&\geq \frac{\omega_{n-2}}{r_{n-1}\omega_{n-1}} 2\omega_{n-1} \int_0^{r_{n-1}} \left(r_{n-1} - \frac{t}{\sqrt{n}} \right)^{n-1} dt \\
&= \frac{\omega_{n-2}}{r_{n-1}\omega_{n-1}} \simeq 1.
\end{aligned}
$$

Finally,

$$(3.7) \qquad |C_1 \cap e_n^{\perp}| = \omega_{n-1} r_{n-1}^{n-1} = 1.$$

Since $|C \cap e_j^{\perp}| = s^{n-1}|C_1 \cap e_j^{\perp}| \simeq |C_1 \cap e_j^{\perp}|$ for all $j \leq n$, the lemma is proved. $\square$

Starting with C, we easily pass to a "similar" isotropic body.

Lemma 3.2 *There exist $a_1, R_1 \simeq \sqrt{n}$ and $b_1 \simeq 1/\sqrt{n}$ such that the symmetric convex body*

$$(3.8) \qquad K = \{y = (x,t) : |t| \leq R_1, \|x\|_2 \leq a_1 - b_1|t|\}$$

is isotropic.

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Proof. Consider the body C of the previous Lemma. We first observe (see [13], p. 71) that

$$(3.9) \qquad L_C^{2n} = \prod_{j=1}^{n} \int_C \langle y, e_j \rangle^2 dy.$$

Because of (3.2), this implies that $L_C \simeq 1$. By the symmetries of C there exists a diagonal operator $T = \mathrm{diag}(u, \ldots, u, v)$ such that $K = T(C)$ is isotropic. For every $\theta \in S^{n-1}$ we have

$$(3.10) \qquad 1 \simeq L_C^2 = L_K^2 = \int_K \langle x, \theta \rangle^2 dx = \int_C \langle x, T\theta \rangle^2 dx \simeq \|T\theta\|_2^2.$$

This shows that $u \simeq 1$ and $v \simeq 1$. Finally, K can be written in the form (3.8) with $R_1 = av$, $a_1 = au$ and $b_1 = bu/v$. This completes the proof. $\qquad \square$

Lemma 3.3 *Let K be the body in Lemma 3.2. If $0 < s \leq c_1\sqrt{n}$, then*

$$(3.11) \qquad \mathrm{Prob}\big(\{(x,t) : |t| \geq s\}\big) \geq c_2 \exp(-c_3 s),$$

where $c_1, c_2, c_3 > 0$ are absolute constants.

Proof. Direct computation shows that

$$\begin{aligned}
\mathrm{Prob}\big(\{(x,t) : |t| \geq s\}\big) &= 2\omega_{n-1} \int_s^{R_1} (a_1 - b_1 t)^{n-1} dt \\
&= 2\omega_{n-1} \frac{a_1^n}{nb_1} \left(\left(1 - \frac{b_1 s}{a_1}\right)^n - \left(1 - \frac{b_1 R_1}{a_1}\right)^n \right).
\end{aligned}$$

Since $\omega_{n-1} a_1^{n-1} = |K \cap e_n^\perp| \simeq 1$ and $a_1/(nb_1) \simeq 1$, we see that

$$(3.12) \qquad 2\omega_{n-1} \frac{a_1^n}{nb_1} \geq c_4$$

for some absolute constant $c_4 > 0$. If $s \leq a_1/(2b_1) \simeq n$, using the numerical inequality $1 - x \geq e^{-2x}$ for $x \in [0, 1/2]$, we obtain

$$(3.13) \qquad \left(1 - \frac{b_1 s}{a_1}\right)^n \geq \exp(-2b_1 n s/a_1) \geq \exp(-c_3 s).$$

On the other hand,

$$(3.14) \qquad \left(1 - \frac{b_1 R_1}{a_1}\right)^n \leq \exp(-b_1 R_1 n/a_1) \leq \exp(-c_5\sqrt{n}).$$

If $s \leq c_1\sqrt{n}$ for a suitable absolute constant $c_1 > 0$, then

$$(3.15) \qquad \exp(-c_5\sqrt{n}) \leq \frac{1}{2} \exp(-c_3 s).$$

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It follows that if $s \leq c_1\sqrt{n}$, then

$$(3.16) \qquad \text{Prob}\big(\{(x,t) : |t| \geq s\}\big) \geq (c_4/2)\exp(-c_3 s).$$

This gives the result, with $c_2 = c_4/2$. $\qquad\square$

Lemma 3.4 *Let K be a convex body of volume 1 in $\mathbb{R}^n$. If $q \geq 1$, then*

$$(3.17) \qquad \text{Prob}\,(y \in K : |\langle y, \theta \rangle| \geq \alpha\|f_\theta\|_q s) \leq e^{-qs}$$

for all $\theta \in S^{n-1}$ and $s \geq 1$, where $\alpha > 0$ is an absolute constant.

Proof. Let $q \geq 1$ and $\theta \in S^{n-1}$. Markov's inequality shows that

$$(3.18) \qquad \text{Prob}\,\big(y \in K : |\langle y, \theta \rangle| \geq e^3\|f_\theta\|_q\big) \leq e^{-3q}$$

Since $y \mapsto |\langle y, \theta \rangle|$ is a seminorm, from Borell's lemma (see [14], Appendix III) we get

$$(3.19) \quad \text{Prob}\,\big(y \in K : |\langle y, \theta \rangle| \geq e^3\|f_\theta\|_q s\big) \leq (1 - e^{-3q})\left(\frac{e^{-3q}}{1-e^{-3q}}\right)^{\frac{s+1}{2}} \leq e^{-qs}$$

for every $s \geq 1$. This proves the lemma with $\alpha = e^3$. $\qquad\square$

Remark 3.5 The same lemma is proved in [17] as a consequence of a much more general optimal L^q-norm inequality of Carbery and Wright (see [9]) for polynomials over convex bodies. The simple argument which is presented here was kindly communicated to the author by R. Latala.

Let K be the body from Lemma 3.2. The next two claims describe two "contradictory" properties of K.

Claim 3.6 *We have $c_1\sqrt{n}B_2^n \subseteq K \subseteq c_2\sqrt{n}B_2^n$, where $c_1, c_2 > 0$ are absolute constants.*

Proof. The problem is two-dimensional. For every $y = (x, t) \in K$ we have

$$(3.20) \qquad \|y\|_2^2 = \|x\|_2^2 + t^2 \leq a_1^2 + R_1^2 \leq c_2^2 n,$$

where $c_2 > 0$ is an absolute constant, because $a_1, R_1 \simeq \sqrt{n}$. This shows that $K \subseteq c_2\sqrt{n}B_2^n$. For the other inclusion, we observe that the inradius of K is equal to $\min\{R_1, d\}$, where d is the distance from $(0,0)$ to the line $y = a_1 - b_1 t$ in $\mathbb{R}^2$. We have

$$(3.21) \qquad d = \frac{a_1}{\sqrt{1+b_1^2}} \simeq \sqrt{n},$$

and hence $K \supseteq c_1\sqrt{n}B_2^n$ for some absolute constant $c_1 > 0$. $\qquad\square$

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Claim 3.7 *We have $\|\langle \cdot, e_n \rangle\|_{L^{\psi_2}(K)} \geq c\sqrt[4]{n}$, where $c > 0$ is an absolute constant.*

Proof. Let $q \geq 1$. If $\alpha\|\langle \cdot, e_n \rangle\|_q \leq c_1\sqrt{n}$, Lemmas 3.3 and 3.4 show that

$$(3.22) \quad c_2 \exp(-c_3\alpha\|\langle \cdot, e_n \rangle\|_q) \leq \mathrm{Prob}\big(\{y \in K : |\langle y, e_n \rangle| \geq \alpha\|\langle \cdot, e_n \rangle\|_q\}\big) \leq e^{-q}.$$

For these values of q it follows that

$$(3.23) \qquad\qquad c_3\alpha\|\langle \cdot, e_n \rangle\|_q \geq q + \log c_2.$$

Since e_n defines a ψ_1-direction for K, we have

$$(3.24) \qquad\qquad \|\langle \cdot, e_n \rangle\|_q \leq c_4 q\|\langle \cdot, e_n \rangle\|_1 \leq c_5 q.$$

Therefore, we can find $q_* \simeq \sqrt{n}$ such that $\alpha\|\langle \cdot, e_n \rangle\|_{q_*} \leq c_1\sqrt{n}$. Going back to (3.23) we see that

$$(3.25) \qquad\qquad \|\langle \cdot, e_n \rangle\|_{\psi_2} \geq c_6 \frac{\|\langle \cdot, e_n \rangle\|_{q_*}}{\sqrt{q_*}} \geq c\sqrt[4]{n}$$

for some absolute constant $c > 0$. $\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\quad\square$

Lemma 3.2 and the Claims 3.6 and 3.7 are summarized in the next theorem.

Theorem 3.8 *There exists an isotropic convex body of revolution K in $\mathbb{R}^n$ with the following properties:*

$$(3.26) \qquad\qquad c_1\sqrt{n}B_2^n \subseteq K \subseteq c_2\sqrt{n}B_2^n$$

and

$$(3.27) \qquad\qquad \|\langle \cdot, e_n \rangle\|_{\psi_2} \geq c_3\sqrt[4]{n}$$

where $c_1, c_2, c_3 > 0$ are absolute constants. $\qquad\qquad\qquad\qquad\qquad\quad\square$

4 L_q-centroid bodies

Let K be a convex body of volume 1 in $\mathbb{R}^n$ and let $q \geq 1$. The L_q-centroid body $Z_q(K)$ of K is the symmetric convex body whose support function is given by

$$(4.1) \qquad\qquad N_q(K, x) := \|f_x\|_q = \left(\int_K |\langle y, x \rangle|^q dy \right)^{1/q}.$$

It is easy to check that $Z_p(K) \subseteq Z_q(K) \subseteq Z_\infty(K)$ for every $1 \leq p \leq q \leq \infty$, where $Z_\infty(K) = \widehat{K} := \mathrm{co}\{K, -K\}$. If K has its centre of mass at the origin, then $Z_q(K) \simeq \widehat{K}$ for all $q \geq n$. This is a consequence of the Brunn-Minkowski inequality (for a proof, see [16]). L_q-centroid bodies were introduced in [12] under a different normalization.

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For every $p, q \geq 1$ we define

$$(4.2) \qquad A_q(K) = \int_{S^{n-1}} N_q(K, \theta) \sigma(d\theta)$$

and

$$(4.3) \qquad A_{q,p}(K) = \left(\int_{S^{n-1}} N_q^p(K, \theta) \sigma(d\theta) \right)^{1/p}.$$

The next proposition describes the behavior of $p \mapsto A_{q,p}(K)$ for a fixed value of q.

Proposition 4.1 *Let K be a convex body of volume 1 in $\mathbb{R}^n$ with centre of mass at the origin. For every $p, q \in [1, n]$ we have*

$$(4.4) \qquad A_{q,p}(K) \simeq \max \left\{ A_q(K), \frac{R(Z_q(K))\sqrt{p}}{\sqrt{n}} \right\}.$$

If $p \geq n$, then $A_{q,p}(K) \simeq R(Z_q(K))$.

Proof. Let V be a symmetric convex body in $\mathbb{R}^n$, and let $\| \cdot \|$ be the norm induced by V to $\mathbb{R}^n$. For every $p \geq 1$, let

$$(4.5) \qquad M_p := M_p(V) = \left(\int_{S^{n-1}} \|\theta\|^p \sigma(d\theta) \right)^{1/p}.$$

The behavior of $p \mapsto M_p$ was clarified by Litvak, Milman and Schechtman in [11]: If $R = \max\{\|x\|_2 : x \in V\}$ then

$$(4.6) \qquad M_p \simeq \max \left\{ M_1, \frac{R\sqrt{p}}{\sqrt{n}} \right\}$$

for all $p \in [1, n]$, and $M_p \simeq R$ if $p \geq n$. A direct application to the polar body of $Z_q(K)$ gives the result. $\qquad\square$

Proposition 4.2 *There exist $c_1, c_2 > 0$ and $n_0 \in \mathbb{N}$ with the following property: if $n \geq n_0$ and K is an isotropic convex body in $\mathbb{R}^n$ then, for every $2 \leq q \leq c_1\sqrt{n}$,*

$$(4.7) \qquad I_q(K) := \left(\int_K \|y\|_2^q dy \right)^{1/q} \leq c_2\sqrt{n} \frac{A_q(K)}{\sqrt{q}}.$$

For the proof we will need two simple observations.

Claim 4.3 *Let K be an isotropic convex body in $\mathbb{R}^n$. For every $2 \leq q \leq n$ we have*

$$(4.8) \qquad R(Z_q(K)) \leq c_3 q L_K$$

and

$$(4.9) \qquad A_{q,q}(K) \simeq \sqrt{q/n} I_q(K) \geq c_4 \sqrt{q} L_K$$

where $c_3, c_4 > 0$ are absolute constants.

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Proof of the Claim. The first assertion follows from the fact that K is a ψ_1-body. For the second we use (2.6) and integration over K. The last inequality is a direct consequence of Hölder's inequality: we have $I_q(K) \geq I_2(K) = \sqrt{n}L_K$. □

Proof of Proposition 4.2. Observe that $Z_2(K) = L_K B_2^n$, which implies $R(Z_2(K)) = A_2(K) = L_K$. Also, when $q \to \infty$, both $R(Z_q(K))$ and $A_q(K)$ tend to $R(K)$. So, if we define

$$(4.10) \qquad N(K) := \{q \geq 2 : R(Z_q(K))\sqrt{q} < \sqrt{n}A_q(K)\},$$

we immediately see that $2 \in N(K)$ and $N(K)$ is bounded.

We set $q_* := \sup\{q \geq 2 : [2,q] \subseteq N(K)\}$. Then, q_* is well-defined and the continuity of $R(Z_q(K)$ and $A_q(K)$ with respect to q shows that

$$(4.11) \qquad R(Z_{q_*}(K))\sqrt{q_*} = \sqrt{n}A_{q_*}(K).$$

From Proposition 4.1, this last equation shows that

$$(4.12) \qquad A_{q_*,q_*}(K) \simeq A_{q_*}(K).$$

Going back to (4.11) and using Claim 4.3 we get

$$(4.13) \qquad q_* \geq c_1\sqrt{n}.$$

Finally, since $[2, c_1\sqrt{n}] \subseteq N(K)$, for every $2 \leq q \leq c_1\sqrt{n}$ we have $A_{q,q}(K) \simeq A_q(K)$ and this implies that

$$(4.14) \qquad I_q(K) \simeq \sqrt{n/q}A_{q,q}(K) \leq c_2\sqrt{n}\frac{A_q(K)}{\sqrt{q}}$$

for some absolute constant $c_2 > 0$. □

We can now give a proof of Theorem C based on the following criterion from [17].

Lemma 4.4 *Let $\delta \geq 1$ and let $1 \ll \phi(n) \ll n$ be a positive constant. For every isotropic convex body K in $\mathbb{R}^n$, the following statements are equivalent:*
(a) For every $t \geq 1$,

$$(4.15) \qquad \mathrm{Prob}\left(\{y \in K : \|y\|_2 \geq \delta t\sqrt{n}L_K\}\right) \leq \exp\left(-\phi(n)t\right).$$

(b) For every $2 \leq q \leq c\phi(n)$,

$$(4.16) \qquad I_q(K) = \left(\int_K \|y\|_2^q dy\right)^{1/q} \leq c(\delta)\sqrt{n}L_K,$$

where $c(\delta) \simeq \delta$. □

Proof of Theorem C. We assume that K is an isotropic convex body in $\mathbb{R}^n$ which satisfies

$$(4.17) \qquad \int_{S^{n-1}} \|f_\theta\|_{\psi_2} \sigma(d\theta) \leq \gamma L_K$$

for some $\gamma > 0$. Since $\|f_\theta\|_q \leq c_3 \sqrt{q}\|f_\theta\|_{\psi_2}$ for every $q \geq 2$, we get

$$(4.18) \qquad A_q(K) = \int_{S^{n-1}} \|f_\theta\|_q \sigma(d\theta) \leq c_4 \gamma \sqrt{q} L_K$$

for every $q \geq 2$, where $c_4 > 0$ is an absolute constant. Now, Proposition 4.2 shows that

$$(4.19) \qquad I_q(K) \leq c_5 \gamma \sqrt{n} L_K$$

for every $2 \leq q \leq c_6 \sqrt{n}$, where $c_5, c_6 > 0$ are absolute constants. Then, we can apply Proposition 4.4 with $\delta \simeq \gamma$ and $\phi(n) \simeq \sqrt{n}$ to get

$$(4.20) \qquad \text{Prob}\left(\left\{y \in K : \|y\|_2 \geq c_1 \gamma t \sqrt{n} L_K\right\}\right) \leq \exp\left(-c_2 t \sqrt{n}\right)$$

for every $t \geq 1$, where $c_1, c_2 > 0$ are absolute constants. $\qquad\square$

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