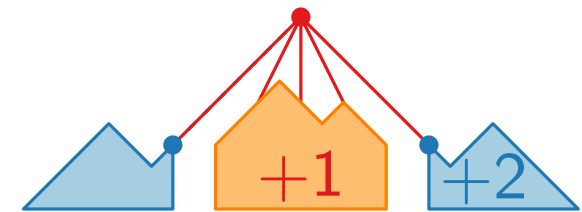
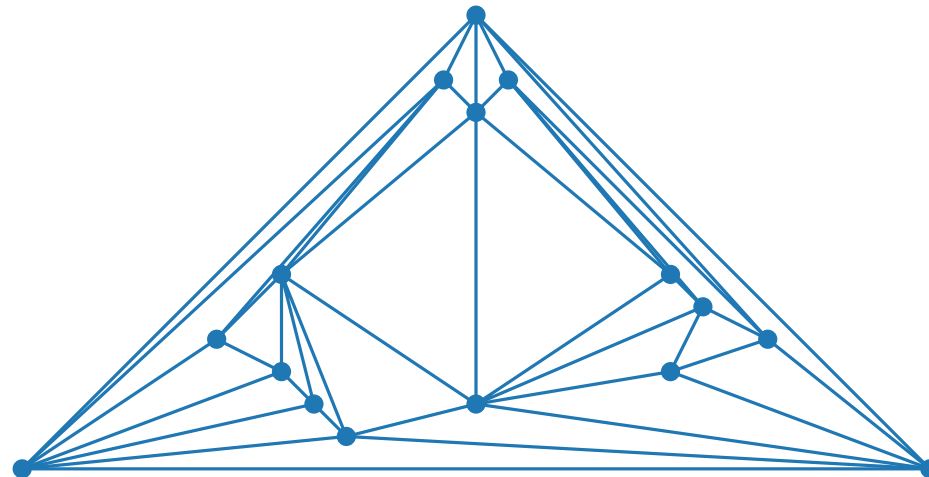
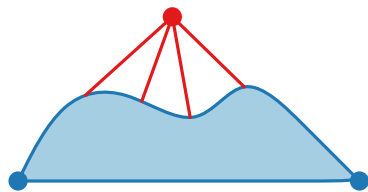


Visualisation of graphs

Planar straight-line drawings

Canonical order

Antonios Symvonis · Chrysanthi Raftopoulou
Fall semester 2020



Motivation

- So far we looked at planar and straight-line drawings of trees and series-parallel graphs.

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“The Aesthetics of Graph Visualization”

3.2. Edge Placement Heuristics

By far the most agreed-upon edge placement heuristic is to *minimize the number of edge crossings* in a graph [BMRW98, Har98, DH96, Pur02, TR05, TBB88]. The importance of avoiding edge crossings has also been extensively validated in terms of user preference and performance (see Section 4). Similarly, based on perceptual principles, it is beneficial to *minimize the number of edge bends* within a graph [Pur02, TR05, TBB88]. Edge bends make edges more difficult to follow because an edge with a sharp bend is more likely to be perceived as two separate objects. This leads to the heuristic of *keeping edge bends uniform* with respect to the bend's position on the edge and its angle [TR05]. If an edge must be bent to satisfy other aesthetic criteria, the angle of the bend should be as little as possible, and the bend placement should evenly divide the edge.

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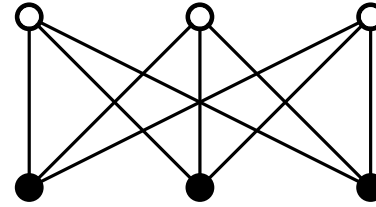
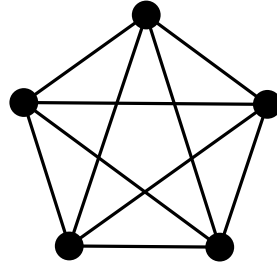
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- crossings reduce readability
- bends reduce readability

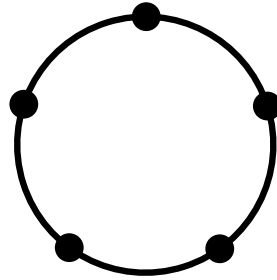
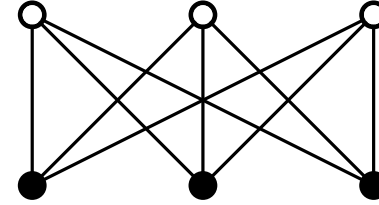
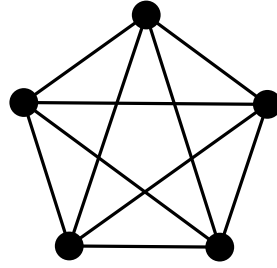
Planar graphs

- **Characterisation:** A graph is **planar** iff it contains neither a K_5 nor a $K_{3,3}$ minor.
[Kuratowski 1930, Wagner 1936]



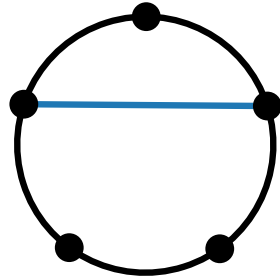
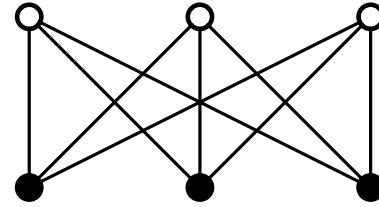
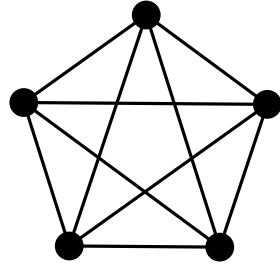
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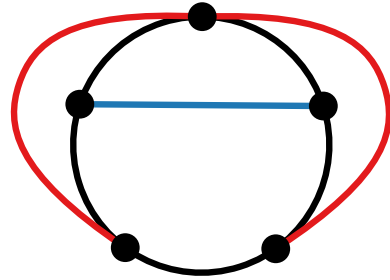
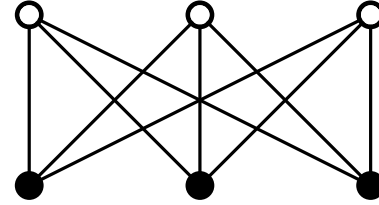
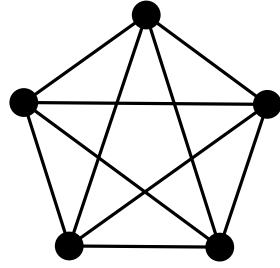
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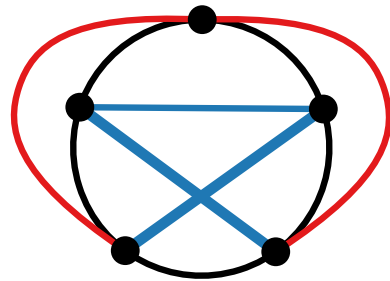
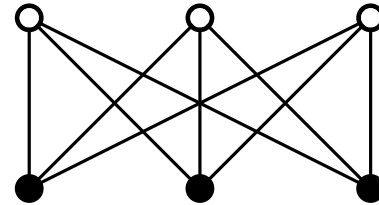
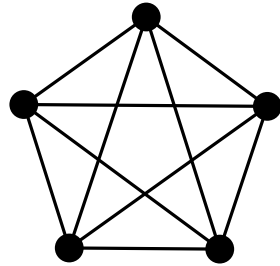
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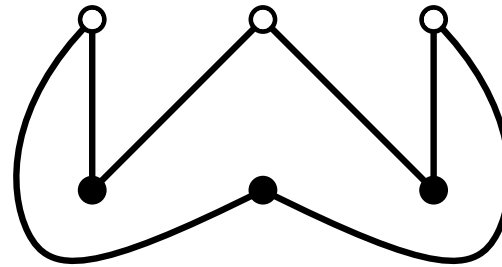
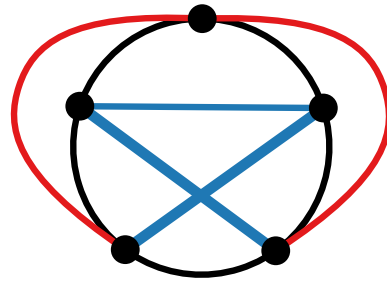
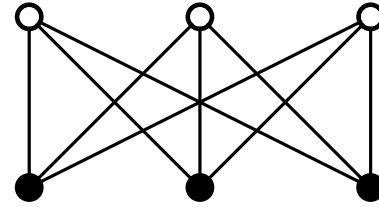
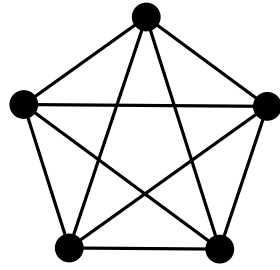
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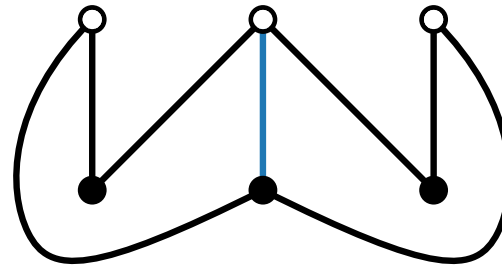
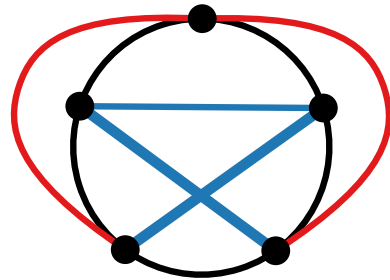
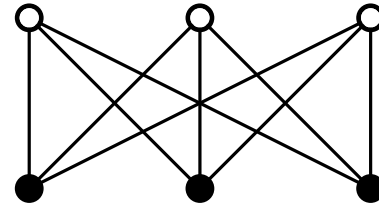
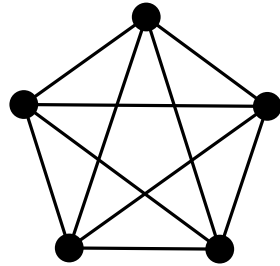
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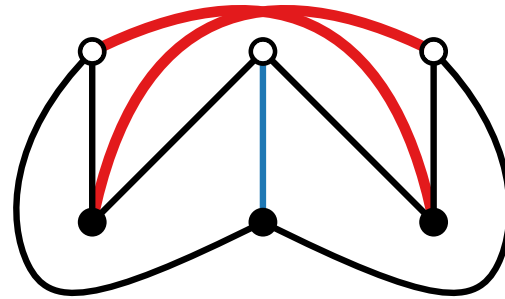
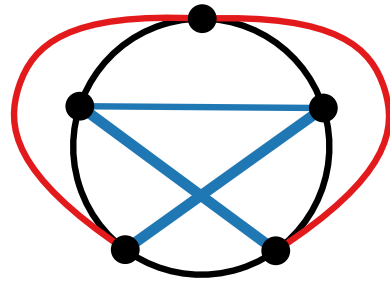
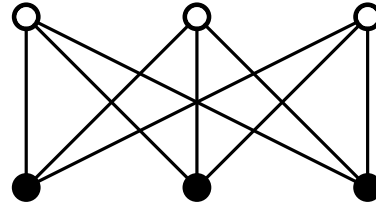
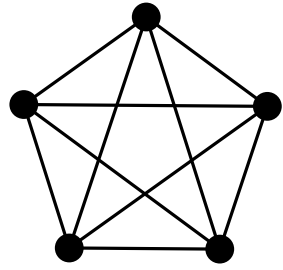
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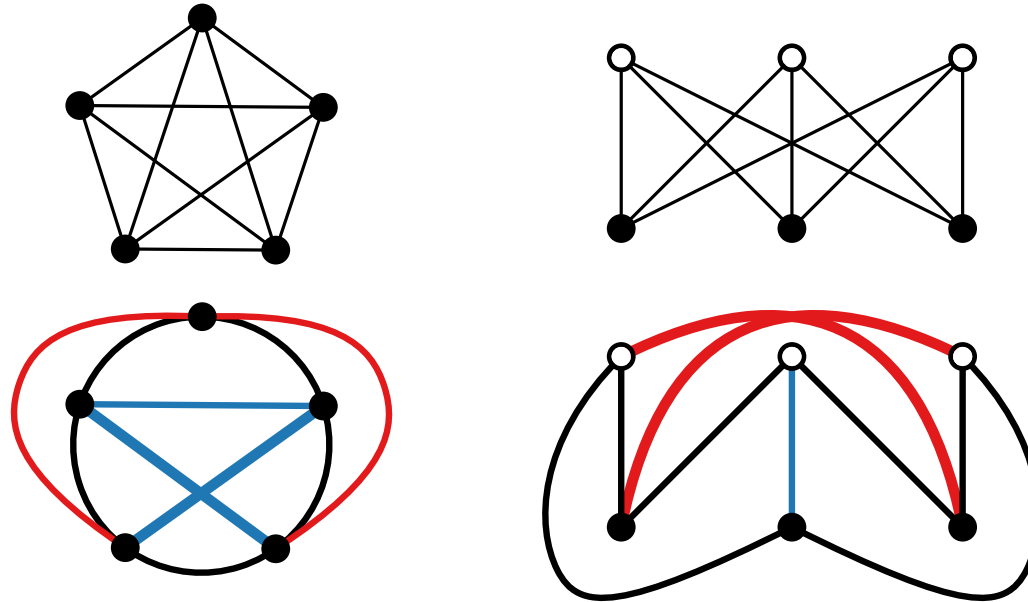
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- Recognition:** For a graph G with n vertices, there is an $\mathcal{O}(n)$ time algorithm to test if G is planar. [Hopcroft & Tarjan 1974]
 - Also computes an *embedding* in $\mathcal{O}(n)$.

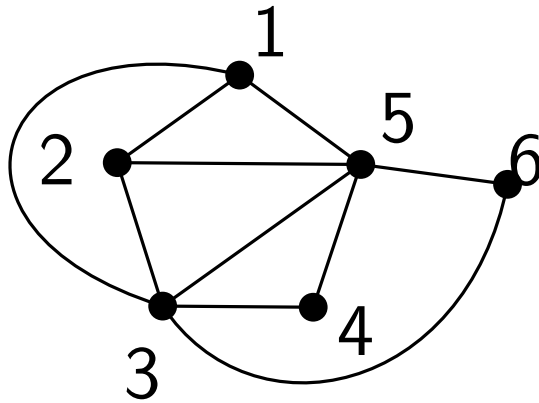
Planar graphs

- **Embedding of planar graph:**
 - clockwise circular order of the edges incident to each vertex
 - outerface (clockwise order of edges)

Planar graphs

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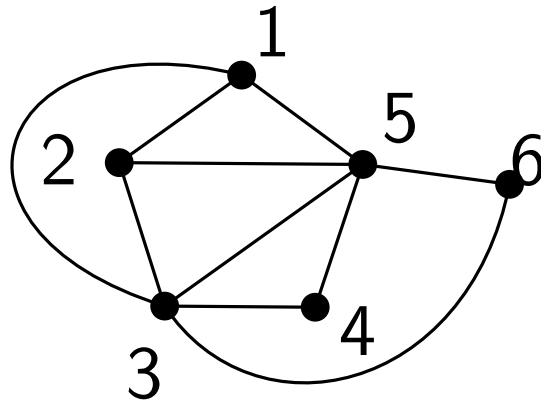
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Planar graphs

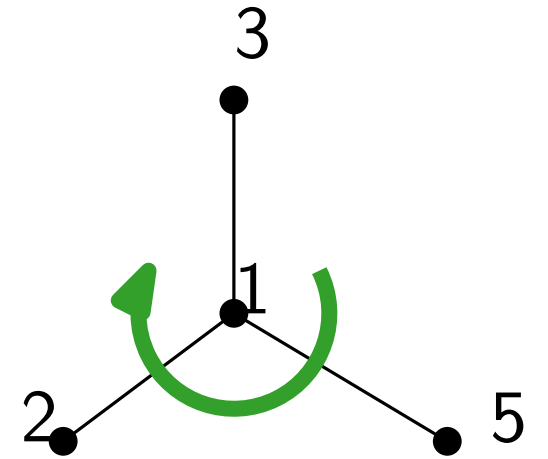
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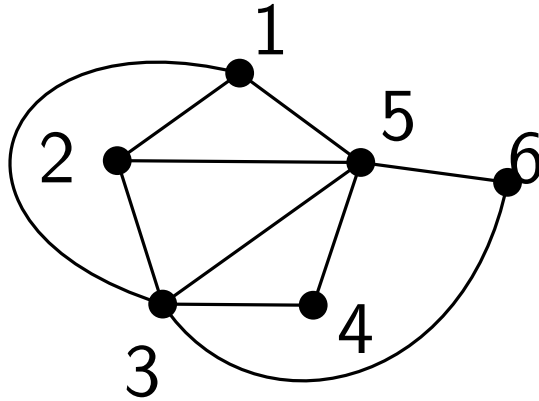
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$$2 : \{(2, 1), (2, 5), (2, 3)\}$$

$$3 : \{(3, 1), (3, 2), (3, 5), (3, 4), (3, 6)\}$$

$$4 : \{(4, 3), (4, 5)\}$$

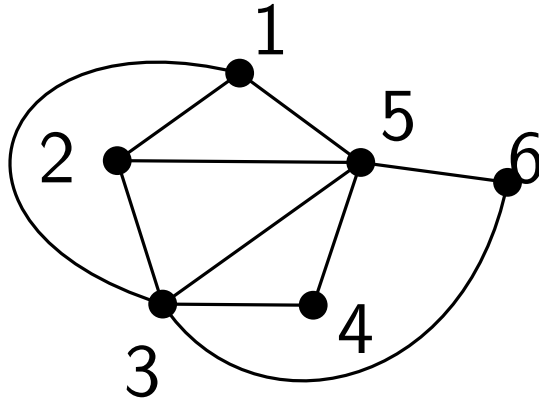
$$5 : \{(5, 6), (5, 4), (5, 3), (5, 2), (5, 1)\}$$

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■ Outerface:

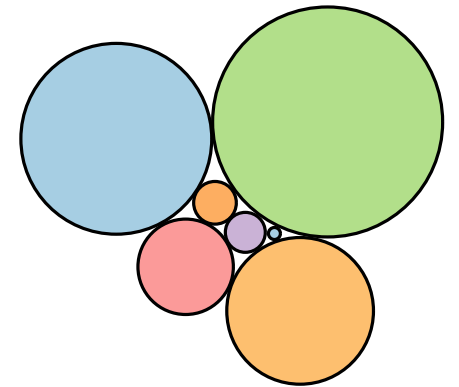
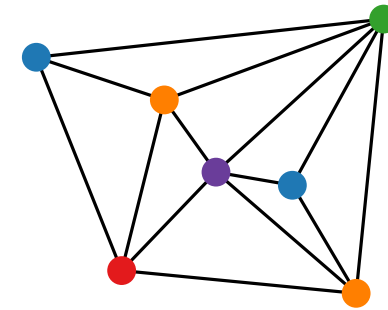
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Planar graphs

- **Straight-line drawing:** Every planar graph has an embedding where the edges are **straight-line** segments. [Wagner 1936, Fáry 1948, Stein 1951]
 - The algorithms implied by this theory produce drawings with area *not bounded* by any **polynomial on n** .

Planar graphs

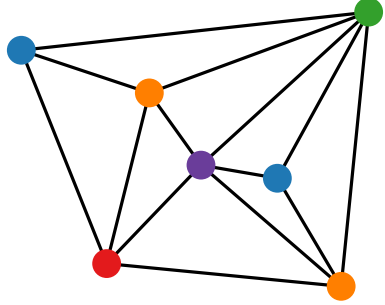
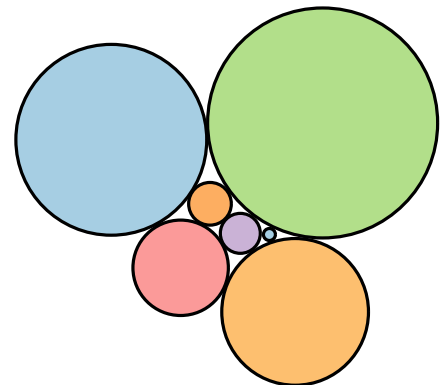
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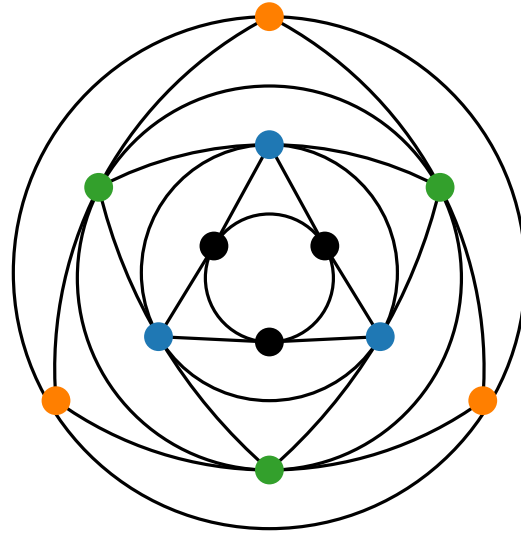
- Every 3-connected planar graph has an embedding with **convex polygons** as its faces (i.e., implies straight lines). [Tutte 1963: How to draw a graph]
 - **Idea:** Place vertices in the barycentre of neighbours.
 - **Drawback:** Requires large grids.

Planar graphs

- **Coin graph:**
Exponential area

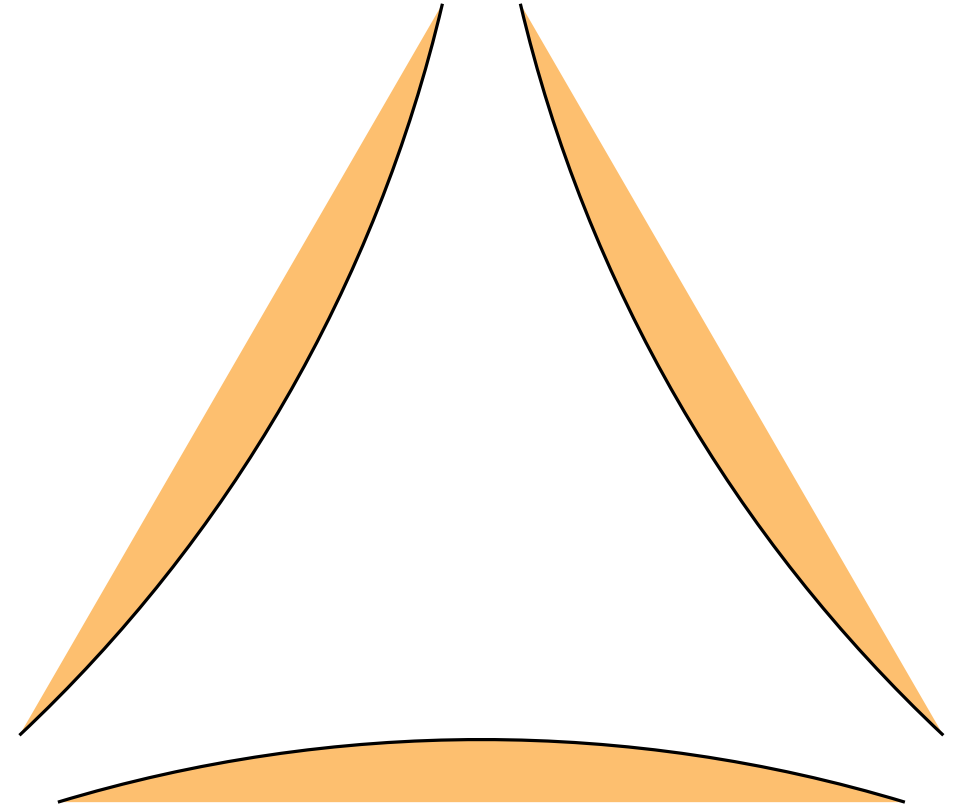
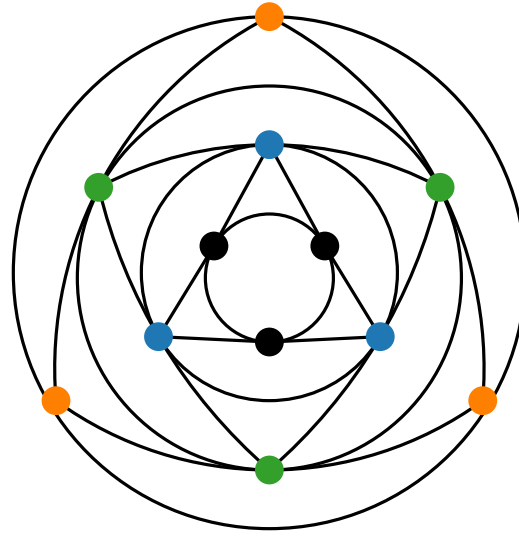
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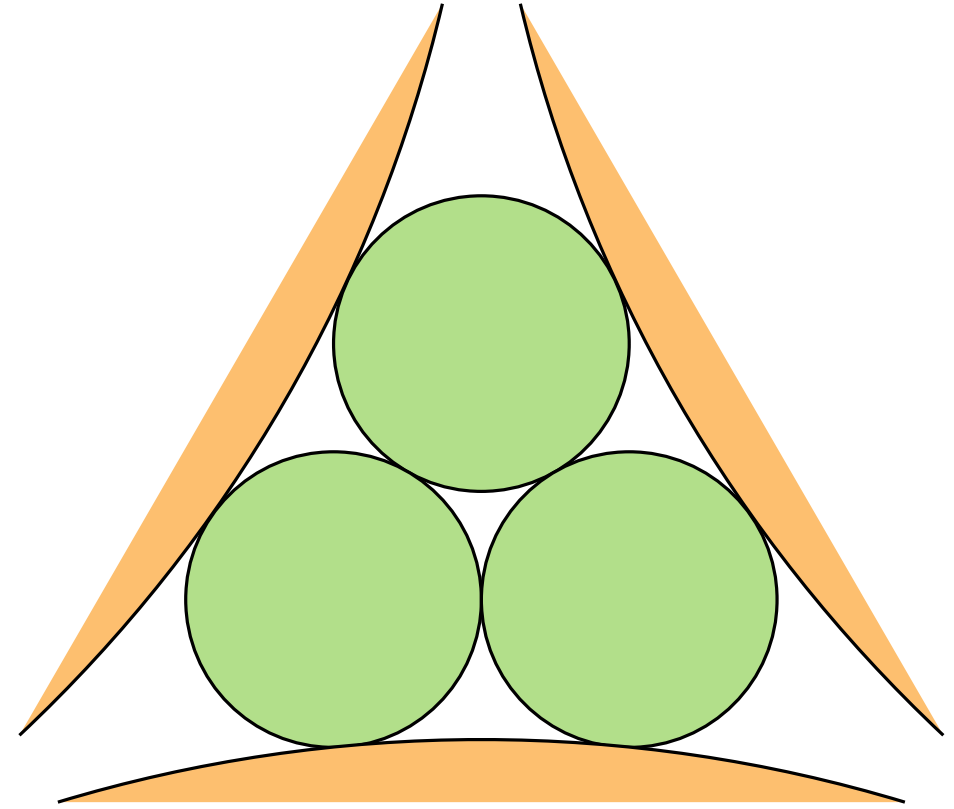
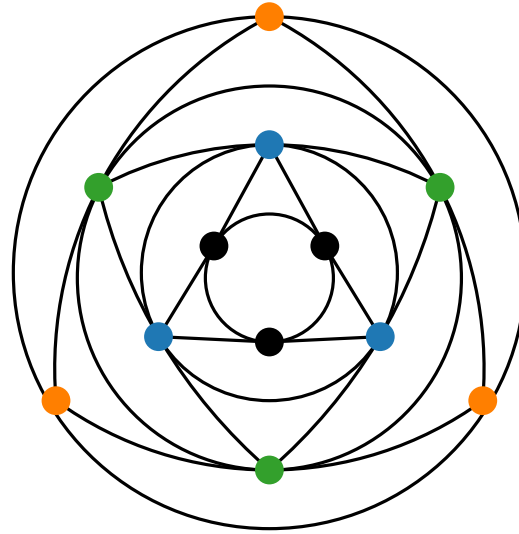
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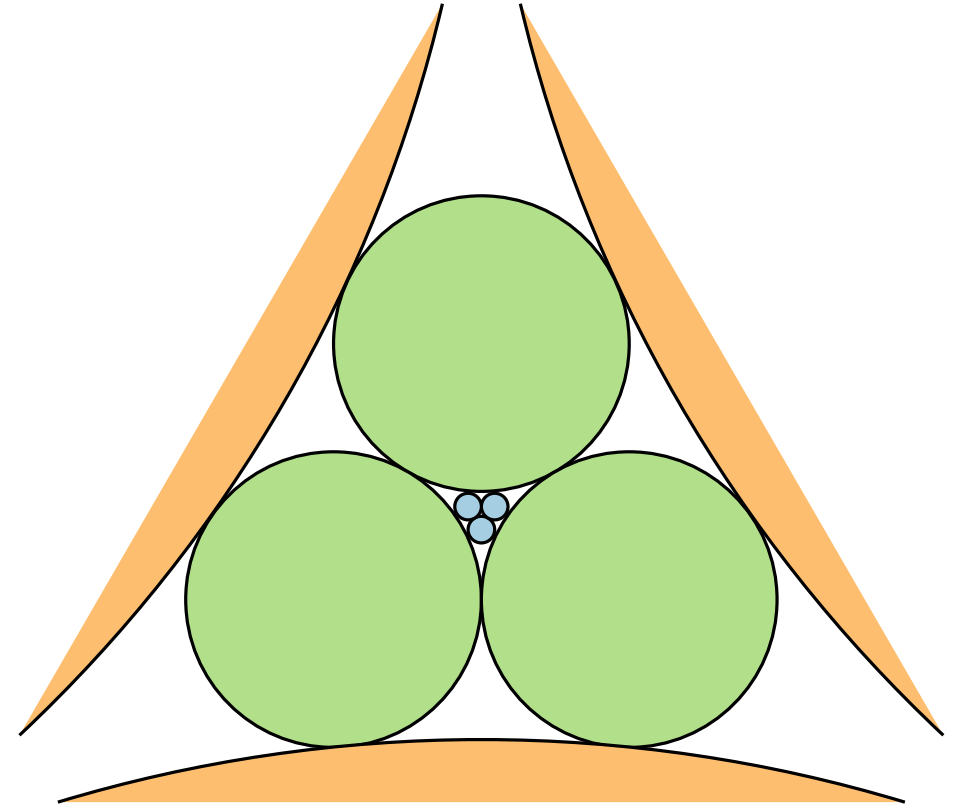
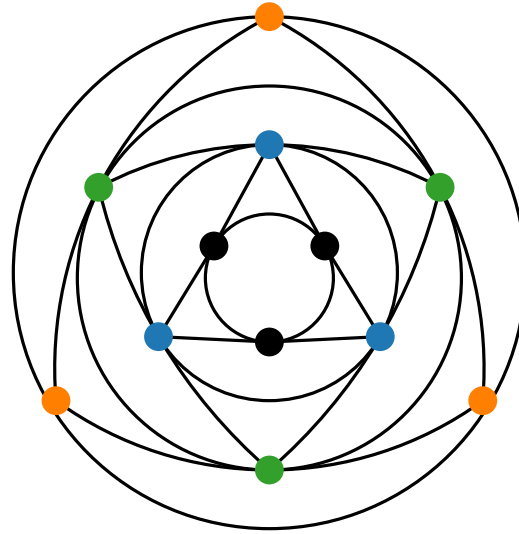
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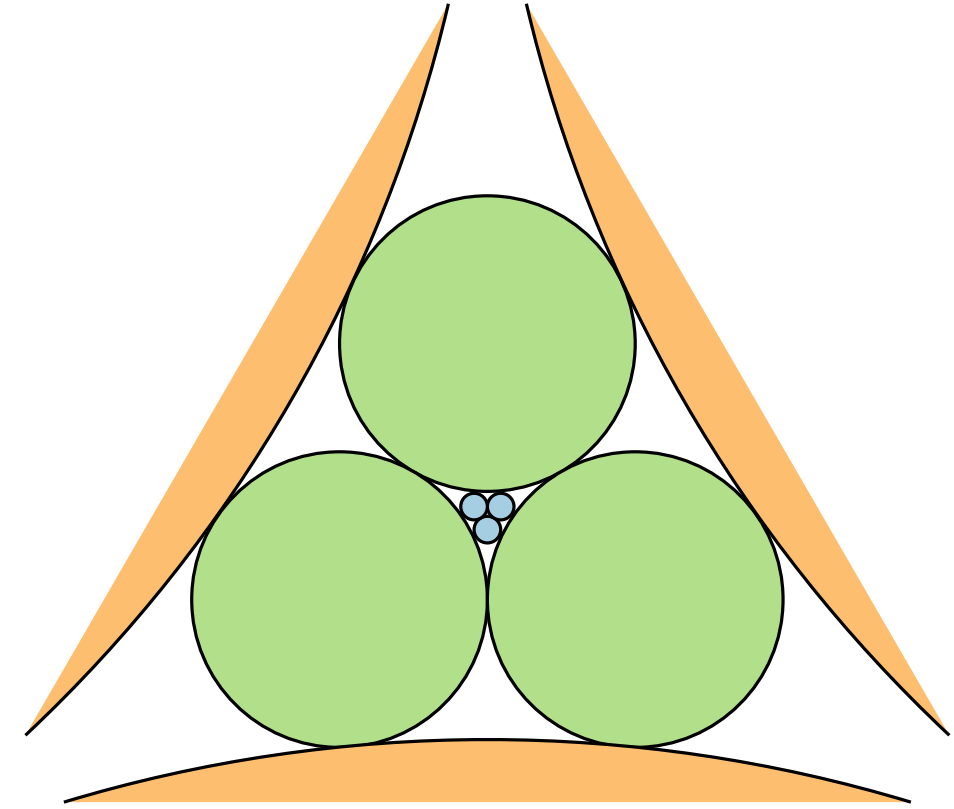
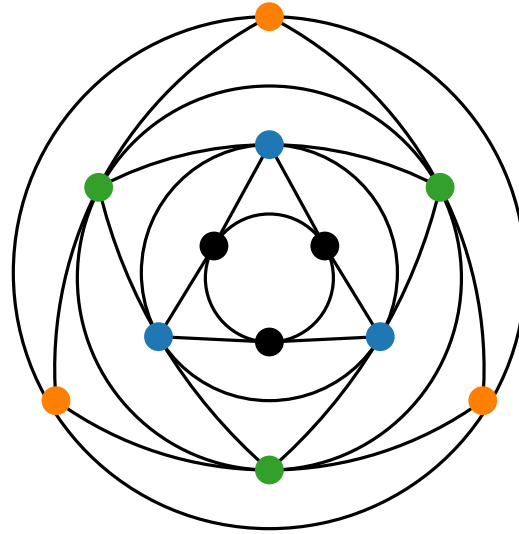
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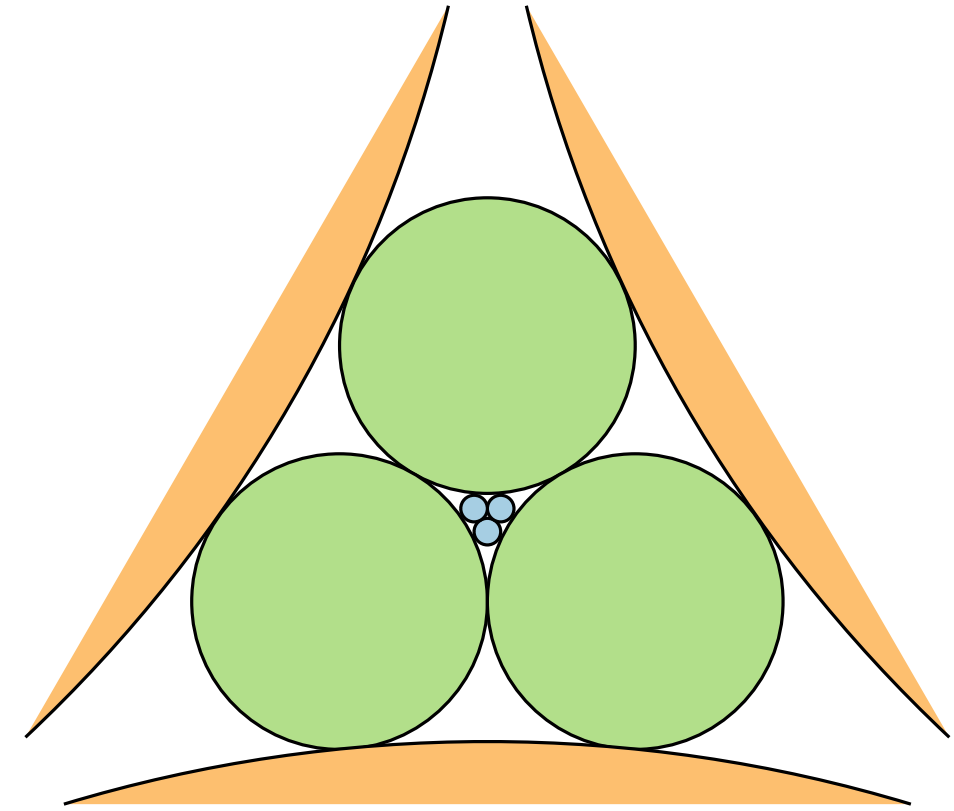
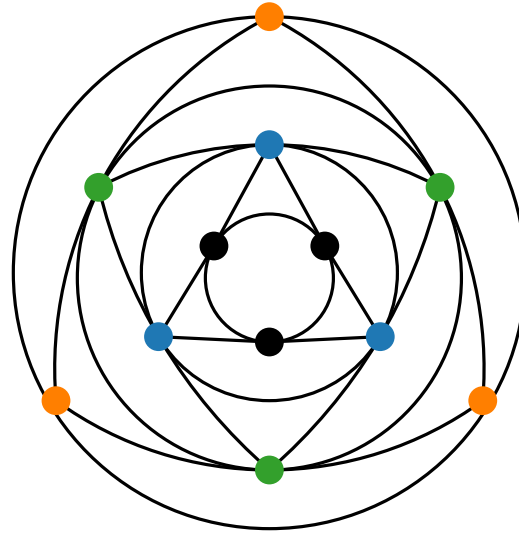
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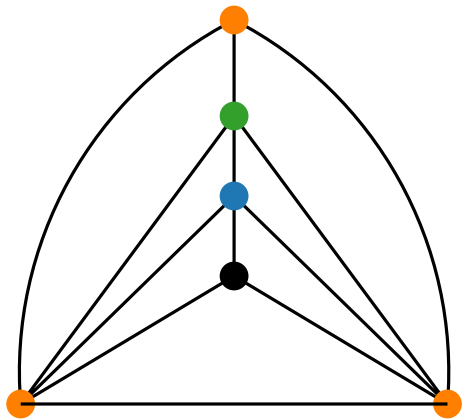
- **Barycentric representation:**
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Planar graphs

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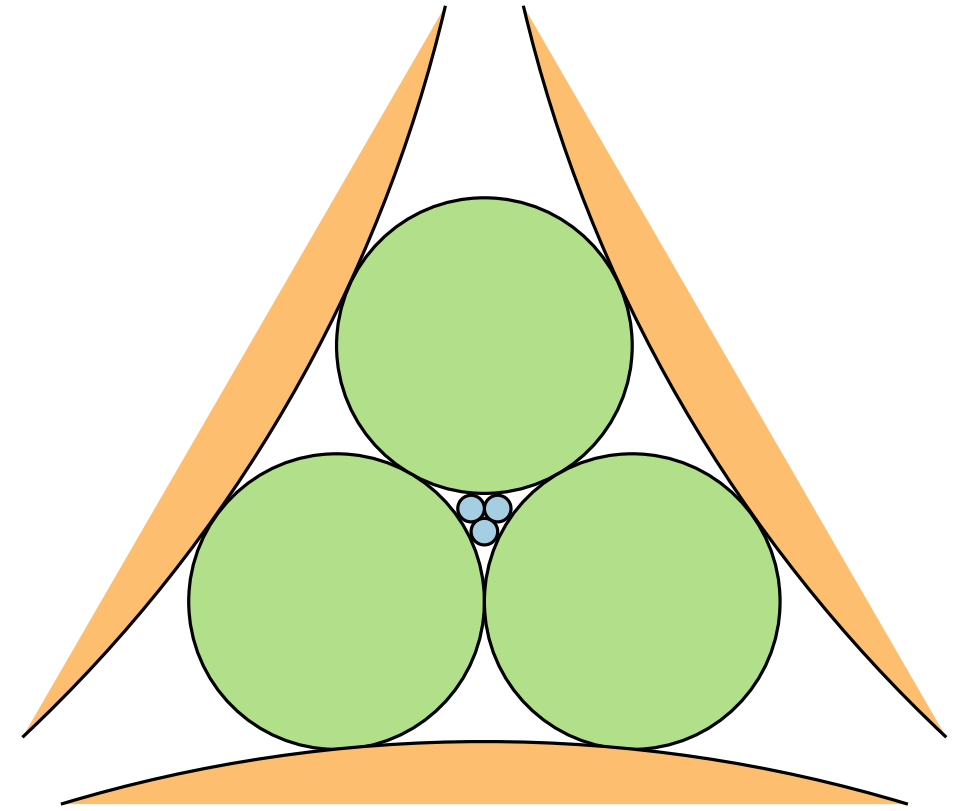
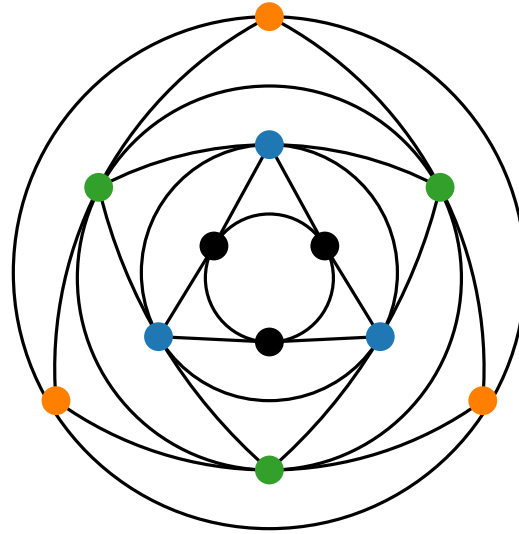


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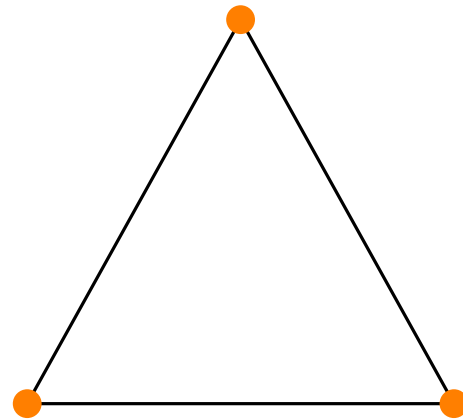
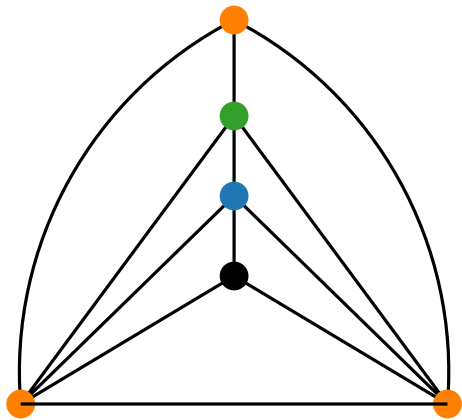


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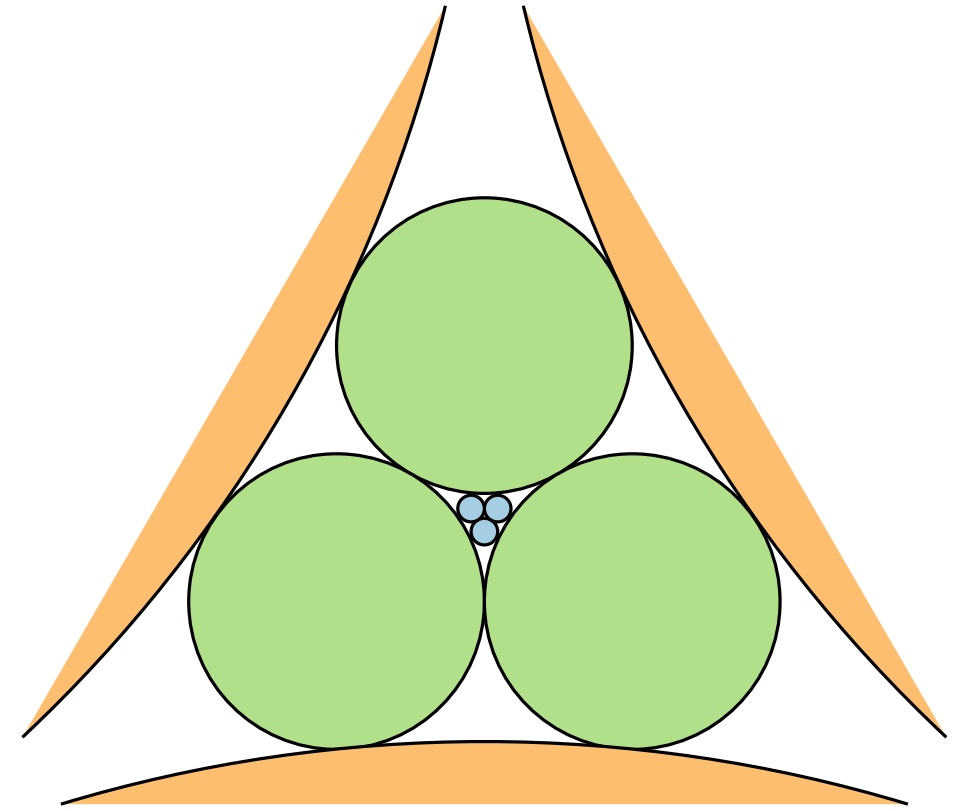
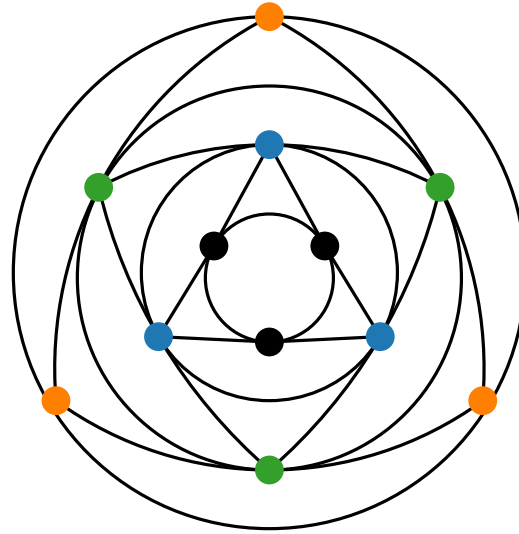


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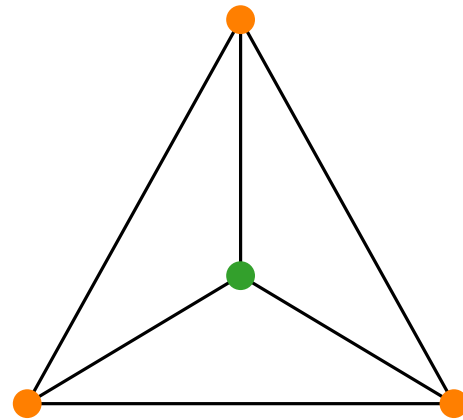
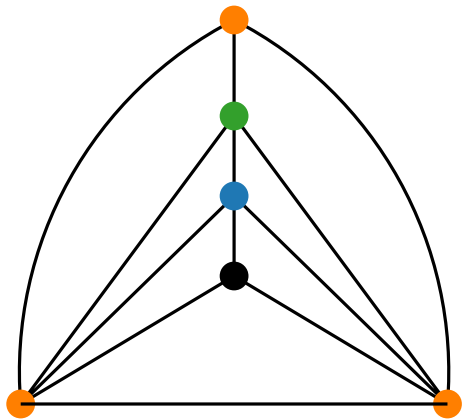


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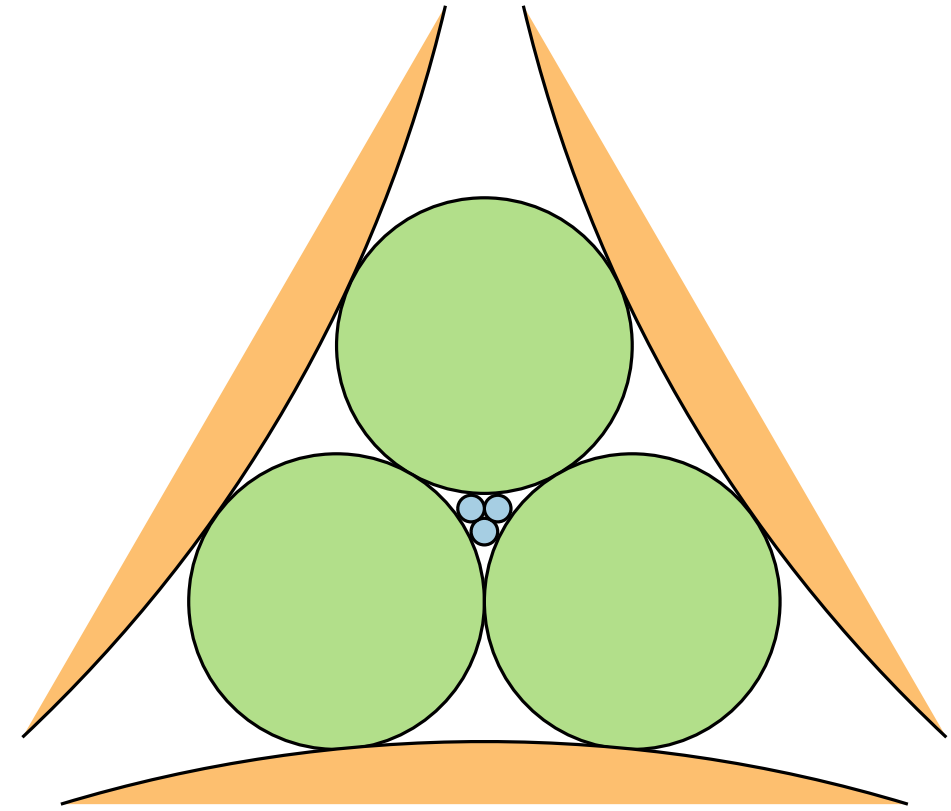
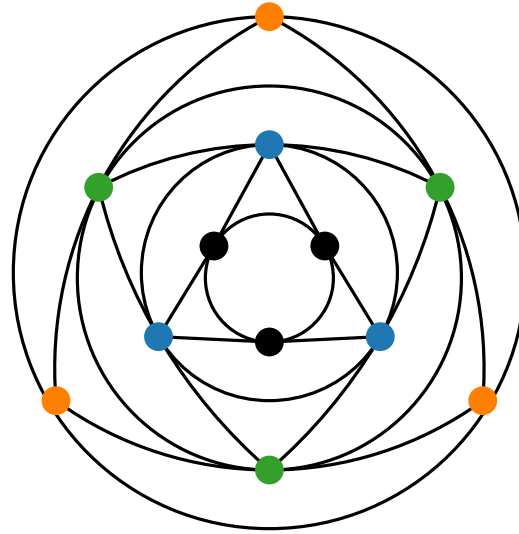


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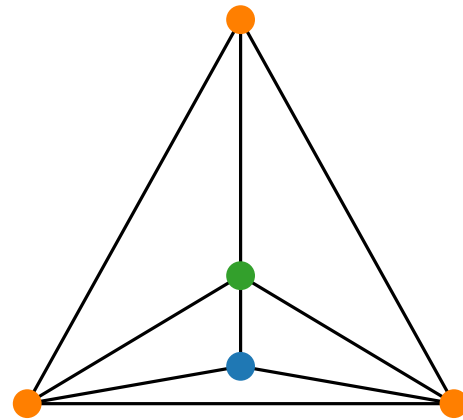
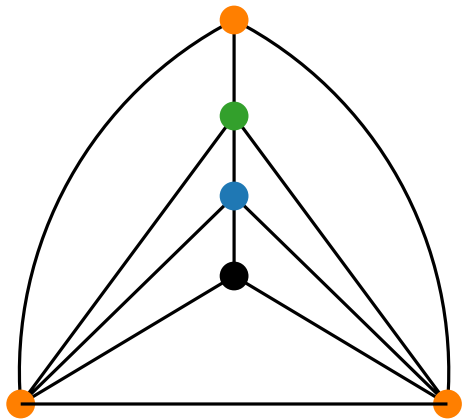


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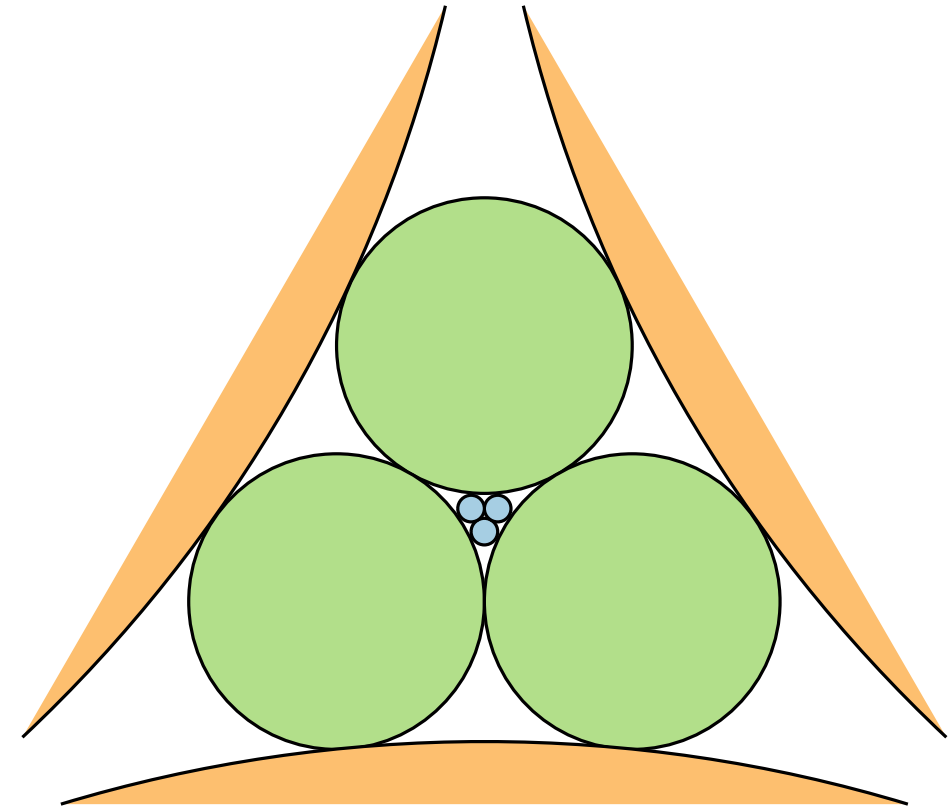
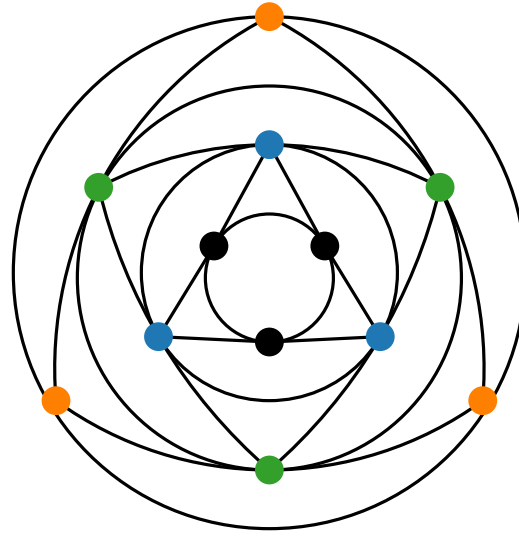


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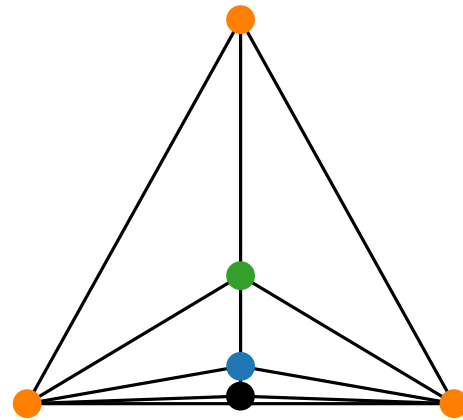
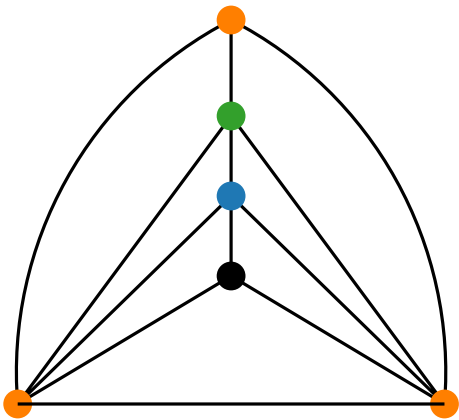


Planar graphs

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- **Barycentric representation:**
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Planar graphs

- Every planar graph has at most $3n - 6$ edges
- A *planar triangulation* is a planar graph with $3n - 6$ edges

Planar graphs

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- A *planar triangulation* is a planar graph with $3n - 6$ edges
- **Properties of planar triangulations:**
 - Every face is a triangle
 - graph is 3-connected
 - Unique embedding (up to choice of outerface)
 - Every plane graph is subgraph of a plane triangulation

Planar graphs

- Every planar graph has at most $3n - 6$ edges
 - A *planar triangulation* is a planar graph with $3n - 6$ edges
 - **Properties of planar triangulations:**
 - Every face is a triangle
 - graph is 3-connected
 - Unique embedding (up to choice of outerface)
 - Every plane graph is subgraph of a plane triangulation
- with planar embedding
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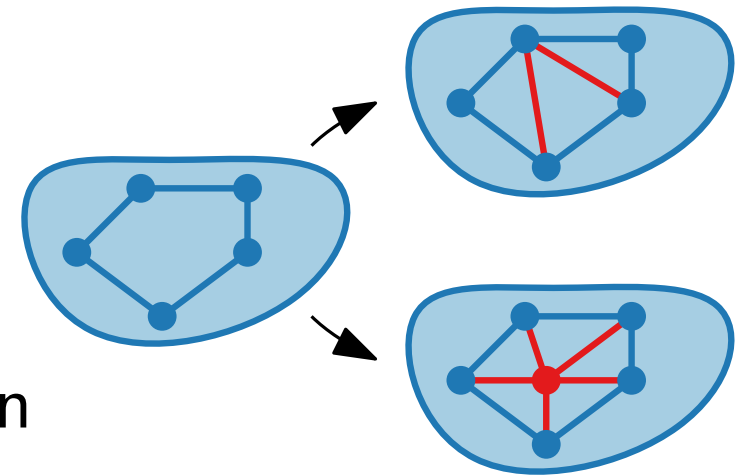
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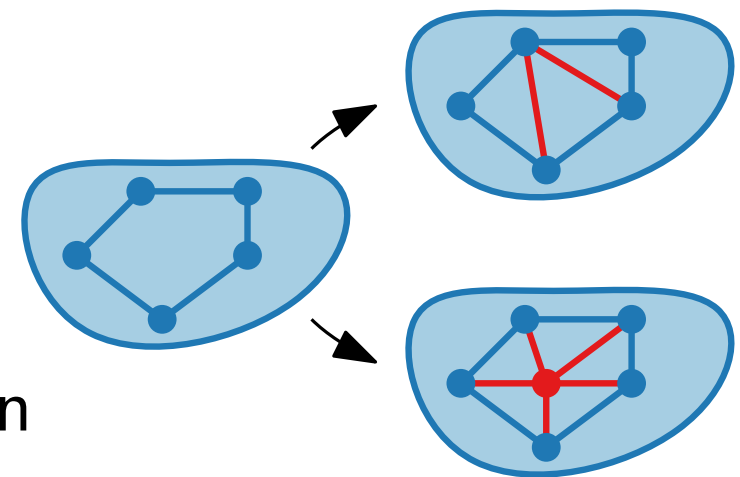
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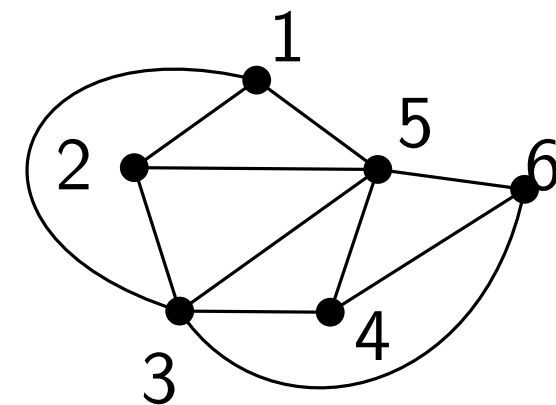
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- We focus on **triangulations:**

- A *plane (inner) triangulation* is a plane graph where every (inner) face is a triangle.



Planar straight-line drawings

Goal:

For an n -vertex planar graph create a planar straight-line drawing of size $O(n^2)$.

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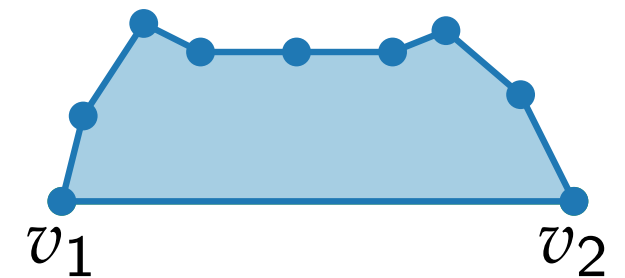
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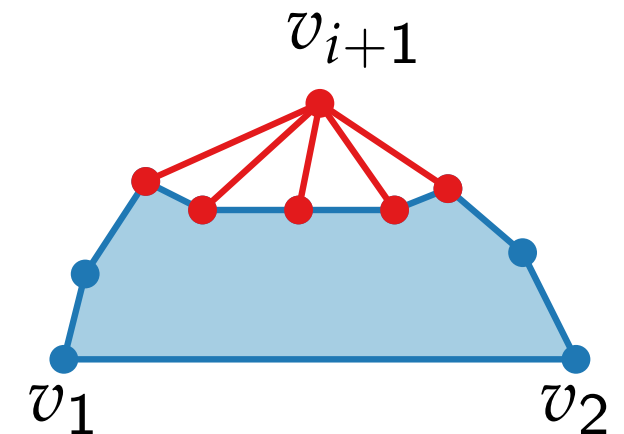
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- Start with single edge (v_1, v_2) . Let this be G_2 .
- To obtain G_{i+1} , add v_{i+1} to G_i so that neighbours of v_{i+1} are on the outer face of G_i .
- Neighbours of v_{i+1} in G_i have to form path of length at least two.



Canonical order – definition

Definition.

Let $G = (V, E)$ be a triangulated plane graph on $n \geq 3$ vertices. An order $\pi = (v_1, v_2, \dots, v_n)$ is called a **canonical order**, if the following conditions hold for each k , $3 \leq k \leq n$:

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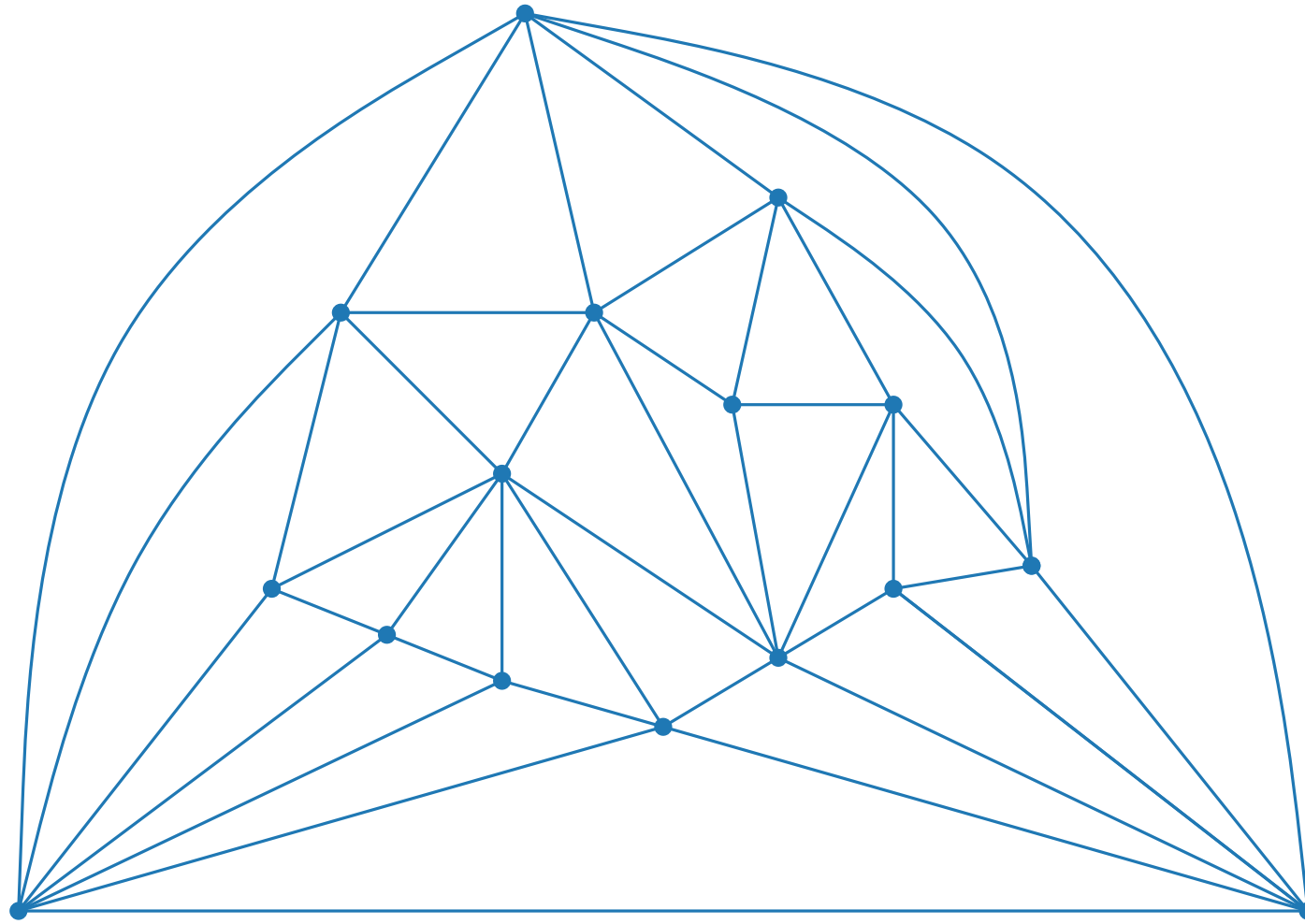
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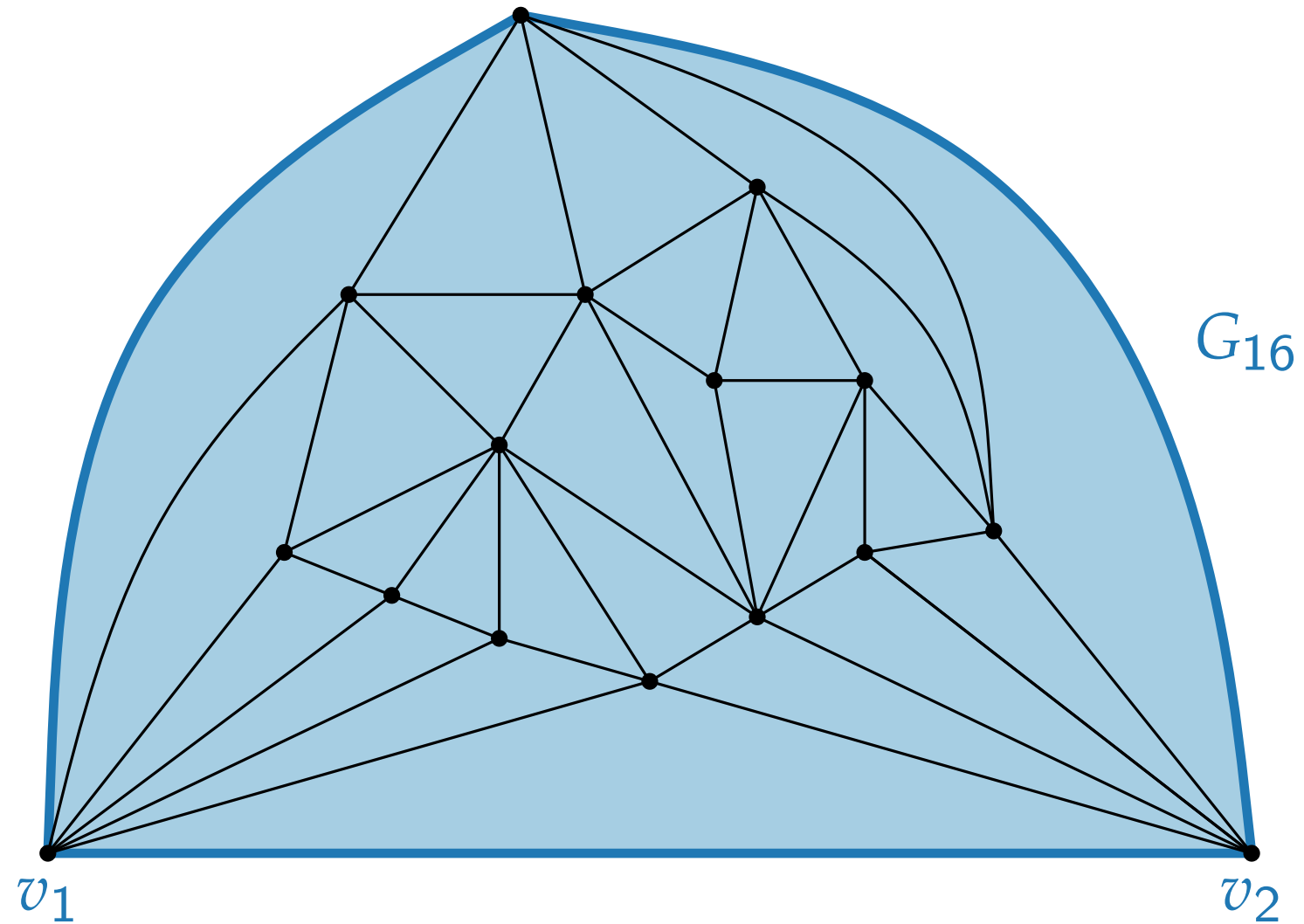
Compute:

- either $\{v_3, v_4, \dots, v_n\}$ (adding vertices)
- or $\{v_n, v_{n-1}, \dots, v_3\}$ (removing vertices)

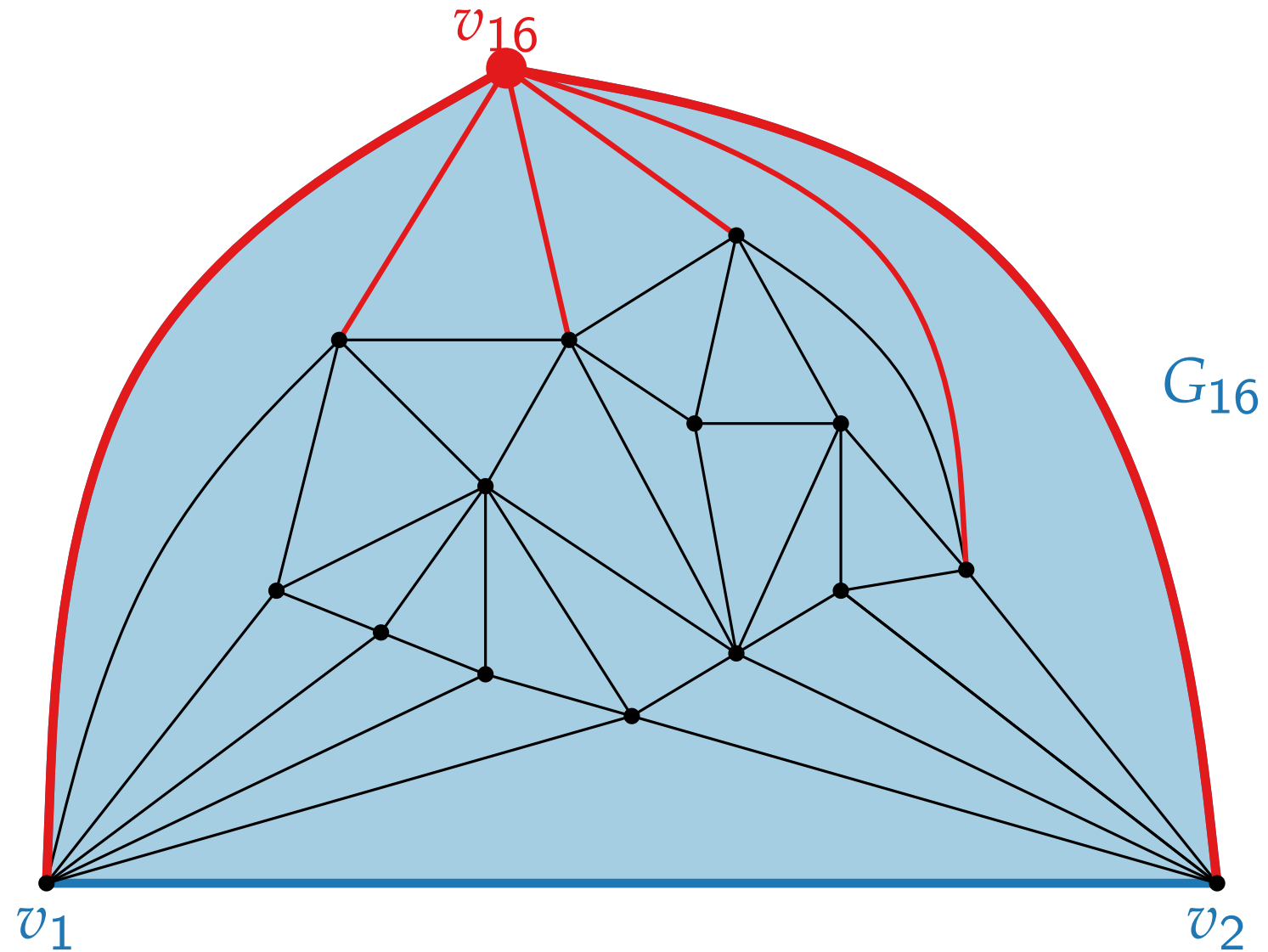
Canonical order – example



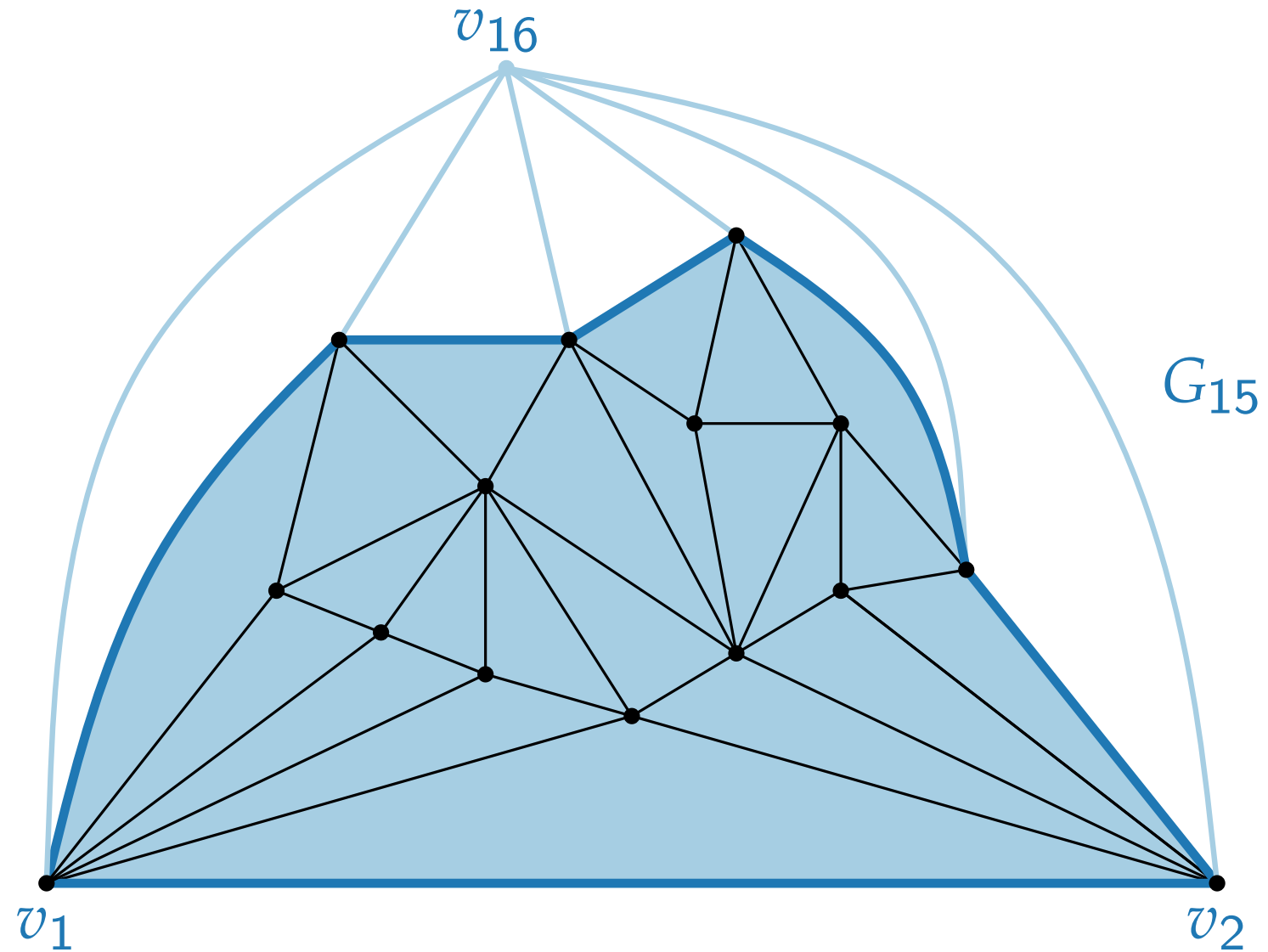
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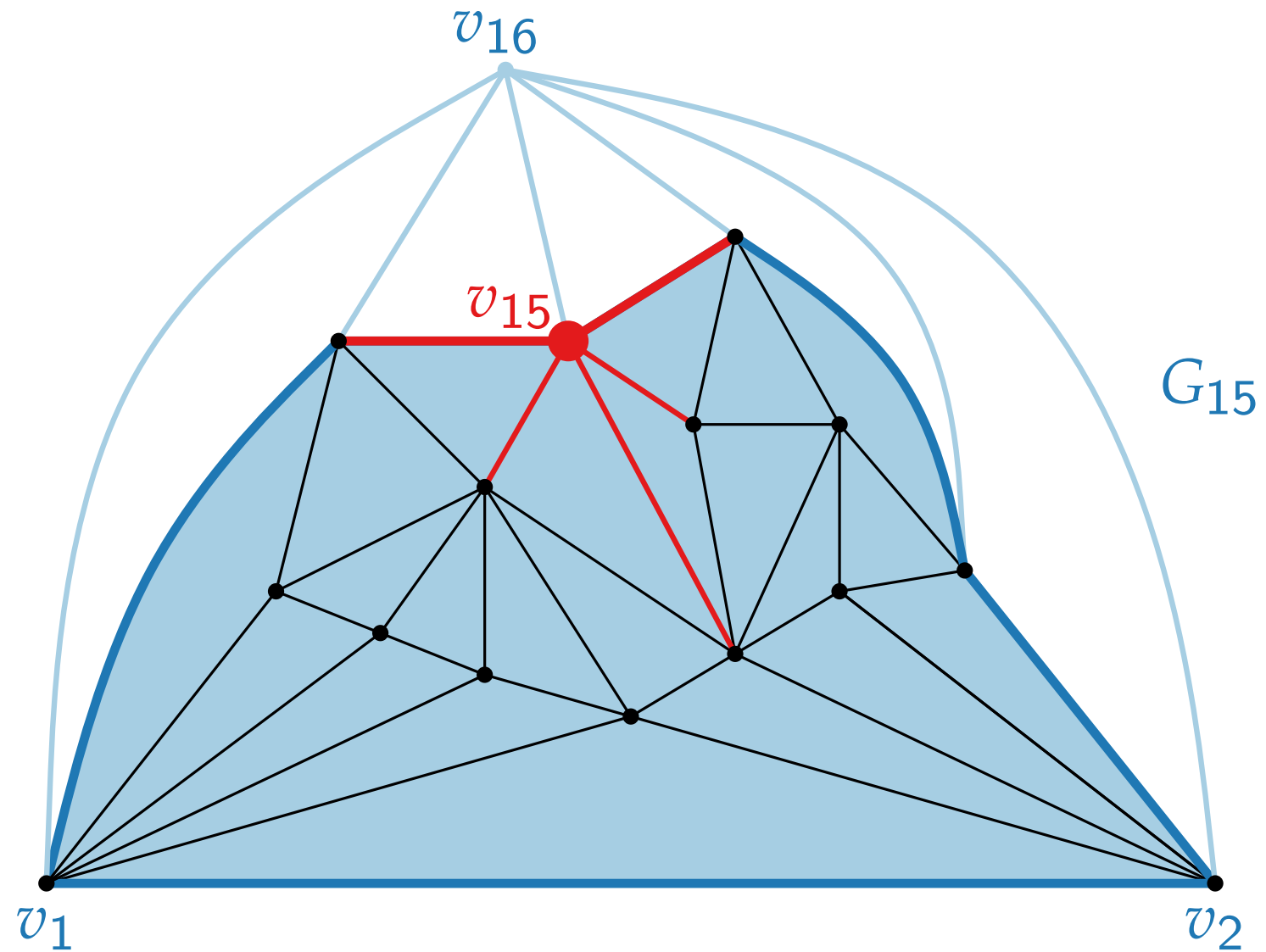
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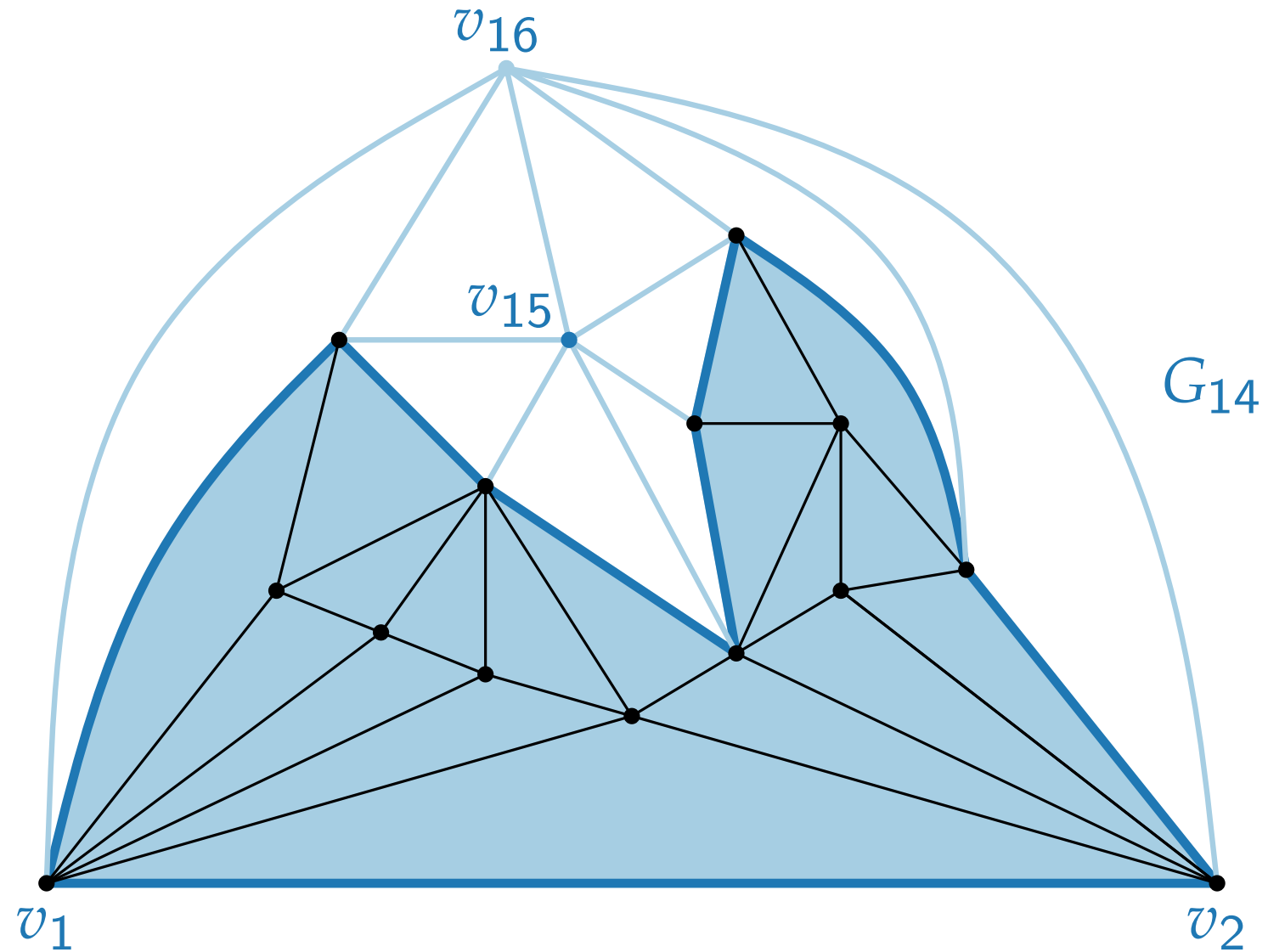
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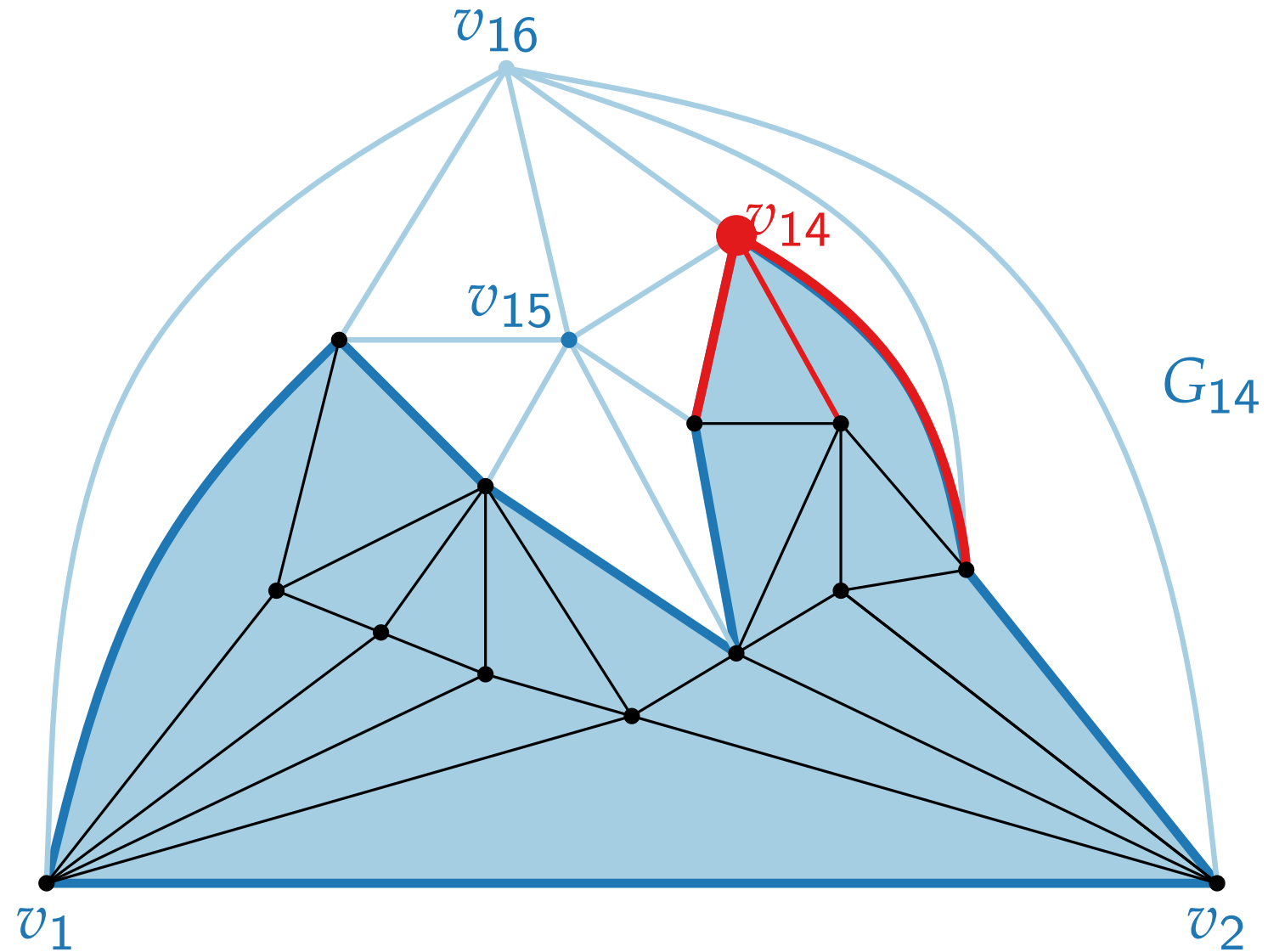
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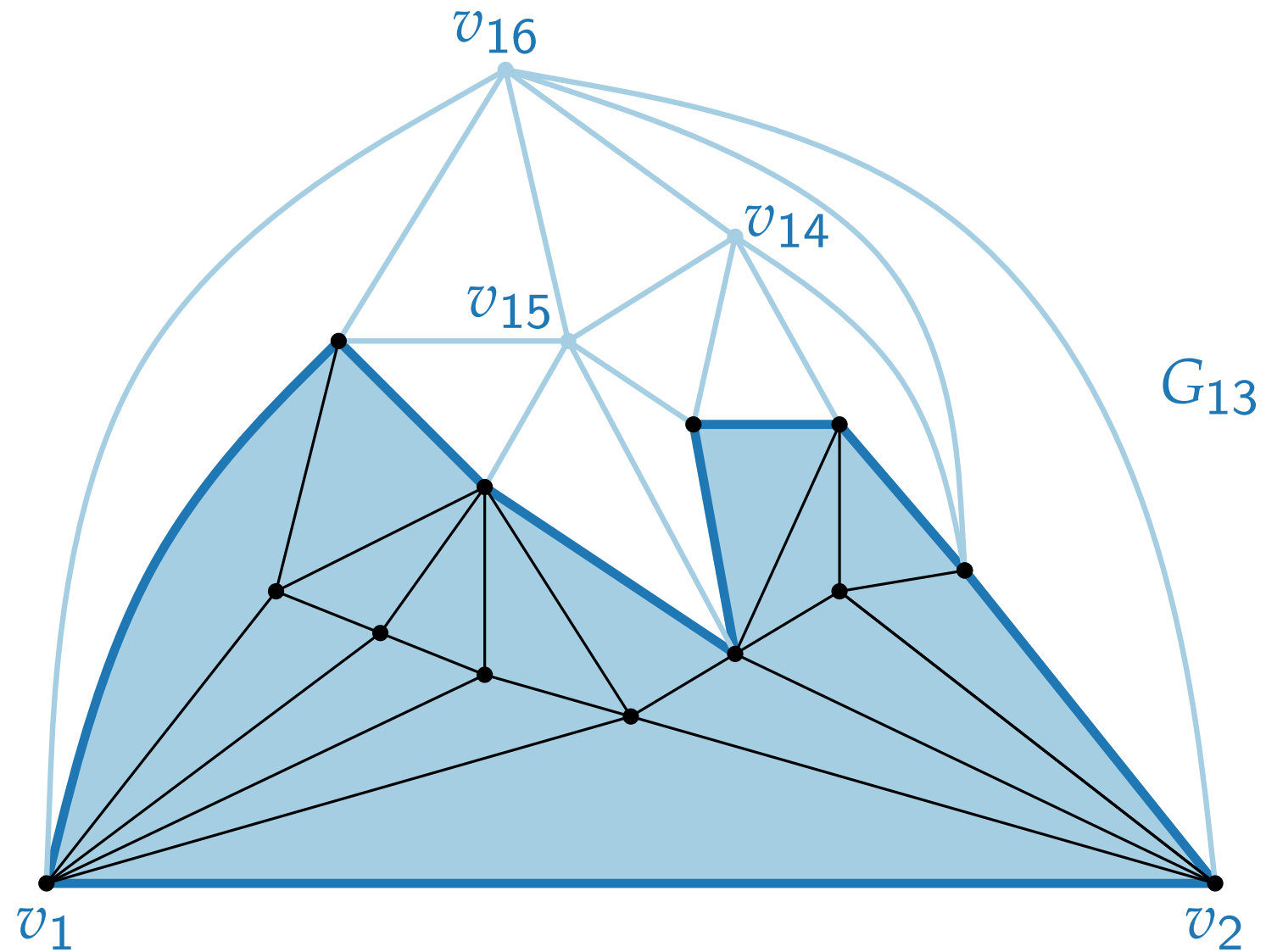
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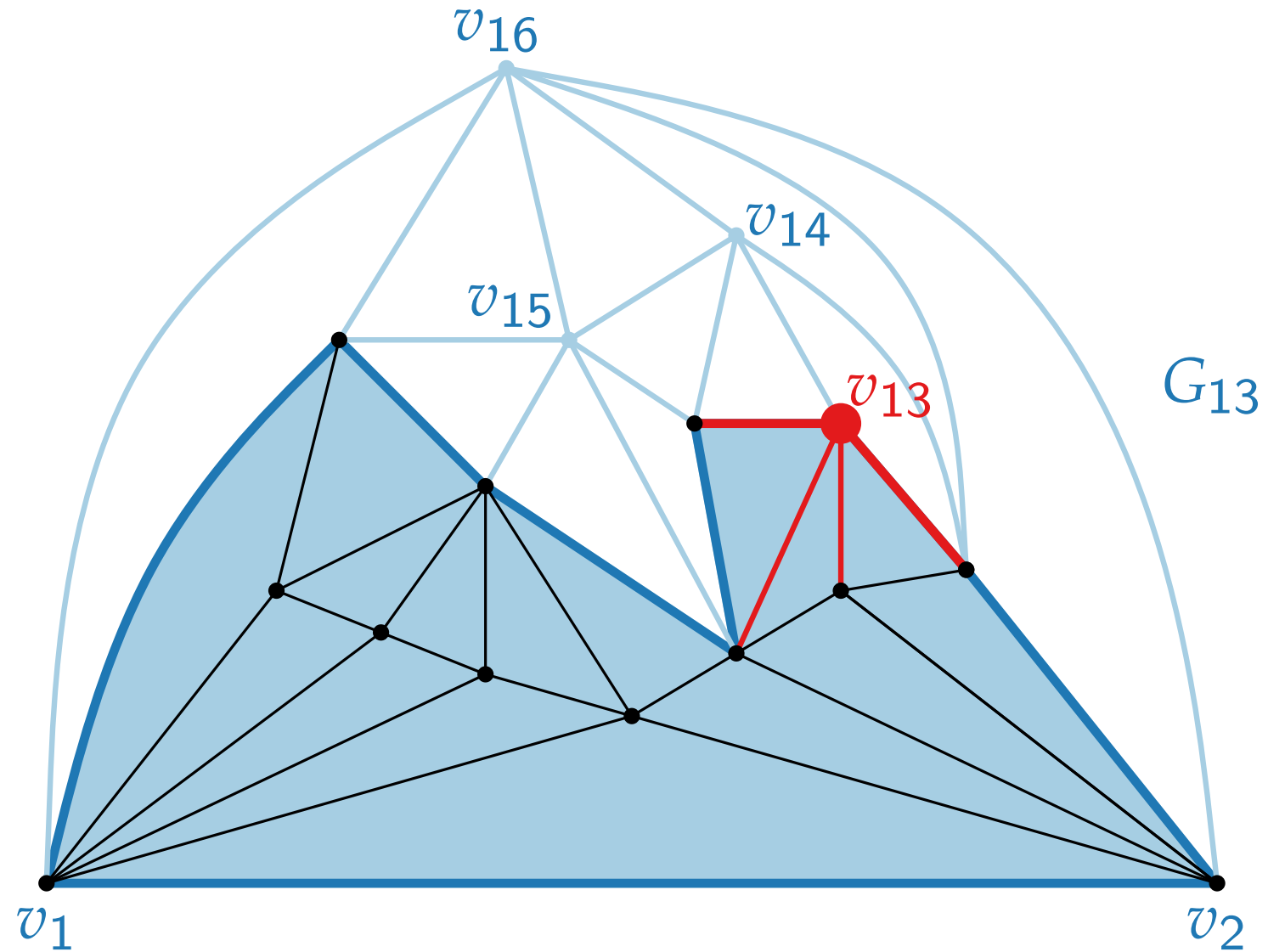
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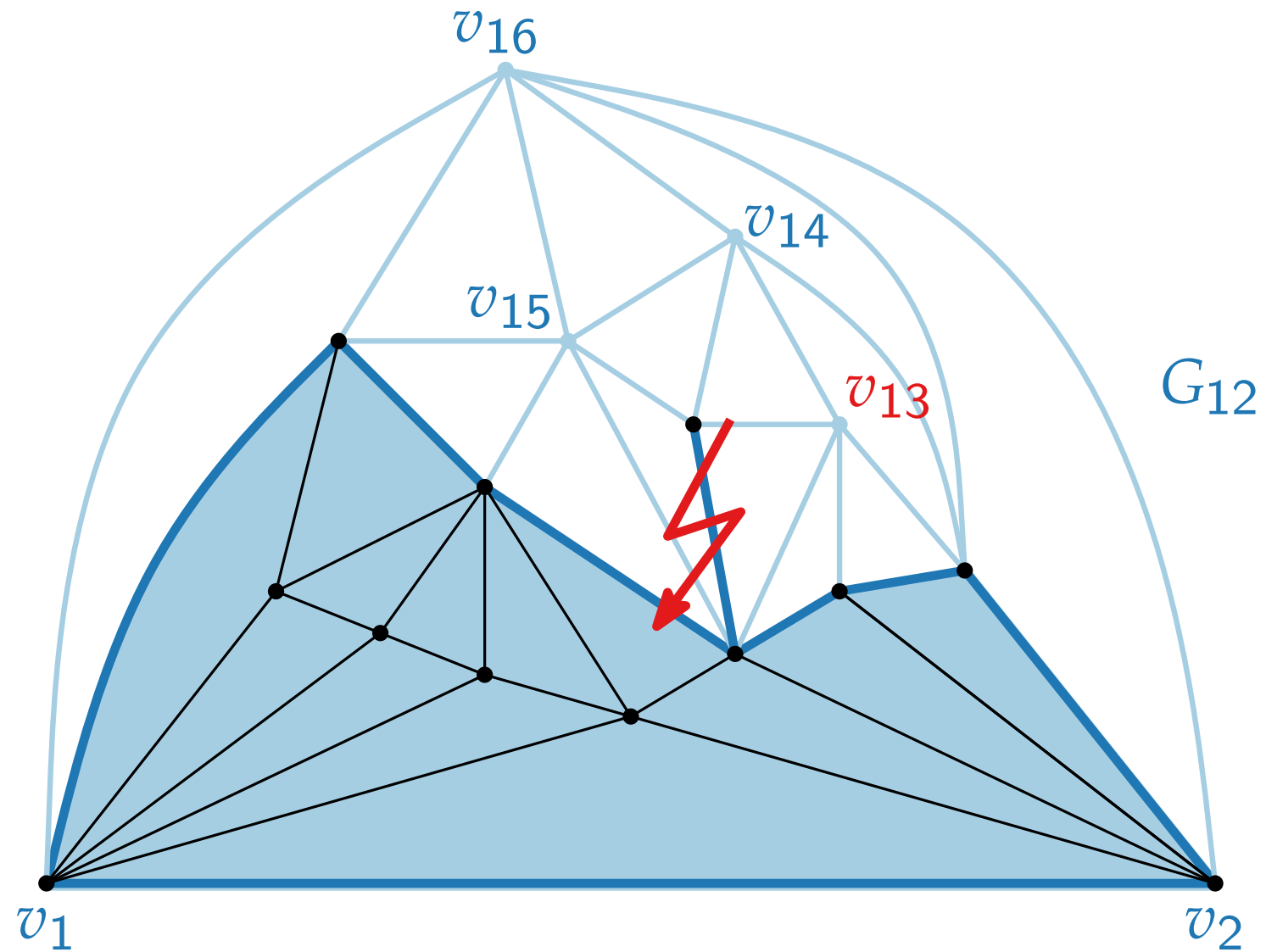
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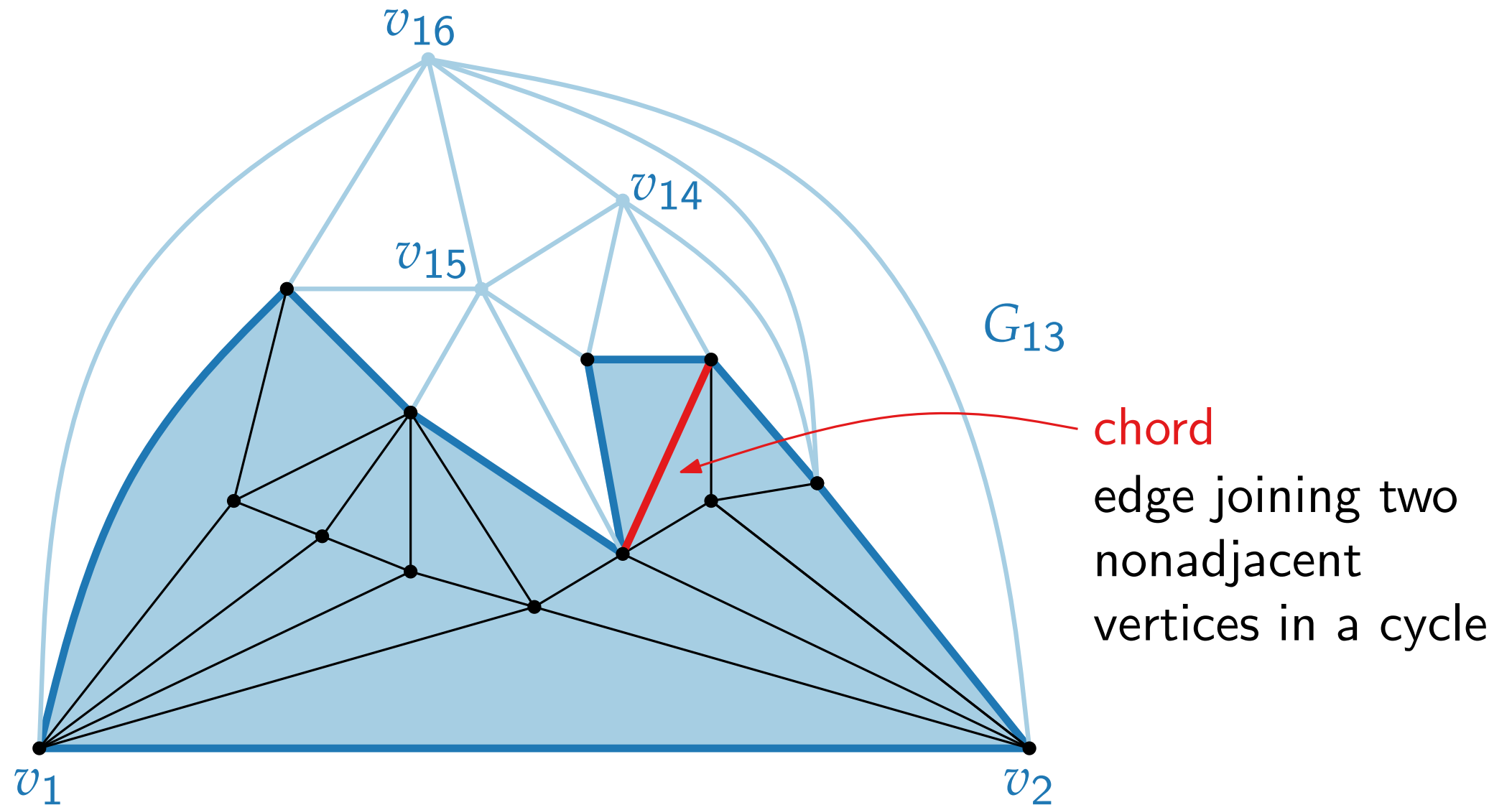
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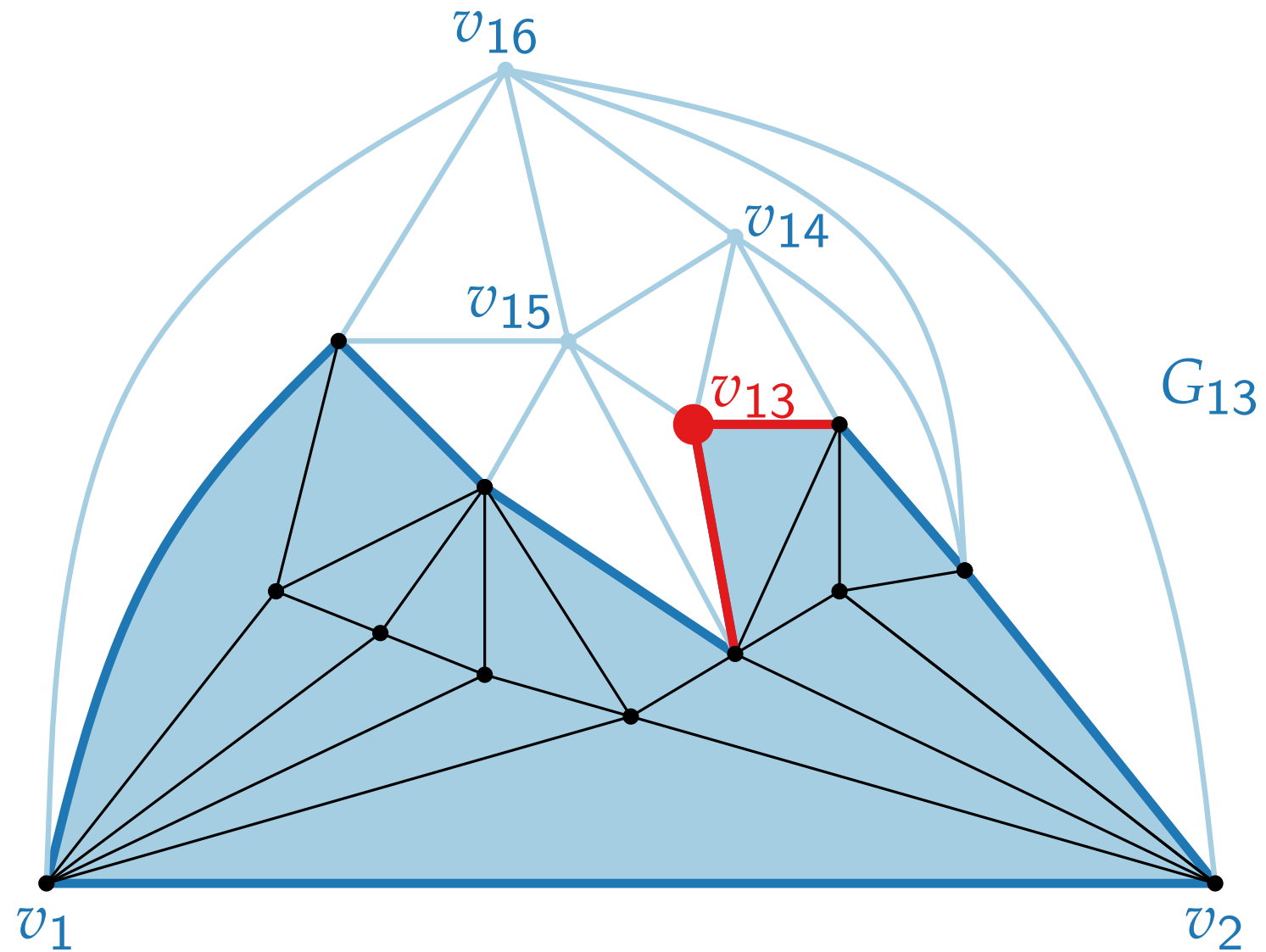
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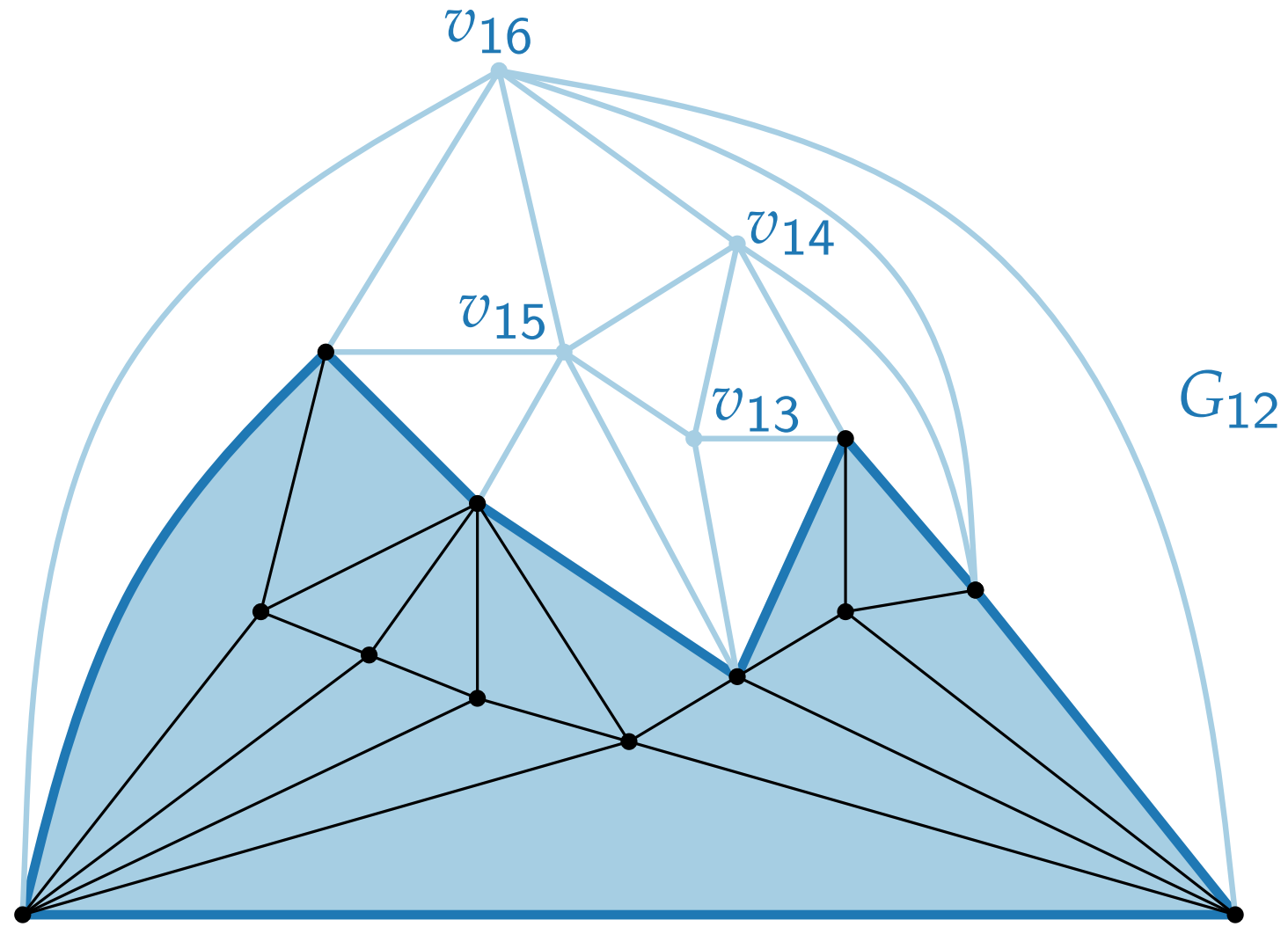
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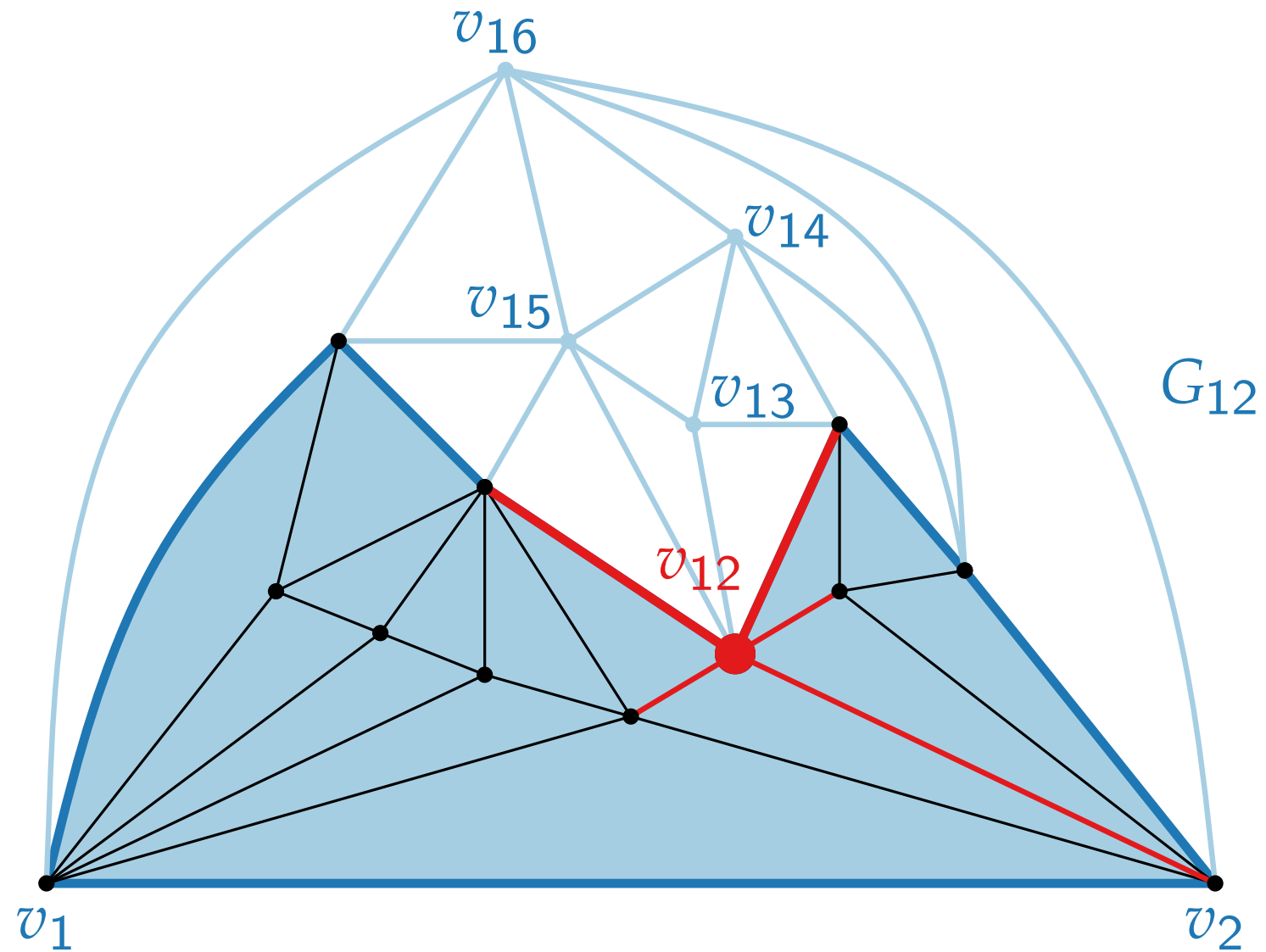
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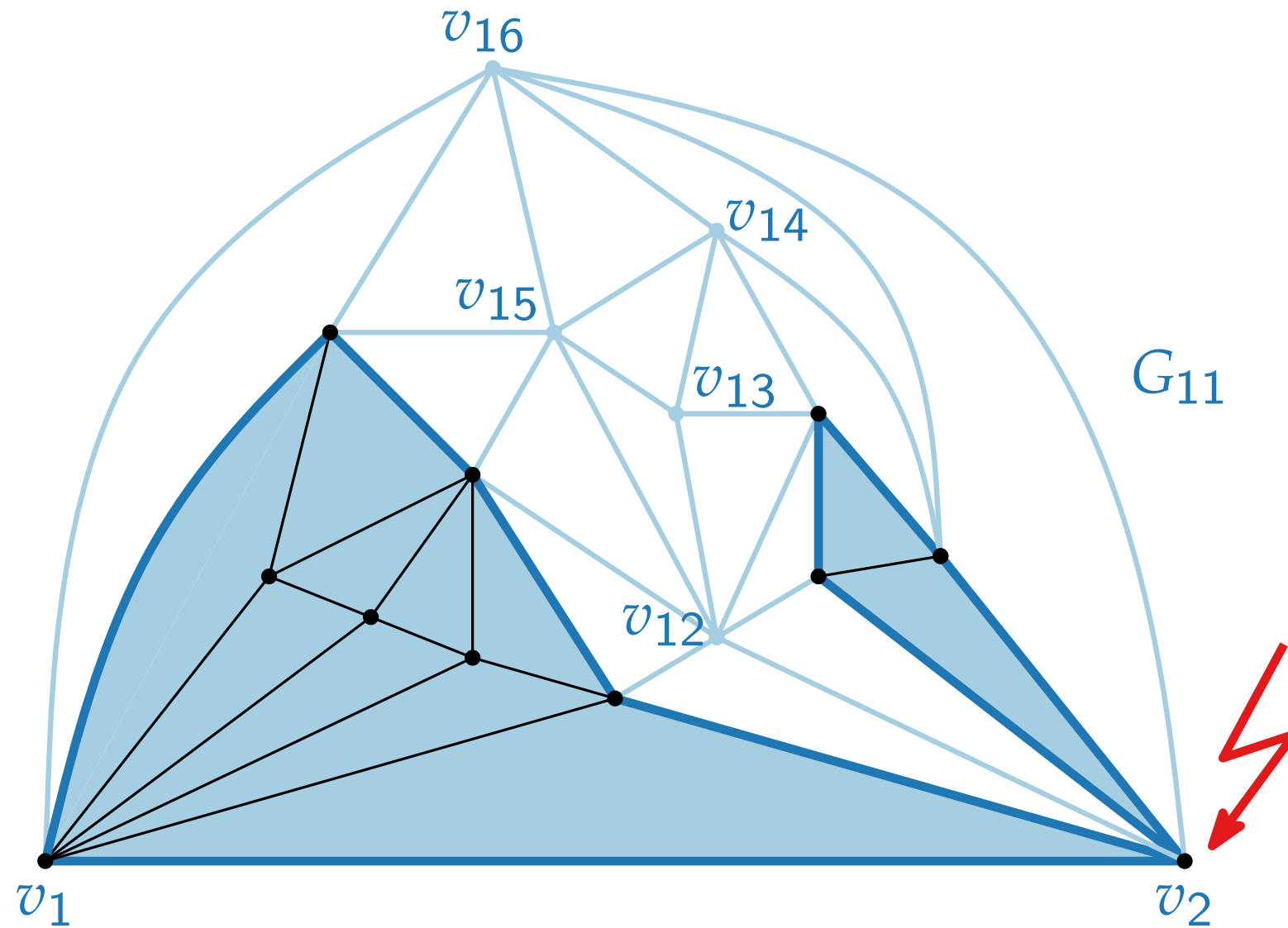
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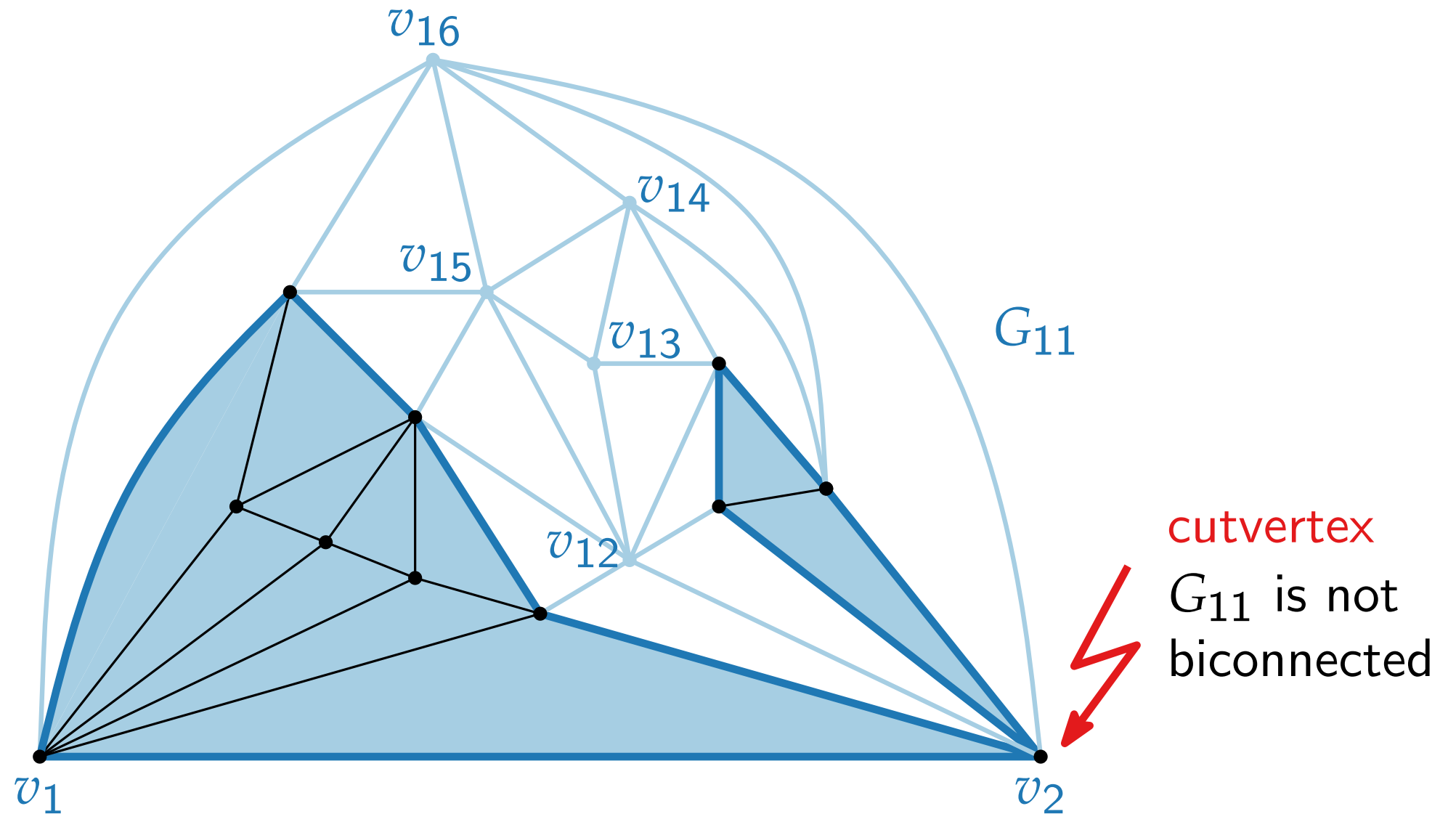
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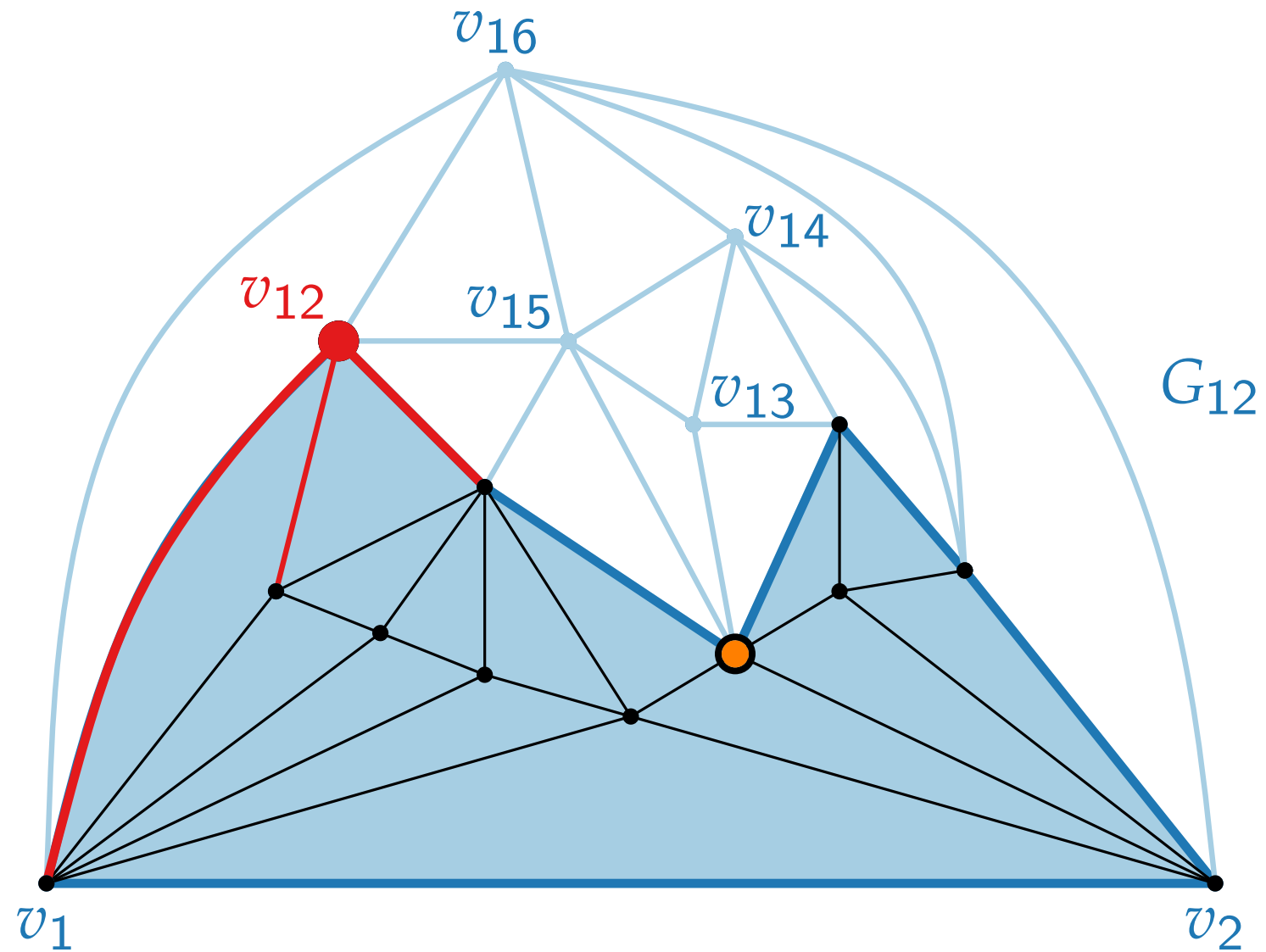
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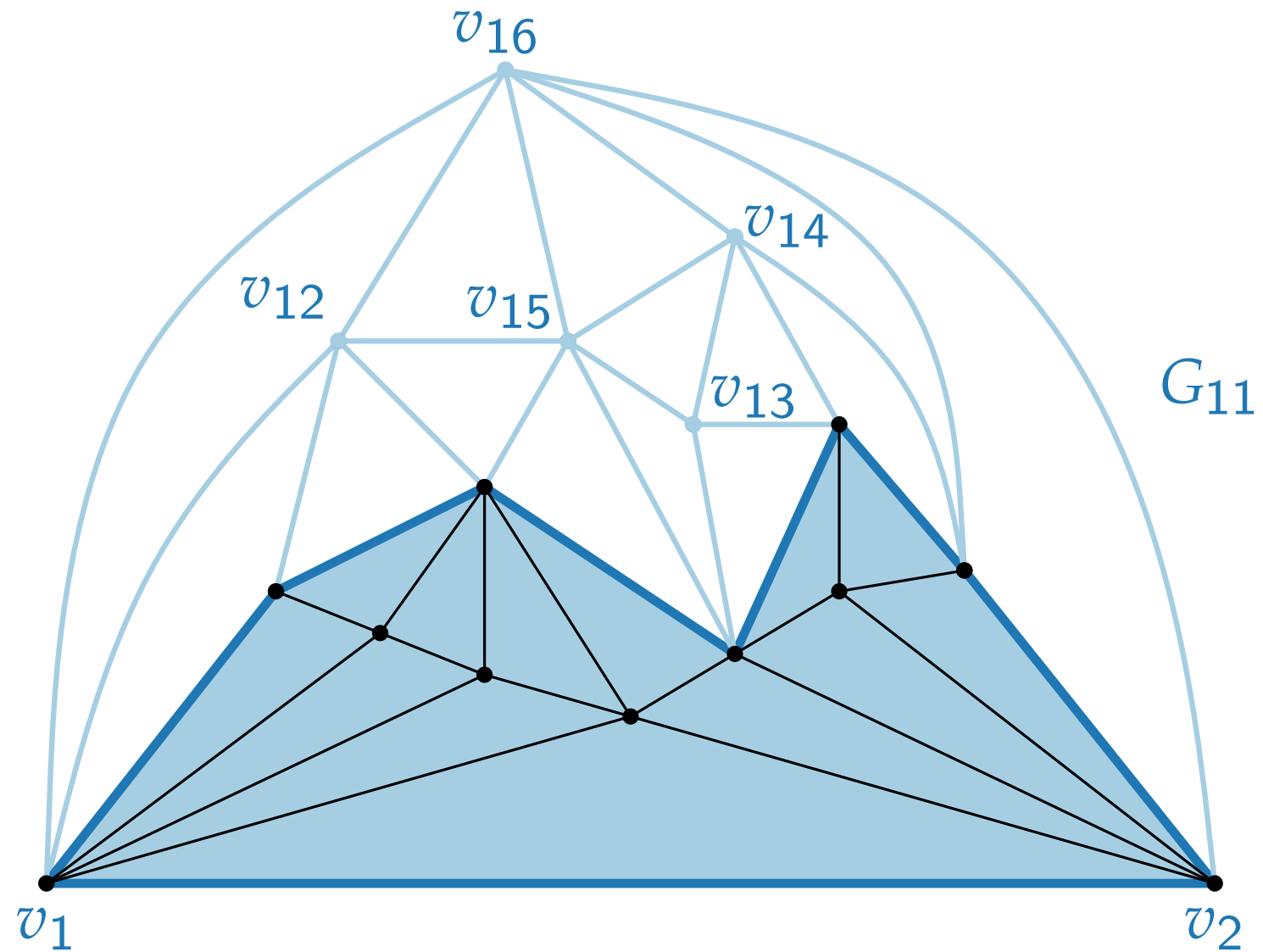
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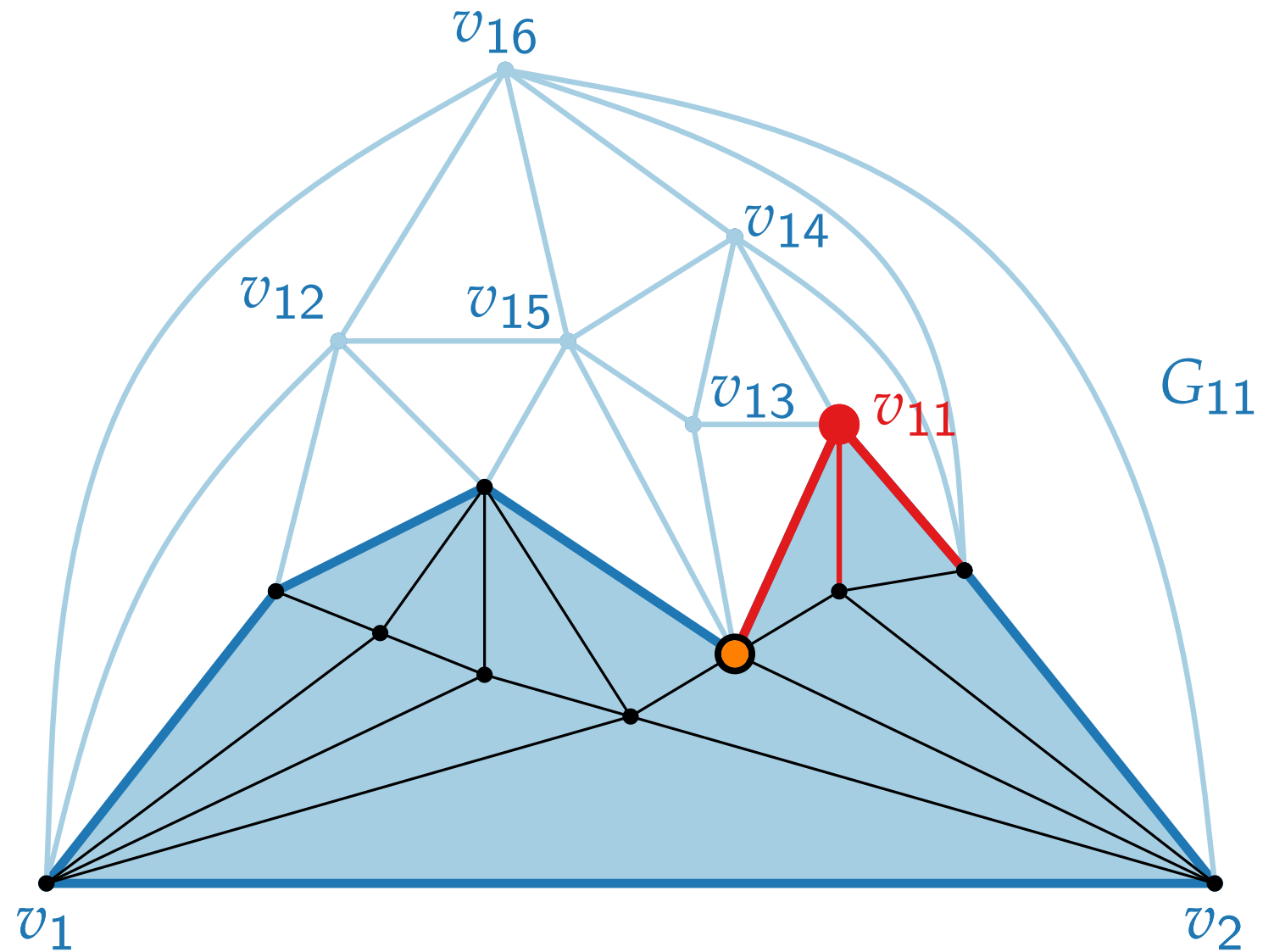
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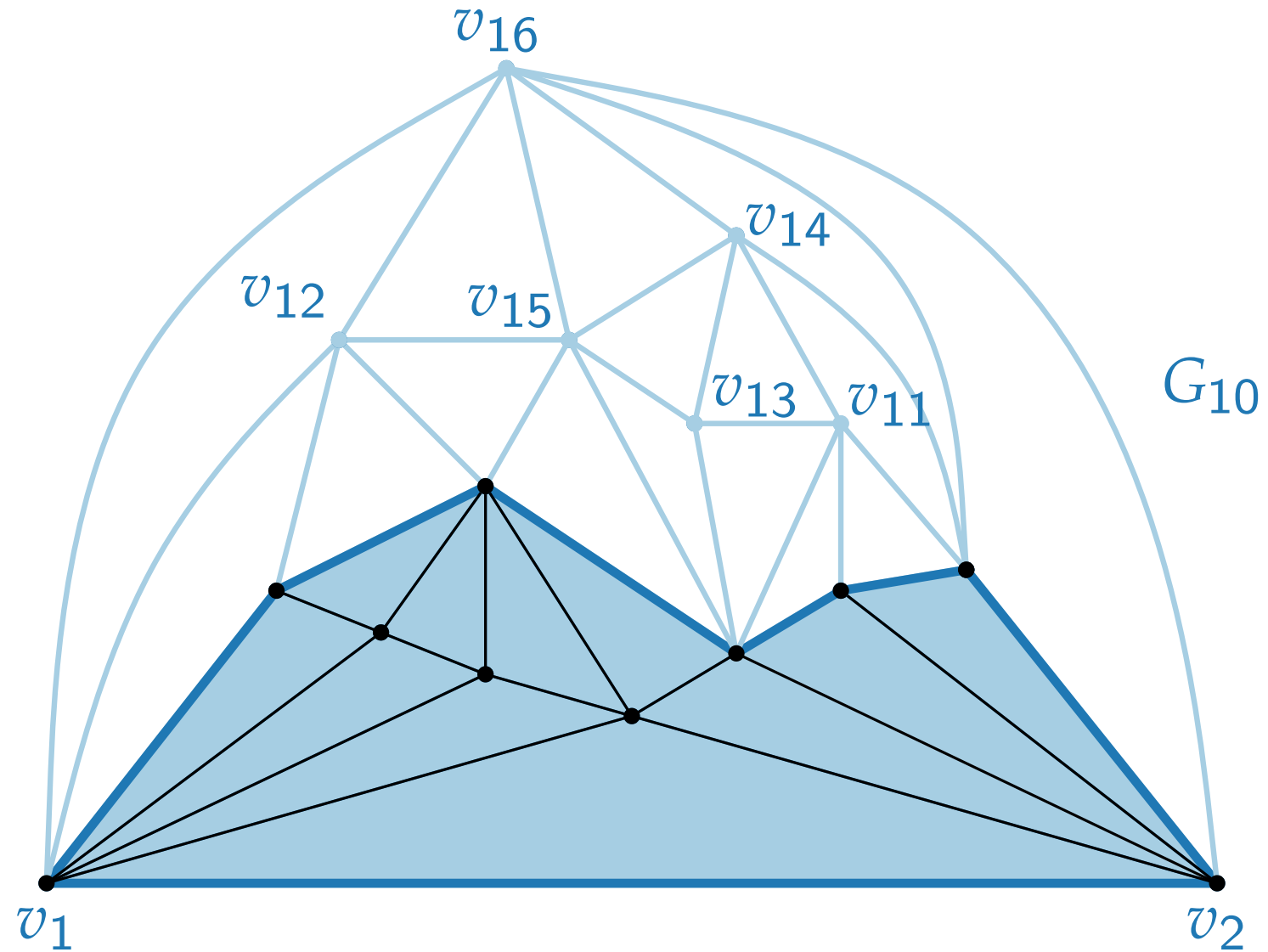
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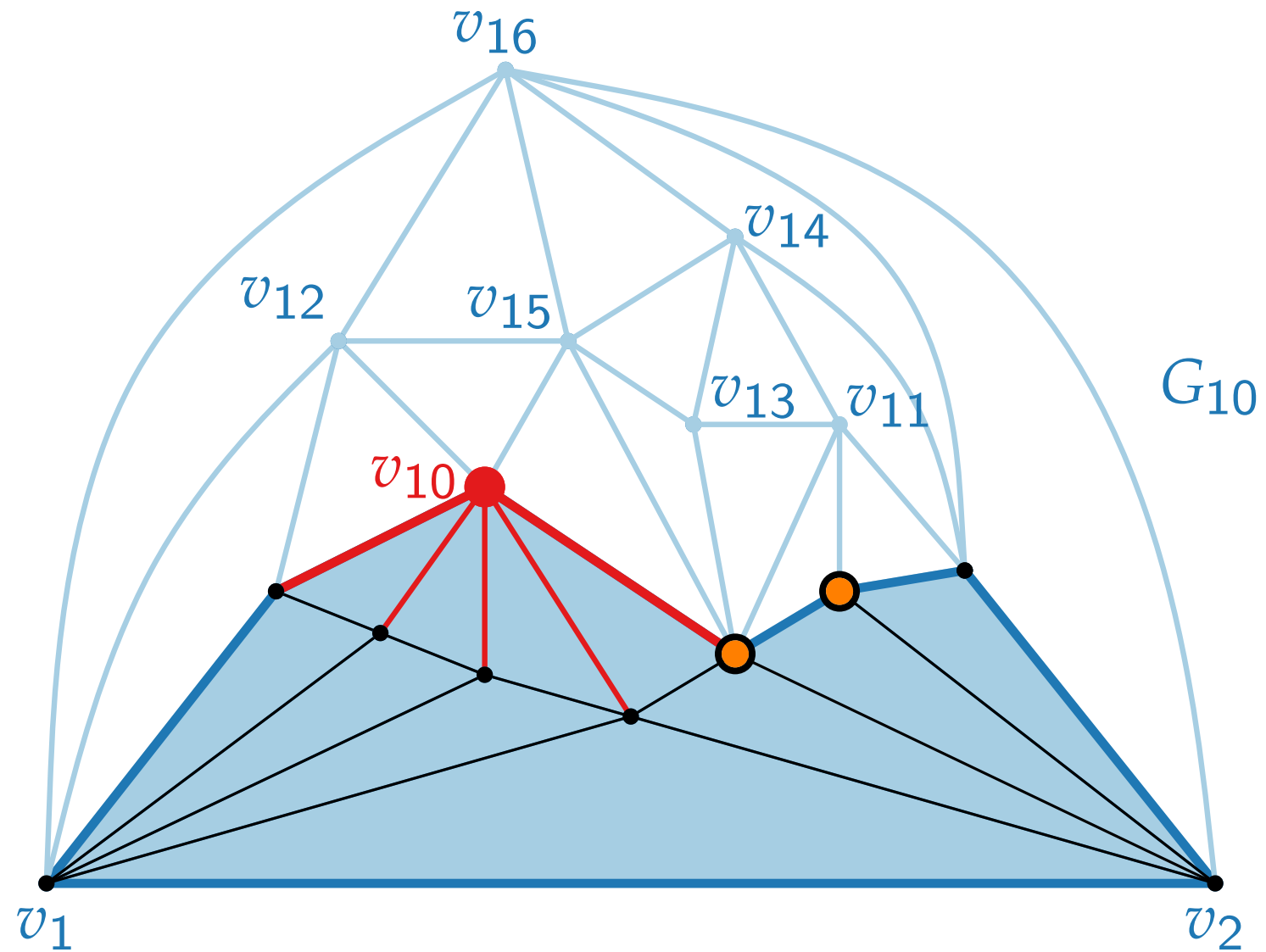
Canonical order – example



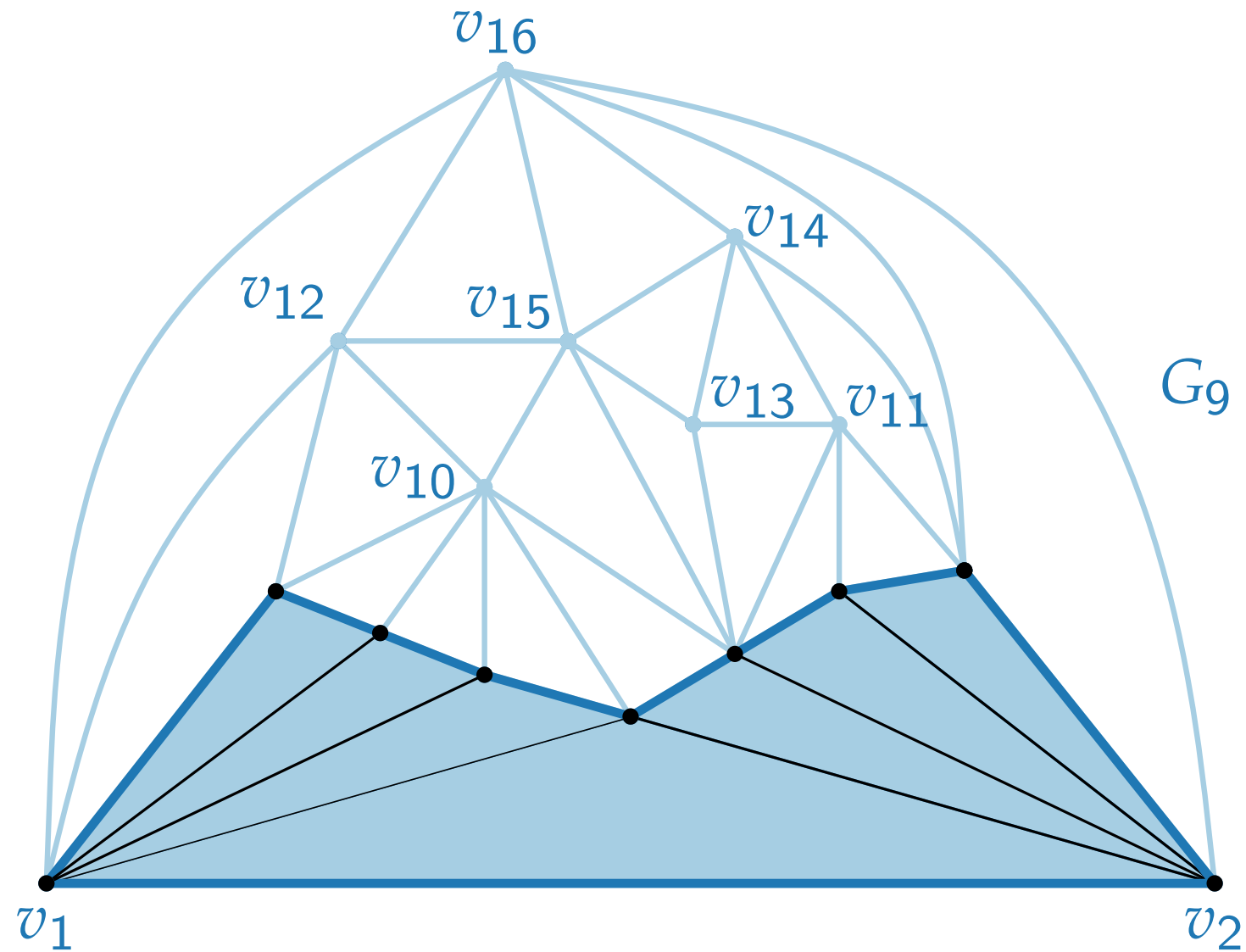
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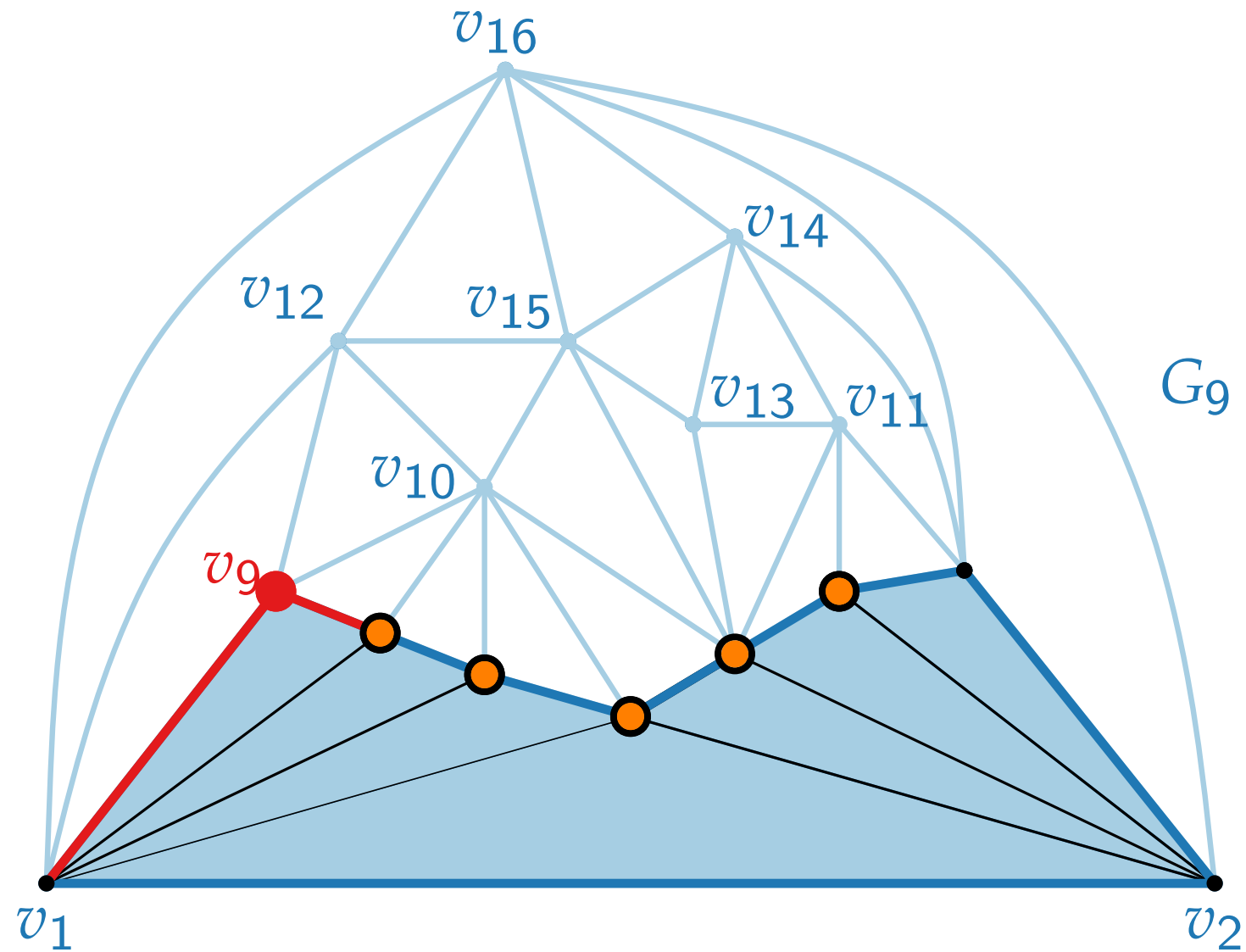
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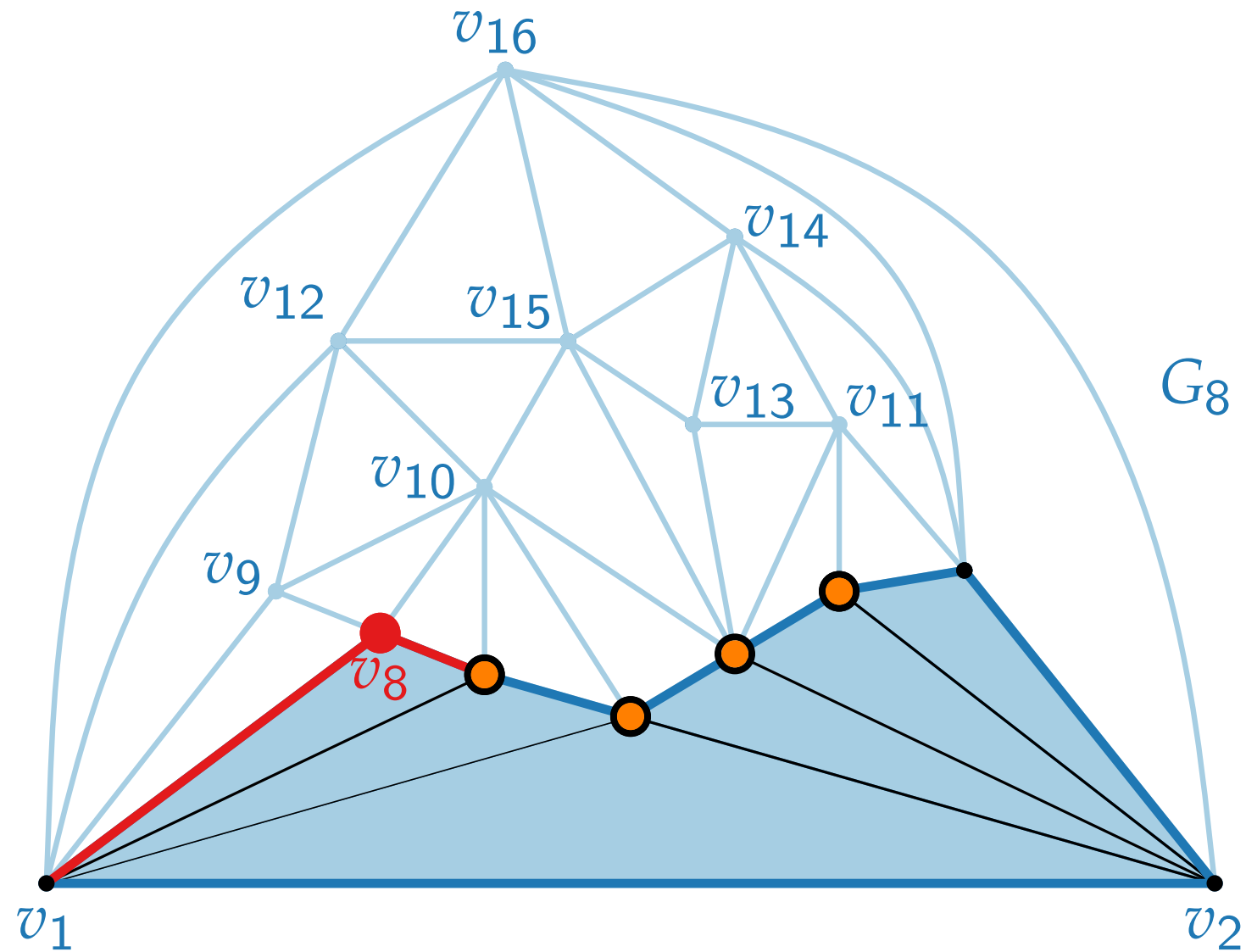
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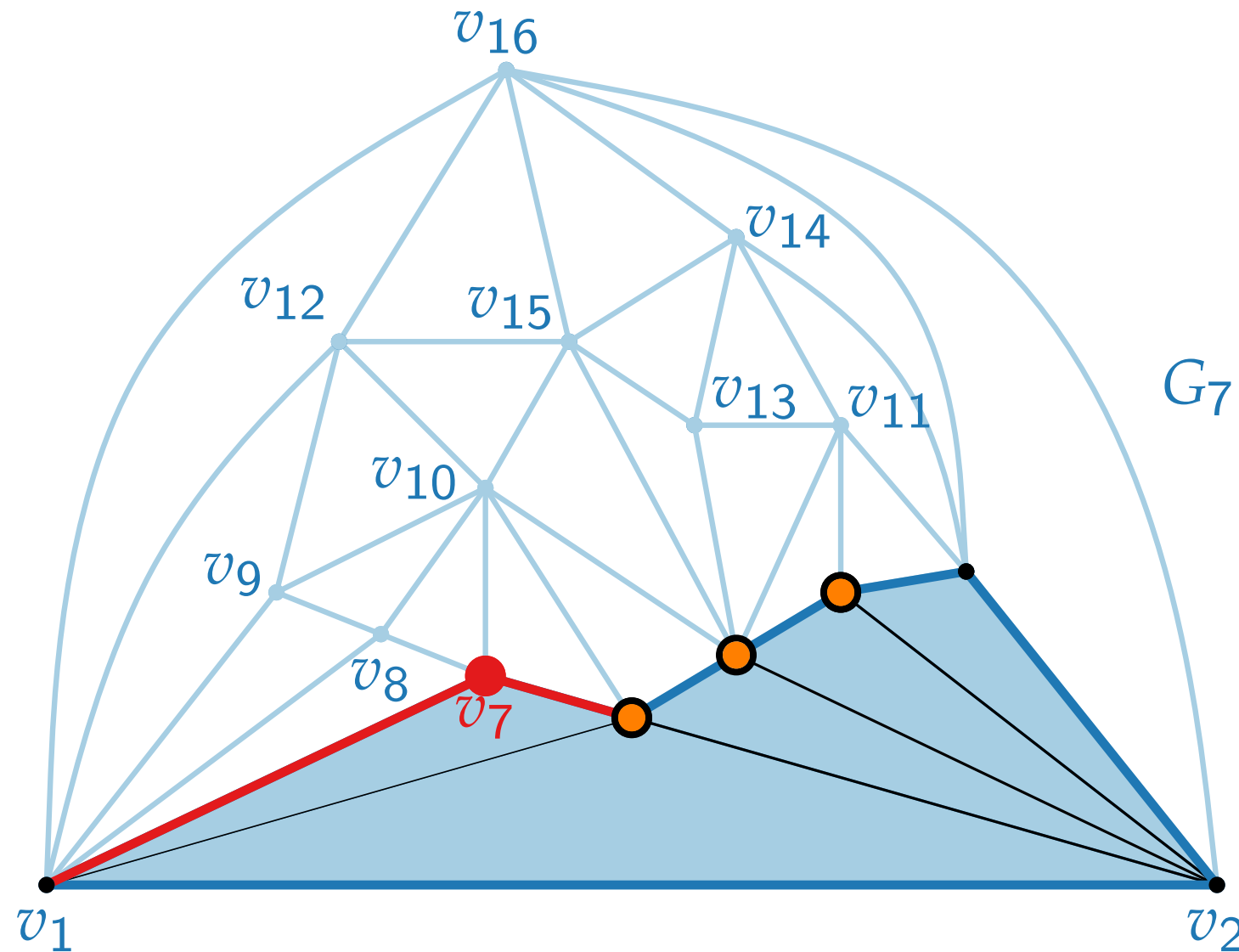
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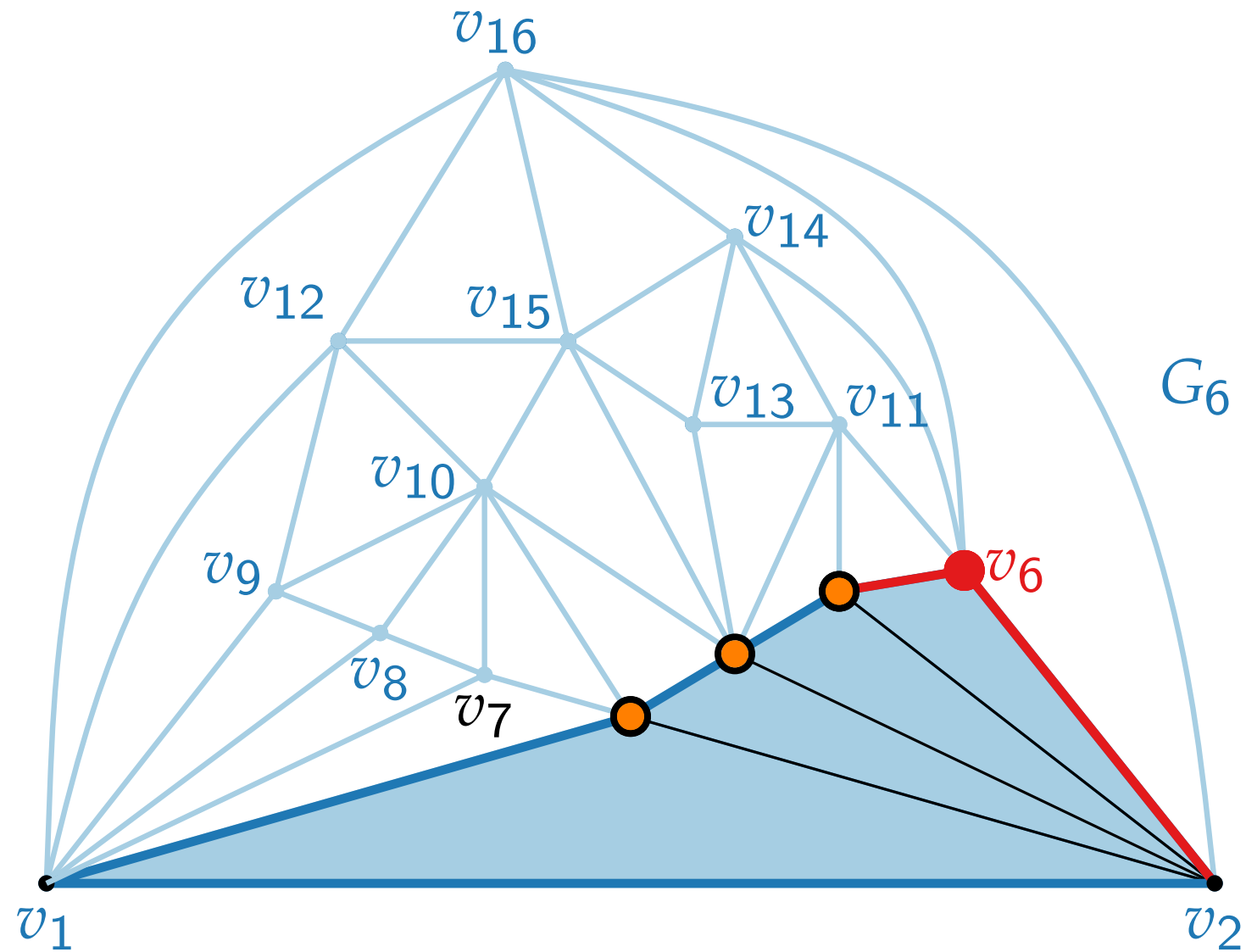
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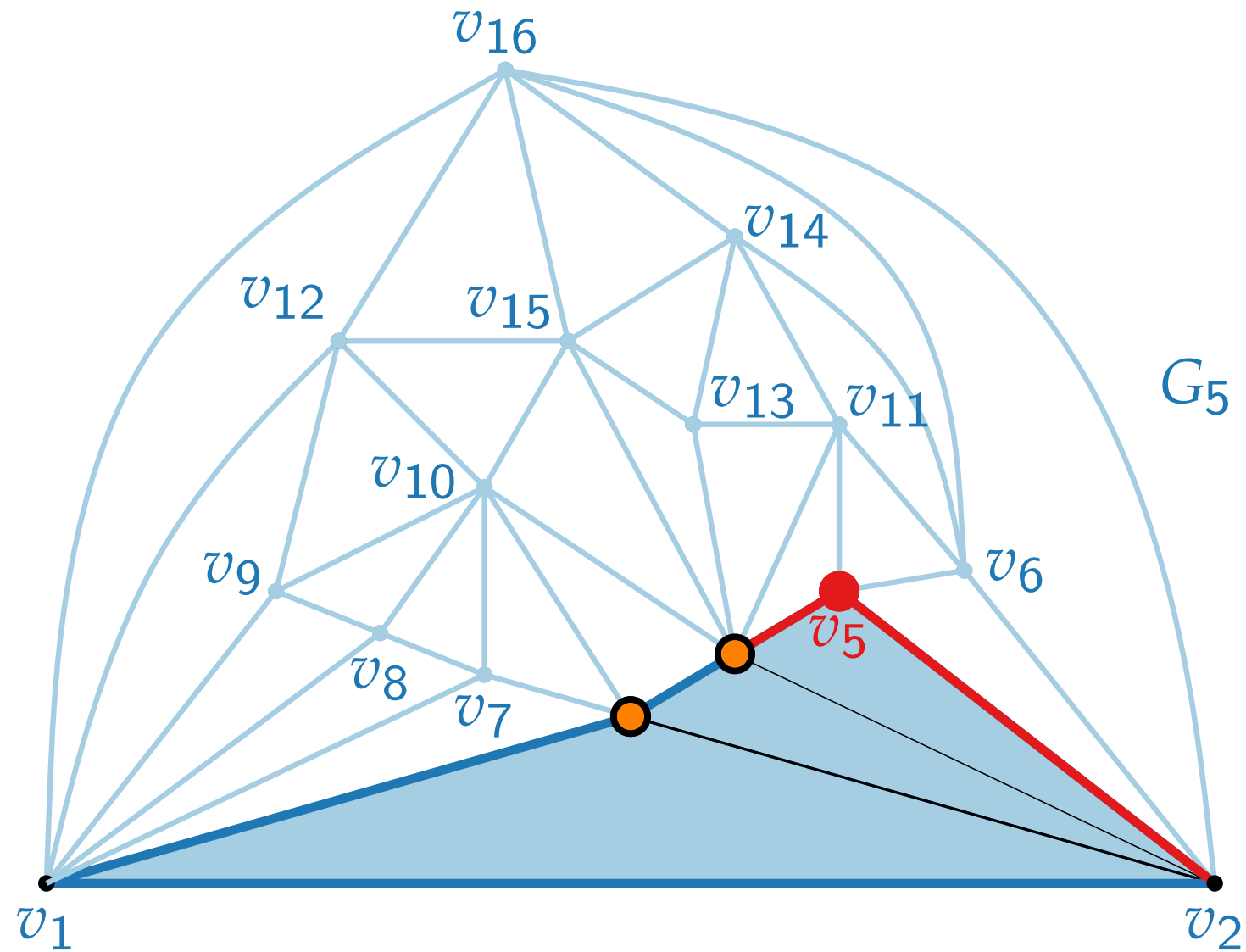
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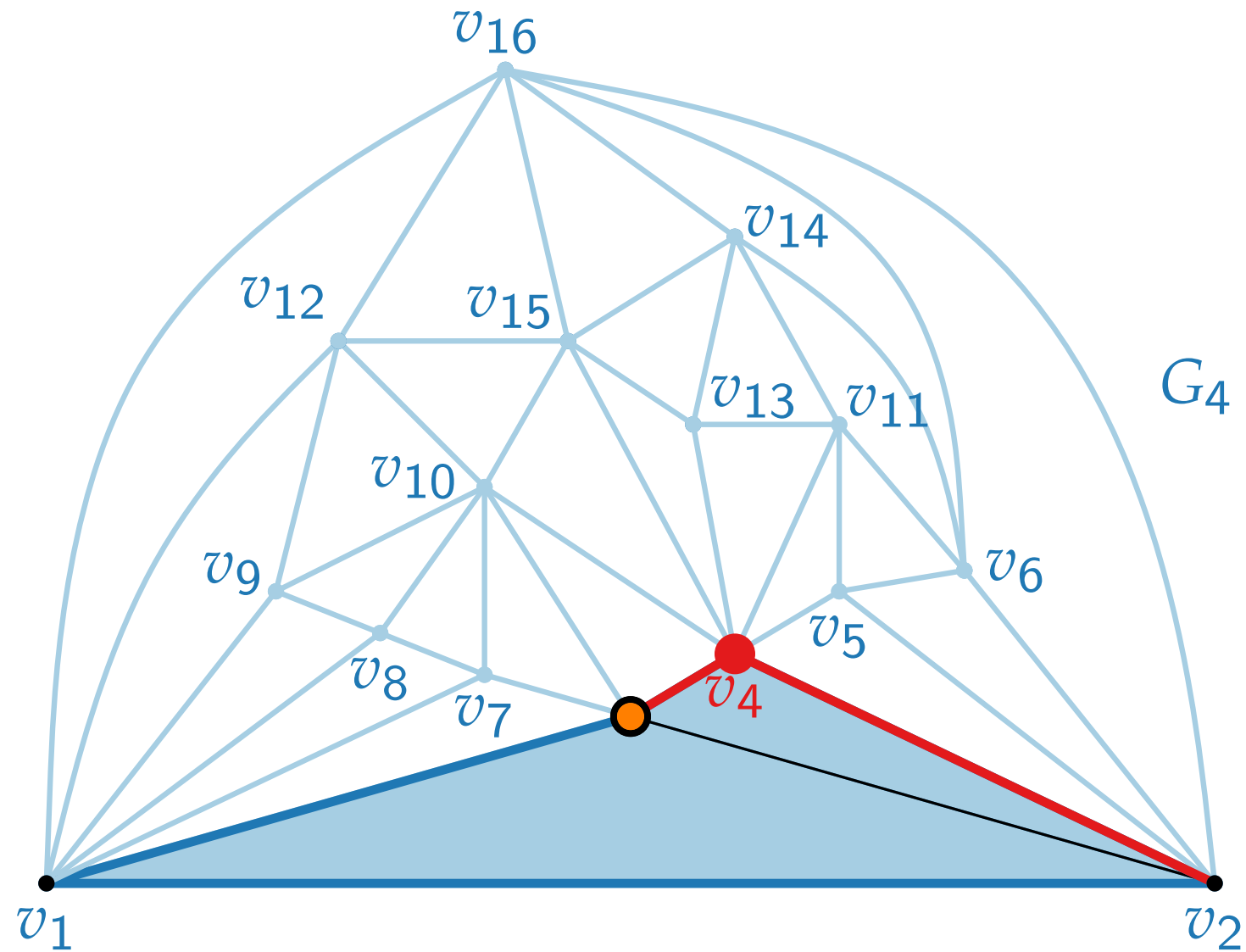
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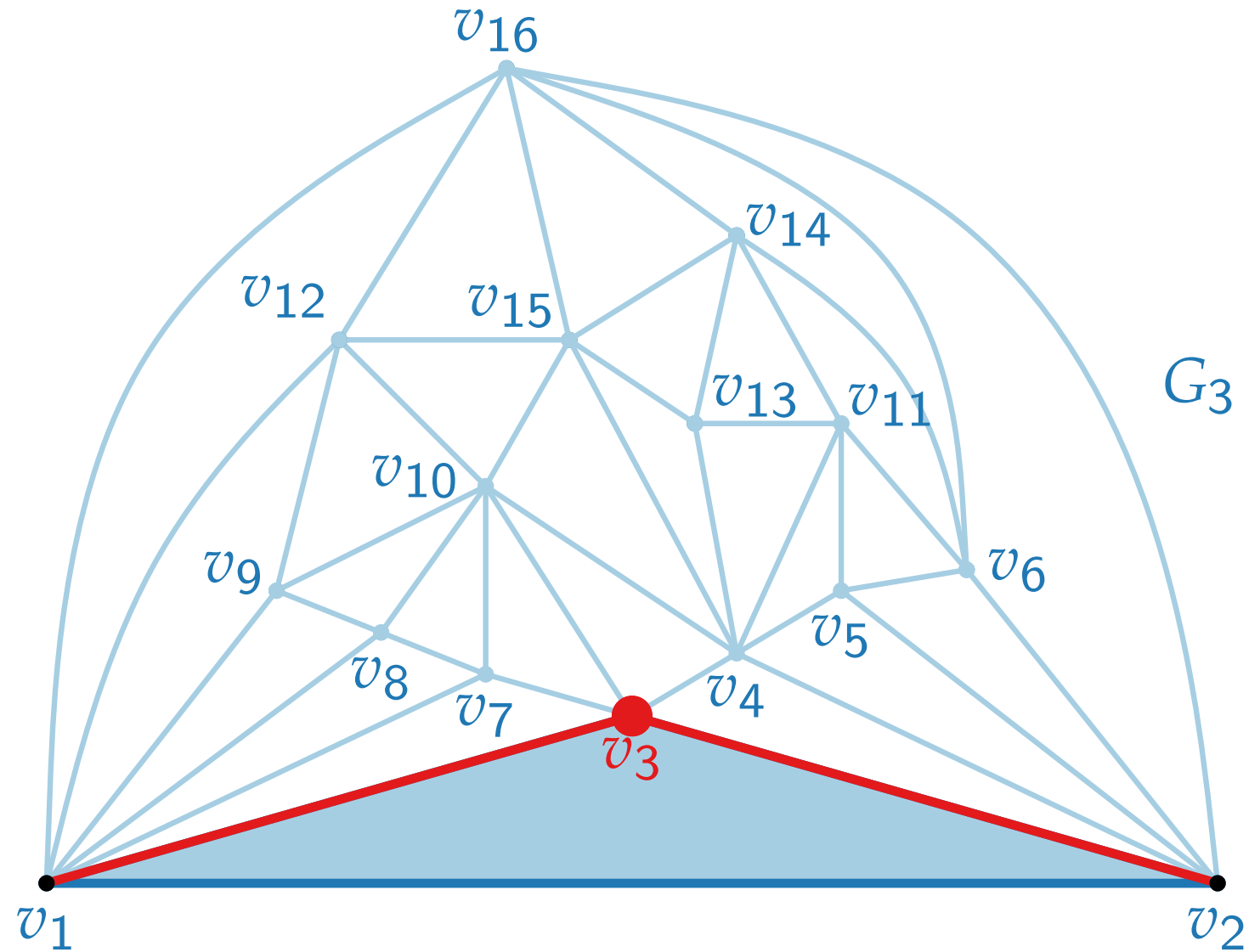
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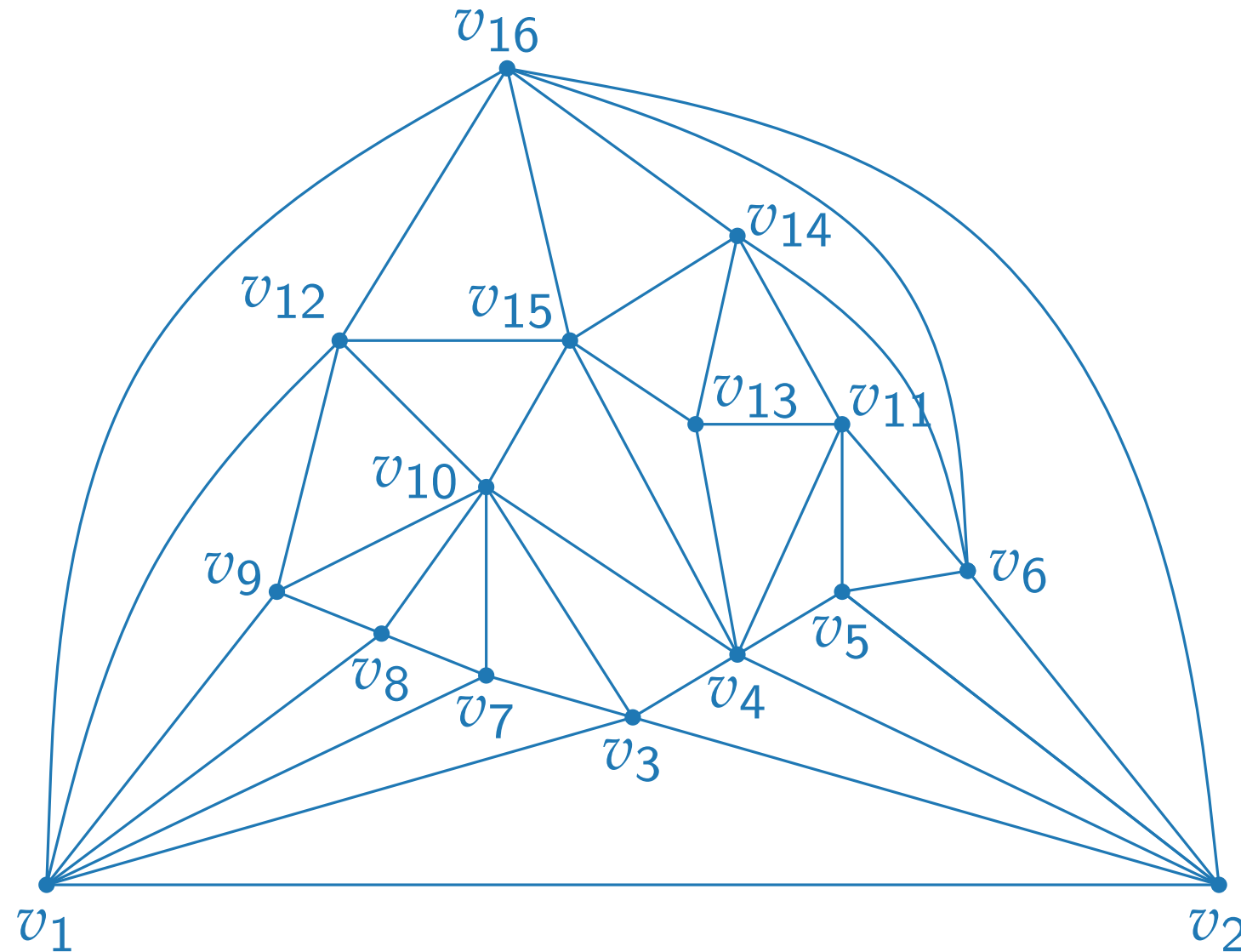
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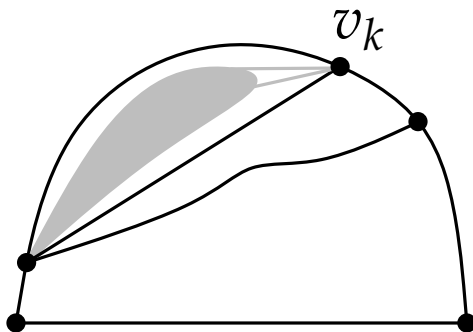
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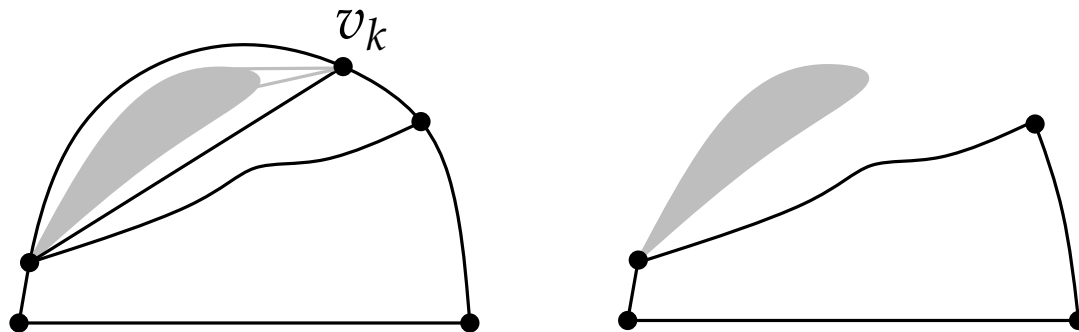
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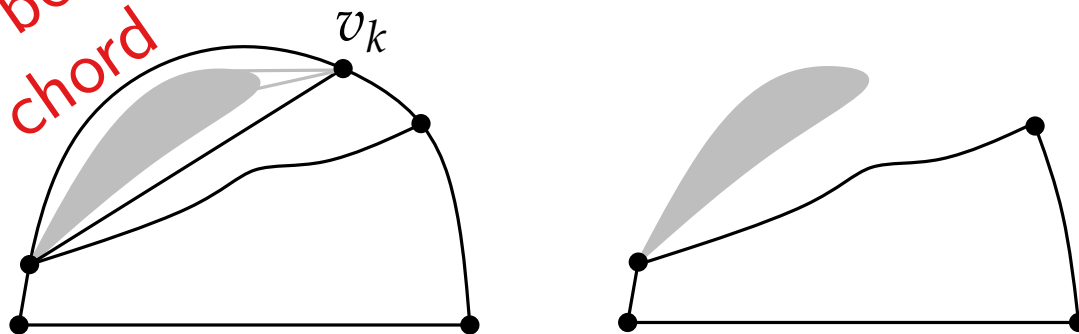
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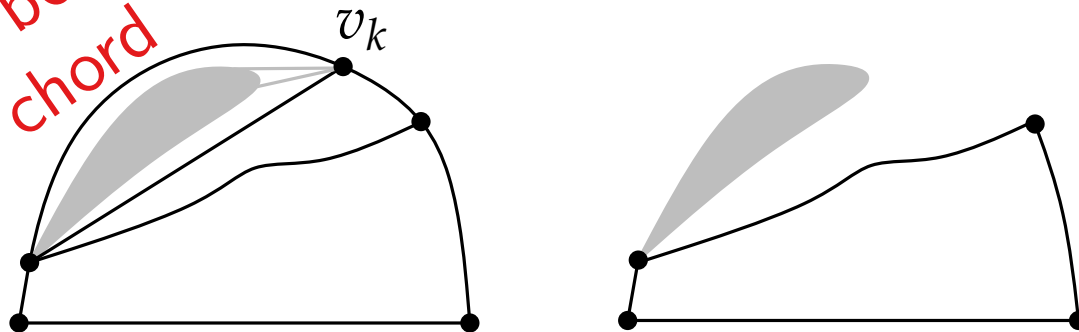
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Have to show:

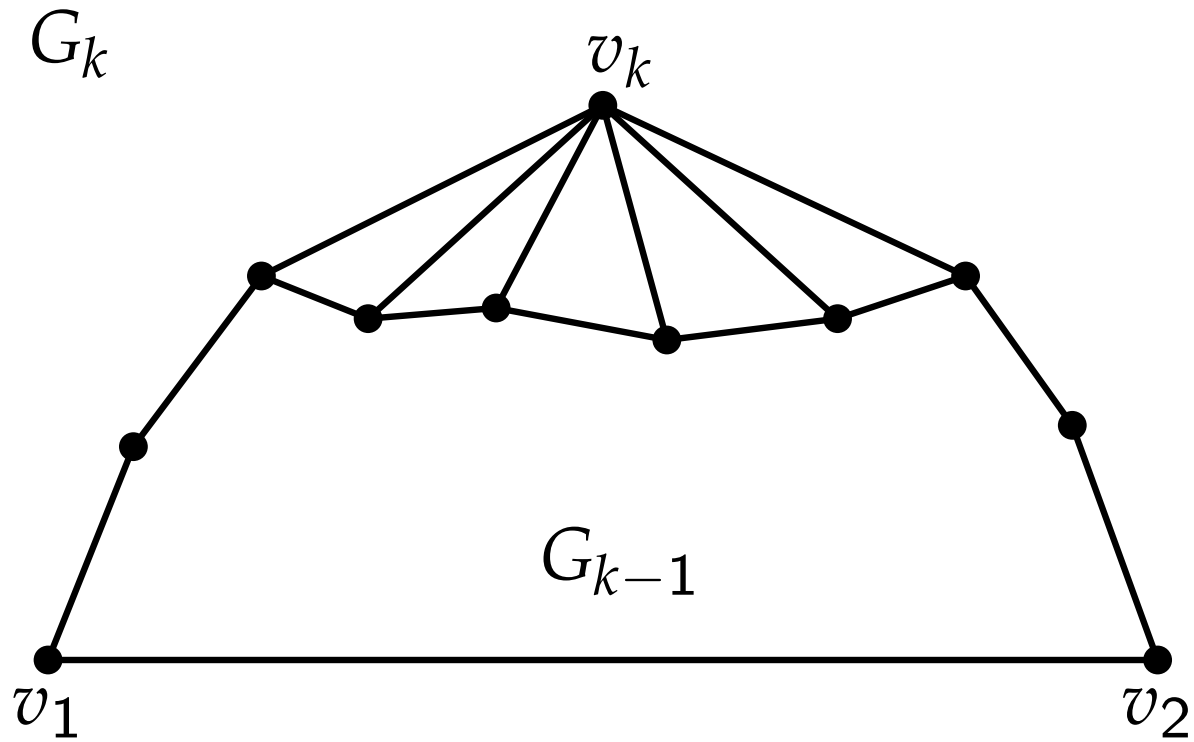
1. v_k not adjacent to chord is sufficient
2. Such v_k exists

Canonical order – existence

Claim 1. If v_k is not adjacent to a chord then removal of v_k leaves the graph biconnected.

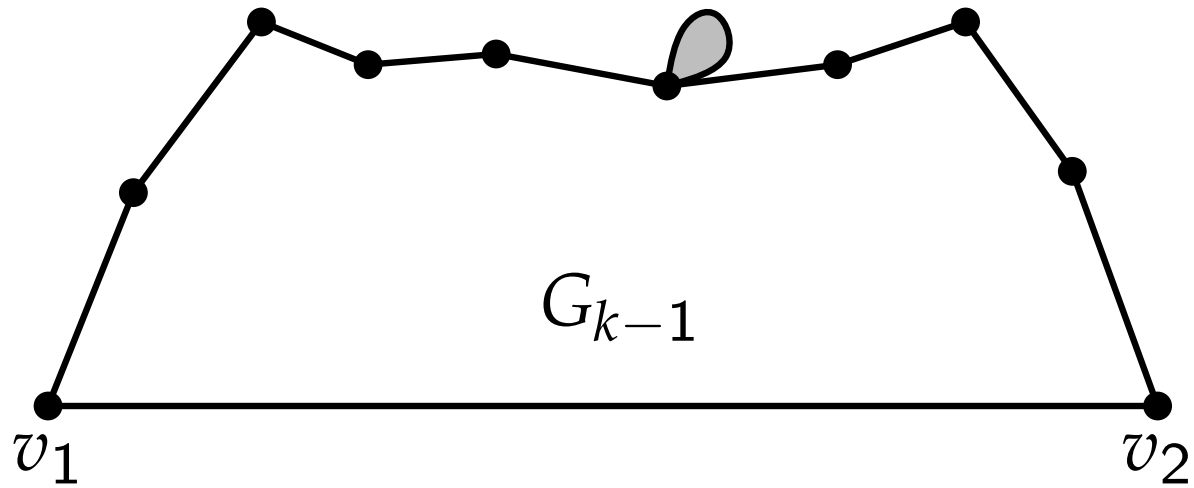
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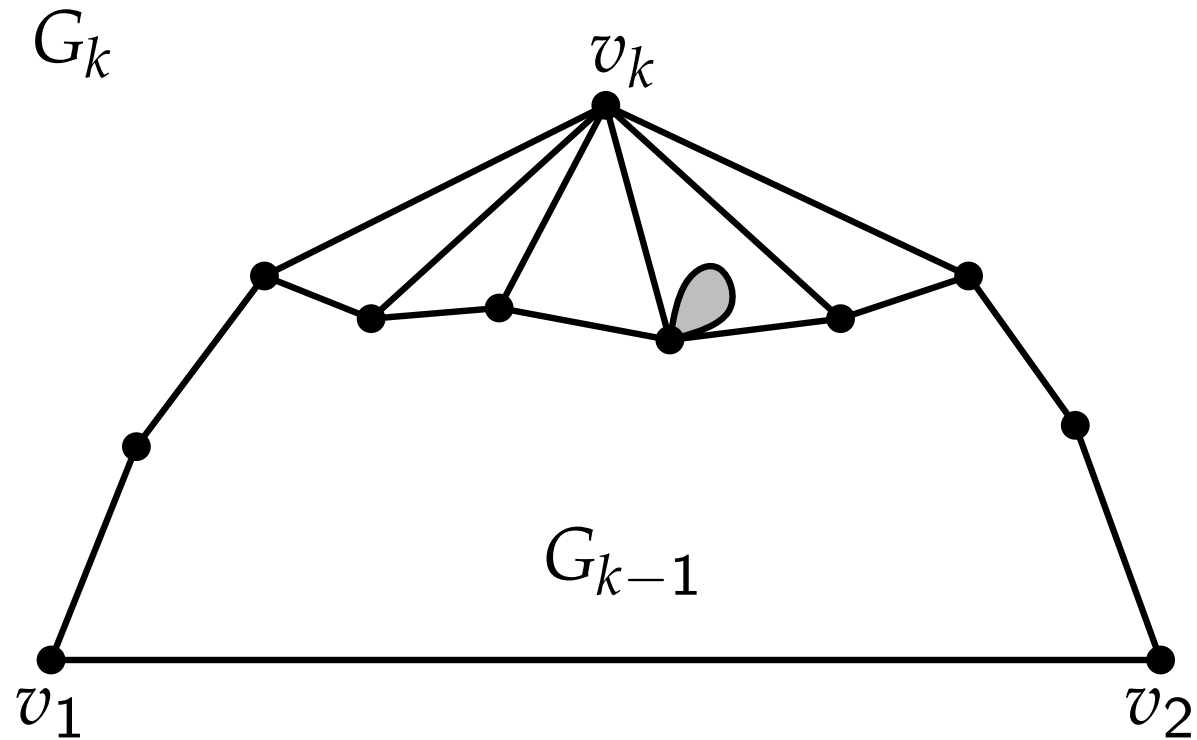
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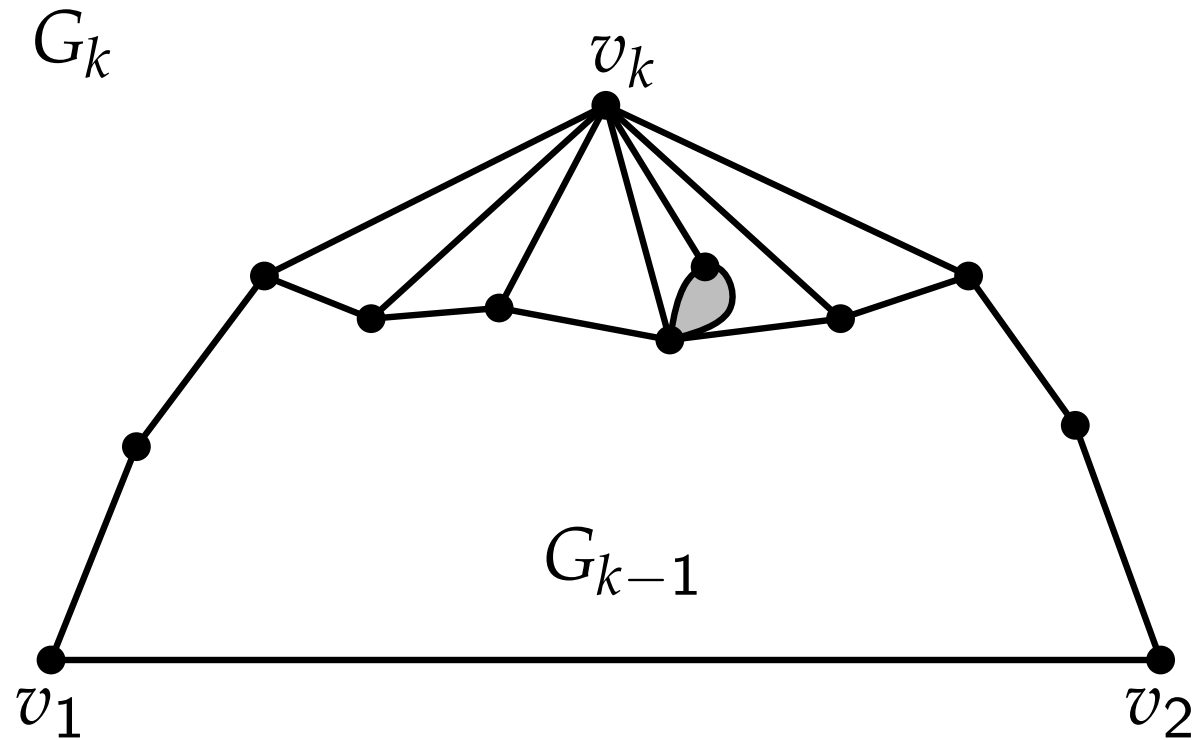
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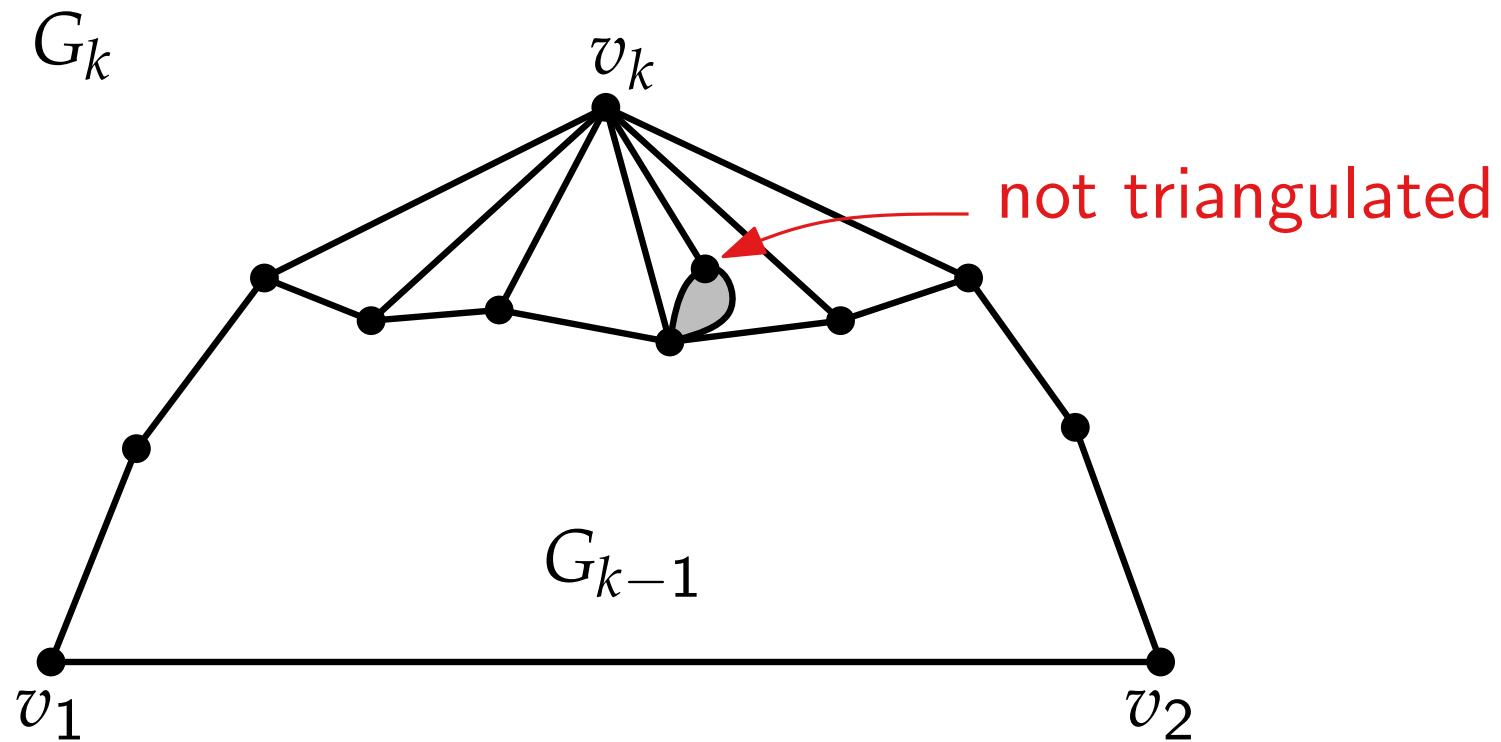
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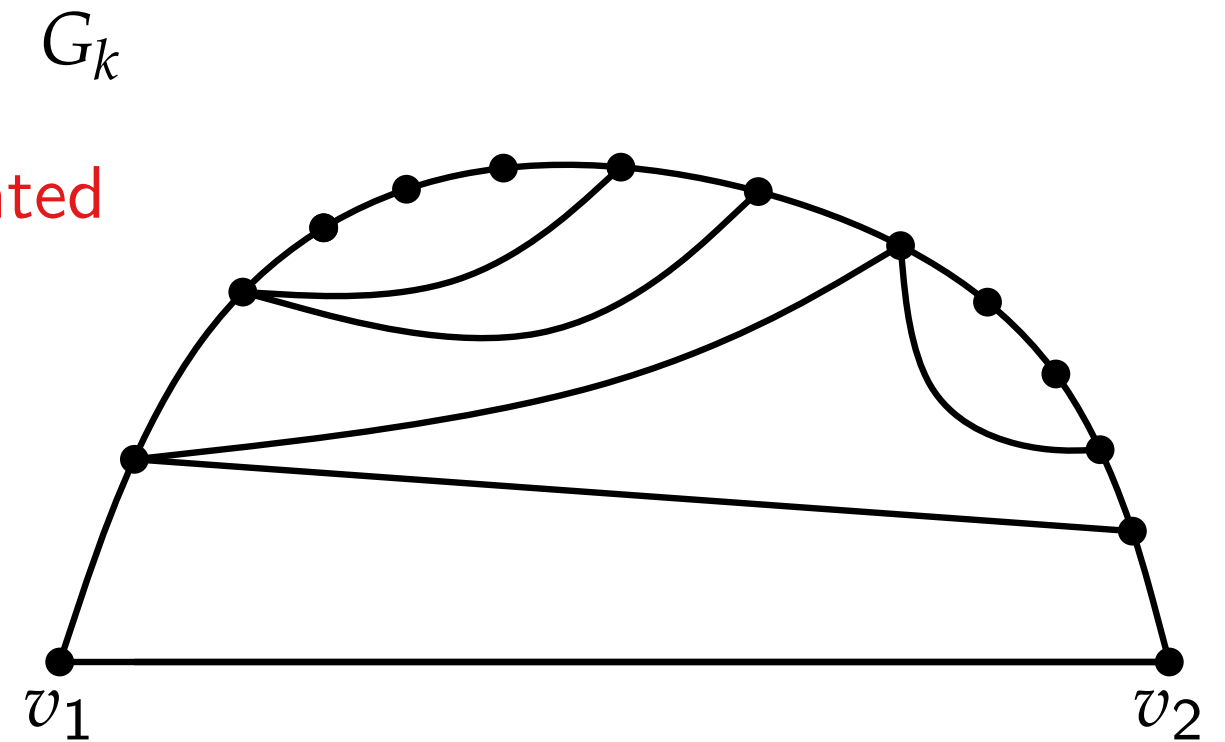
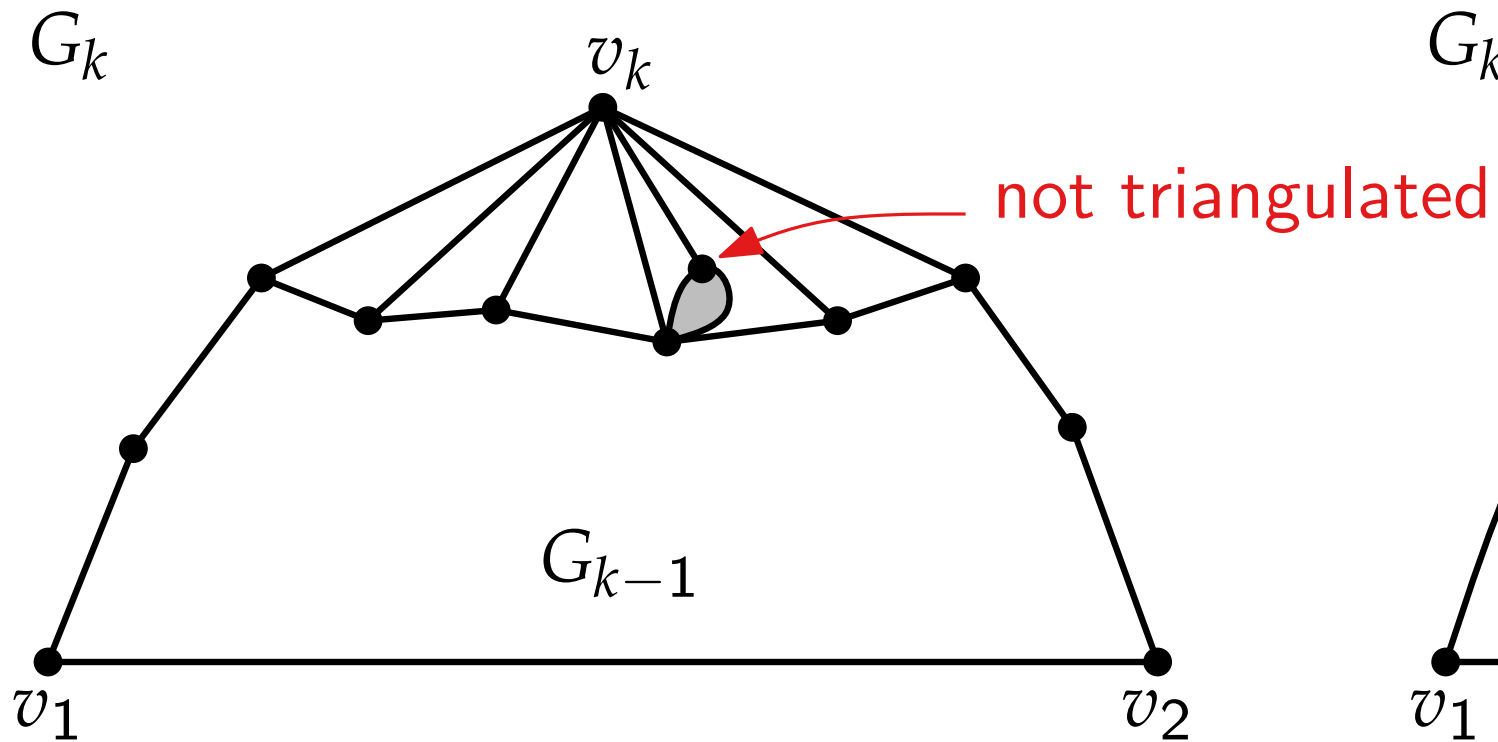


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Claim 2.

There exists a vertex in G_k that is not adjacent to a chord as choice for v_k .

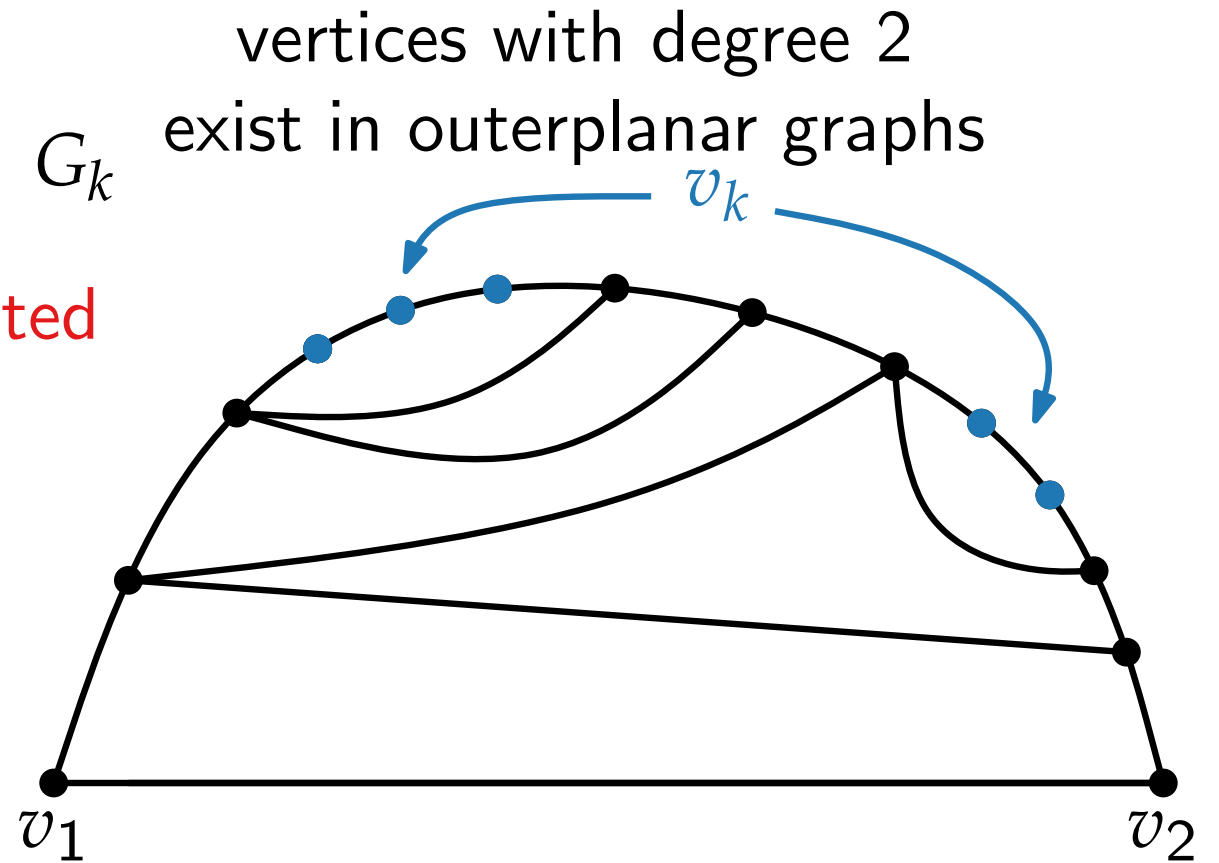
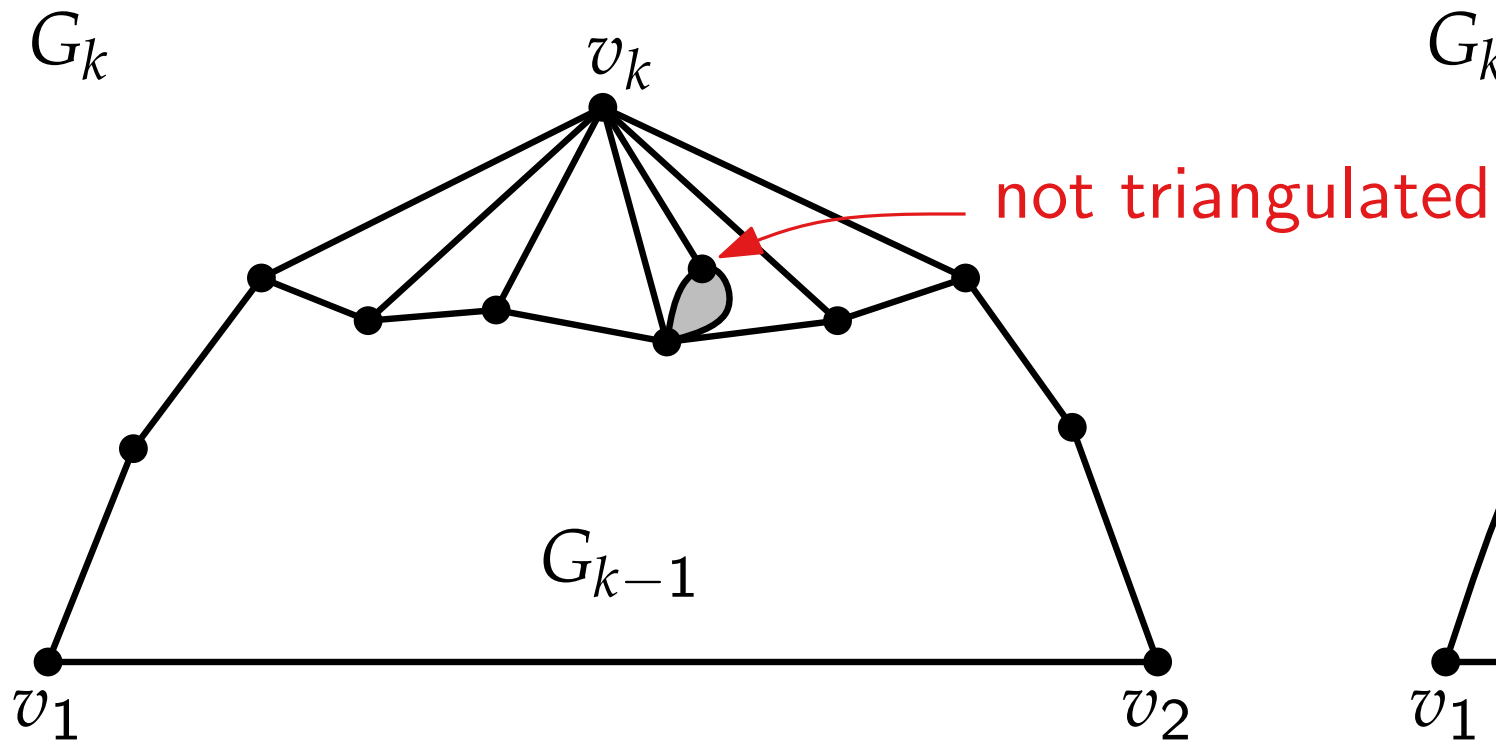


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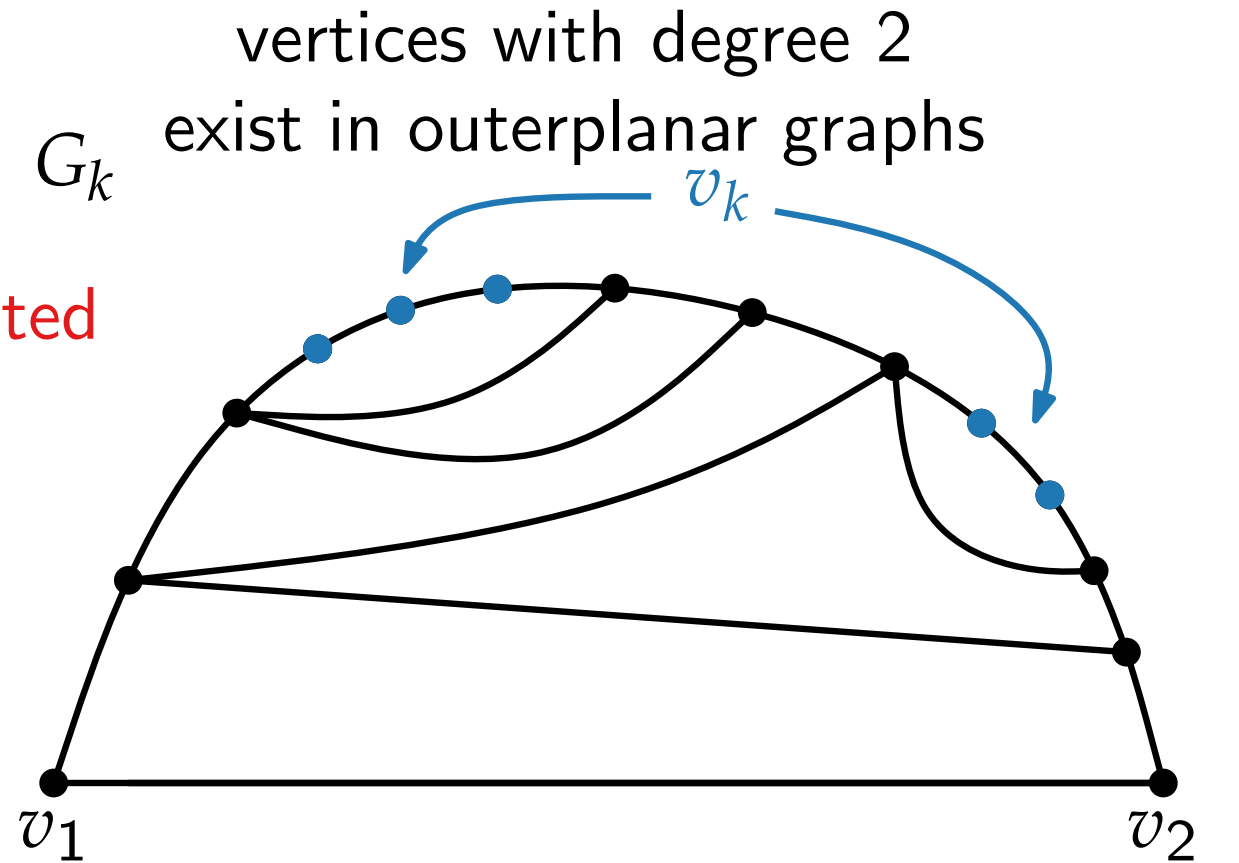
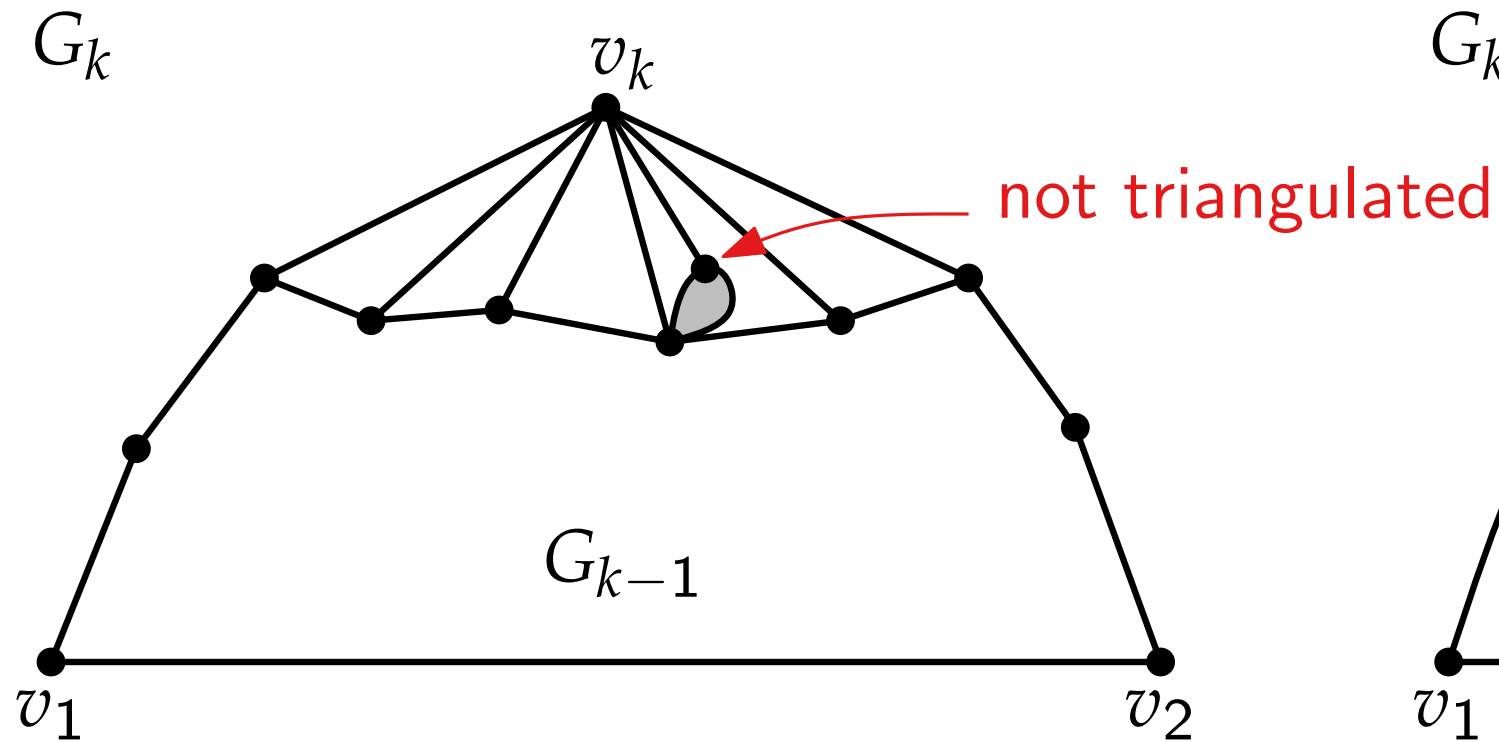


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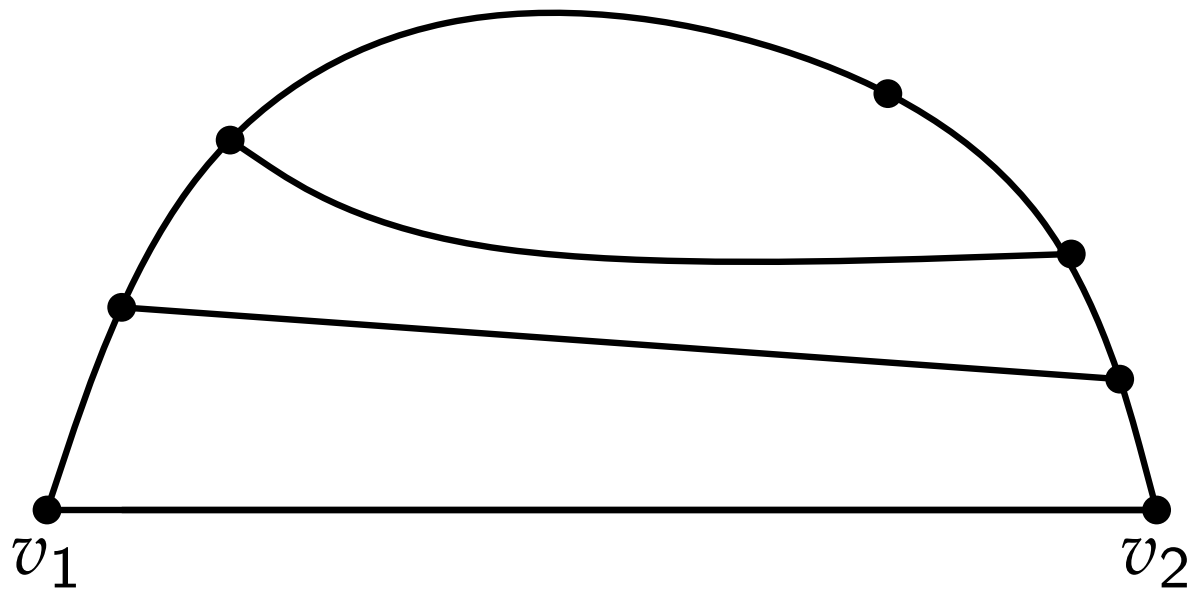


This completes proof of Lemma. \square

Canonical order – implementation

■ chords of G_k belong to faces:

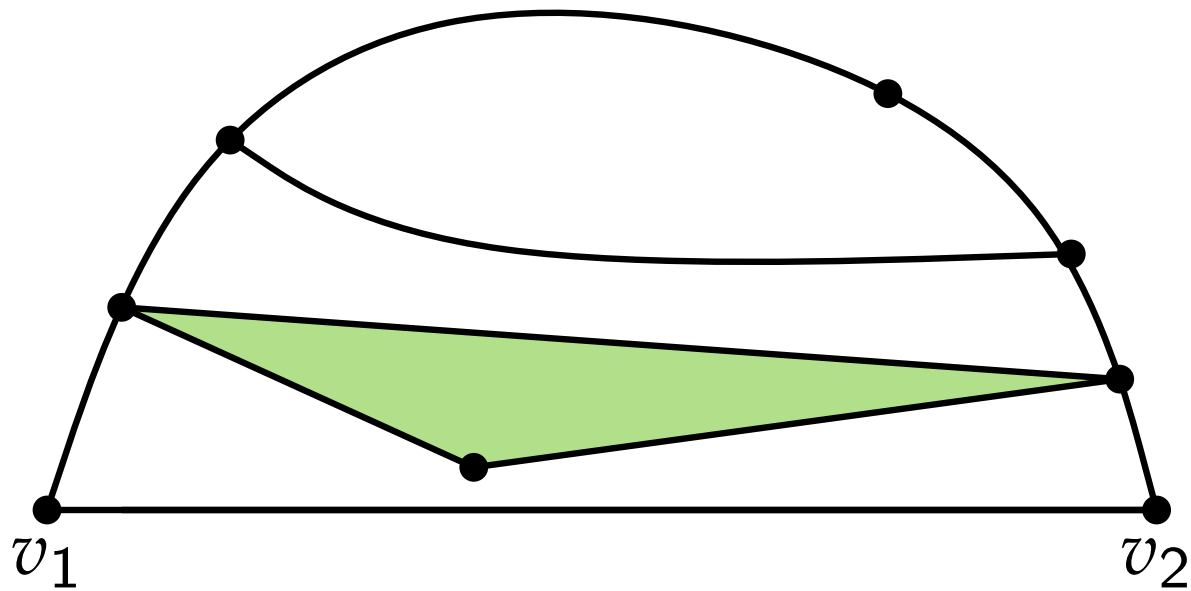
G_k



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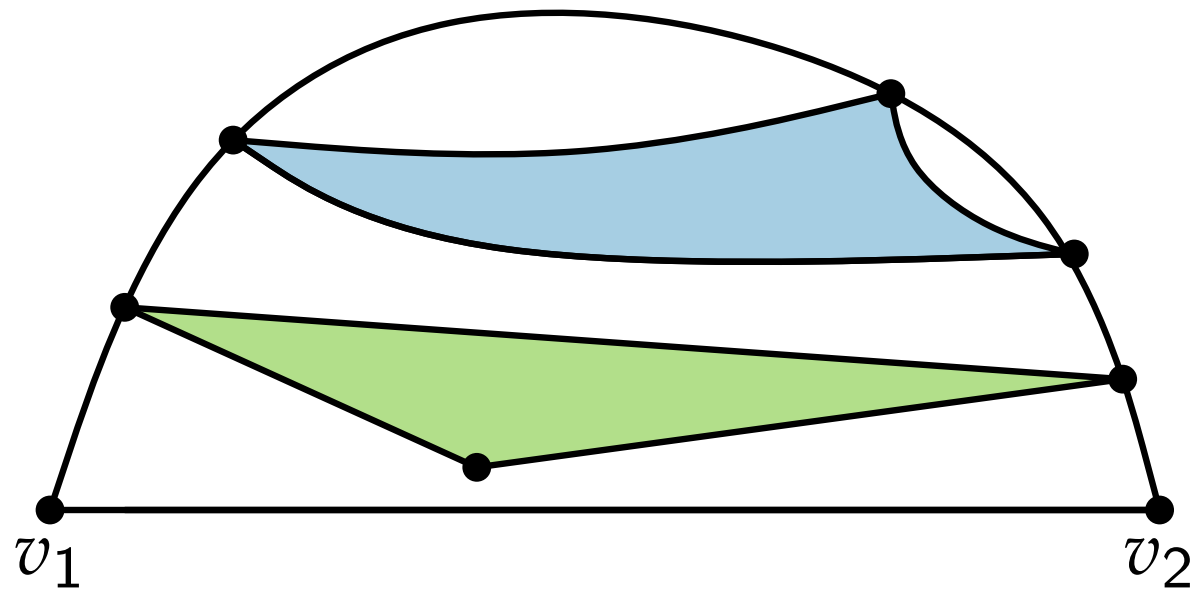


- f has two vertices on the outerface and one internal

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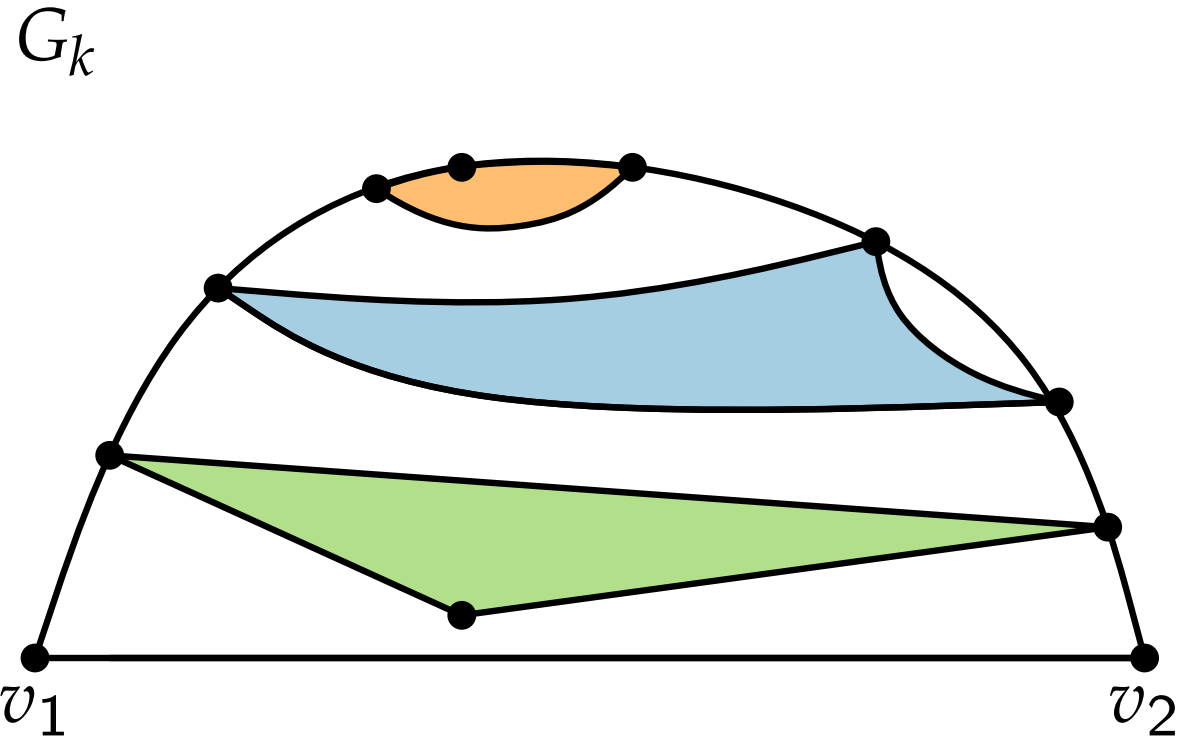
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- f has two vertices on the outerface and one internal
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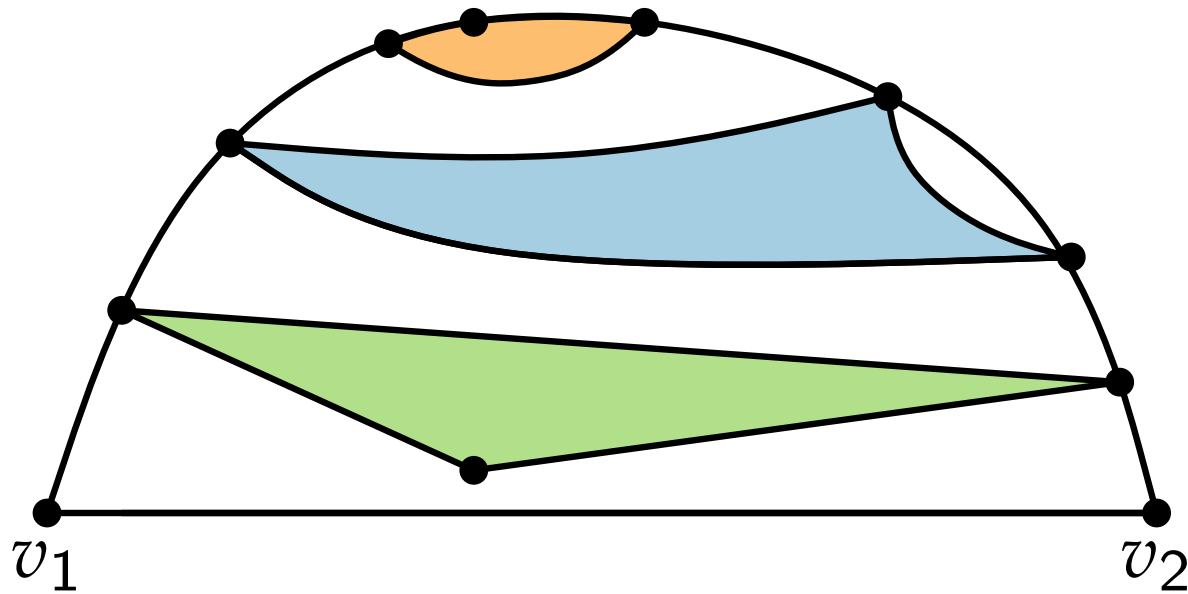


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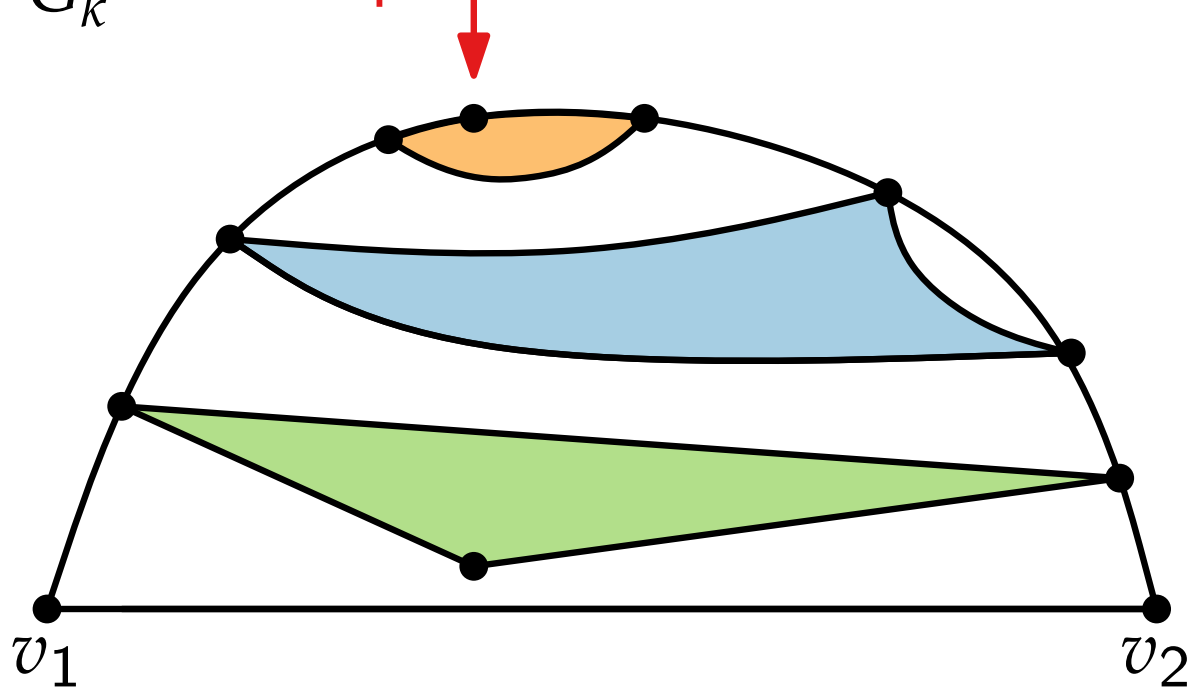
- chords are associated with separating faces
- v_k belongs to no separating faces *

- f has two vertices on the outerface and one internal
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Canonical order – implementation

■ chords of G_k belong to faces:

G_k * except for these vertices!



■ chords are associated with separating faces

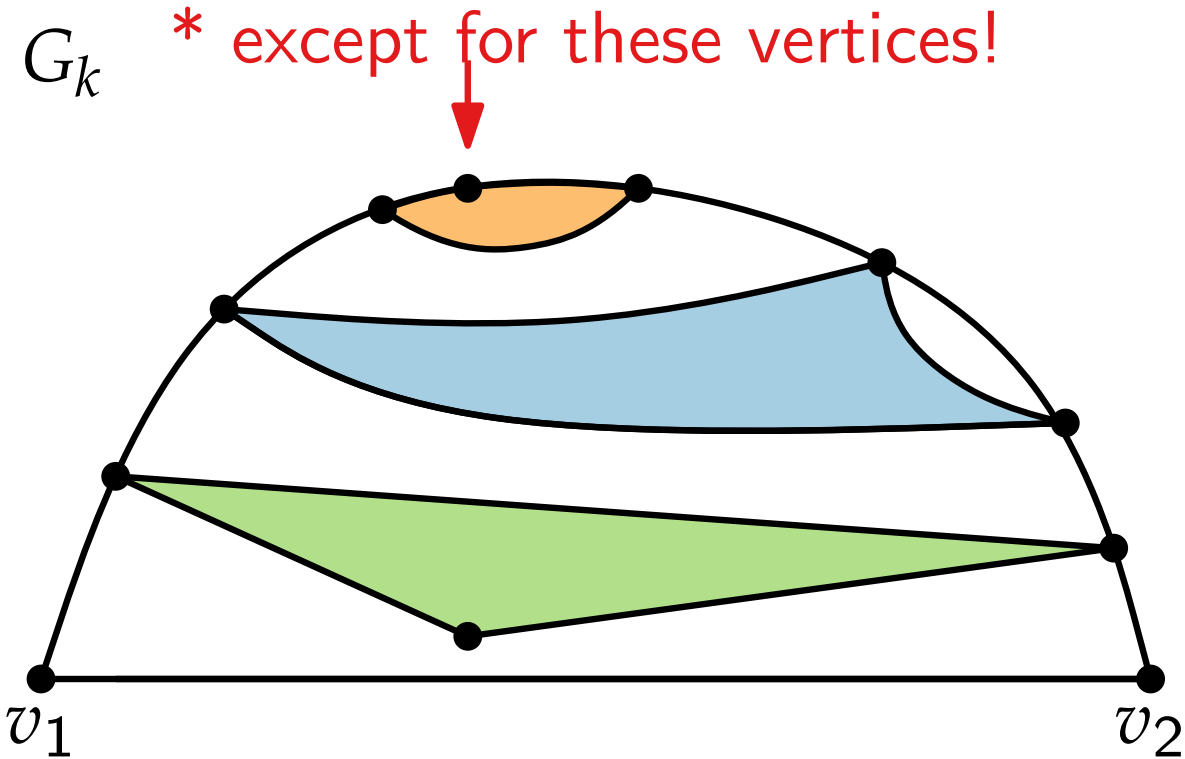
■ v_k belongs to no separating faces *

■ f has two vertices on the outface and one internal

■ f has three vertices on the outface and at least two chords

■ f has three consecutive vertices on the outface

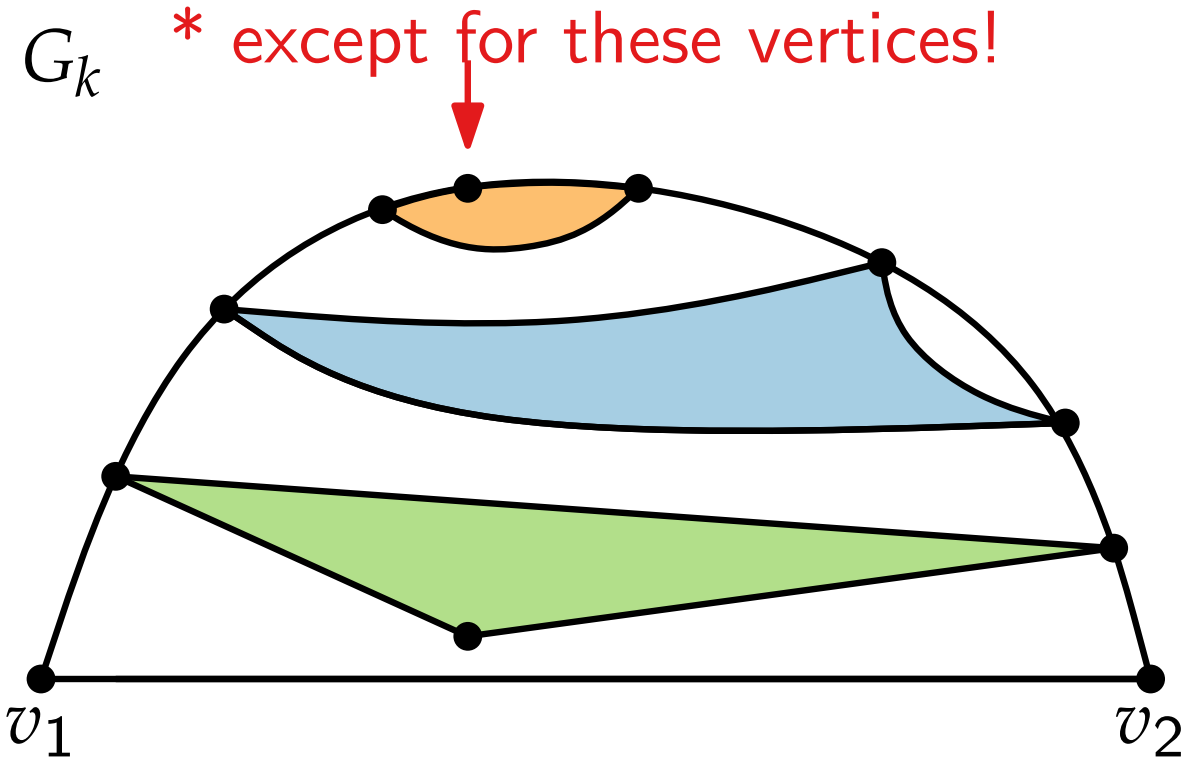
Canonical order – implementation



- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e

- chords are associated with separating faces
- v_k belongs to no separating faces *

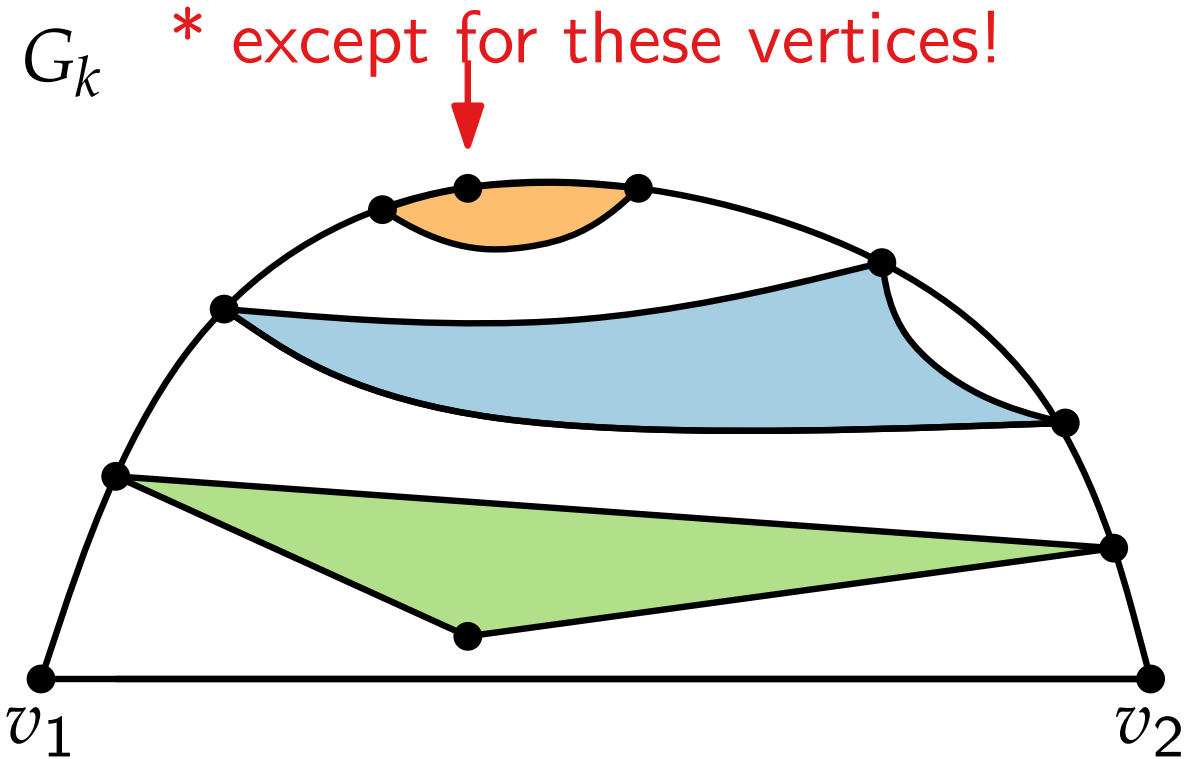
Canonical order – implementation



- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $outV(f)$ = # vertices of f on f_{out}
- $outE(f)$ = # edges of f on f_{out}
- $sepF(v)$ = # separation faces that contain v

- chords are associated with separating faces
- v_k belongs to no separating faces *

Canonical order – implementation



- chords are associated with separating faces
- v_k belongs to no separating faces *

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $outV(f)$ = # vertices of f on f_{out}
- $outE(f)$ = # edges of f on f_{out}
- $sepF(v)$ = # separation faces that contain v

$f \in F(v)$ is separating iff

- $outV(f)=3$ or
- $outV(f)=2$ and $outE(f)=0$

Canonical order – implementation

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $outV(f)$ = # vertices of f on f_{out}
- $outE(f)$ = # edges of f on f_{out}
- $sepF(v)$ = # separation faces that contain v

Canonical order – implementation

Algorithm CanonicalOrder- Initialization

```
forall  $v \in V$  do  
   $\lfloor$  sepF( $v$ )  $\leftarrow 0$ ;  
forall  $f \in F$  do  
   $\lfloor$  outV( $f$ ), outE( $f$ )  $\leftarrow 0$ ;
```

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- outV(f) = # vertices of f on f_{out}
- outE(f) = # edges of f on f_{out}
- sepF(v) = # separation faces that contain v

Canonical order – implementation

Algorithm CanonicalOrder- Initialization

```

forall  $v \in V$  do
  └ sepF( $v$ )  $\leftarrow 0$ ;
forall  $f \in F$  do
  └ outV( $f$ ), outE( $f$ )  $\leftarrow 0$ ;
forall  $v \in f_{out}$  do
  ┌ forall  $f \in F(v): f \neq f_{out}$  do
  └   └ outV( $f$ )++;
forall  $e \in f_{out}$  do
  ┌ forall  $f \in F(e): f \neq f_{out}$  do
  └   └ outE( $f$ )++;
  
```

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- outV(f) = # vertices of f on f_{out}
- outE(f) = # edges of f on f_{out}
- sepF(v) = # separation faces that contain v

Canonical order – implementation

Algorithm CanonicalOrder- Initialization

```

forall  $v \in V$  do
  └ sepF( $v$ )  $\leftarrow$  0;
forall  $f \in F$  do
  └ outV( $f$ ), outE( $f$ )  $\leftarrow$  0;
forall  $v \in f_{out}$  do
  ┌ forall  $f \in F(v): f \neq f_{out}$  do
  │   └ outV( $f$ )++;
forall  $e \in f_{out}$  do
  ┌ forall  $f \in F(e): f \neq f_{out}$  do
  │   └ outE( $f$ )++;

```

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- outV(f) = # vertices of f on f_{out}
- outE(f) = # edges of f on f_{out}
- sepF(v) = # separation faces that contain v

```

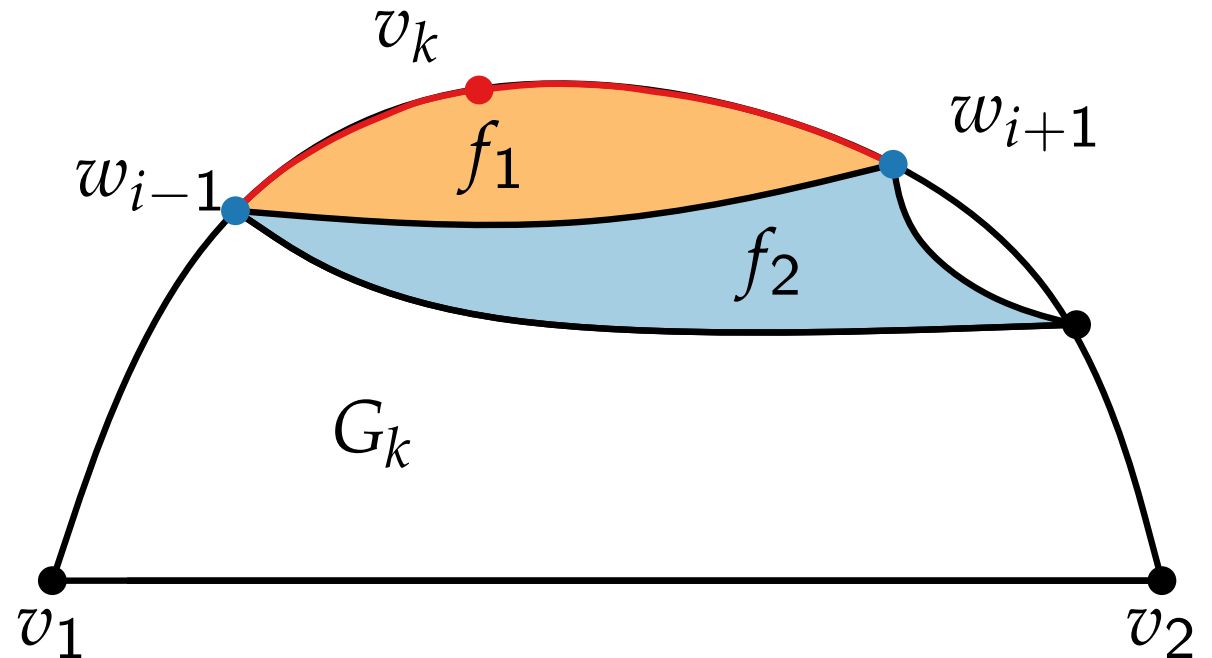
forall  $v \in f_{out}$  do
  ┌ forall  $f \in F(v): f \neq f_{out}$  do
  │   ┌ if outV( $f$ )=3 or outV( $f$ )=2
  │   │   and outE( $f$ )=0 then
  │   │   └ sepF( $v$ )++;

```

Canonical order – implementation

Remove degree 2 vertex v_k

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $outV(f)$ = # vertices of f on f_{out}
- $outE(f)$ = # edges of f on f_{out}
- $sepF(v)$ = # separation faces that contain v

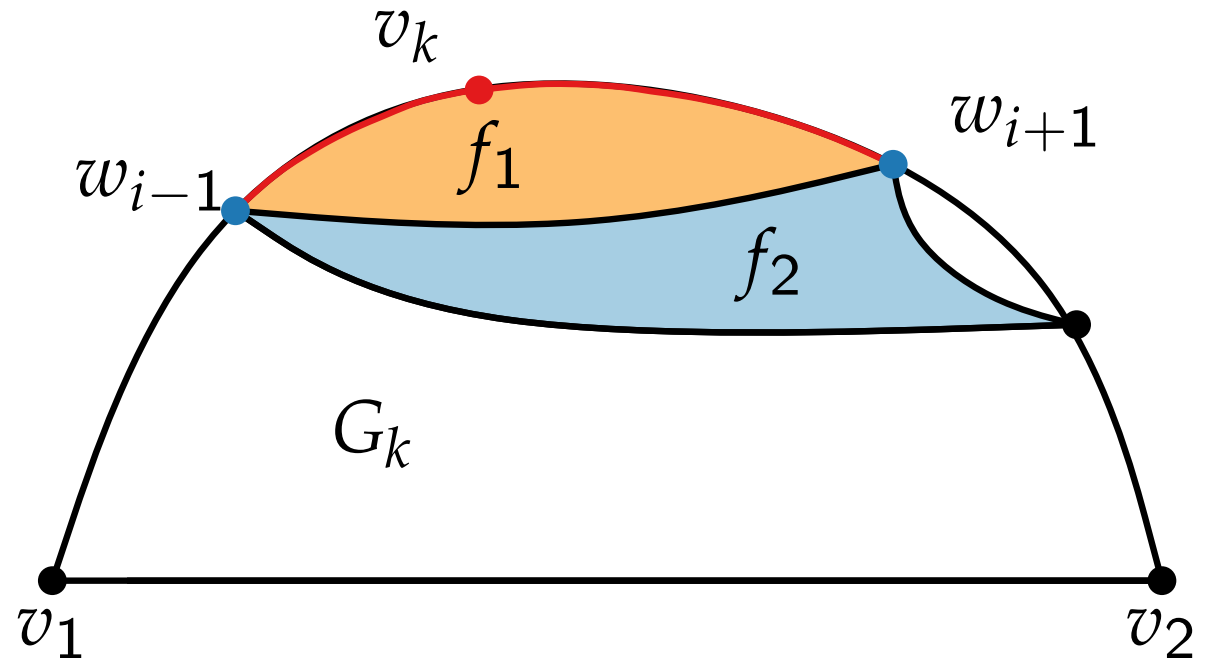


Canonical order – implementation

Remove degree 2 vertex v_k

- v_k and f_1 are removed
- $\text{outE}(f_2)$ increases by one
- $\text{sepF}(w_{i-1})$ decreases by one
- $\text{sepF}(w_{i+1})$ decreases by one

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v

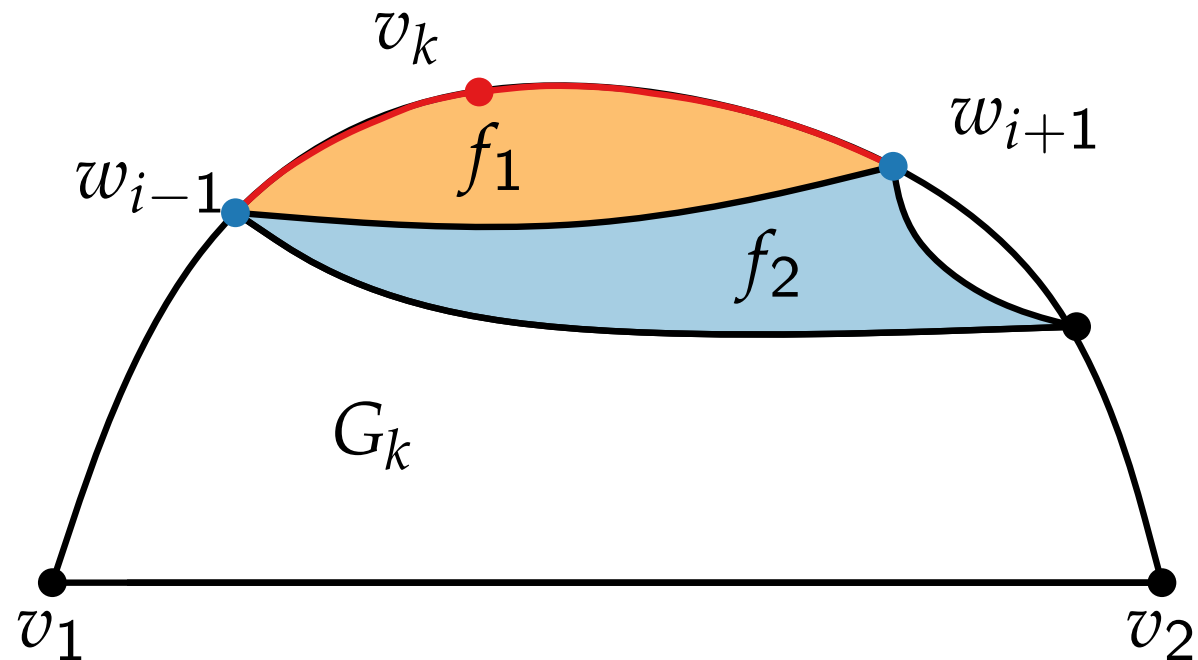


Canonical order – implementation

Remove degree 2 vertex v_k

- v_k and f_1 are removed
- $\text{outE}(f_2)$ increases by one
- $\text{sepF}(w_{i-1})$ decreases by one
- $\text{sepF}(w_{i+1})$ decreases by one
- if f_2 has $\text{outV}(f_2)=2$,
 f_2 is not a separating face
 - $\text{sepF}(w_{i-1})$ decreases by one
 - $\text{sepF}(w_{i+1})$ decreases by one

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v

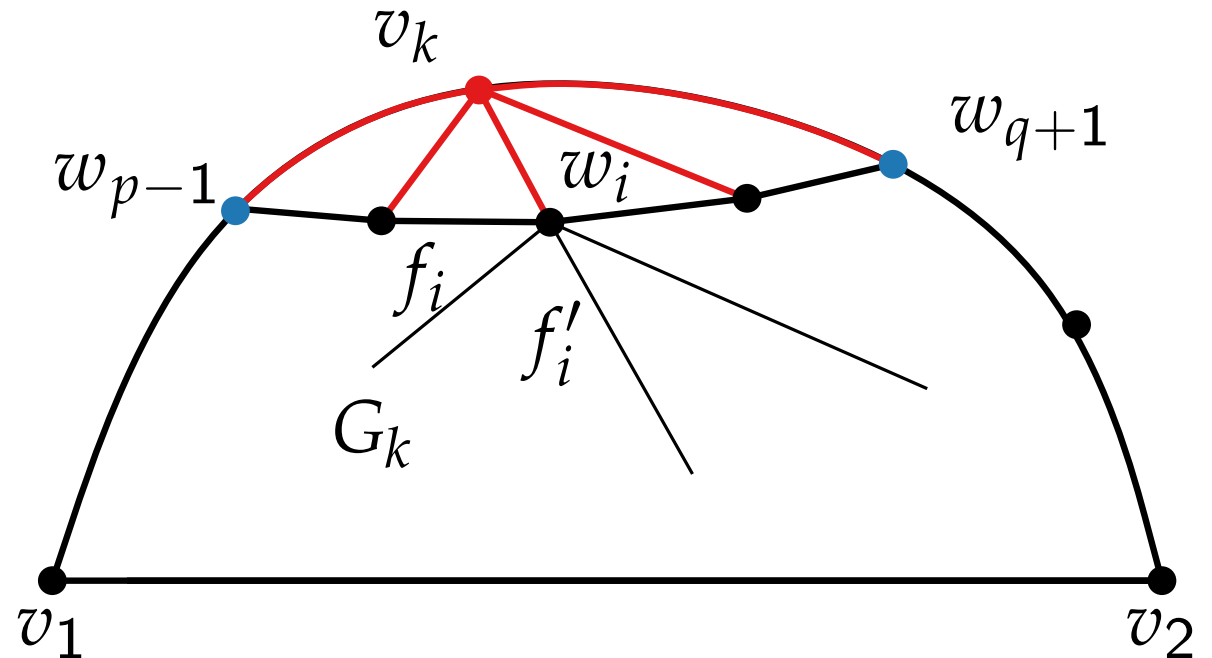


Canonical order – implementation

Remove v_k with $\text{sepF}(v_k) = 0$

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f) = \#$ vertices of f on f_{out}
- $\text{outE}(f) = \#$ edges of f on f_{out}
- $\text{sepF}(v) = \#$ separation faces that contain v

- face f_i contains edge (w_{i-1}, w_i) of the outerface of G_{k-1}
- face f'_i contains edges of w_i that are in the interior of G_{k-1}



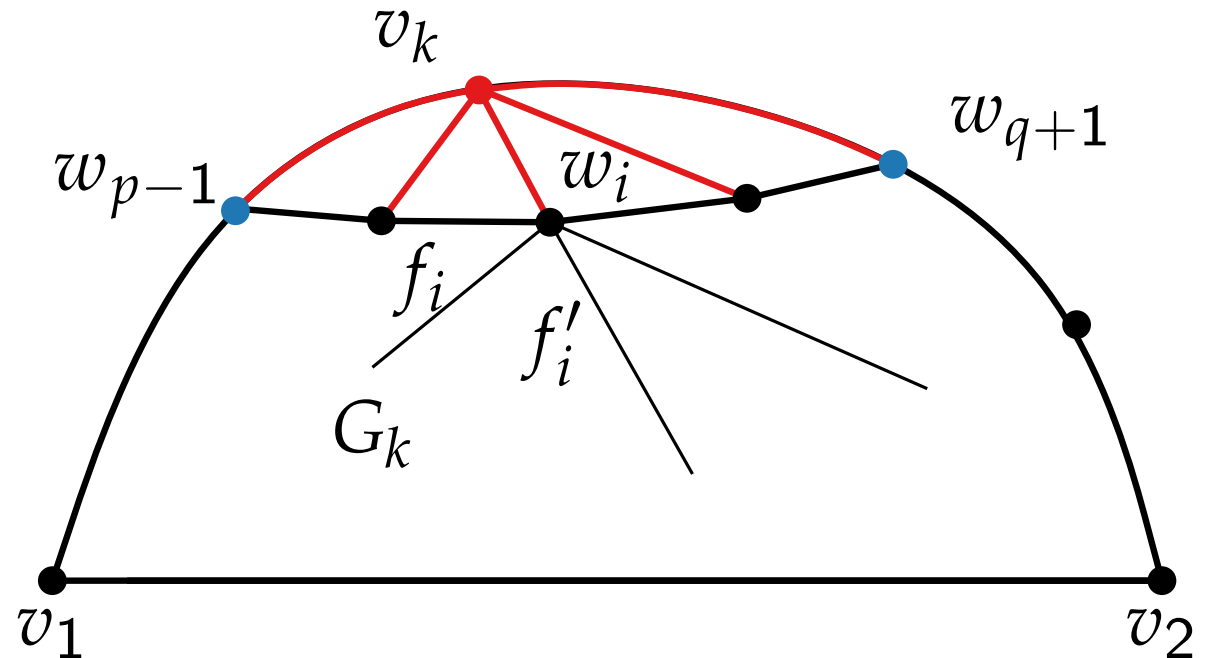
Canonical order – implementation

Remove v_k with $\text{sepF}(v_k) = 0$

- v_k and faces that contain v_k are removed
- $\text{outV}(f_i)$ increases by two, $p + 1 \leq i \leq q$
- $\text{outV}(f_p)$, $\text{outV}(f_{q+1})$ increases by one
- $\text{outV}(f'_i)$ increases by one, $p \leq i \leq q$
- $\text{outE}(f_i)$ increases by one, $p \leq i \leq q + 1$

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v

- face f_i contains edge (w_{i-1}, w_i) of the outerface of G_{k-1}
- face f'_i contains edges of w_i that are in the interior of G_{k-1}



Canonical order – implementation

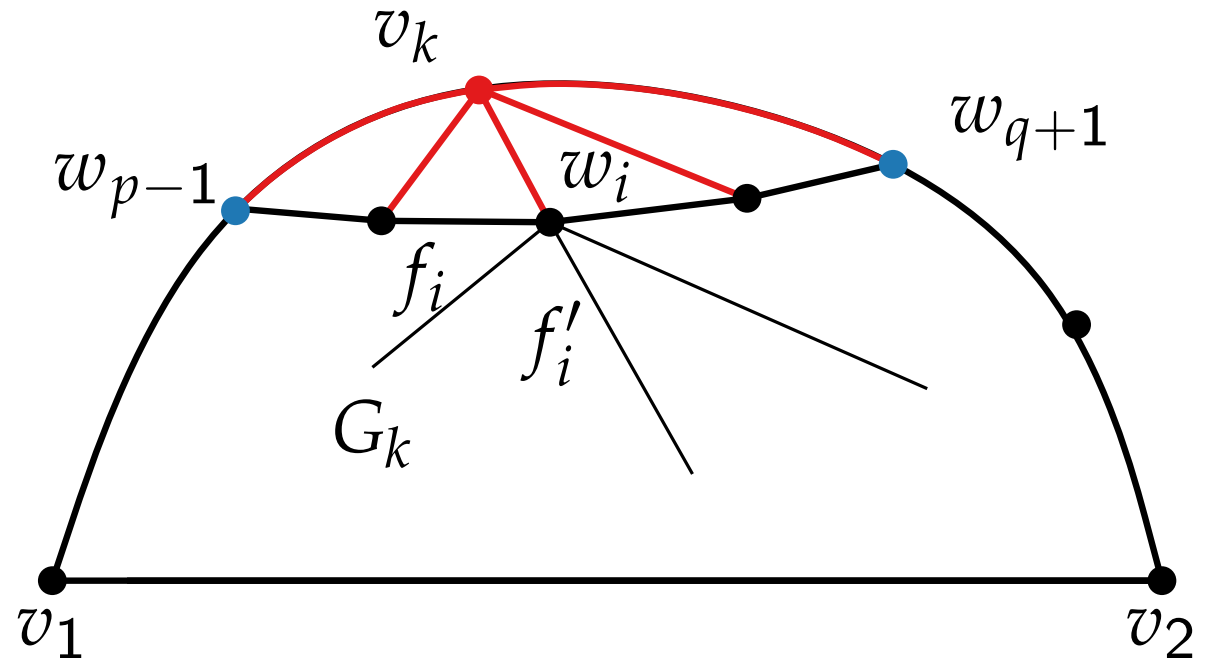
Remove v_k with $\text{sepF}(v_k) = 0$

- v_k and faces that contain v_k are removed
- $\text{outV}(f_i)$ increases by two, $p + 1 \leq i \leq q$
- $\text{outV}(f_p)$, $\text{outV}(f_{q+1})$ increases by one
- $\text{outV}(f'_i)$ increases by one, $p \leq i \leq q$
- $\text{outE}(f_i)$ increases by one, $p \leq i \leq q + 1$

- if f_i or f'_i becomes separating
 - increase $\text{sepF}(u)$ by one for all its vertices u

- face f_i contains edge (w_{i-1}, w_i) of the outerface of G_{k-1}
- face f'_i contains edges of w_i that are in the interior of G_{k-1}

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v

Canonical order – implementation

Algorithm CanonicalOrder

initialize;

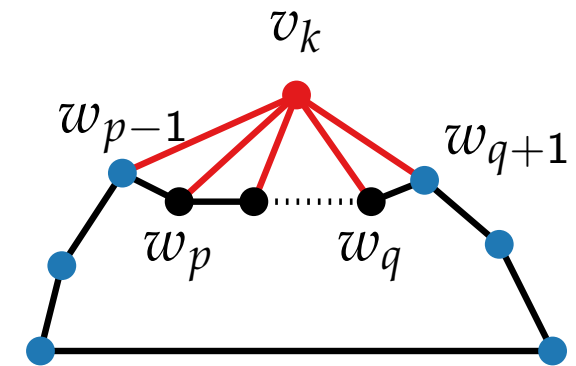
for $k = n$ **to** 3 **do**

 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

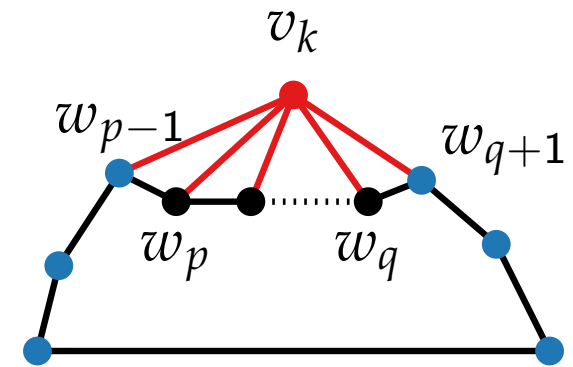
 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

 replace v_k with path $P = w_p \dots w_q$ in f_{out} ;

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

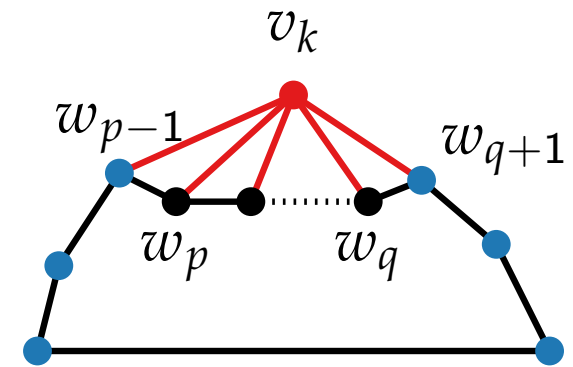
 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

 replace v_k with path $P = w_p \dots w_q$ in f_{out} ;

forall $p - 1 \leq i \leq q$ **do**

 remove face $\{v_k, w_i, w_{i+1}\}$ from $F(w_i)$ and $F(w_{i+1})$;

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

 replace v_k with path $P = w_p \dots w_q$ in f_{out} ;

forall $p - 1 \leq i \leq q$ **do**

 └ remove face $\{v_k, w_i, w_{i+1}\}$ from $F(w_i)$ and $F(w_{i+1})$;

forall $w \in w_{p-1} P w_{q+1}$ **do**

forall $f \in F(w)$ **do**

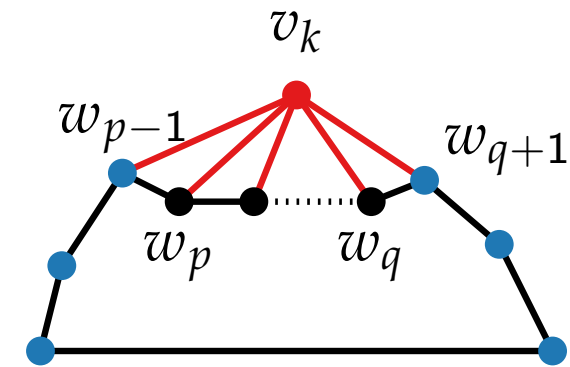
 └ update $\text{outV}(f)$;

forall $e \in w_{p-1} P w_{q+1}$ **do**

forall $f \in F(e)$ **do**

 └ update $\text{outE}(f)$;

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

choose $v_k \neq v_1, v_2$ such that

– $\text{sepf}(v) = 0$ or

– or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

replace v_k with path $P = w_p \dots w_q$ in f_{out} ;

forall $p - 1 \leq i \leq q$ **do**

└ remove face $\{v_k, w_i, w_{i+1}\}$ from $F(w_i)$ and $F(w_{i+1})$;

forall $w \in w_{p-1} P w_{q+1}$ **do**

└ **forall** $f \in F(w)$ **do**

└└ update $\text{outV}(f)$;

forall $e \in w_{p-1} P w_{q+1}$ **do**

└ **forall** $f \in F(e)$ **do**

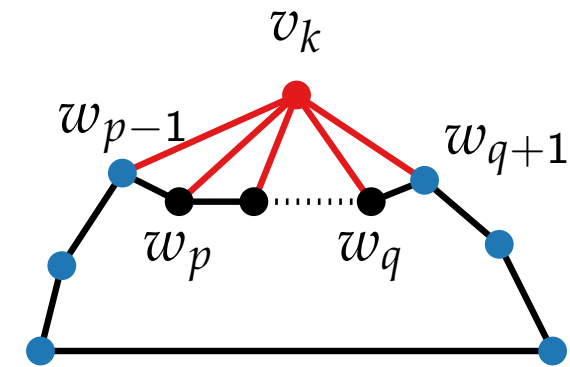
└└ update $\text{outE}(f)$;

forall $w \in P \cup N(P)$ **do**

└ **forall** $f \in F(w)$ **do**

└└ update $\text{sepF}(w)$;

- f_{out} = current outerface
- $F(v)$ = faces that contain v
- $F(e)$ = faces that contain e
- $\text{outV}(f)$ = # vertices of f on f_{out}
- $\text{outE}(f)$ = # edges of f on f_{out}
- $\text{sepF}(v)$ = # separation faces that contain v



Canonical order – implementation

Algorithm CanonicalOrder

initialize;

for $k = n$ **to** 3 **do**

 choose $v_k \neq v_1, v_2$ such that

 – $\text{sepf}(v) = 0$ or

 – or $F(v) = \{f\}$, $\text{outV}(f) = 3$ and $\text{outE}(f) = 2$

 replace v_k with path $P = w_p \dots w_q$ in f_{out} ;

forall $p - 1 \leq i \leq q$ **do**

 └ remove face $\{v_k, w_i, w_{i+1}\}$ from $F(w_i)$ and $F(w_{i+1})$;

forall $w \in w_{p-1} P w_{q+1}$ **do**

forall $f \in F(w)$ **do**

 └ update $\text{outV}(f)$;

forall $e \in w_{p-1} P w_{q+1}$ **do**

forall $f \in F(e)$ **do**

 └ update $\text{outE}(f)$;

forall $w \in P \cup N(P)$ **do**

forall $f \in F(w)$ **do**

 └ update $\text{sepF}(w)$;

■ f_{out} = current outerface

■ $F(v)$ = faces that contain v

■ $F(e)$ = faces that contain e

■ $\text{outV}(f)$ = # vertices of f on f_{out}

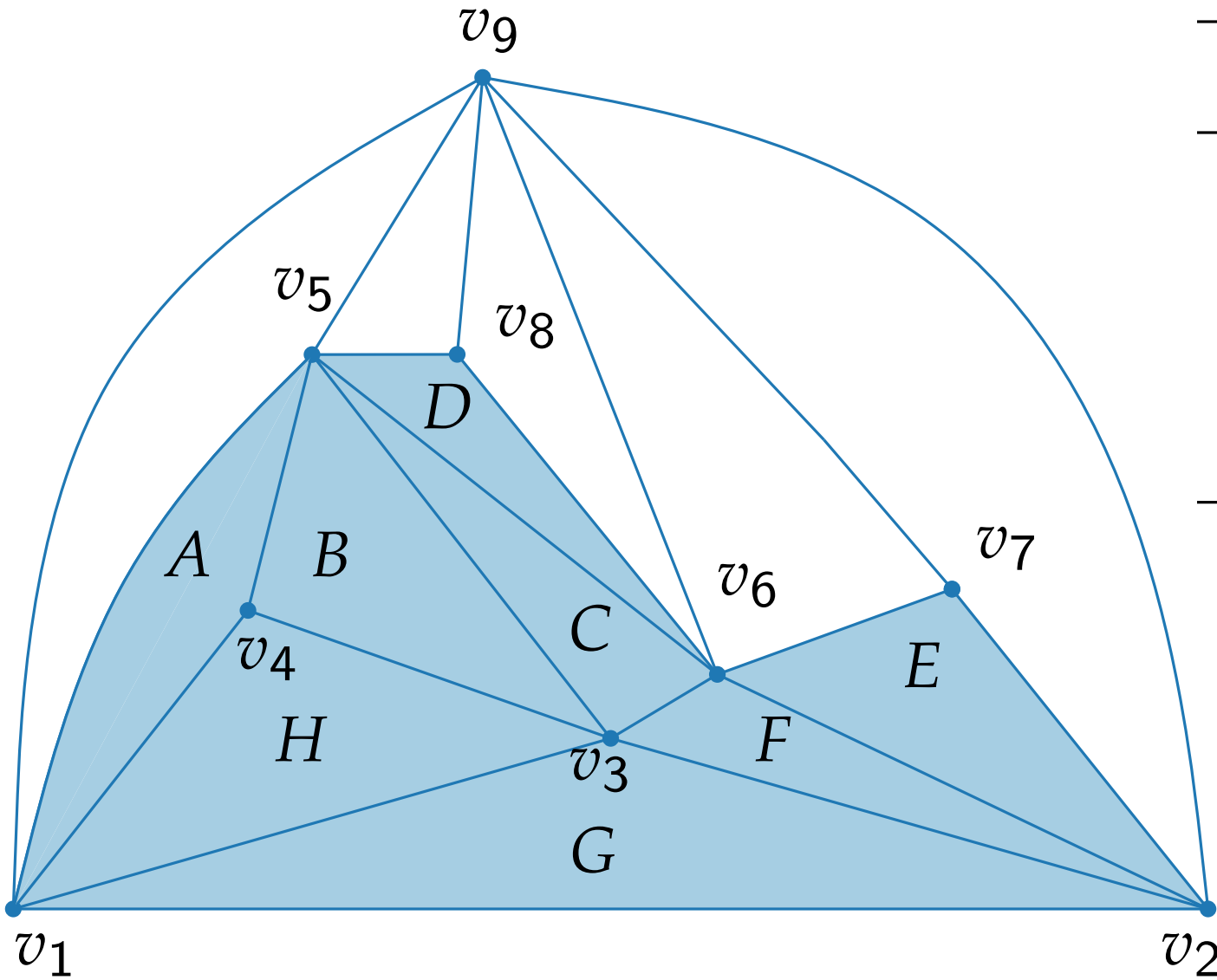
■ $\text{outE}(f)$ = # edges of f on f_{out}

■ $\text{sepF}(v)$ = # separation faces that contain v

Lemma.

Algorithm CanonicalOrder computes a canonical order of a plane graph in $\mathcal{O}(n)$ time.

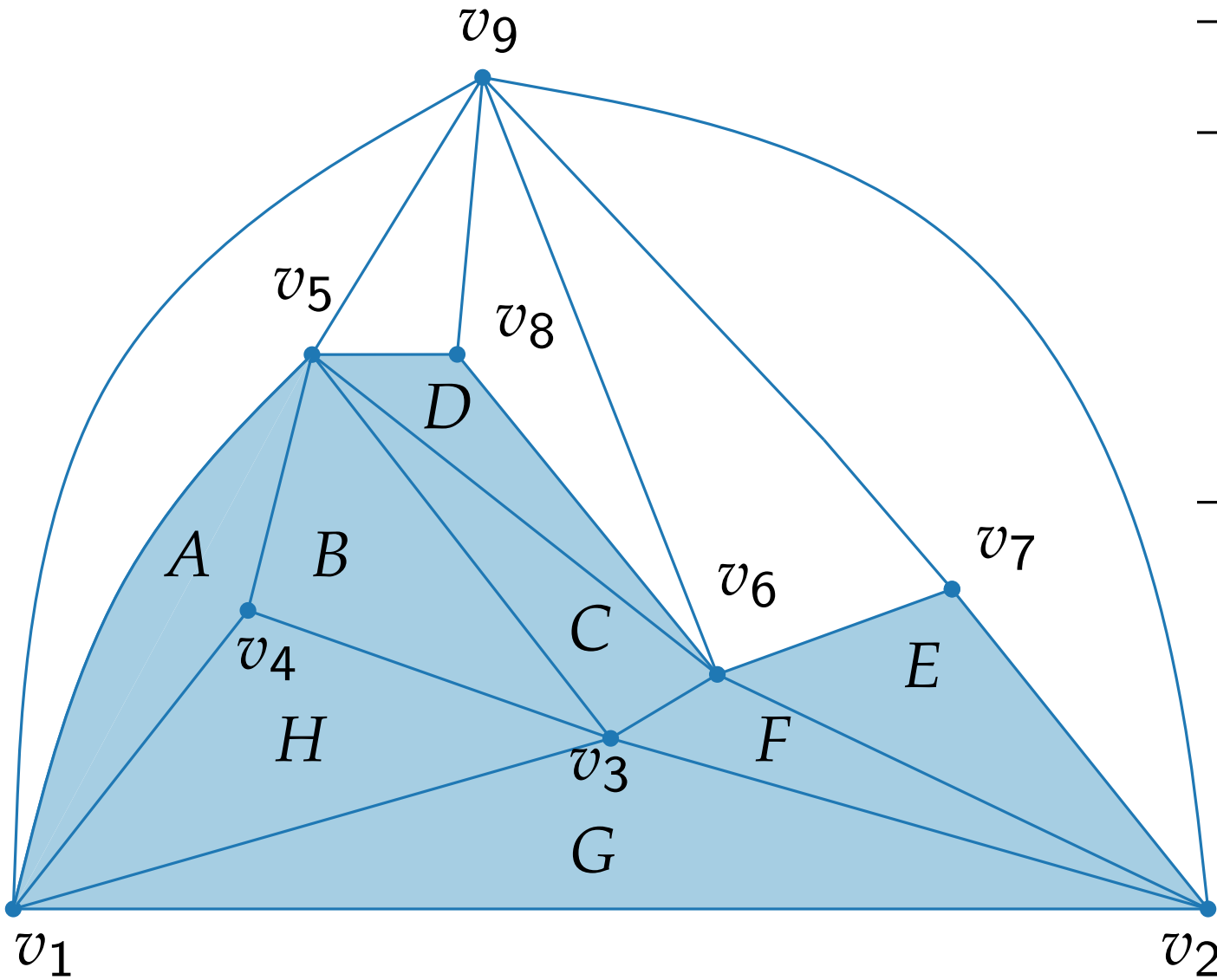
Canonical order – example



	A	B	C	D	E	F	G	H
$\text{outV}(f)$								
$\text{outE}(f)$								

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$						

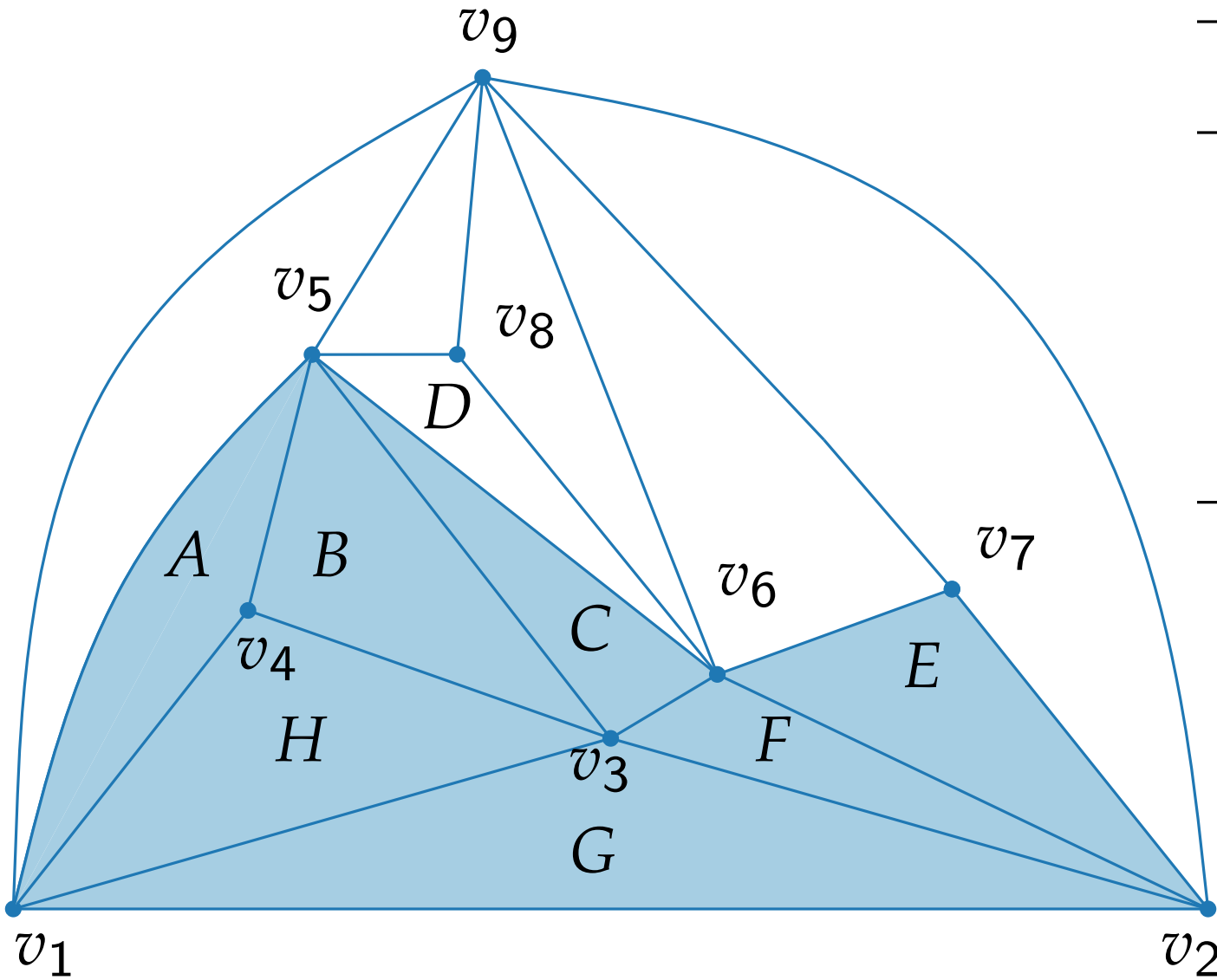
Canonical order – example



	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>	<i>G</i>	<i>H</i>
$\text{outV}(f)$	2	1	2	3	3	2	2	1
$\text{outE}(f)$	1	0	0	2	2	0	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$			2	4	1	1

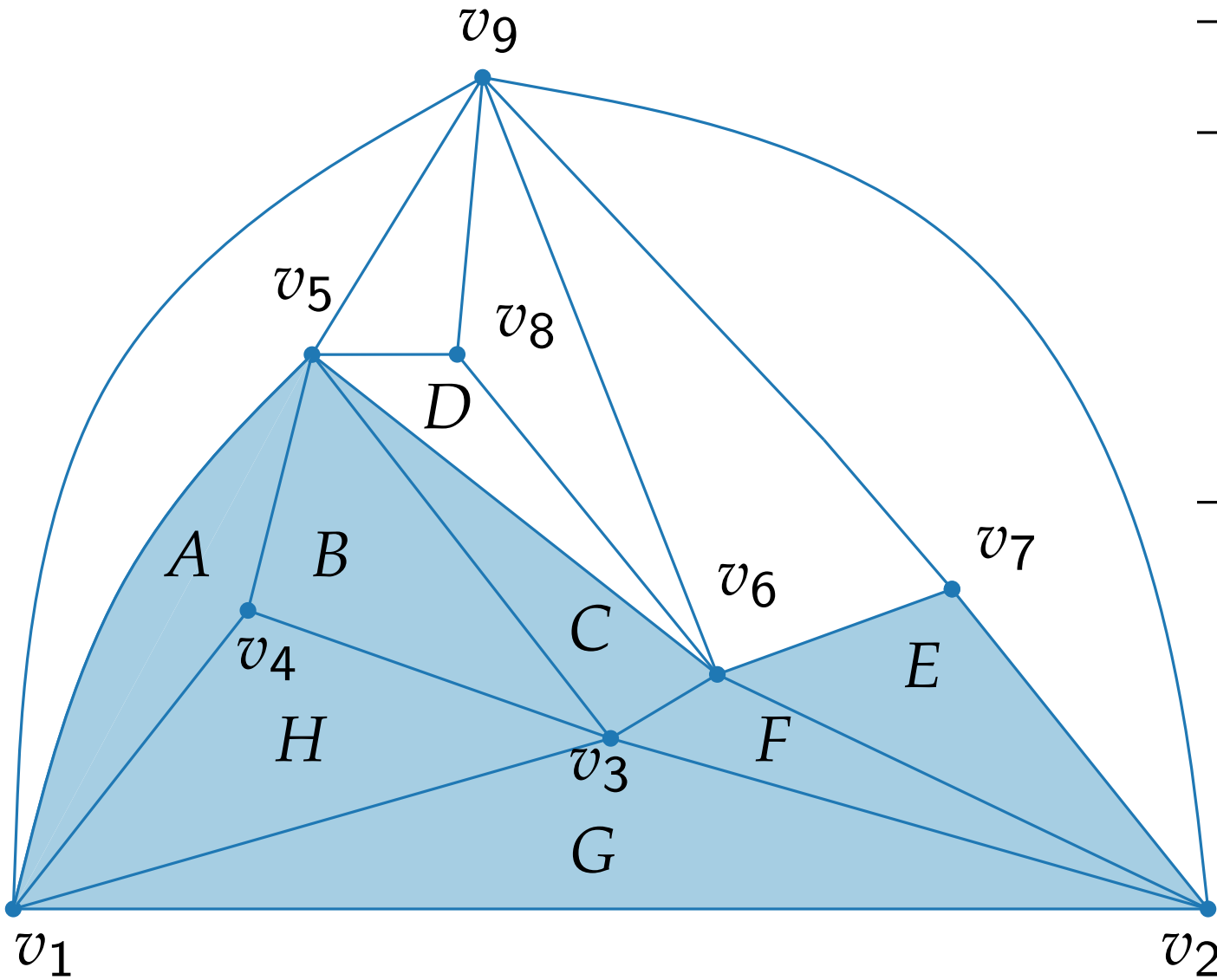
Canonical order – example



	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>	<i>G</i>	<i>H</i>
$\text{outV}(f)$	2	1	2	3	3	2	2	1
$\text{outE}(f)$	1	0	0	2	2	0	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$			2	4	1	1

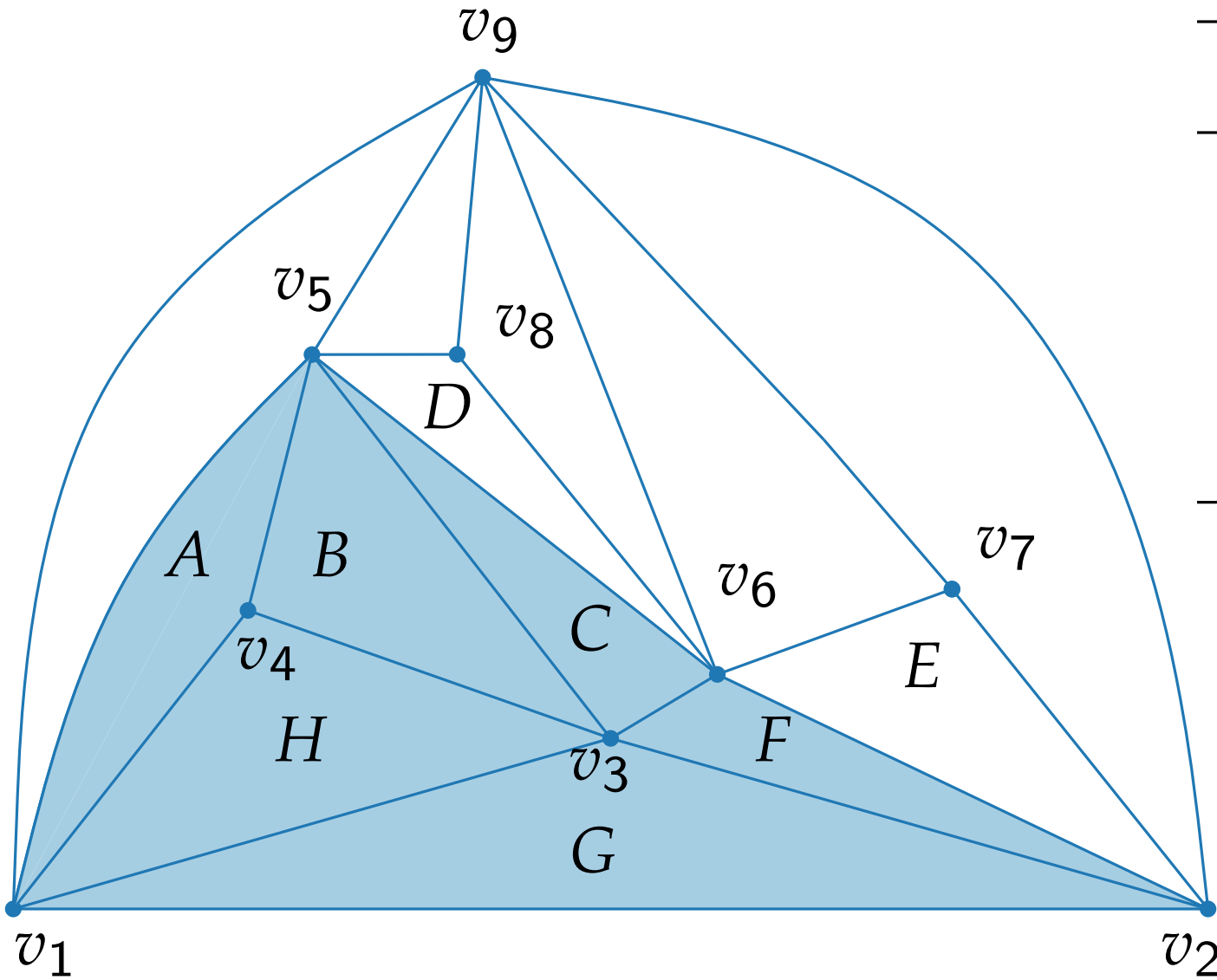
Canonical order – example



	A	B	C	D	E	F	G	H
outV(f)	2	1	2		3	2	2	1
outE(f)	1	0	1		2	0	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
sepF(v)			0	2	1	

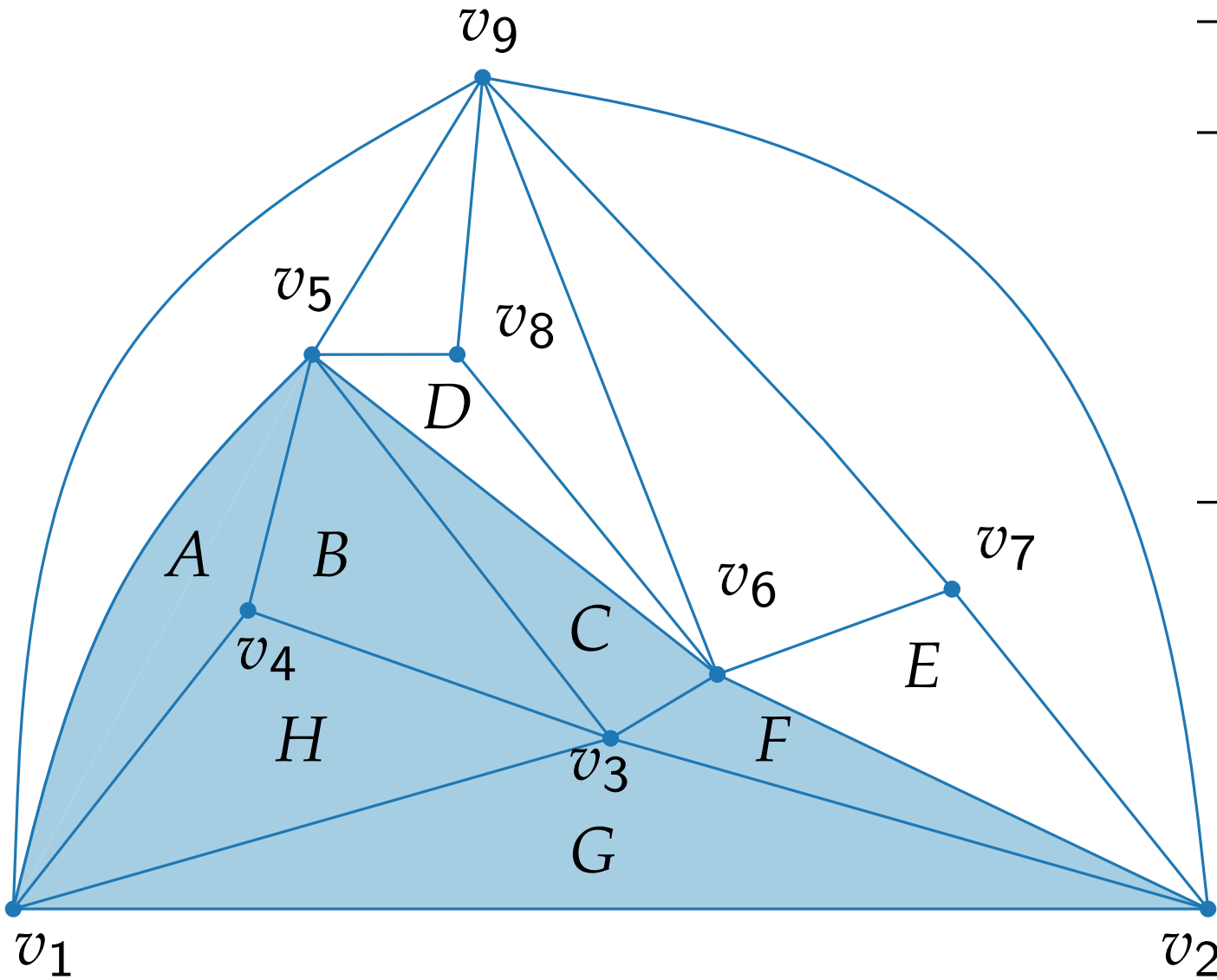
Canonical order – example



	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	<i>F</i>	<i>G</i>	<i>H</i>
$\text{outV}(f)$	2	1	2		3	2	2	1
$\text{outE}(f)$	1	0	1		2	0	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$			0	2	1	

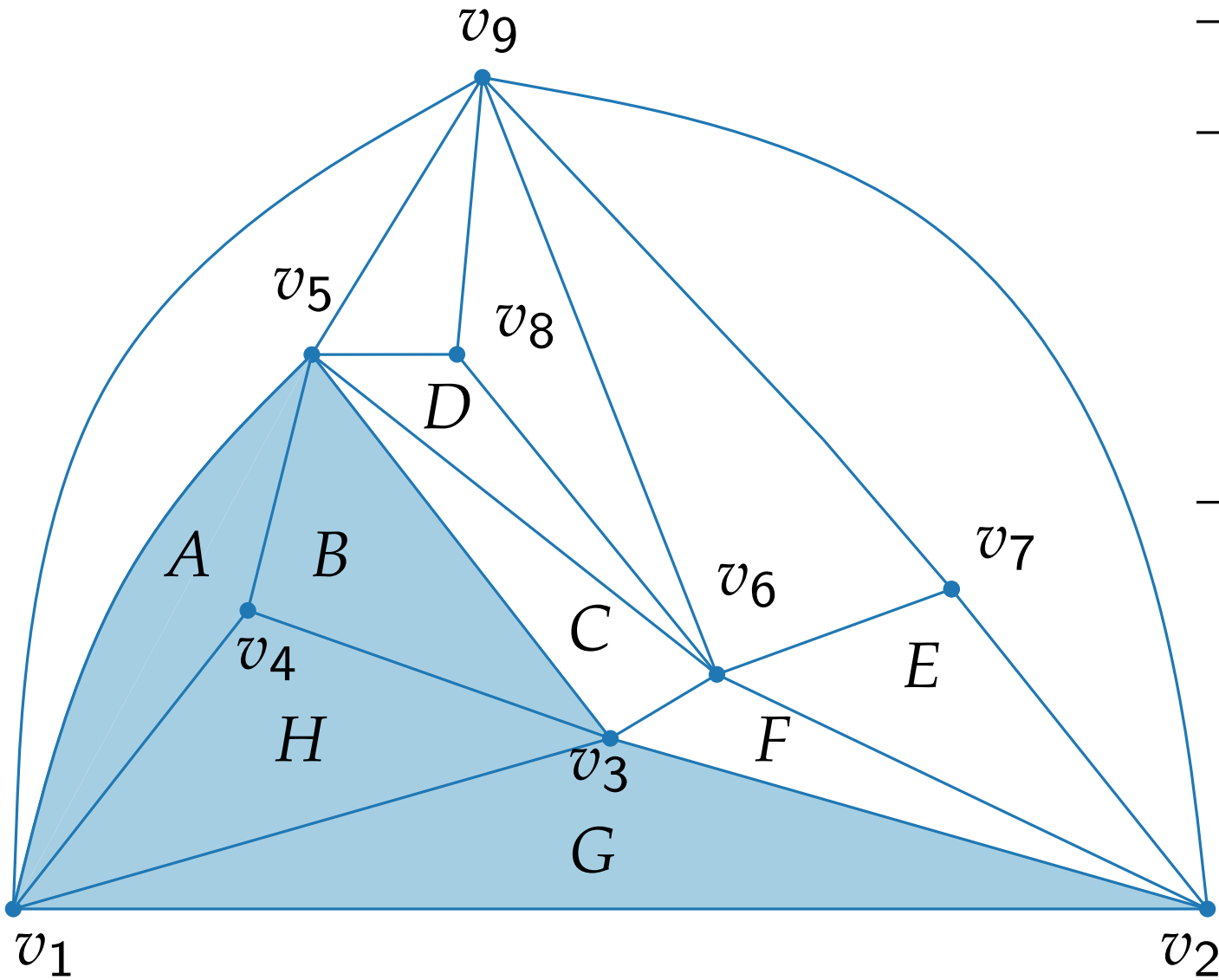
Canonical order – example



	A	B	C	D	E	F	G	H
$\text{outV}(f)$	2	1	2			2	2	1
$\text{outE}(f)$	1	0	1			1	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$			0	0		

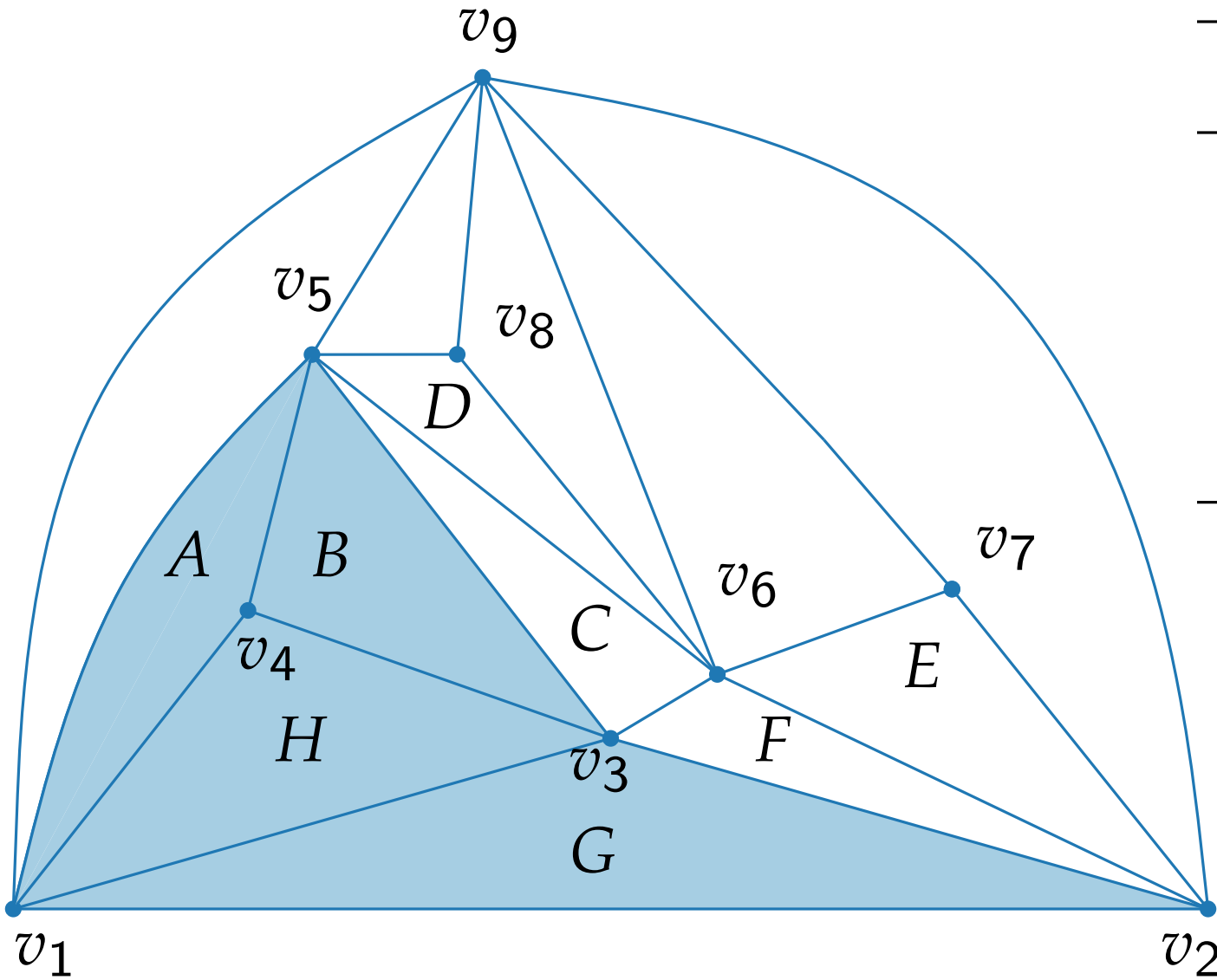
Canonical order – example



	A	B	C	D	E	F	G	H
outV(f)	2	1	2			2	2	1
outE(f)	1	0	1			1	1	0

	v_3	v_4	v_5	v_6	v_7	v_8
sepF(v)			0	0		

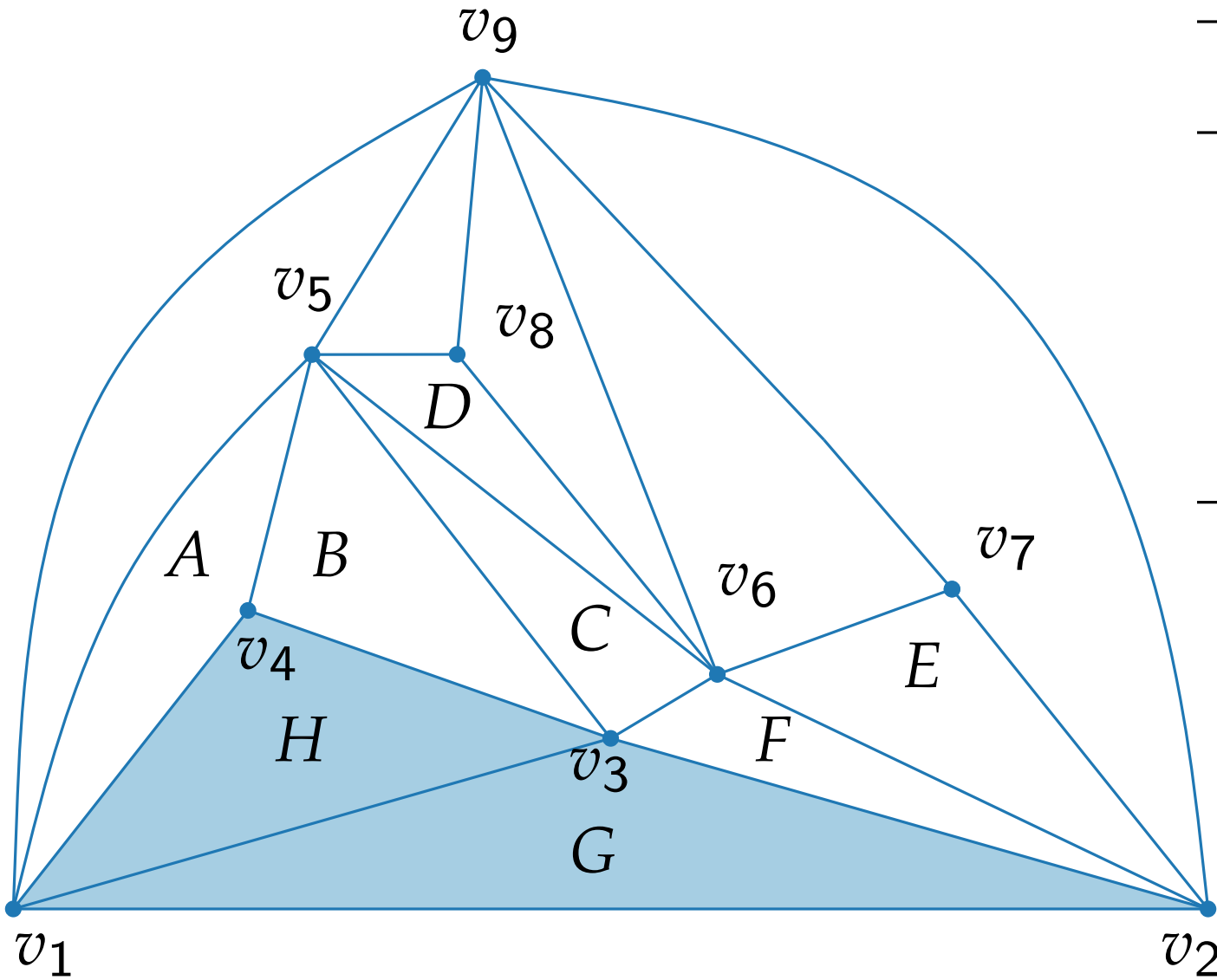
Canonical order – example



	A	B	C	D	E	F	G	H
$\text{outV}(f)$	2	2					3	2
$\text{outE}(f)$	1	1					2	0

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$	2		0			

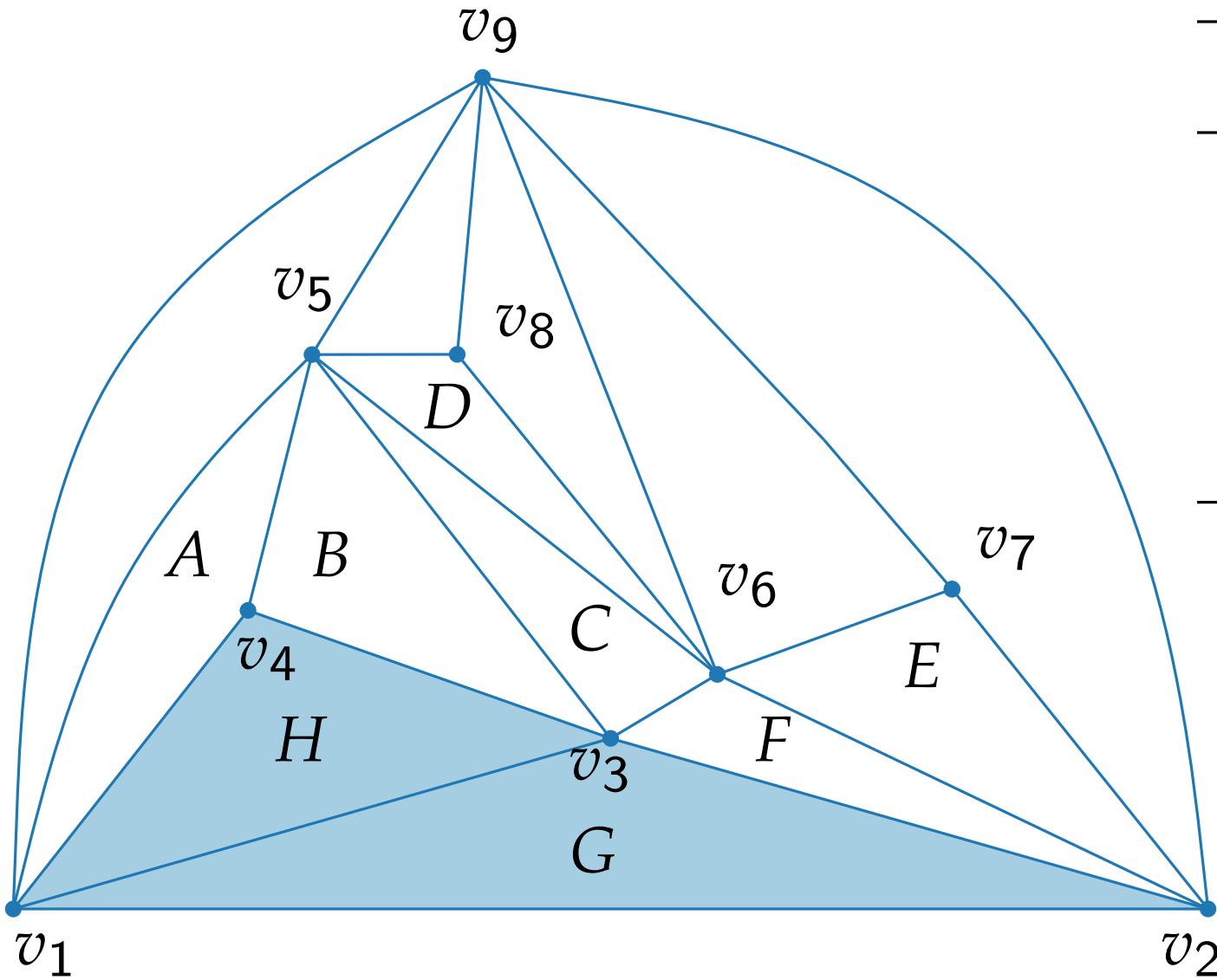
Canonical order – example



	A	B	C	D	E	F	G	H
outV(f)	2	2					3	2
outE(f)	1	1					2	0

	v_3	v_4	v_5	v_6	v_7	v_8
sepF(v)	2		0			

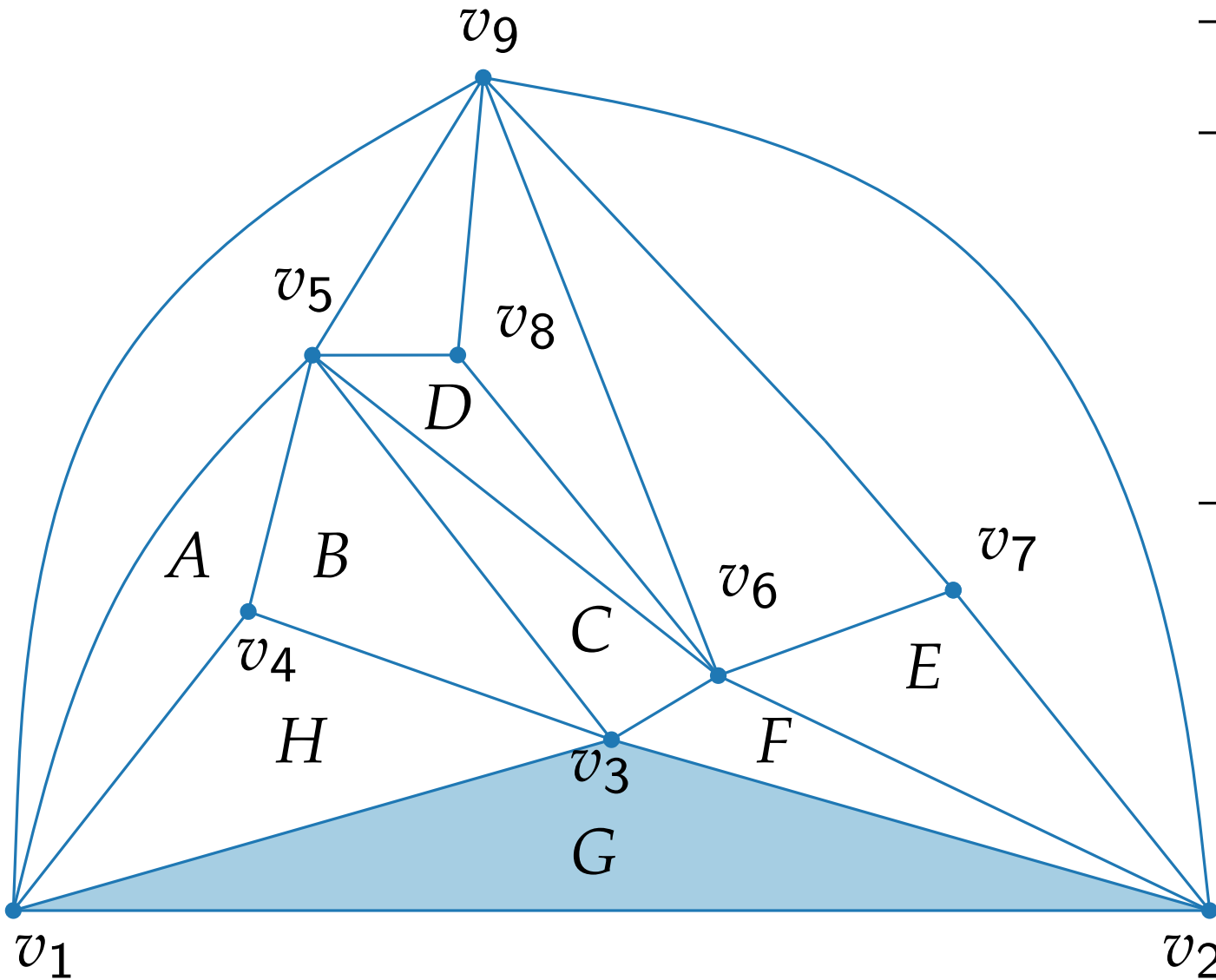
Canonical order – example



	A	B	C	D	E	F	G	H
outV(f)							3	3
outE(f)							2	2

	v_3	v_4	v_5	v_6	v_7	v_8
sepF(v)	2	1				

Canonical order – example



	A	B	C	D	E	F	G	H
$\text{outV}(f)$							3	3
$\text{outE}(f)$							2	2

	v_3	v_4	v_5	v_6	v_7	v_8
$\text{sepF}(v)$	2	1				

Order:

$\{v_1, v_2, v_3, v_4, v_5, v_6, v_7, v_8, v_9\}$

Literature

- [HGD Ch. 6.5] canonical order
- [dFPP90] de Fraysseix, Pach, Pollack "*How to draw a planar graph on a grid*", Combinatorica, 1990
- [Kant96] Kant "*Drawing planar graphs using the canonical ordering*", Algorithmica, 1996
- [BBC11] Badent, Brandes, Cornelsen "*More Canonical Ordering*", JGAA, 2011