# Random approximation and the vertex index of convex bodies 

Silouanos Brazitikos, Giorgos Chasapis and Labrini Hioni


#### Abstract

We prove that there exists an absolute constant $\alpha>1$ with the following property: if $K$ is a convex body in $\mathbb{R}^{n}$ whose center of mass is at the origin, then a random subset $X \subset K$ of cardinality $\operatorname{card}(X)=\lceil\alpha n\rceil$ satisfies with probability greater than $1-e^{-c_{1} n}$ $$
K \subseteq c_{2} n \operatorname{conv}(X)
$$ where $c_{1}, c_{2}>0$ are absolute constants. As an application we show that the vertex index of any convex body $K$ in $\mathbb{R}^{n}$ is bounded by $c_{3} n^{2}$, where $c_{3}>0$ is an absolute constant, thus extending an estimate of Bezdek and Litvak for the symmetric case.


## 1 Introduction

The starting point of this article is the following fact, which appears in [13] and [3]: If $K$ is an origin symmetric convex body in $\mathbb{R}^{n}$ then for any $d>1$ there exist $N \leqslant d n$ points $x_{1}, \ldots, x_{N} \in K$ such that

$$
\operatorname{absconv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \subseteq K \subseteq \gamma_{d} \sqrt{n} \operatorname{absconv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right)
$$

where $\gamma_{d}:=\frac{\sqrt{d}+1}{\sqrt{d}-1}$. For the proof one assumes that the Euclidean unit ball $B_{2}^{n}$ is the ellipsoid of minimal volume containing $K$, and makes essential use of a theorem of Batson, Spielman and Srivastava [4] on extracting an approximate John's decomposition with few vectors from a John's decomposition of the identity. An extension of this result to the non-symmetric case was recently obtained by the first named author in [8: There exists an absolute constant $\alpha>1$ with the following property: if $K$ is a convex body whose minimal volume ellipsoid is the Euclidean unit ball, then there exist $N \leqslant \alpha n$ points $x_{1}, \ldots, x_{N} \in K \cap S^{n-1}$ such that

$$
\begin{equation*}
K \subseteq B_{2}^{n} \subseteq c n^{3 / 2} \operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \tag{1.1}
\end{equation*}
$$

where $c>0$ is an absolute constant. The proof involves a more delicate theorem of Srivastava from [26]. Using (1.1) one can establish the following "quantitative diameter version" of Helly's theorem (see [8): If $\left\{P_{i}: i \in I\right\}$ is a finite family of convex bodies in $\mathbb{R}^{n}$ with $\operatorname{diam}\left(\bigcap_{i \in I} P_{i}\right)=1$, then there exist $s \leqslant \alpha n$ and $i_{1}, \ldots i_{s} \in I$ such that

$$
\operatorname{diam}\left(P_{i_{1}} \cap \cdots \cap P_{i_{s}}\right) \leqslant c n^{3 / 2}
$$

where $c>0$ is an absolute constant. For this application it is crucial to choose the points $x_{1}, \ldots, x_{N}$ in 1.1) among the contact points of $K$ and its minimal volume ellipsoid.

Our first main result shows that if we choose $x_{1}, \ldots, x_{N}$ independently and uniformly from $K$ then we can have a random version of (1.1) with an improved dependence on the dimension.

Theorem 1.1. There exists an absolute constant $\alpha>1$ with the following property: if $K$ is a convex body in $\mathbb{R}^{n}$ whose center of mass is at the origin and $x_{1}, \ldots, x_{N}, N=\lceil\alpha n\rceil$, are independent random points uniformly distributed in $K$ then, with probability greater than $1-e^{-c_{1} n}$ we have

$$
K \subseteq c_{2} n \operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right)
$$

where $c_{1}, c_{2}>0$ are absolute constants.

For the proof we may assume that $K$ is an isotropic convex body (see Section 2 for background information) and we use the so-called one-sided $L_{q}$-centroid bodies of $K$; these are the convex bodies $Z_{q}^{+}(K), q \geqslant 1$, with support functions

$$
h_{Z_{q}^{+}(K)}(y)=\left(2 \int_{K}\langle x, y\rangle_{+}^{q} d x\right)^{1 / q}
$$

where $a_{+}=\max \{a, 0\}$. We show that if $N \geqslant \alpha n$, where $\alpha>1$ is an absolute constant, then $N$ independent random points $x_{1}, \ldots, x_{N}$ uniformly distributed in $K$ satisfy

$$
\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq c_{1} Z_{2}^{+}(K) \supseteq c_{2} L_{K} B_{2}^{n}
$$

with probability greater than $1-\exp \left(-c_{3} n\right)$, where $c_{1}, c_{2}, c_{3}>0$ are absolute constants. Since $K$ is contained in $(n+1) L_{K} B_{2}^{n}$, Theorem 1.1 follows.

A natural question, which is closely related to Theorem 1.1, is to fix $N \geqslant \alpha n$ and to ask for the largest value $t(N, n)$ for which $N$ independent random points $x_{1}, \ldots, x_{N}$ uniformly distributed in $K$ satisfy

$$
\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq t(N, n) K
$$

with probability "exponentially close" to 1. A sharp answer to this question would unify Theorem 1.1 and the following result from [11] which deals with the case where $N$ is exponential in $n$ : For every $\delta \in(0,1)$ there exists $n_{0}=n_{0}(\delta)$ such that for every $n \geqslant n_{0}$, if $C \log n / n \leqslant \gamma \leqslant 1$ and $K$ is a centered convex body in $\mathbb{R}^{n}$, then $N=\exp (\gamma n)$ independent random points $x_{1}, \ldots, x_{N}$ chosen uniformly from $K$ satisfy with probability greater than $1-\delta$

$$
K \supseteq \operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq c(\delta) \gamma K
$$

where $c(\delta)$ is a constant depending on $\delta$. We prove the following.
Theorem 1.2. Let $\beta \in(0,1)$. There exist a constant $\alpha=\alpha(\beta)>1$ depending only on $\beta$ and an absolute constant $c_{1}>0$ with the following property: let $K$ be a centered convex body in $\mathbb{R}^{n}$, $\alpha n \leqslant N \leqslant e^{n}$ and $x_{1}, \ldots, x_{N}$ be independent random points uniformly distributed in $K$; then

$$
\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq \frac{c_{1} \beta \log (N / n)}{n} K
$$

with probability greater than $1-e^{-N^{1-\beta}} n^{\beta}$.
In fact, Theorem 1.1 is a special case of Theorem 1.2 by setting $\beta=1 / 2$ and $N=\lceil\alpha n\rceil$. The proof of Theorem 1.2 is given in Section 3.

Theorem 1.1 is very naturally related to the question of estimating the vertex index of a not necessarily symmetric $n$-dimensional convex body. The vertex index of a symmetric convex body $K$ in $\mathbb{R}^{n}$ was introduced in [6] as follows:

$$
\mathrm{vi}(K)=\inf \left\{\sum_{j=1}^{N}\left\|y_{j}\right\|_{K}: K \subseteq \operatorname{conv}\left(\left\{y_{1}, \ldots, y_{N}\right\}\right)\right\}
$$

where $\|\cdot\|_{K}$ is the norm with unit ball $K$ in $\mathbb{R}^{n}$. This index is closely related to the illumination parameter of a convex body, introduced by K. Bezdek in [5] and to a well-known conjecture of Boltyanski and Hadwiger about covering of an $n$-dimensional convex body by $2^{n}$ smaller positively homothetic copies (see [6] and [12]). Bezdek and Litvak proved that

$$
\frac{c_{1} n^{3 / 2}}{\operatorname{ovr}(K)} \leqslant \operatorname{vi}(K) \leqslant c_{2} n^{3 / 2}
$$

where $c_{1}, c_{2}>0$ are absolute constants and $\operatorname{ovr}(K)$ is the outer volume ratio of $K$ (see Section 2 for the definition). To the best of our knowledge the notion of vertex index has not been studied in the not necessarily
symmetric case. A way to define it for an arbitrary convex body $K$ in $\mathbb{R}^{n}$ is to consider first any $z \in \operatorname{int}(K)$ and to set

$$
\operatorname{vi}_{z}(K)=\inf \left\{\sum_{j=1}^{N} p_{K, z}\left(y_{j}\right): K \subseteq \operatorname{conv}\left(\left\{y_{1}, \ldots, y_{N}\right\}\right)\right\}
$$

where

$$
p_{K, z}(x)=p_{K-z}(x)=\inf \{t>0: x \in t(K-z)\}
$$

is the Minkowski functional of $K$ with respect to $z$. Then, one may define the (generalized) vertex index of $K$ by

$$
\operatorname{vi}(K)=\operatorname{vi}_{\operatorname{bar}(K)}(K)
$$

where $\operatorname{bar}(K)$ is the center of mass of $K$. With this definition, we clearly have $\operatorname{vi}(K)=\operatorname{vi}(K-\operatorname{bar}(K))$, and hence we may restrict our attention to centered convex bodies (i.e. convex bodies whose center of mass is at the origin). In Section 4 we establish some elementary properties of this index and using Theorem 1.1 we obtain the following general estimate.

Theorem 1.3. There exist two absolute constants $c_{1}, c_{2}>0$ such that for every $n \geqslant 2$ and for every centered convex body $K$ in $\mathbb{R}^{n}$,

$$
\frac{c_{1} n^{3 / 2}}{\operatorname{ovr}(\operatorname{conv}(K,-K))} \leqslant \operatorname{vi}(K) \leqslant c_{2} n^{2}
$$

The lower bound of Theorem 1.3 is not sharp, even in the symmetric case. Gluskin and Litvak 13] have proved that for every $n \geqslant 1$ there exists a symmetric convex body $K$ in $\mathbb{R}^{n}$ such that

$$
\operatorname{ovr}(K) \geqslant c \sqrt{\frac{n}{\log (2 n)}} \quad \text { and } \quad \operatorname{vi}(K) \geqslant c n^{3 / 2}
$$

It would be interesting to provide alternative lower bounds for $\mathrm{vi}(K)$ and of course it would be also interesting to decide whether, in the non-symmetric case, the upper bound vi $(K) \leqslant C n^{2}$ of Theorem 1.3 is sharp or not.

## 2 Notation and background

We work in $\mathbb{R}^{n}$, which is equipped with a Euclidean structure $\langle\cdot, \cdot\rangle$. We denote by $\|\cdot\|_{2}$ the corresponding Euclidean norm, and write $B_{2}^{n}$ for the Euclidean unit ball and $S^{n-1}$ for the unit sphere. Volume is denoted by $|\cdot|$. We use the same notation $|X|$ for the cardinality of a finite set $X$. We write $\omega_{n}$ for the volume of $B_{2}^{n}$ and $\sigma$ for the rotationally invariant probability measure on $S^{n-1}$. The letters $c, c^{\prime}, c_{1}, c_{2}, \ldots$ denote absolute positive constants which may change from line to line.

We refer to the book of Schneider [25] for basic facts from the Brunn-Minkowski theory and to the book of Artstein-Avidan, Giannopoulos and V. Milman 11 for basic facts from asymptotic convex geometry.

A convex body in $\mathbb{R}^{n}$ is a compact convex subset $K$ of $\mathbb{R}^{n}$ with non-empty interior. We say that $K$ is symmetric if $x \in K$ implies that $-x \in K$, and that $K$ is centered if its center of mass

$$
\operatorname{bar}(K)=\frac{1}{|K|} \int_{K} x d x
$$

is at the origin. The support function of $K$ is defined by $h_{K}(y)=\max \{\langle x, y\rangle: x \in K\}$. The circumradius of $K$ is the radius of the smallest ball which is centered at the origin and contains $K$, i.e. $R(K)=\max \left\{\|x\|_{2}\right.$ : $x \in K\}$.

If $0 \in \operatorname{int}(K)$ then the polar body $K^{\circ}$ of $K$ is defined by

$$
K^{\circ}:=\left\{y \in \mathbb{R}^{n}:\langle x, y\rangle \leqslant 1 \text { for all } x \in K\right\}
$$

and the Minkowski functional of $K$ is defined by

$$
p_{K}(x)=\inf \{t>0: x \in t K\} .
$$

Recall that $p_{K}$ is subadditive and positively homogeneous.
We say that a convex body $K$ is in John's position if the ellipsoid of maximal volume inscribed in $K$ is the Euclidean unit ball $B_{2}^{n}$. John's theorem ([16], see also [1, Chapter 2]) states that $K$ is in John's position if and only if $B_{2}^{n} \subseteq K$ and there exist $v_{1}, \ldots, v_{m} \in \operatorname{bd}(K) \cap S^{n-1}$ (contact points of $K$ and $B_{2}^{n}$ ) and positive real numbers $a_{1}, \ldots, a_{m}$ such that

$$
\sum_{j=1}^{m} a_{j} v_{j}=0
$$

and the identity operator $I_{n}$ is decomposed in the form

$$
\begin{equation*}
I_{n}=\sum_{j=1}^{m} a_{j} v_{j} \otimes v_{j} \tag{2.1}
\end{equation*}
$$

where $\left(v_{j} \otimes v_{j}\right)(y)=\left\langle v_{j}, y\right\rangle v_{j}$. We say that a convex body $K$ is in Löwner's position if the ellipsoid of minimal volume containing $K$ is the Euclidean unit ball $B_{2}^{n}$. One can check that this holds true if and only if $K^{\circ}$ is in John's position (see [1, Lemma 2.1.8]); in particular, we have a decomposition of the identity similar to 2.1. The outer volume ratio of a convex body $K$ in $\mathbb{R}^{n}$ is the quantity

$$
\operatorname{ovr}(K)=\inf \left\{\left(\frac{|\mathcal{E}|}{|K|}\right)^{1 / n}: \mathcal{E} \text { is an ellipsoid and } K \subseteq \mathcal{E}\right\}
$$

If $K$ is in Löwner's position then $\left(\left|B_{2}^{n}\right| /|K|\right)^{1 / n}=\operatorname{ovr}(K)$.
A convex body $K$ in $\mathbb{R}^{n}$ is called isotropic if it has volume 1 , it is centered, and its inertia matrix is a multiple of the identity matrix: there exists a constant $L_{K}>0$ such that

$$
\int_{K}\langle x, \theta\rangle^{2} d x=L_{K}^{2}
$$

for every $\theta$ in the Euclidean unit sphere $S^{n-1}$. It is known that every convex body has an isotropic affine image, and if $K$ is isotropic then

$$
c L_{K} B_{2}^{n} \subseteq K \subseteq(n+1) L_{K} B_{2}^{n}
$$

where $c>0$ is an absolute constant. A simple proof of the left hand side inclusion is given in [9, Section 3.2.1], while the right hand side inclusion was proved in [17]. The hyperplane conjecture asks if there exists an absolute constant $C>0$ such that

$$
L_{n}:=\max \left\{L_{K}: K \text { is isotropic in } \mathbb{R}^{n}\right\} \leqslant C
$$

for all $n \geqslant 1$. Bourgain proved in [7] that $L_{n} \leqslant c \sqrt[4]{n} \log n$, while Klartag [18] obtained the bound $L_{n} \leqslant c \sqrt[4]{n}$. A second proof of Klartag's bound appears in 19 . We refer the reader to the article of V. Milman and Pajor [21] and to the book [9] for an updated exposition of isotropic log-concave measures and more information on the hyperplane conjecture.

Let $K$ be a centered convex body of volume 1 in $\mathbb{R}^{n}$. The $L_{q}$-centroid body $Z_{q}(K)$ of $K$ is the centrally symmetric convex body with support function

$$
h_{Z_{q}(K)}(y)=\left(\int_{K}|\langle x, y\rangle|^{q} d x\right)^{1 / q}
$$

Note that $K$ is isotropic if and only if it is centered and $Z_{2}(K)=L_{K} B_{2}^{n}$. Also, if $T \in S L(n)$ then $Z_{q}(T(K))=T\left(Z_{q}(K)\right)$. From Hölder's inequality it follows that $Z_{1}(K) \subseteq Z_{p}(K) \subseteq Z_{q}(K) \subseteq Z_{\infty}(K)$ for all
$1 \leqslant p \leqslant q \leqslant \infty$, where $Z_{\infty}(K)=\operatorname{conv}(K,-K)$. Using Borell's lemma (see [9, Chapter 1]) one can check that

$$
\begin{equation*}
Z_{q}(K) \subseteq \bar{c}_{1} \frac{q}{p} Z_{p}(K) \tag{2.2}
\end{equation*}
$$

for all $1 \leqslant p<q$, where $\bar{c}_{1}>0$ is an absolute constant. In particular, if $K$ is isotropic then $R\left(Z_{q}(K)\right) \leqslant$ $\bar{c}_{1} q L_{K}$. One can also check that if $K$ is centered, then $Z_{q}(K) \supseteq c_{2} Z_{\infty}(K)$ for all $q \geqslant n$. For a proof of all these assertions see [9, Chapter 5]. The class of $L_{q}$-centroid bodies of $K$ was introduced (with a different normalization) by Lutwak, Yang and Zhang in [20]. An asymptotic approach to this family was developed by Paouris in [22] and 23].

For the proof of Theorem 1.2 we generalize arguments from [10] where $L_{q}$-centroid bodies are used in order to describe the asymptotic shape of the absolute convex hull of $N$ random points chosen from a convex body. The use of one-sided $L_{q}$-centroid bodies allows one to consider the convex hull itself.

## 3 Random approximation of convex bodies

Let $K$ be a centered convex body of volume 1 in $\mathbb{R}^{n}$. For every $q \geqslant 1$ we consider the one-sided $L_{q}$-centroid body $Z_{q}^{+}(K)$ of $K$ with support function

$$
h_{Z_{q}^{+}(K)}(y)=\left(2 \int_{K}\langle x, y\rangle_{+}^{q} d x\right)^{1 / q}
$$

where $a_{+}=\max \{a, 0\}$. In a dual form, the one-sided $L_{q}$-centroid bodies were introduced in [15]. When $K$ is symmetric, it is clear that $Z_{q}^{+}(K)=Z_{q}(K)$. In any case, we easily verify that

$$
Z_{q}^{+}(K) \subseteq 2^{1 / q} Z_{q}(K)
$$

Note that $Z_{q}^{+}(K) \subseteq 2^{1 / q} K$ for all $q \geqslant 1$. One can check that if $1 \leqslant q \leqslant r<\infty$ then

$$
\begin{equation*}
\left(\frac{2}{e}\right)^{\frac{1}{q}-\frac{1}{r}} Z_{q}^{+}(K) \subseteq Z_{r}^{+}(K) \subseteq \frac{C r}{q}\left(\frac{2 e-2}{e}\right)^{\frac{1}{q}-\frac{1}{r}} Z_{q}^{+}(K) \tag{3.1}
\end{equation*}
$$

where $C>0$ is an absolute constant. This double inclusion is stated as (2.3) in [14, Section 2] and is the analogue of 2.2 . One can verify it following the proof of 2.2 ) and using Grünbaum's lemma (see [1, Proposition 1.5.16]). The next lemma is also due to Guédon and E. Milman.

Lemma 3.1. There exists an absolute constant $\bar{c}_{0}>0$ such that, for every isotropic convex body $K$ in $\mathbb{R}^{n}$,

$$
Z_{2}^{+}(K) \supseteq \bar{c}_{0} L_{K} B_{2}^{n} .
$$

Equivalently, for any $\theta \in S^{n-1}$,

$$
h_{Z_{2}^{+}(K)}(\theta)=\left(2 \int_{K}\langle x, y\rangle_{+}^{2} d x\right)^{1 / 2} \geqslant \bar{c}_{0} L_{K}
$$

Finally, we need the next lemma, which appears in [14] (see also [9, Theorem 13.2.7]).
Lemma 3.2. Let $K$ be a centered convex body of volume 1 in $\mathbb{R}^{n}$. Then, for every $\theta \in S^{n-1}$,

$$
\left(\frac{2}{e^{2}}\right)^{1 / q}\left(\frac{\Gamma(n) \Gamma(q+1)}{\Gamma(n+q+1)}\right)^{1 / q} h_{K}(\theta) \leqslant h_{Z_{q}^{+}(K)}(\theta) \leqslant 2^{1 / q} h_{K}(\theta)
$$

Proof. We sketch the proof of the left hand side inequality. Let

$$
H_{\theta}^{+}=\left\{x \in \mathbb{R}^{n}:\langle x, \theta\rangle \geqslant 0\right\}, \quad H_{\theta}(t)=\left\{x \in \mathbb{R}^{n}:\langle x, \theta\rangle=t\right\}
$$

and

$$
f_{\theta}(t)=\left|K \cap H_{\theta}(t)\right|
$$

First observe that, by the Brunn-Minkowski inequality, $f_{\theta}^{\frac{1}{n-1}}$ is concave on its support, and hence we have

$$
f_{\theta}(t) \geqslant\left(1-\frac{t}{h_{K}(\theta)}\right)^{n-1} f_{\theta}(0)
$$

for all $t \in\left[0, h_{K}(\theta)\right]$. Therefore,

$$
\begin{aligned}
h_{Z_{q}^{+}(K)}^{q}(\theta)= & 2 \int_{0}^{h_{K}(\theta)} t^{q} f_{\theta}(t) d t \geqslant 2 \int_{0}^{h_{K}(\theta)} t^{q}\left(1-\frac{t}{h_{K}(\theta)}\right)^{n-1} f_{\theta}(0) d t \\
& =2 f_{\theta}(0) h_{K}^{q+1}(\theta) \int_{0}^{1} s^{q}(1-s)^{n-1} d s \\
& =\frac{\Gamma(n) \Gamma(q+1)}{\Gamma(q+n+1)} 2 f_{\theta}(0) h_{K}^{q+1}(\theta)
\end{aligned}
$$

Observe that

$$
2 f_{\theta}(0) h_{K}(\theta)=\frac{f_{\theta}(0)}{\left\|f_{\theta}\right\|_{\infty}} 2\left\|f_{\theta}\right\|_{\infty} h_{K}(\theta) \geqslant \frac{f_{\theta}(0)}{\left\|f_{\theta}\right\|_{\infty}}\left(2\left|K \cap H_{\theta}^{+}\right|\right)
$$

We know that $\left\|f_{\theta}\right\|_{\infty} \leqslant e f_{\theta}(0)$ by a result of Fradelizi (see e.g. [9, Theorem 2.2.2]) and that $\left|K \cap H_{\theta}^{+}\right| \geqslant e^{-1}$ by Grünbaum's lemma (see [1, Proposition 1.5.16]). Combining the above we get the result.

Theorem 1.2 (and thus Theorem 1.1) will follow from the next fact, which generalizes the work of Dafnis, Giannopoulos and Tsolomitis [10] to the not necessarily symmetric setting.

Theorem 3.3. Let $\beta \in(0,1)$. There exist a constant $\alpha=\alpha(\beta)>1$ depending only on $\beta$ and absolute constants $c_{1}, c_{2}>0$ with the following property: if $K$ is a centered convex body of volume 1 in $\mathbb{R}^{n}, N \geqslant \alpha n$, and $x_{1}, \ldots, x_{N}$ are independent random points uniformly distributed in $K$ then for $q=c_{1} \beta \log (N / n)$ the inclusion

$$
\begin{equation*}
\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq c_{2} Z_{q}^{+}(K) \tag{3.2}
\end{equation*}
$$

holds with probability greater than $1-e^{-N^{1-\beta}} n^{\beta}$.
Our proof of 3.2 uses the family of one-sided $L_{q}$-centroid bodies of $K$. In particular, we need the following estimate (the idea of the proof can be traced back in [10]; see also [24]).

Lemma 3.4. There exists an absolute constant $C>1$ with the following property: for every $n \geqslant 1$, every centered convex body $K$ of volume 1 in $\mathbb{R}^{n}$ and every $q \geqslant 2$,

$$
\inf _{\theta \in S^{n-1}} \mu_{K}\left(\left\{x:\langle x, \theta\rangle>\frac{1}{2} h_{Z_{q}^{+}(K)}(\theta)\right\}\right) \geqslant C^{-q}
$$

where $\mu_{K}$ is the Lebesgue measure on $K$.
Proof. Let $K$ be a centered convex body of volume 1 in $\mathbb{R}^{n}$, let $q \geqslant 2$ and let $\theta \in S^{n-1}$. We apply the Paley-Zygmund inequality

$$
\begin{equation*}
\mathbb{P}(g \geqslant t \mathbb{E}(g)) \geqslant(1-t)^{2} \frac{[\mathbb{E}(g)]^{2}}{\mathbb{E}\left(g^{2}\right)} \tag{3.3}
\end{equation*}
$$

for the non-negative random variable

$$
g_{\theta}(x)=2\langle x, \theta\rangle_{+}^{q}
$$

on $\left(K, \mu_{K}\right)$. Applying (3.1) with $r=2 q$ we see that

$$
\mathbb{E}\left(g_{\theta}^{2}\right)=h_{Z_{2 q}^{+}(K)}^{2 q}(\theta) \leqslant C_{1}^{q} h_{Z_{q}^{+}(K)}^{2 q}(\theta)=C_{1}^{q}\left[\mathbb{E}\left(g_{\theta}\right)\right]^{2},
$$

where $C_{1}>0$ is an absolute constant. From 3.3) we get

$$
\begin{aligned}
\mu_{K}\left(\left\{x:\langle x, \theta\rangle>t h_{Z_{q}^{+}(K)}(\theta)\right\}\right) & =\mu_{K}\left(\left\{x:\langle x, \theta\rangle>t\left[\mathbb{E}\left(g_{\theta}\right)\right]^{1 / q}\right\}\right)=\mu_{K}\left(\left\{x:\langle x, \theta\rangle_{+}>t\left[\mathbb{E}\left(g_{\theta}\right)\right]^{1 / q}\right\}\right) \\
& =\mu_{K}\left(\left\{x:\langle x, \theta\rangle_{+}^{q}>t^{q} \mathbb{E}\left(g_{\theta}\right)\right\}\right)=\mu_{K}\left(\left\{x: g_{\theta}(x)>2 t^{q} \mathbb{E}\left(g_{\theta}\right)\right\}\right) \\
& \geqslant\left(1-2 t^{q}\right)^{2} \frac{\left[\mathbb{E}\left(g_{\theta}\right)\right]^{2}}{\mathbb{E}\left(g_{\theta}^{2}\right)} \geqslant \frac{\left(1-2 t^{q}\right)^{2}}{C_{1}^{q}}
\end{aligned}
$$

for every $t \in\left(0,2^{-\frac{1}{q}}\right)$. Choosing $t=\frac{1}{2}$ we get the lemma with $C=4 C_{1}$.
Proof of Theorem 3.3 . Let $q \geqslant 2$ and consider the random polytope $C_{N}:=\operatorname{conv}\left\{x_{1}, \ldots, x_{N}\right\}$. With probability equal to one, $C_{N}$ has non-empty interior and, for every $J=\left\{j_{1}, \ldots, j_{n}\right\} \subset\{1, \ldots, N\}$, the points $x_{j_{1}}, \ldots, x_{j_{n}}$ are affinely independent. Write $H_{J}$ for the affine subspace determined by $x_{j_{1}}, \ldots, x_{j_{n}}$ and $H_{J}^{+}$, $H_{J}^{-}$for the two closed halfspaces whose bounding hyperplane is $H_{J}$.

If $\frac{1}{2} Z_{q}^{+}(K) \nsubseteq C_{N}$, then there exists $x \in \frac{1}{2} Z_{q}^{+}(K) \backslash C_{N}$, and hence, there is a facet of $C_{N}$ defining some affine subspace $H_{J}$ as above that satisfies the following: either $x \in H_{J}^{-}$and $C_{N} \subset H_{J}^{+}$, or $x \in H_{J}^{+}$and $C_{N} \subset H_{J}^{-}$. Observe that, for every $J$, the probability of each of these two events is bounded by

$$
\left(\sup _{\theta \in S^{n-1}} \mu_{K}\left(\left\{x:\langle x, \theta\rangle \leqslant \frac{1}{2} h_{Z_{q}^{+}(K)}(\theta)\right\}\right)\right)^{N-n} \leqslant\left(1-C^{-q}\right)^{N-n}
$$

where $C>0$ is the constant in Lemma 3.4. It follows that

$$
\mathbb{P}\left(\frac{1}{2} Z_{q}^{+}(K) \nsubseteq C_{N}\right) \leqslant 2\binom{N}{n}\left(1-C^{-q}\right)^{N-n}
$$

Since $\binom{N}{n} \leqslant\left(\frac{e N}{n}\right)^{n}$, this probability is smaller than $\exp \left(-N^{1-\beta} n^{\beta}\right)$ if

$$
\left(\frac{2 e N}{n}\right)^{n}\left(1-C^{-q}\right)^{N-n}<\left(\frac{2 e N}{n}\right)^{n} e^{-C^{-q}(N-n)}<\exp \left(-N^{1-\beta} n^{\beta}\right)
$$

and the second inequality is satisfied if

$$
\begin{equation*}
\frac{N}{n}-1>C^{q}\left[\left(\frac{N}{n}\right)^{1-\beta}+\log \left(\frac{2 e N}{n}\right)\right] \tag{3.4}
\end{equation*}
$$

We choose $q=\frac{\beta}{2 \log C} \log \left(\frac{N}{n}\right)$ and $\alpha_{1}(\beta):=C^{4 / \beta}$. Note that if $N \geqslant \alpha_{1}(\beta) n$ then $q \geqslant 2$ and that 3.4) becomes

$$
\begin{equation*}
\frac{N}{n}-1>\left(\frac{N}{n}\right)^{1-\frac{\beta}{2}}+\left(\frac{N}{n}\right)^{\frac{\beta}{2}} \log \left(\frac{2 e N}{n}\right) \tag{3.5}
\end{equation*}
$$

Since

$$
\lim _{t \rightarrow+\infty}\left[t-1-t^{1-\frac{\beta}{2}}-t^{\frac{\beta}{2}} \log (2 e t)\right]=+\infty
$$

we may find $\alpha_{2}(\beta)$ such that 3.5 is satisfied for all $N \geqslant \alpha_{2}(\beta) n$. Setting $\alpha=\max \left\{\alpha_{1}(\beta), \alpha_{2}(\beta)\right\}$ we see that the assertion of the theorem is satisfied with probability greater that $1-e^{-N^{1-\beta} n^{\beta}}$ for all $N \geqslant \alpha n$, with $c_{1}=\frac{1}{2 \log C}$ and $c_{2}=\frac{1}{2}$.

Proof of Theorem 1.2, Let $\beta \in(0,1)$ and let $\alpha=\alpha(\beta)$ be the constant from Theorem 3.3. Let $\alpha n \leqslant N \leqslant e^{n}$ and let $x_{1}, \ldots, x_{N}$ be independent random points uniformly distributed in $K$. Applying Lemma 3.2 with $q=n$ we see that $h_{Z_{n}^{+}(K)} \geqslant c_{1} h_{K}(\theta)$ for all $\theta \in S^{n-1}$, and hence

$$
Z_{n}^{+}(K) \supseteq c_{1} K
$$

where $c_{1}>0$ is an absolute constant. From Theorem 3.3 we know that if $q=c_{2} \beta \log (N / n)$ (note also that $q \leqslant n)$ then

$$
C_{N}=\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq c_{3} Z_{q}^{+}(K)
$$

with probability greater than $1-\exp \left(-N^{1-\beta} n^{\beta}\right)$, where $c_{2}, c_{3}>0$ are absolute constants. From (3.1) we see that

$$
Z_{n}^{+}(K) \subseteq \frac{c_{4} n}{q}\left(\frac{2 e-2}{e}\right)^{\frac{1}{q}-\frac{1}{n}} Z_{q}^{+}(K) \subseteq \frac{2 c_{4} n}{q} Z_{q}^{+}(K)
$$

where $c_{4}>0$ is an absolute constant. Combining the above we get that

$$
C_{N}=\operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right) \supseteq \frac{c_{5} q}{n} K \supseteq \frac{c_{6} \beta \log (N / n)}{n} K
$$

with probability greater than $1-\exp \left(-N^{1-\beta} n^{\beta}\right)$, where $c_{5}, c_{6}>0$ are absolute constants.

## 4 Generalized vertex index

Let $K$ be a convex body in $\mathbb{R}^{n}$. From the definition of the vertex index that we gave in the introduction, we may clearly assume that $K$ is centered, and then

$$
\operatorname{vi}(K)=\inf \left\{\sum_{j=1}^{N} p_{K}\left(y_{j}\right): K \subseteq \operatorname{conv}\left(\left\{y_{1}, \ldots, y_{N}\right\}\right)\right\}
$$

where $p_{K}$ is the Minkowski functional of $K$. Since every origin symmetric convex body is centered, our definition coincides with the one given by Bezdek and Litvak in [6] for the symmetric case.

It is also easy to check that the vertex index is invariant under invertible linear transformations. For every convex body $K$ in $\mathbb{R}^{n}$ and any $T \in G L(n)$ one has

$$
\operatorname{vi}(T(K))=\operatorname{vi}(K)
$$

Another useful observation is that the vertex index is stable under a variant of the Banach-Mazur distance. Recall that the Banach-Mazur distance between two convex bodies $K$ and $L$ in $\mathbb{R}^{n}$ is the quantity

$$
d(K, L)=\inf \{t>0: T(L+y) \subseteq K+x \subseteq t(T(L+y))\}
$$

where the infimum is over all $T \in G L(n)$ and $x, y \in \mathbb{R}^{n}$. Given two centered convex bodies $K$ and $L$, we set

$$
\tilde{d}(K, L)=\inf \{t>0: T(L) \subseteq K \subseteq t T(L)\}
$$

where the infimum is over all $T \in G L(n)$. Note that if $K$ and $L$ are symmetric convex bodies then $\tilde{d}(K, L)=$ $d(K, L)$. With this definition we easily check that if $K$ and $L$ are centered convex bodies in $\mathbb{R}^{n}$ then

$$
\operatorname{vi}(K) \leqslant \tilde{d}(K, L) \operatorname{vi}(L)
$$

The main result of this section is the upper bound in Theorem 1.3 .
Proof of Theorem 1.3. We may assume that $K$ is isotropic. By Theorem 1.1 we can find $N \leqslant \alpha n$ and $x_{1}, \ldots, x_{N} \in K$ such that

$$
K \subseteq C n \operatorname{conv}\left(\left\{x_{1}, \ldots, x_{N}\right\}\right)
$$

where $\alpha, C>0$ are absolute constants. We set $y_{j}=C n x_{j}, 1 \leqslant j \leqslant N$. Then, $K \subseteq \operatorname{conv}\left(\left\{y_{1}, \ldots, y_{N}\right\}\right)$ and $p_{K}\left(y_{j}\right)=C n p_{K}\left(x_{j}\right) \leqslant C n$, therefore

$$
\mathrm{vi}(K) \leqslant \sum_{j=1}^{N} p_{K}\left(y_{j}\right) \leqslant C n N \leqslant C \alpha n^{2}
$$

The result follows with $C_{1}=C \alpha$.
For the lower bound we just check that the argument of [6] remains valid in the not necessarily symmetric case. By the linear invariance of the vertex index we may assume that $B_{2}^{n}$ is the ellipsoid of minimal volume which contains conv $(K,-K)$. In other words, $K \subseteq \operatorname{conv}(K,-K) \subseteq B_{2}^{n}$ and

$$
\left(\frac{\left|B_{2}^{n}\right|}{|\operatorname{conv}(K,-K)|}\right)^{1 / n}=\operatorname{ovr}(\operatorname{conv}(K,-K))
$$

For any $N \in \mathbb{N}$ and $y_{1}, \ldots, y_{N}$ such that $K \subseteq \operatorname{conv}\left(\left\{y_{1}, \ldots, y_{N}\right\}\right)$ we consider the absolute convex hull $Q=\operatorname{conv}\left(\left\{ \pm y_{1}, \ldots, \pm y_{N}\right\}\right) \supseteq \operatorname{conv}(K,-K)$ of $y_{1}, \ldots, y_{N}$. Then,

$$
Q^{\circ}=\left\{x \in \mathbb{R}^{n}:\left|\left\langle x, y_{j}\right\rangle\right| \leqslant 1 \text { for all } j=1, \ldots, N\right\}
$$

and a result of Ball and Pajor [2] provides the lower bound

$$
\left|Q^{\circ}\right| \geqslant\left(\frac{n}{\sum_{j=1}^{N}\left\|y_{j}\right\|_{2}}\right)^{1 / n}
$$

for its volume. Using the Blaschke-Santaló inequality we get

$$
|\operatorname{conv}(K,-K)| \leqslant|Q| \leqslant \frac{\left|B_{2}^{n}\right|^{2}}{\left|Q^{\circ}\right|} \leqslant\left|B_{2}^{n}\right|^{2}\left(\frac{\sum_{j=1}^{N}\left\|y_{j}\right\|_{2}}{n}\right)^{n}
$$

It follows that

$$
1 \leqslant\left(\frac{\left|B_{2}^{n}\right|}{|\operatorname{conv}(K,-K)|}\right)^{1 / n}\left|B_{2}^{n}\right|^{1 / n} \frac{\sum_{j=1}^{N}\left\|y_{j}\right\|_{2}}{n} \leqslant \frac{\operatorname{ovr}(\operatorname{conv}(K,-K)))}{c n^{3 / 2}} \sum_{j=1}^{N}\left\|y_{j}\right\|_{2}
$$

for some absolute constant $c>0$. Since $K \subseteq B_{2}^{n}$, we have $\left\|y_{j}\right\|_{2} \leqslant p_{K}\left(y_{j}\right)$ for all $j=1, \ldots, N$. Therefore,

$$
\sum_{j=1}^{N} p_{K}\left(y_{j}\right) \geqslant \frac{c n^{3 / 2}}{\operatorname{ovr}(\operatorname{conv}(K,-K))}
$$

and taking the infimum over all $N$ and all such $N$-tuples $\left(y_{1}, \ldots, y_{N}\right)$ we get the lower bound for vi $(K)$.
Acknowledgements. We would like to thank Apostolos Giannopoulos for useful discussions. We would also like to thank the referee for comments and valuable suggestions on the presentation of the results of this article. The first named author acknowledges support from Onassis Foundation. The second named author is partly funded by the Department of Mathematics through a University of Athens Special Account Research Grant.

## References

[1] S. Artstein-Avidan, A. Giannopoulos and V. D. Milman, Asymptotic Geometric Analysis, Part I, Mathematical Surveys and Monographs 202, Amer. Math. Soc. (2015).
[2] K. M. Ball and A. Pajor, Convex bodies with few faces, Proc. Amer. Math. Soc. 110 (1990), no. 1, 225-231.
[3] A. Barvinok, Thrifty approximations of convex bodies by polytopes, Int. Math. Res. Not. IMRN (2014), no. 16, 4341-4356.
[4] J. Batson, D. Spielman and N. Srivastava, Twice-Ramanujan Sparsifiers, STOC' 2009: Proceedings of the 41st annual ACM Symposium on Theory of Computing (ACM, New York, 2009), pp. 255-262.
[5] K. Bezdek, The illumination conjecture and its extensions, Period. Math. Hungar. 53 (2006), 59-69.
[6] K. Bezdek and A. E. Litvak, On the vertex index of convex bodies, Adv. Math. 215 (2007), 626-641.
[7] J. Bourgain, On the distribution of polynomials on high dimensional convex sets, in Geom. Aspects of Funct. Analysis, Lecture Notes in Mathematics 1469, Springer, Berlin (1991), 127-137.
[8] S. Brazitikos, Quantitative Helly-type theorem for the diameter of convex sets, Preprint (arXiv:1511.07779).
[9] S. Brazitikos, A. Giannopoulos, P. Valettas and B-H. Vritsiou, Geometry of isotropic convex bodies, Mathematical Surveys and Monographs 196, American Mathematical Society, Providence, RI, 2014.
[10] N. Dafnis, A. Giannopoulos and A. Tsolomitis, Asymptotic shape of a random polytope in a convex body, J. Funct. Anal. 257 (2009), 2820-2839.
[11] A. Giannopoulos and V. D. Milman, Concentration property on probability spaces, Adv. Math. 156 (2000), 77-106.
[12] E. D. Gluskin and A. E. Litvak, Asymmetry of convex polytopes and vertex index of symmetric convex bodies, Discrete Comput. Geom. 40 (2008), 528-536.
[13] E. D. Gluskin and A. E. Litvak, A remark on vertex index of the convex bodies, in Geom. Aspects of Funct. Analysis, Lecture Notes in Math. 2050, Springer, Berlin (2012), 255-265.
[14] O. Guédon and E. Milman, Interpolating thin-shell and sharp large-deviation estimates for isotropic log-concave measures, Geom. Funct. Anal. 21 (2011), 1043-1068.
[15] C. Haberl, $L_{p}$ intersection bodies, Adv. Math. 217 (2008), 2599-2624.
[16] F. John, Extremum problems with inequalities as subsidiary conditions, Courant Anniversary Volume, Interscience, New York (1948), 187-204.
[17] R. Kannan, L. Lovász and M. Simonovits, Isoperimetric problems for convex bodies and a localization lemma, Discrete Comput. Geom. 13 (1995), 541-559.
[18] B. Klartag, On convex perturbations with a bounded isotropic constant, Geom. Funct. Anal. 16 (2006), 12741290.
[19] B. Klartag and E. Milman, Centroid Bodies and the Logarithmic Laplace Transform - A Unified Approach, J. Funct. Anal. 262 (2012), 10-34.
[20] E. Lutwak, D. Yang and G. Zhang, $L^{p}$ affine isoperimetric inequalities, J. Differential Geom. 56 (2000), 111-132.
[21] V. D. Milman and A. Pajor, Isotropic position and inertia ellipsoids and zonoids of the unit ball of a normed $n$-dimensional space, in Geom. Aspects of Funct. Analysis, Lecture Notes in Mathematics 1376, Springer, Berlin (1989), 64-104.
[22] G. Paouris, Concentration of mass in convex bodies, Geom. Funct. Anal. 16 (2006), 1021-1049.
[23] G. Paouris, Small ball probability estimates for log-concave measures, Trans. Amer. Math. Soc. 364 (2012), 287-308.
[24] G. Paouris and E. Werner, Relative entropy of cone measures and $L_{p}$-centroid bodies, Proc. Lond. Math. Soc. 104 (2012), 253-286.
[25] R. Schneider, Convex Bodies: The Brunn-Minkowski Theory, Second expanded edition. Encyclopedia of Mathematics and Its Applications 151, Cambridge University Press, Cambridge, 2014.
[26] N. Srivastava, On contact points of convex bodies, in Geom. Aspects of Funct. Analysis, Lecture Notes in Mathematics 2050, Springer, Berlin (2012), 393-412.

Keywords: Convex bodies, isotropic position, centroid bodies, random polytopal approximation.
2010 MSC: Primary 52A23; Secondary 52A35, 46B06, 60D05.

Silouanos Brazitikos: Department of Mathematics, National and Kapodistrian University of Athens, Panepistimiopolis 157-84, Athens, Greece.
E-mail: silouanb@math.uoa.gr
Giorgos Chasapis: Department of Mathematics, National and Kapodistrian University of Athens, Panepistimiopolis 157-84, Athens, Greece.
E-mail: gchasapis@math.uoa.gr
Labrini Hioni: Department of Mathematics, National and Kapodistrian University of Athens, Panepistimiopolis 157-84, Athens, Greece.
E-mail: lamchioni@math.uoa.gr

