

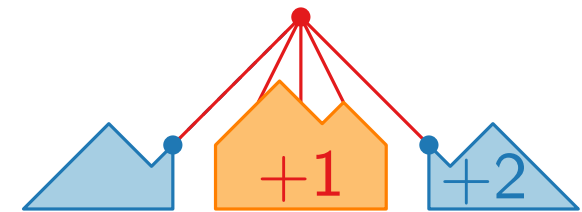
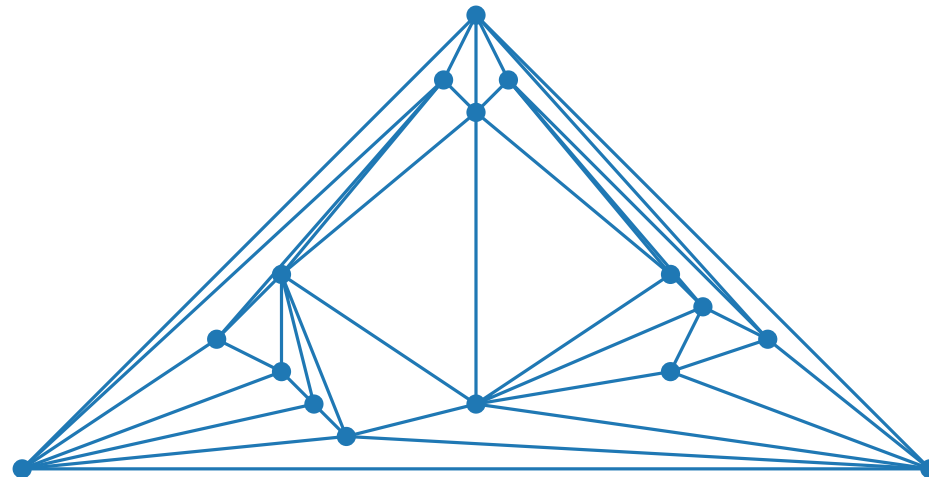
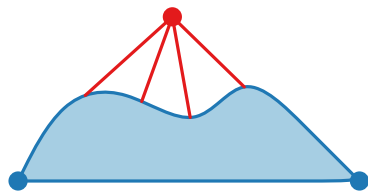
Visualisation of graphs

Planar straight-line drawings

Shift Method

Antonios Symvonis · Chrysanthi Raftopoulou

Fall semester 2020



The original slides of this presentation were created by researchers at Karlsruhe Institute of Technology (KIT), TU Wien, U Wuerzburg, U Konstanz, ...
The original presentation was modified/updated by A. Symvonis and C. Raftopoulou

Planar straight-line drawings

Theorem. [De Fraysseix, Pach, Pollack '90]

Every n -vertex planar graph has a planar straight-line drawing of size $(2n - 4) \times (n - 2)$.

Theorem. [Schnyder '90] Every n -vertex planar graph has a planar straight-line drawing of size $(n - 2) \times (n - 2)$.

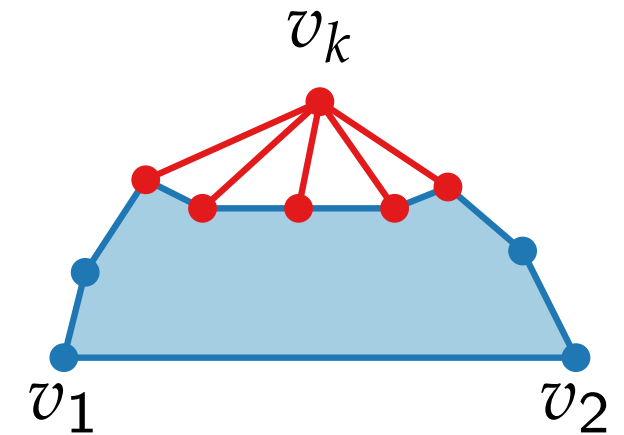
Planar straight-line drawings

Theorem. [De Fraysseix, Pach, Pollack '90]

Every n -vertex planar graph has a planar straight-line drawing of size $(2n - 4) \times (n - 2)$.

Idea: Use the canonical order.

- Start with single edge (v_1, v_2) . Let this be G_2 .
- To obtain G_{i+1} , add v_{i+1} to G_i so that neighbours of v_{i+1} are on the outer face of G_i .
- Neighbours of v_{i+1} in G_i have to form path of length at least two.



Theorem. [Schnyder '90] Every n -vertex planar graph has a planar straight-line drawing of size $(n - 2) \times (n - 2)$.

Canonical order – definition

Definition.

Let $G = (V, E)$ be a triangulated plane graph on $n \geq 3$ vertices. An order $\pi = (v_1, v_2, \dots, v_n)$ is called a **canonical order**, if the following conditions hold for each k , $3 \leq k \leq n$:

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- **(C2)** Edge (v_1, v_2) belongs to the outer face of G_k .
- **(C3)** If $k < n$ then vertex v_{k+1} lies in the outer face of G_k , and all neighbors of v_{k+1} in G_k appear on the boundary of G_k consecutively.

Canonical order – definition

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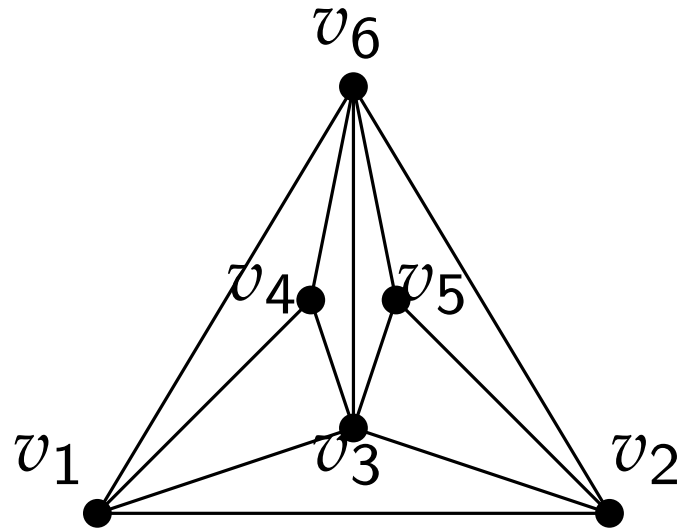
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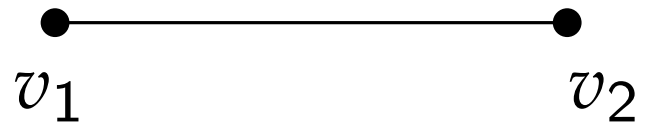
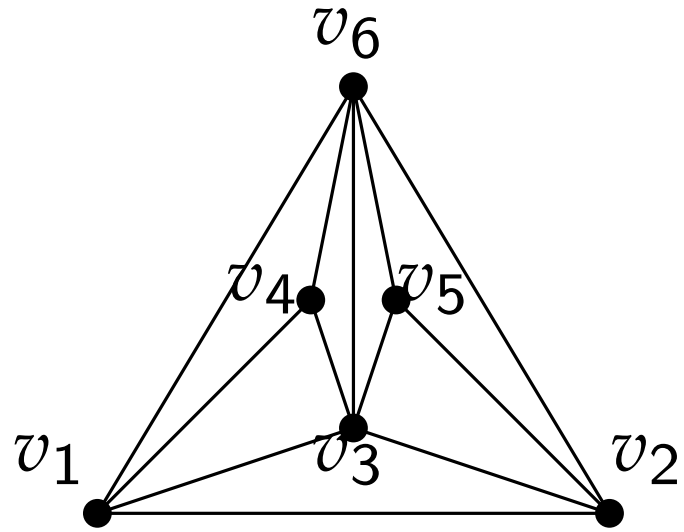
Lemma.

Every triangulated plane graph has a canonical order.

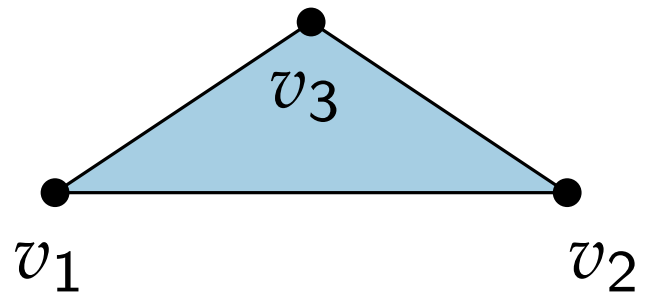
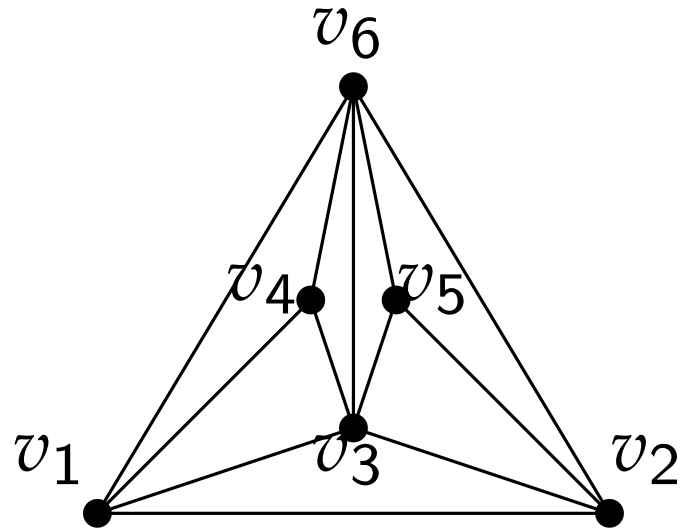
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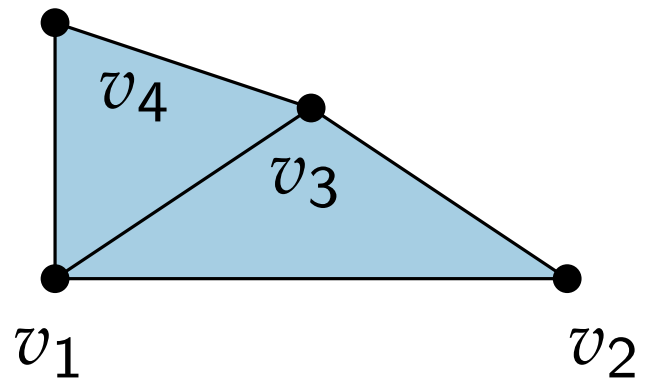
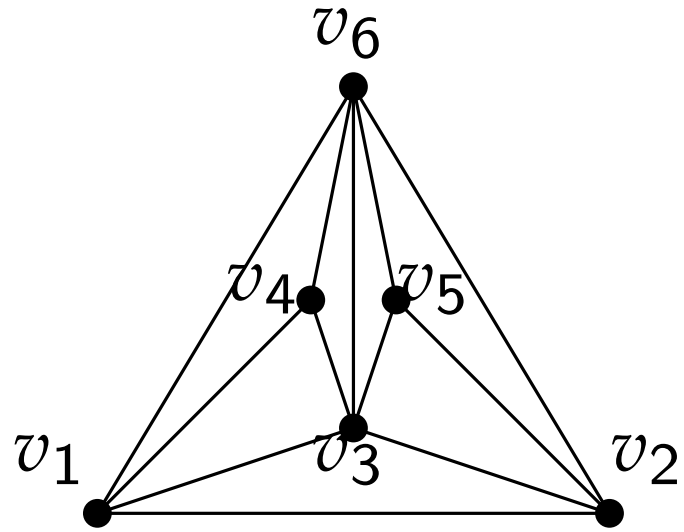
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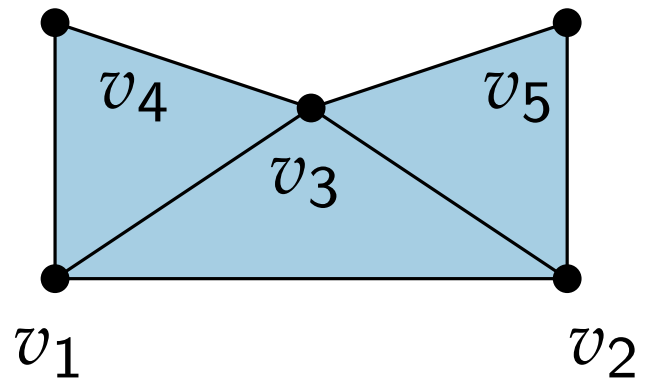
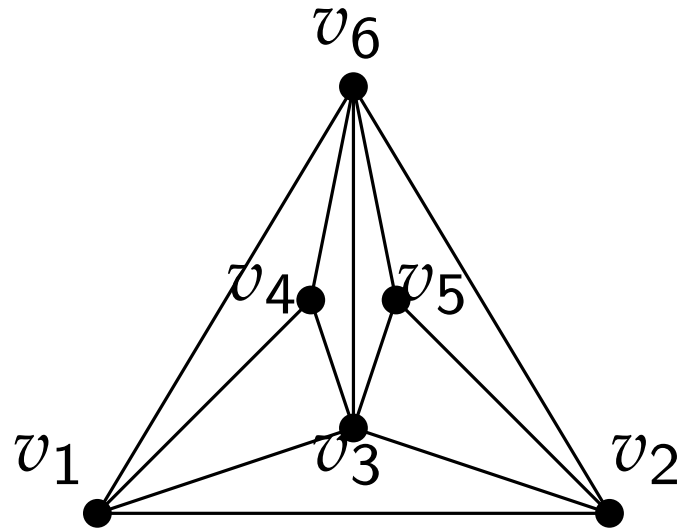
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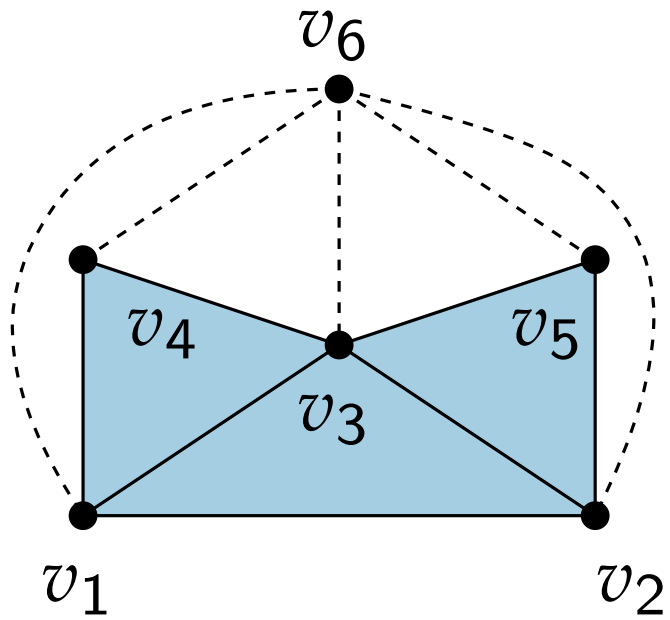
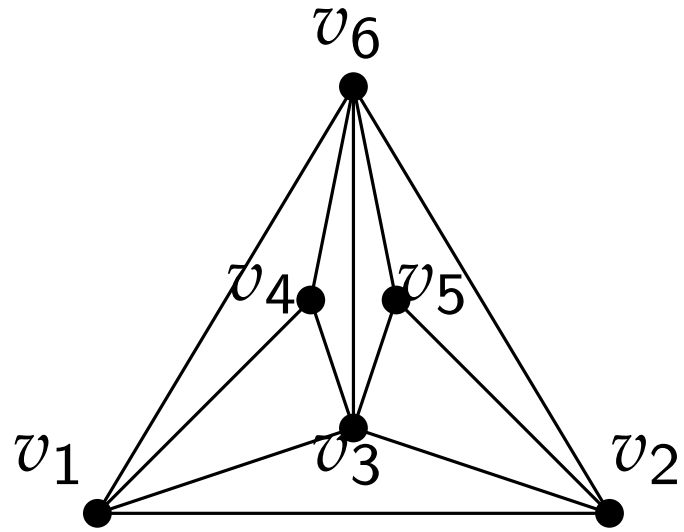
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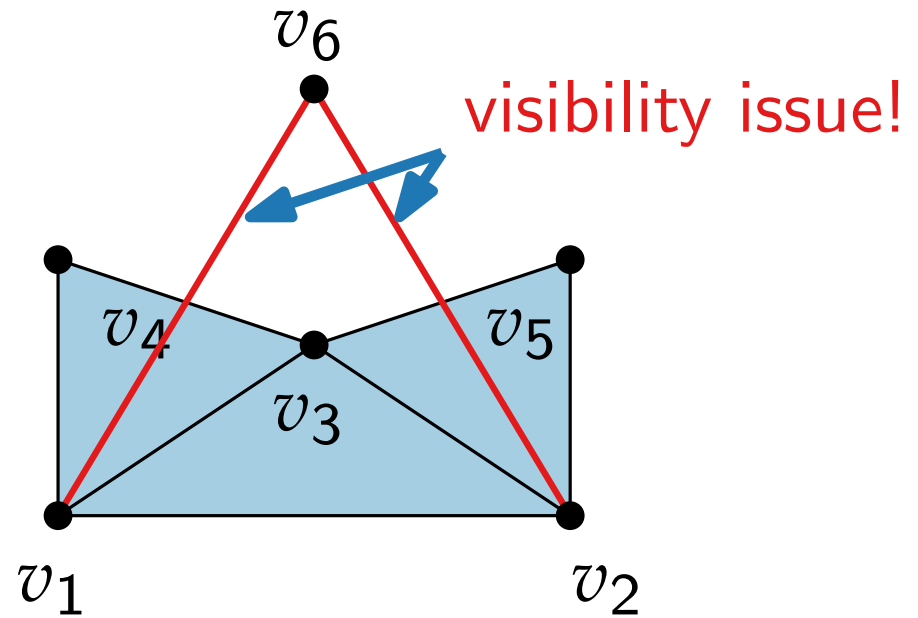
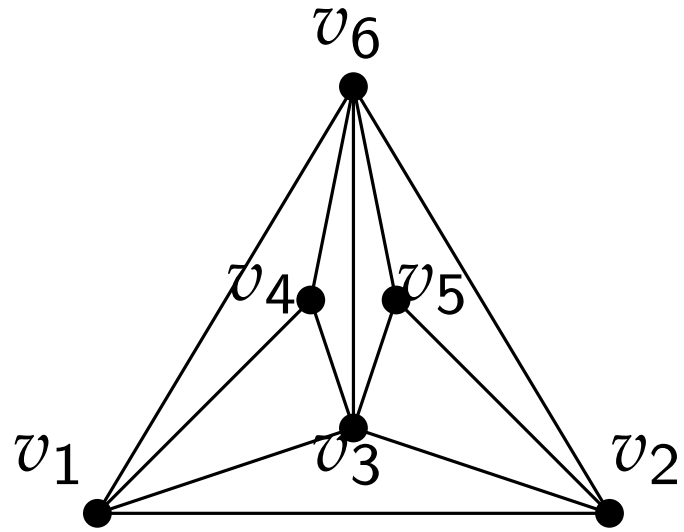
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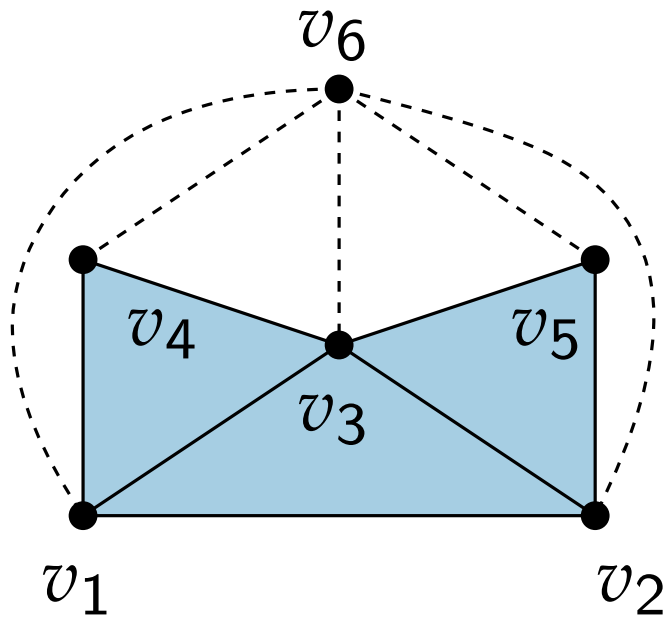
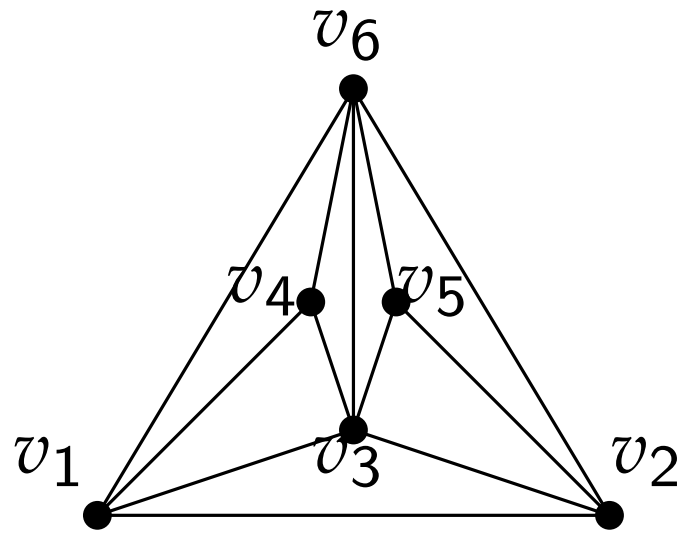
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Constraints

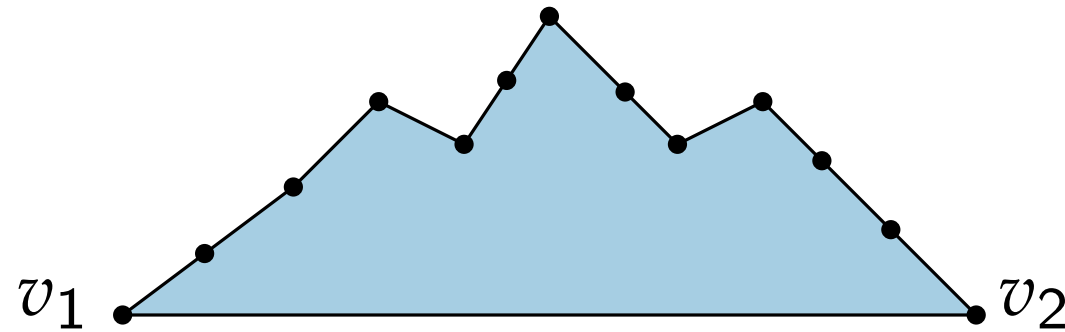


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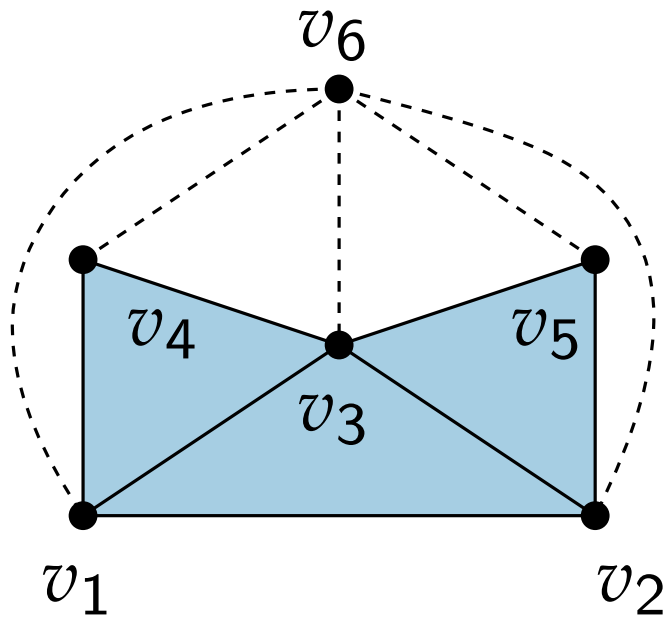
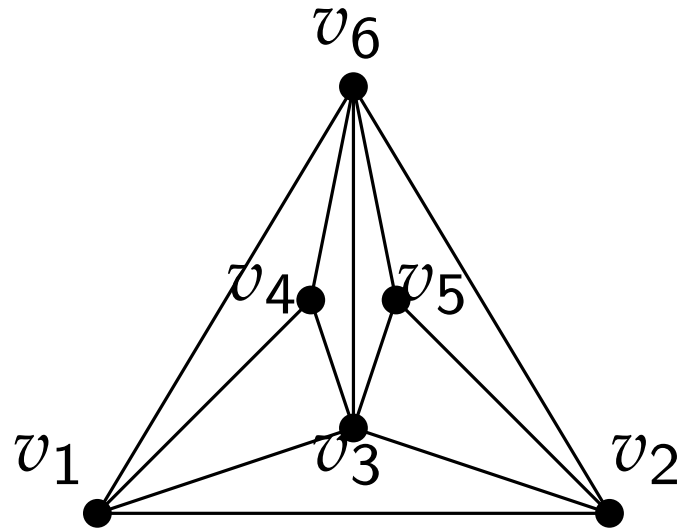


Constraints:

G_{k-1} is drawn such that



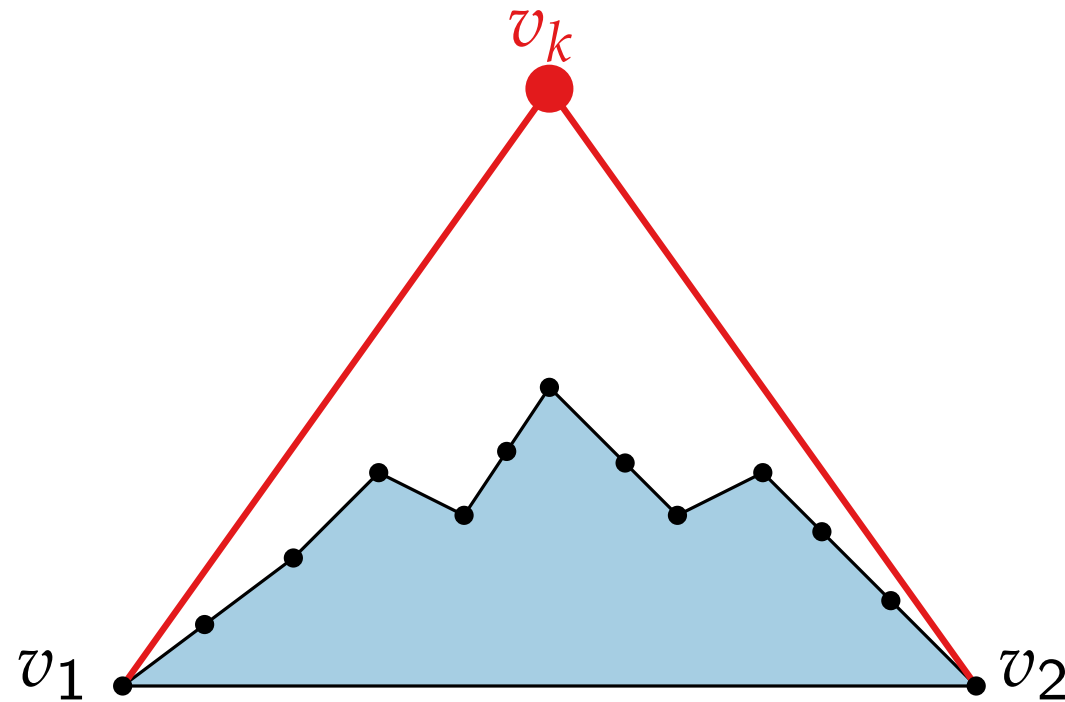
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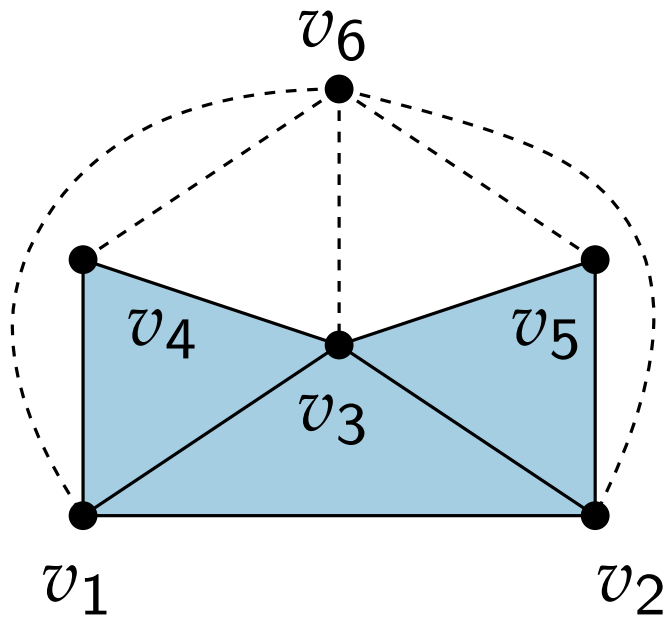
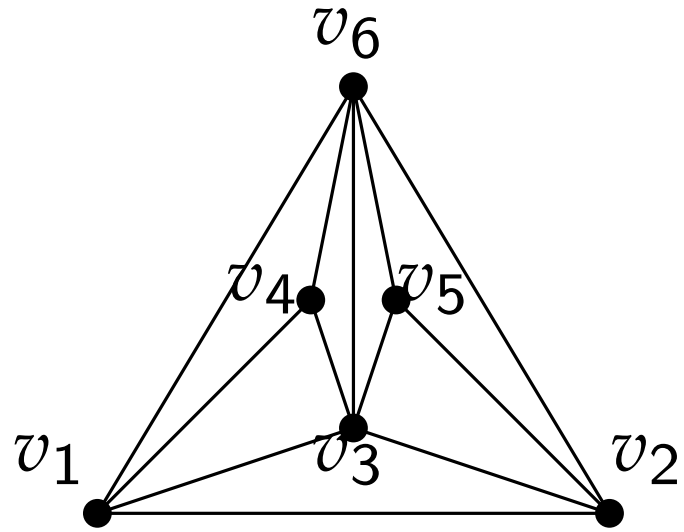
Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,



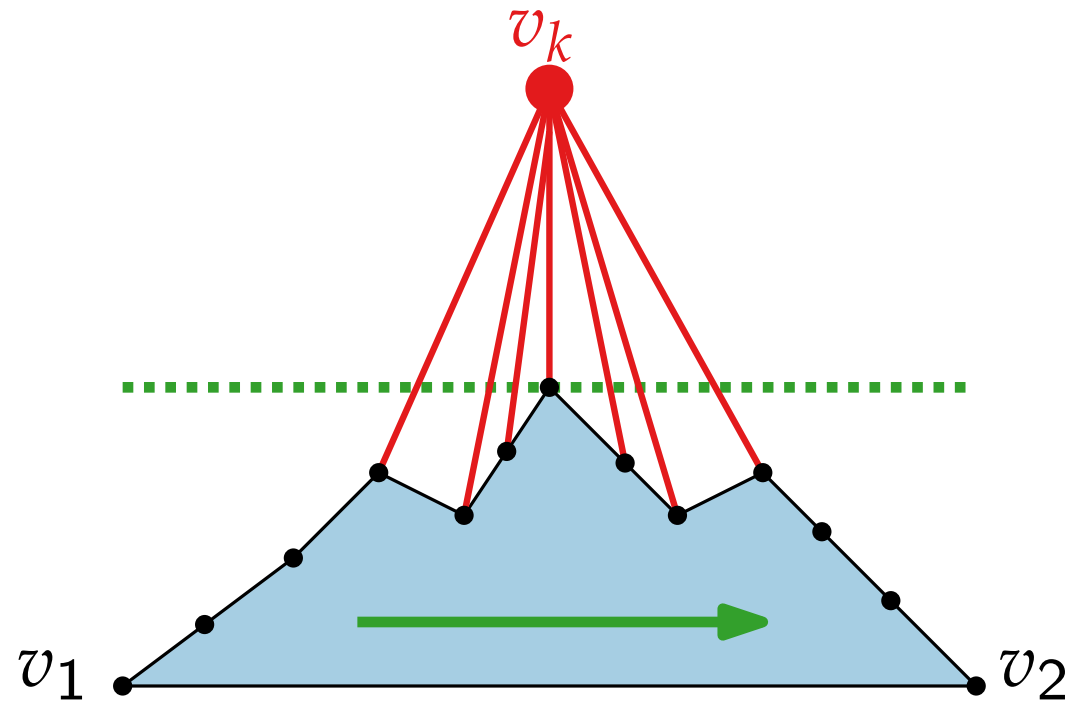
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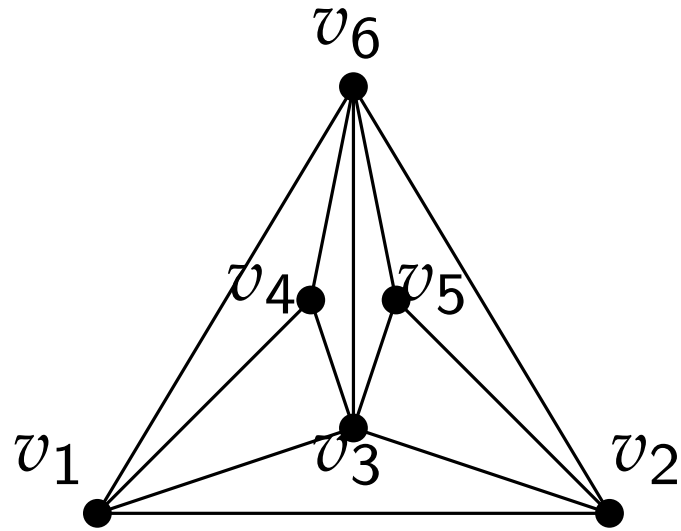
Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- neighbors of v_k on G_{k-1} should be drawn x -monotone,
- v_k is placed above its neighbors on G_{k-1} .



Constraints

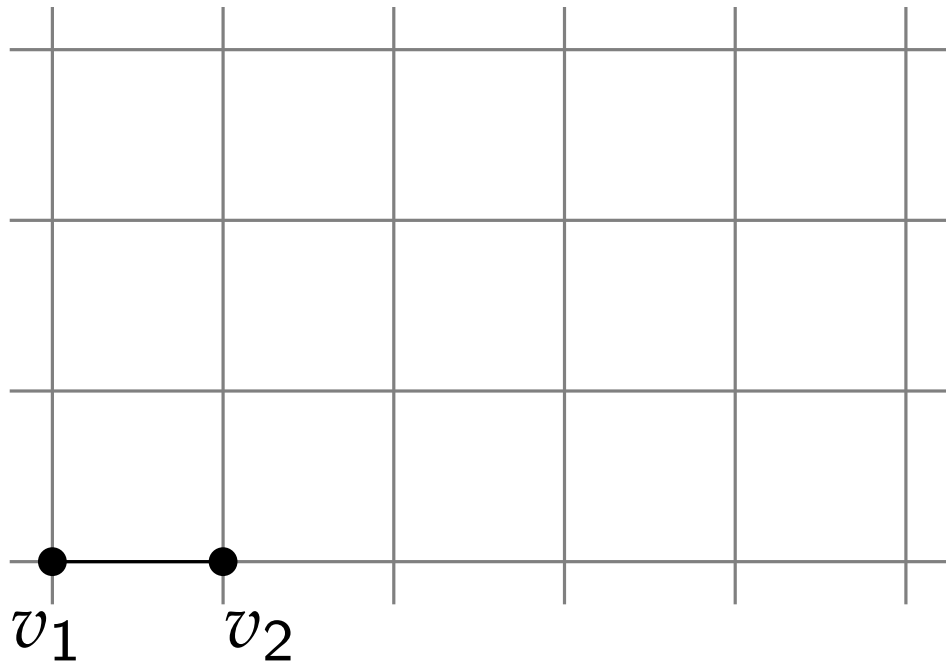
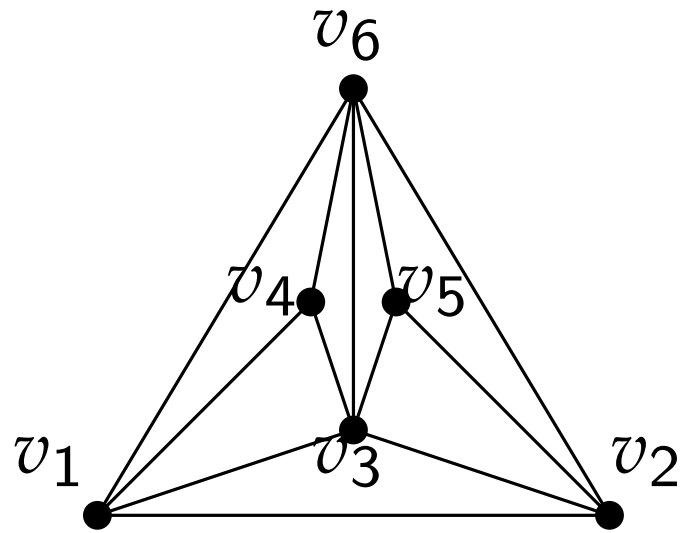


Constraints:

G_{k-1} is drawn such that

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- v_k is placed above its neighbors on G_{k-1} .

Constraints



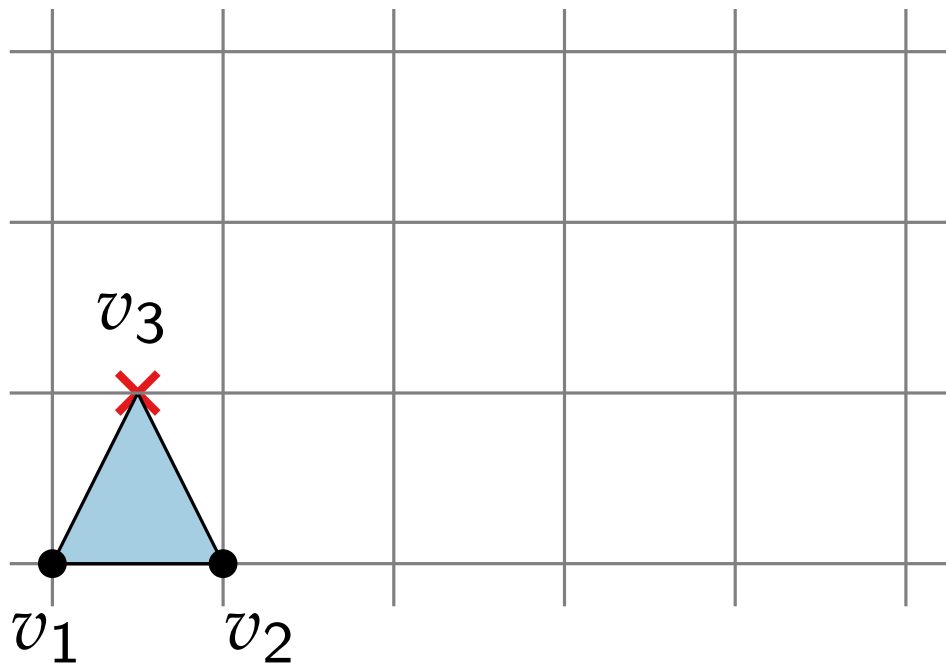
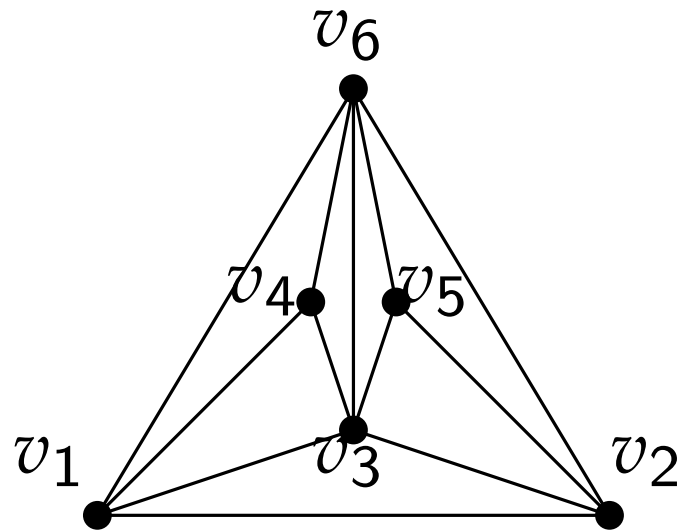
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G_2 : $v_1 : (0, 0)$, $v_2 : (1, 0)$

Constraints



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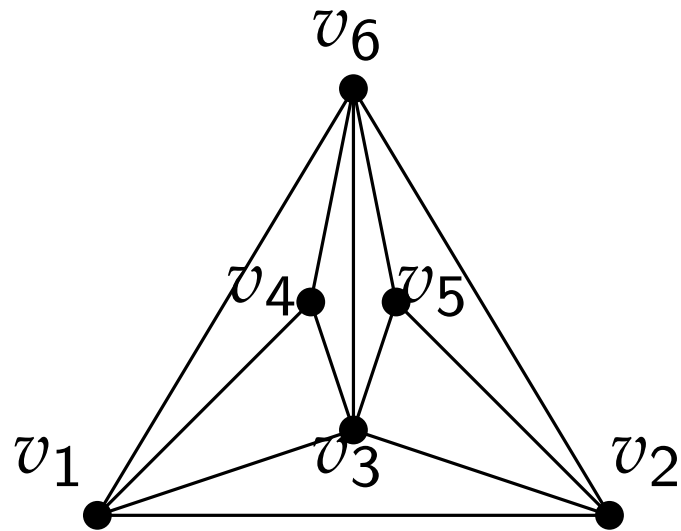
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- Need to make room for v_3

Constraints

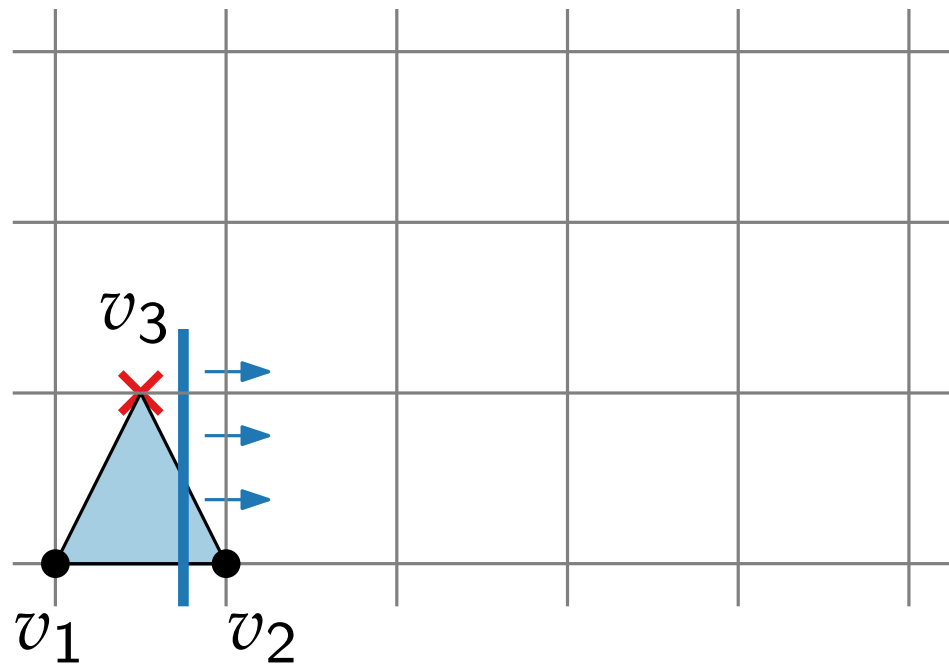


Constraints:

G_{k-1} is drawn such that

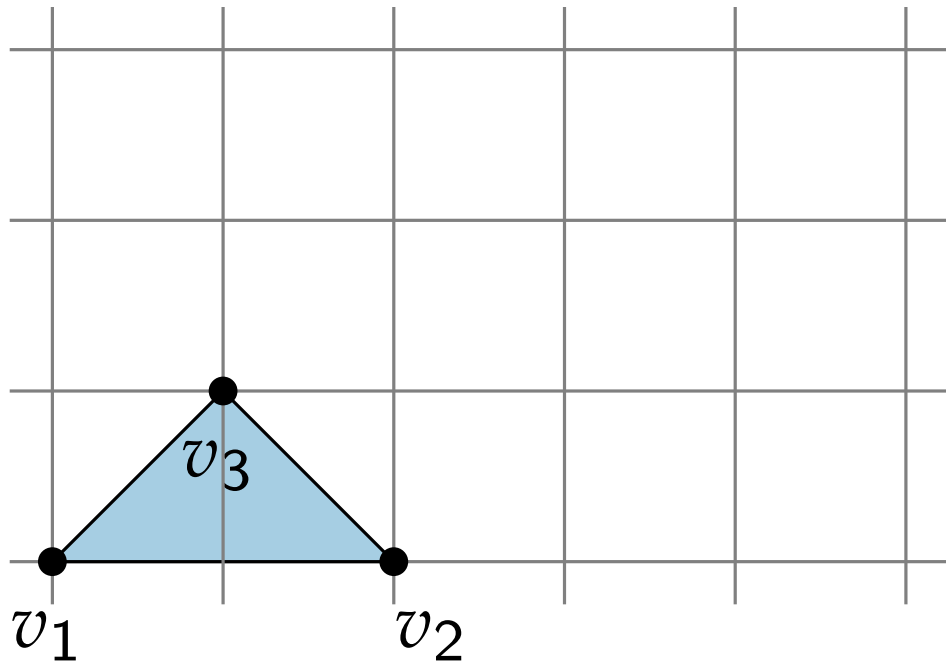
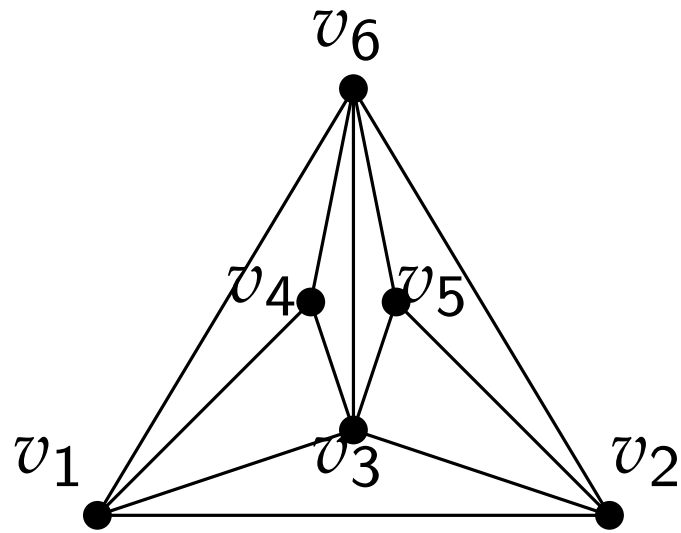
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G_2 : $v_1 : (0, 0)$, $v_2 : (1, 0)$



- Need to make room for v_3
- **Shift** v_2 to the right

Constraints



Constraints:

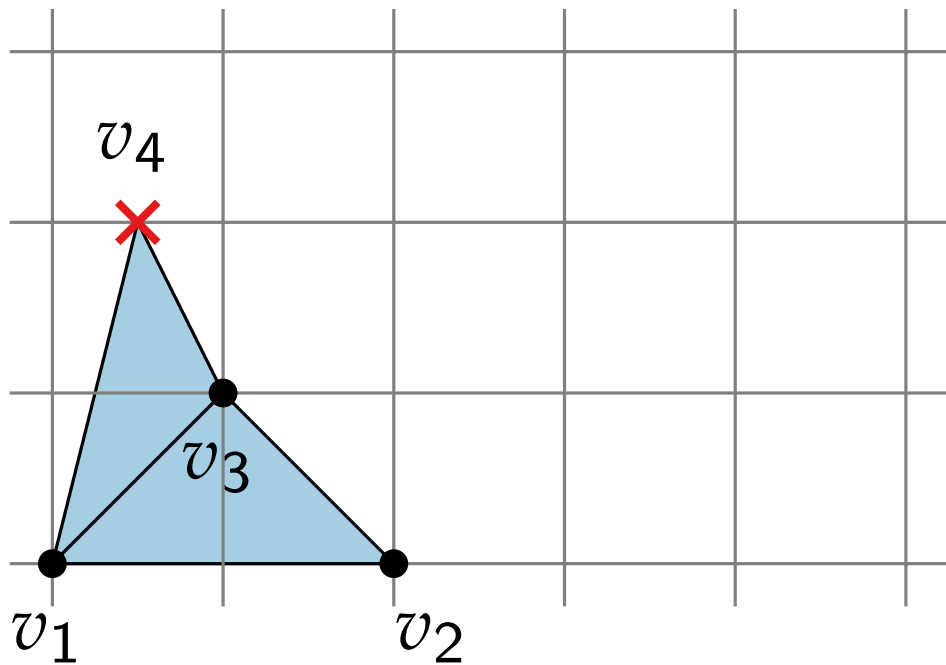
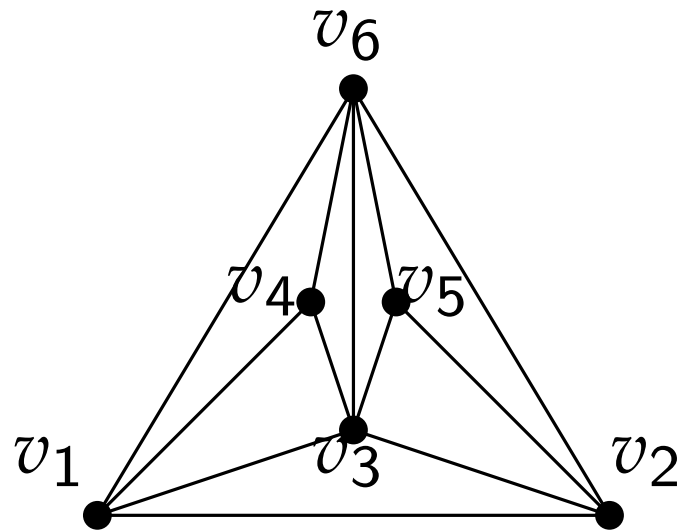
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G_3 : $v_1 : (0, 0)$, $v_2 : (2, 0)$, $v_3 : (1, 1)$

Constraints



Constraints:

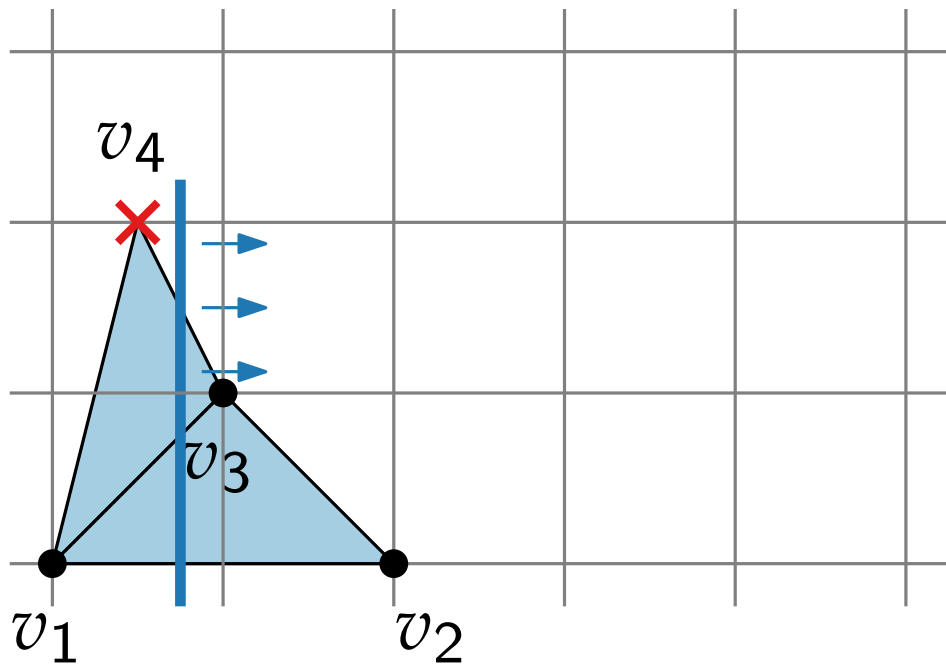
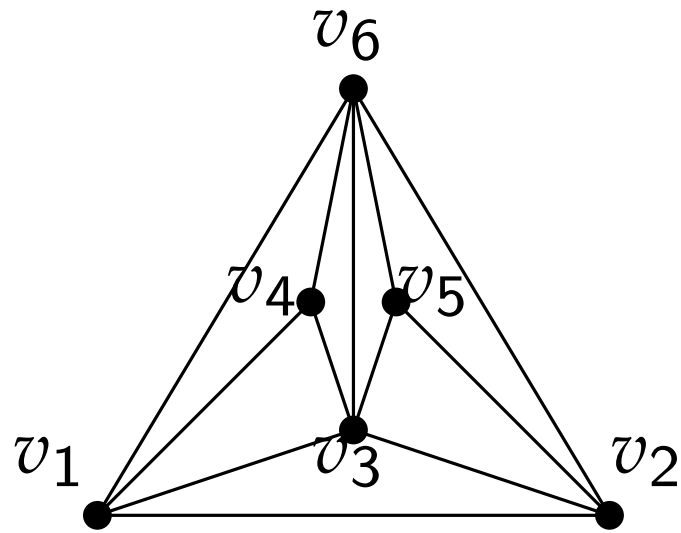
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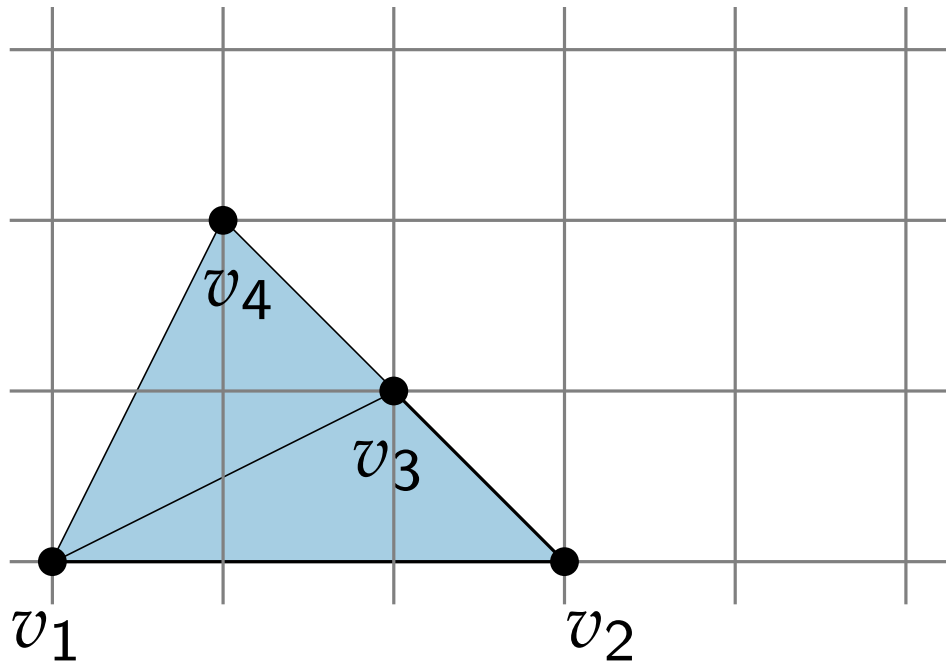
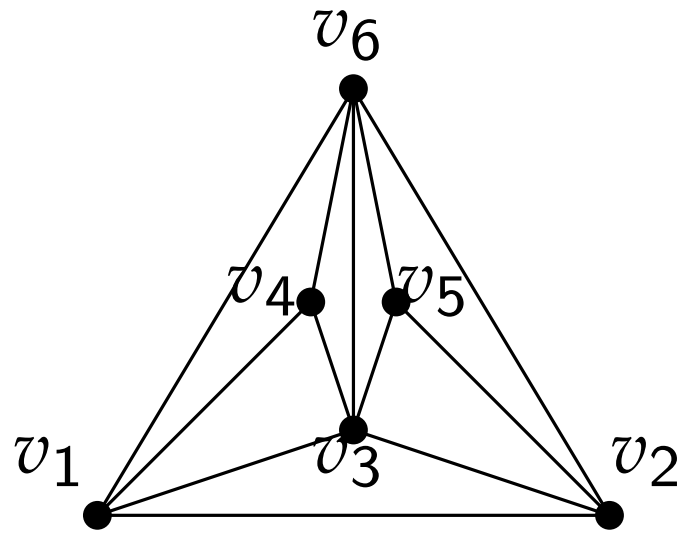
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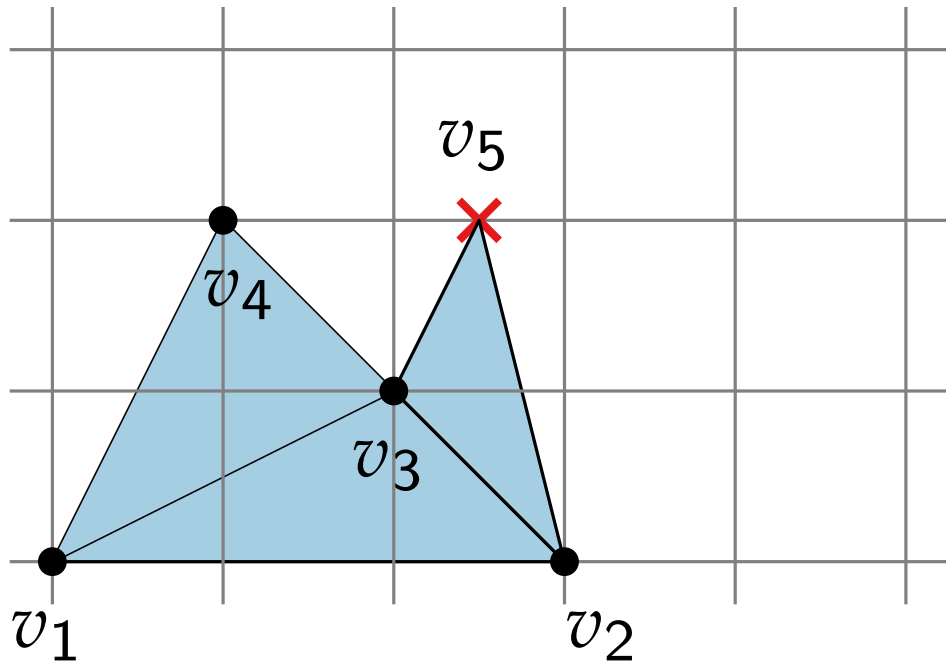
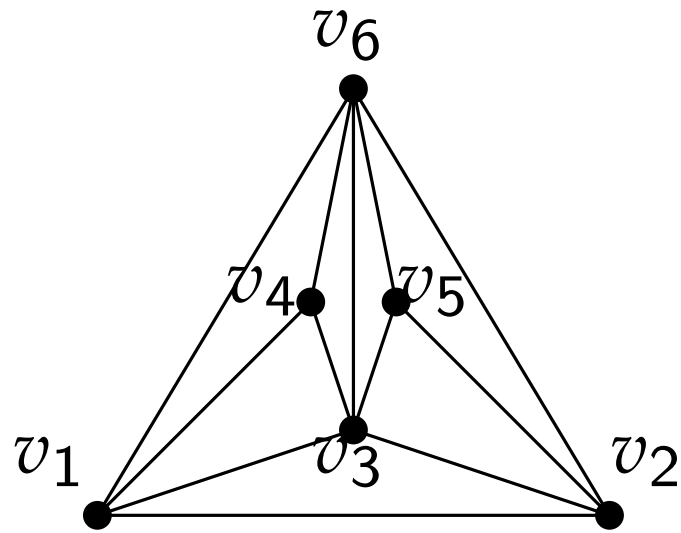
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$$G_3: v_1 : (0, 0), v_2 : (2, 0), v_3 : (1, 1)$$

$$G_4: v_1 : (0, 0), v_2 : (3, 0), v_3 : (2, 1), v_4 : (1, 2)$$

Constraints



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G_{k-1} is drawn such that

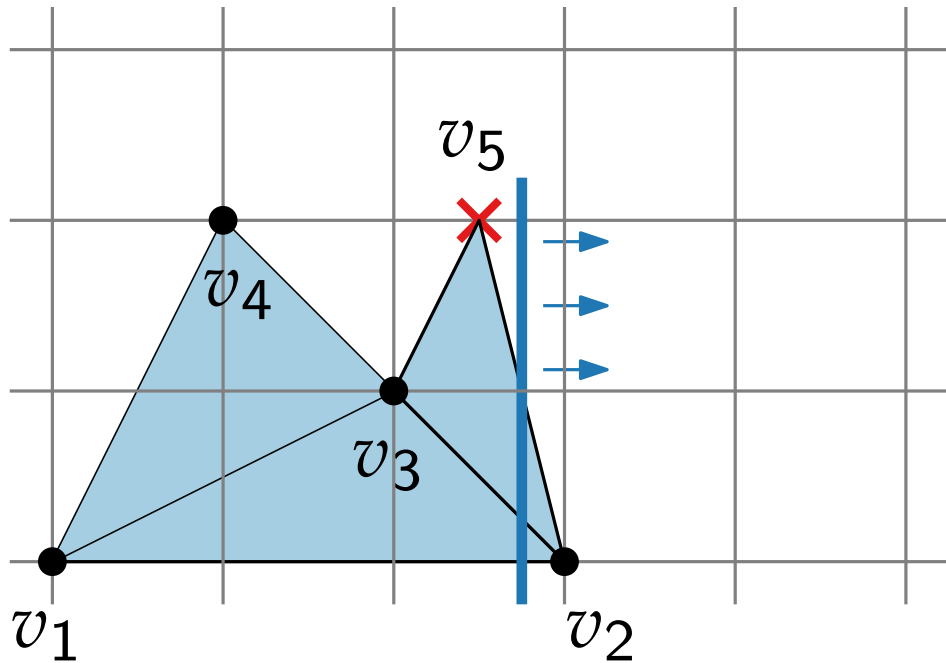
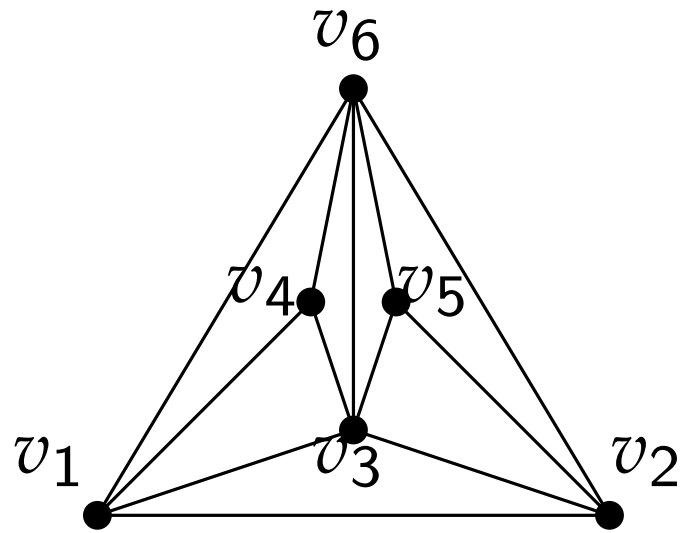
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$$G_3: v_1 : (0, 0), v_2 : (\cancel{2}, \cancel{0}), v_3 : (\cancel{1}, \cancel{1})$$

$$G_4: v_1 : (0, 0), v_2 : (3, 0), v_3 : (2, 1), v_4 : (1, 2)$$

Constraints



Constraints:

G_{k-1} is drawn such that

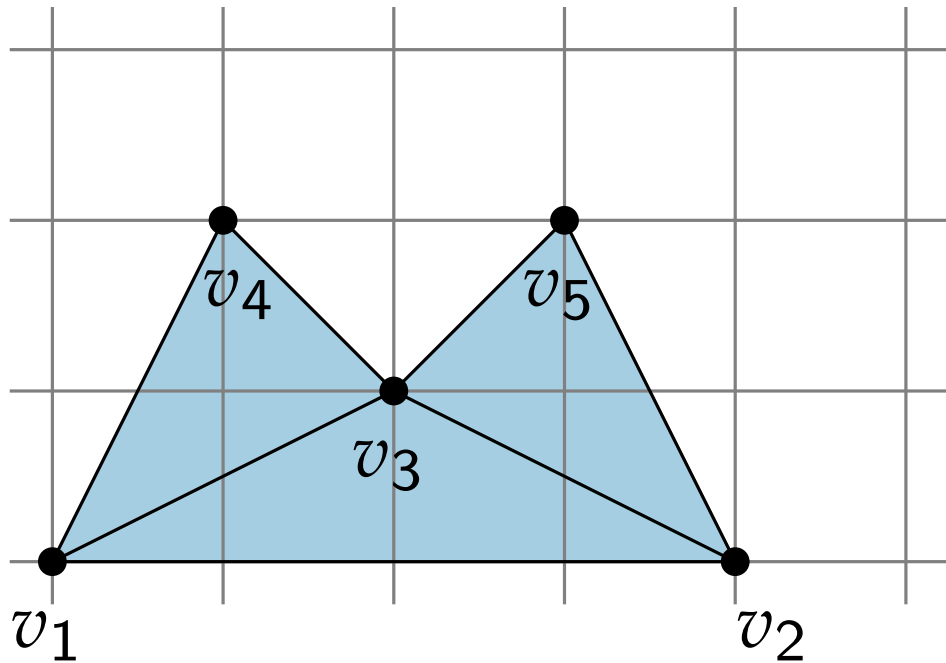
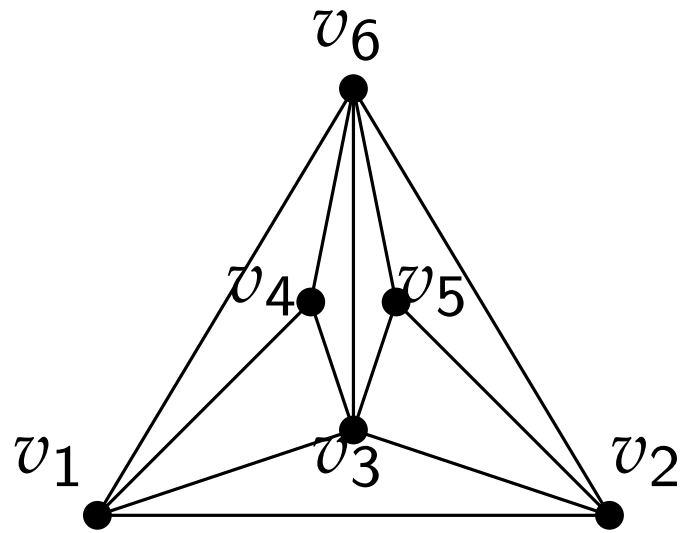
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G_3 : $v_1 : (0, 0)$, $v_2 : (2, 0)$, $v_3 : (1, 1)$

G_4 : $v_1 : (0, 0)$, $v_2 : (3, 0)$, $v_3 : (2, 1)$, $v_4 : (1, 2)$

Constraints



Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
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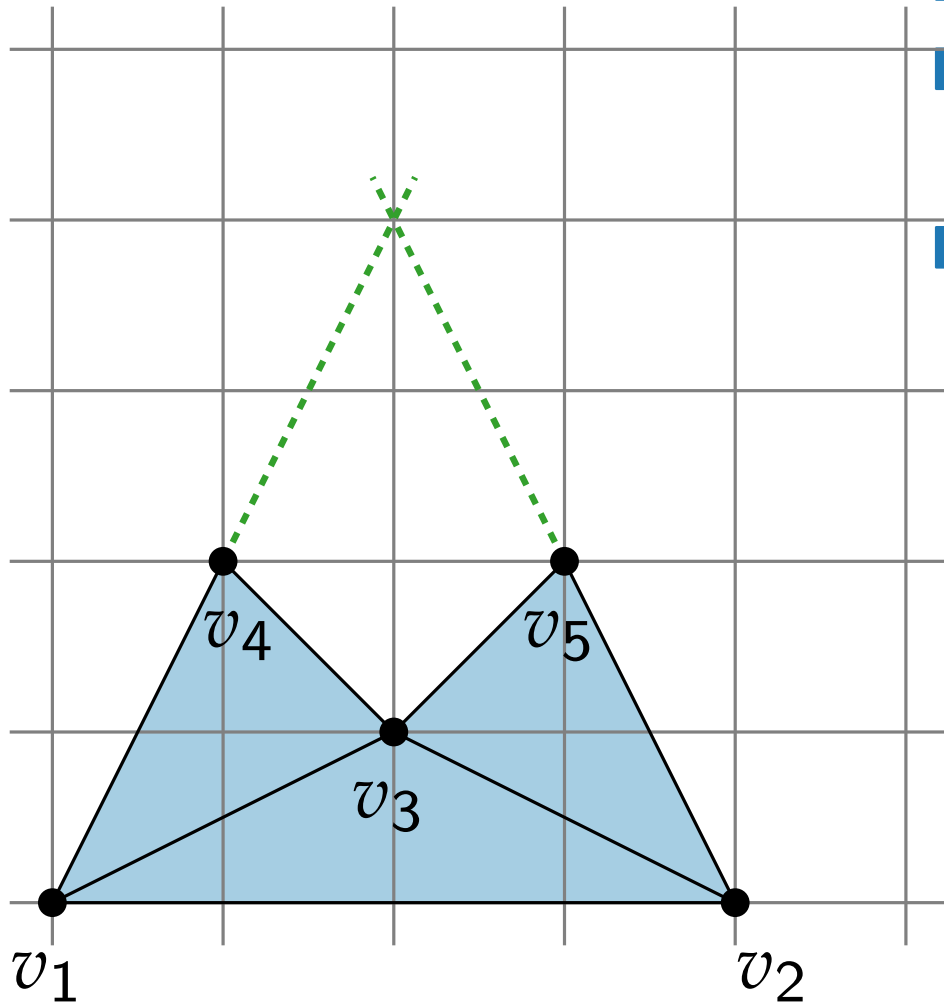
$G_5: v_1 : (0, 0), v_2 : (4, 0), v_3 : (2, 1), v_4 : (1, 2), v_5 : (3, 2)$

Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
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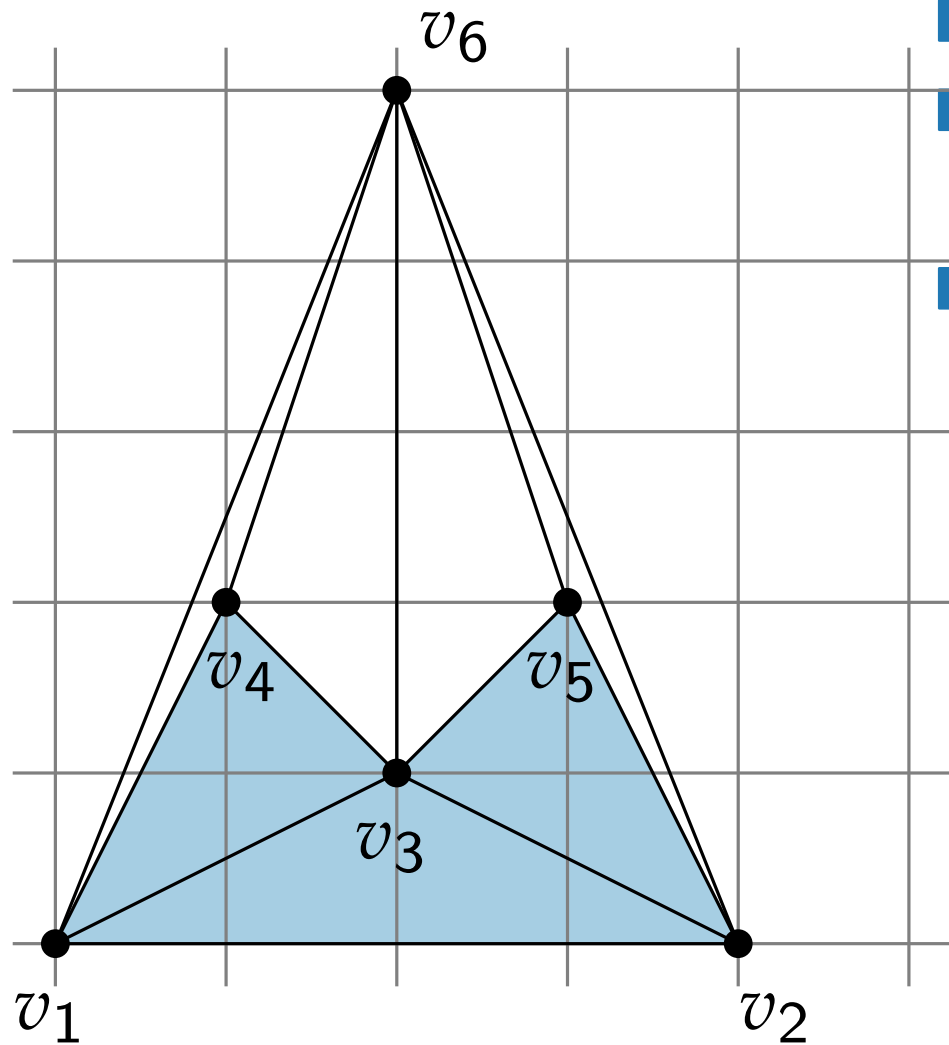
$$G_2: v_1 : (0, 0), v_2 : (1, 0)$$

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$$G_4: v_1 : (0, 0), v_2 : (3, 0), v_3 : (2, 1), v_4 : (1, 2)$$

$$G_5: v_1 : (0, 0), v_2 : (4, 0), v_3 : (2, 1), v_4 : (1, 2), v_5 : (3, 2)$$

Constraints



Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
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- v_k is placed above its neighbors on G_{k-1} .

$G_2: v_1 : (0, 0), v_2 : (1, 0)$

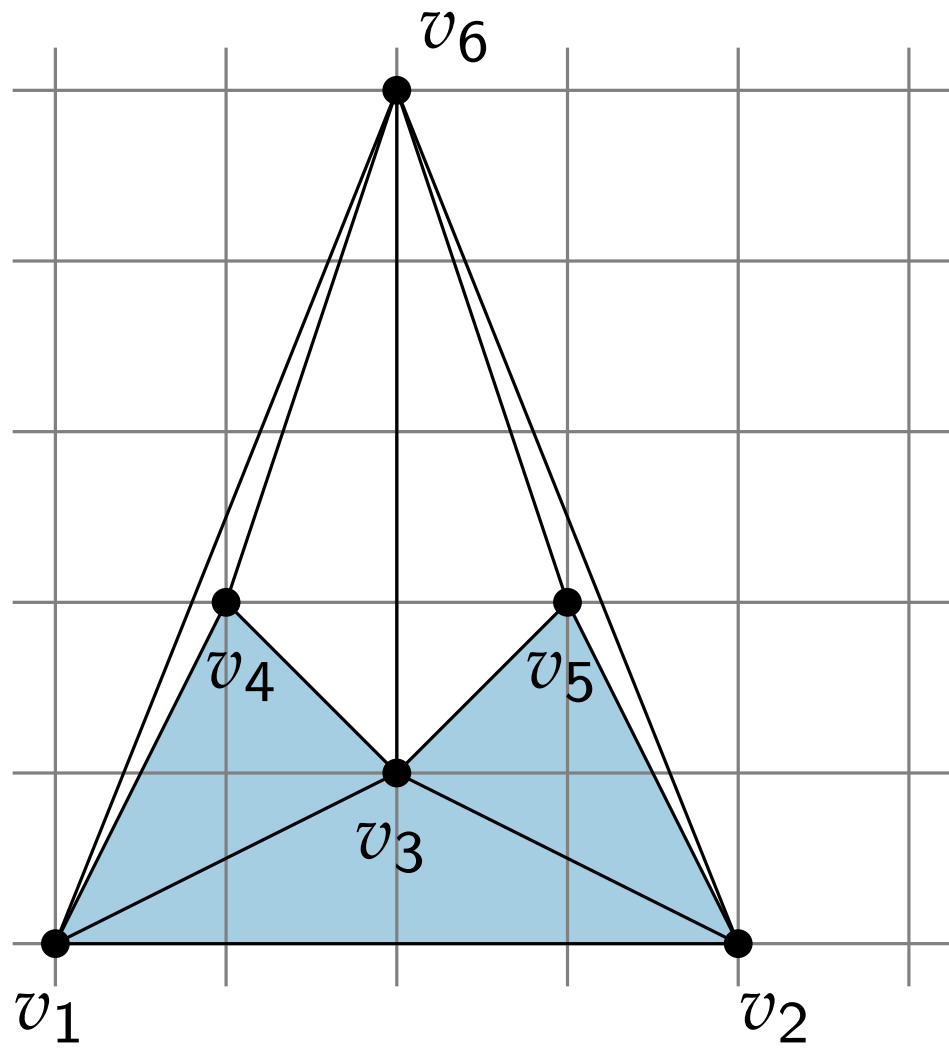
$G_3: v_1 : (0, 0), v_2 : (2, 0), v_3 : (1, 1)$

$G_4: v_1 : (0, 0), v_2 : (3, 0), v_3 : (2, 1), v_4 : (1, 2)$

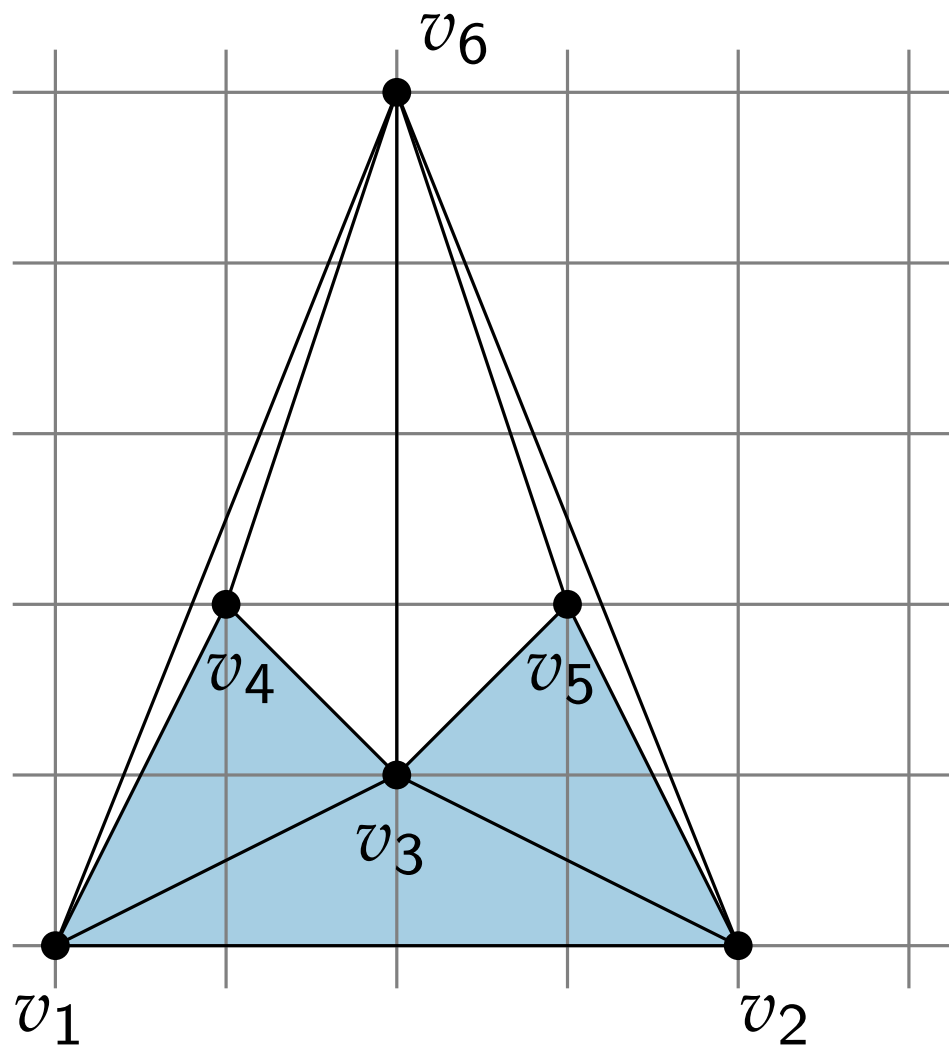
$G_5: v_1 : (0, 0), v_2 : (4, 0), v_3 : (2, 1), v_4 : (1, 2), v_5 : (3, 2)$

$G: v_6 : (2, 5)$

Height



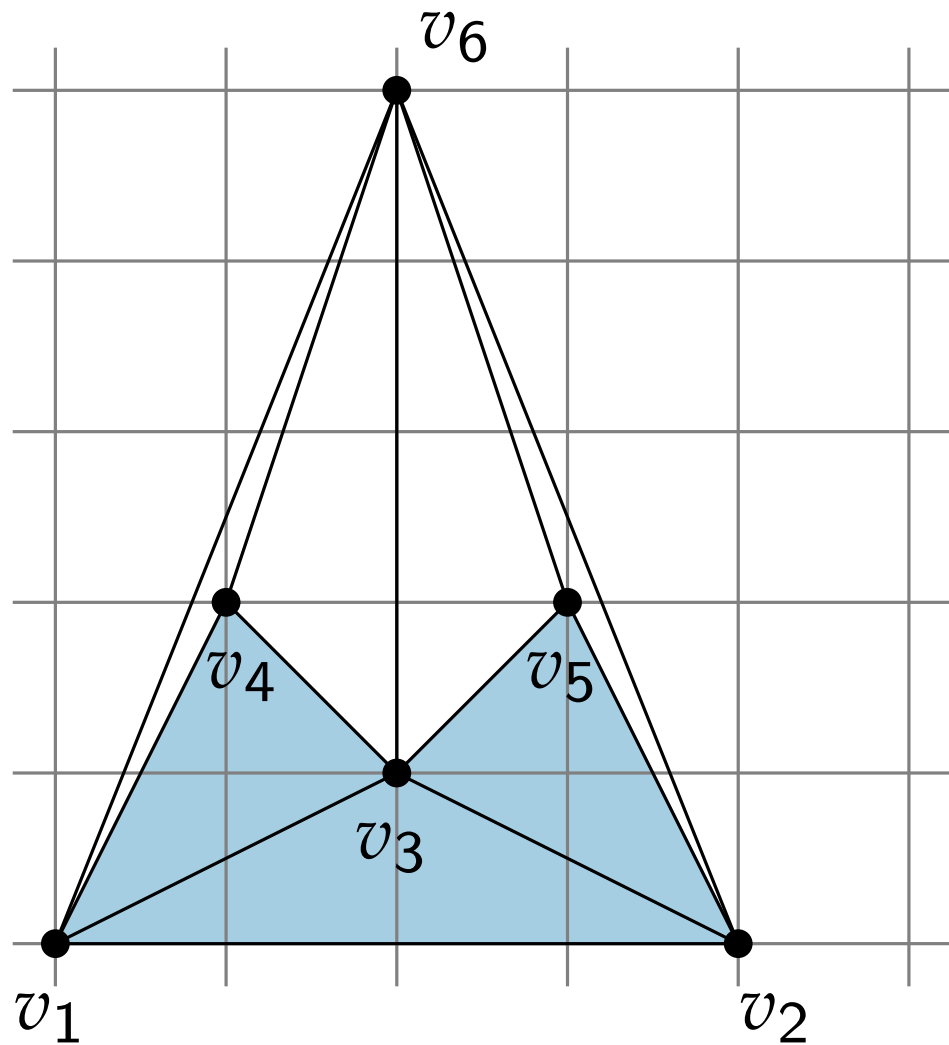
Height



Placement of v_6 depends on

- the **slope** of (v_1, v_4) , (v_2, v_5)
- and the length of (v_1, v_2)
(which is at most $n - 2$)

Height

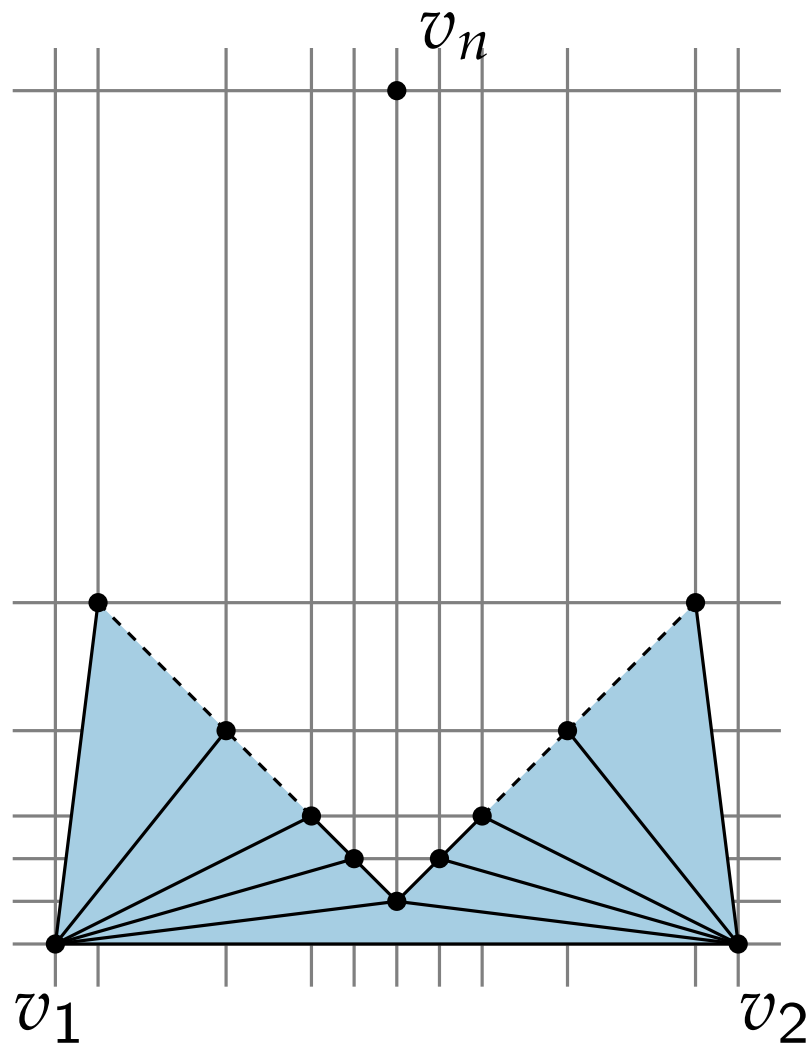


Placement of v_6 depends on

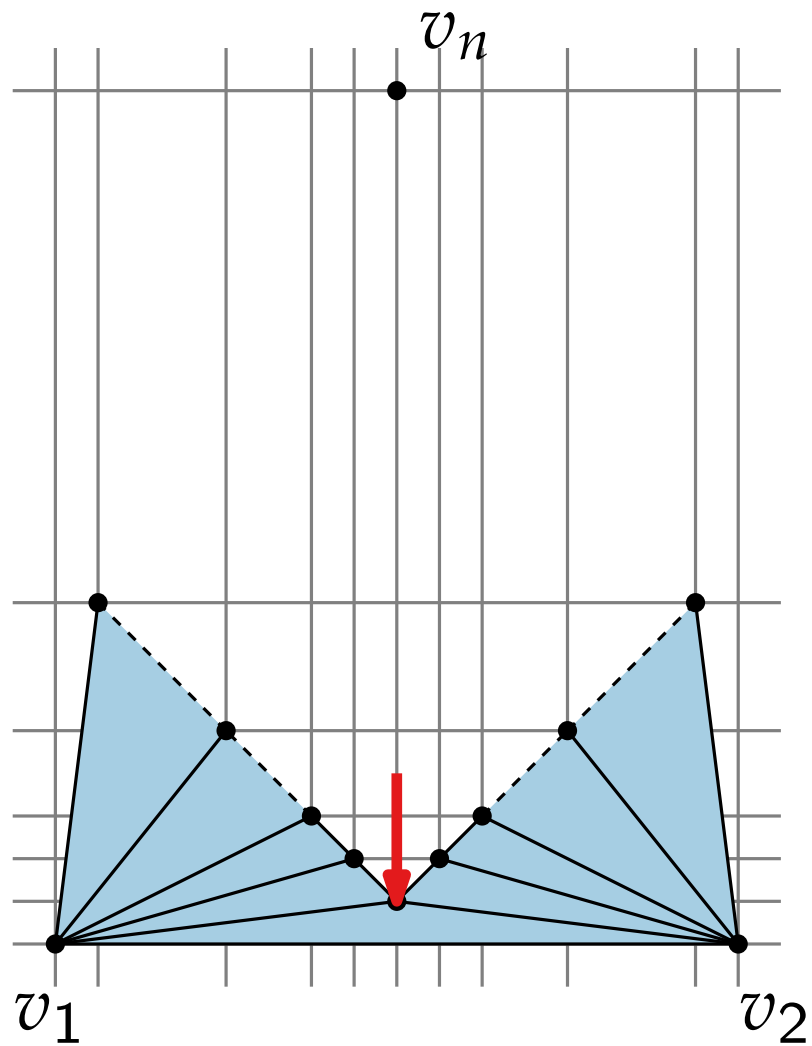
- the **slope** of (v_1, v_4) , (v_2, v_5)
- and the length of (v_1, v_2)
(which is at most $n - 2$)

Can the **height** exceed $\mathcal{O}(n)$?

Height

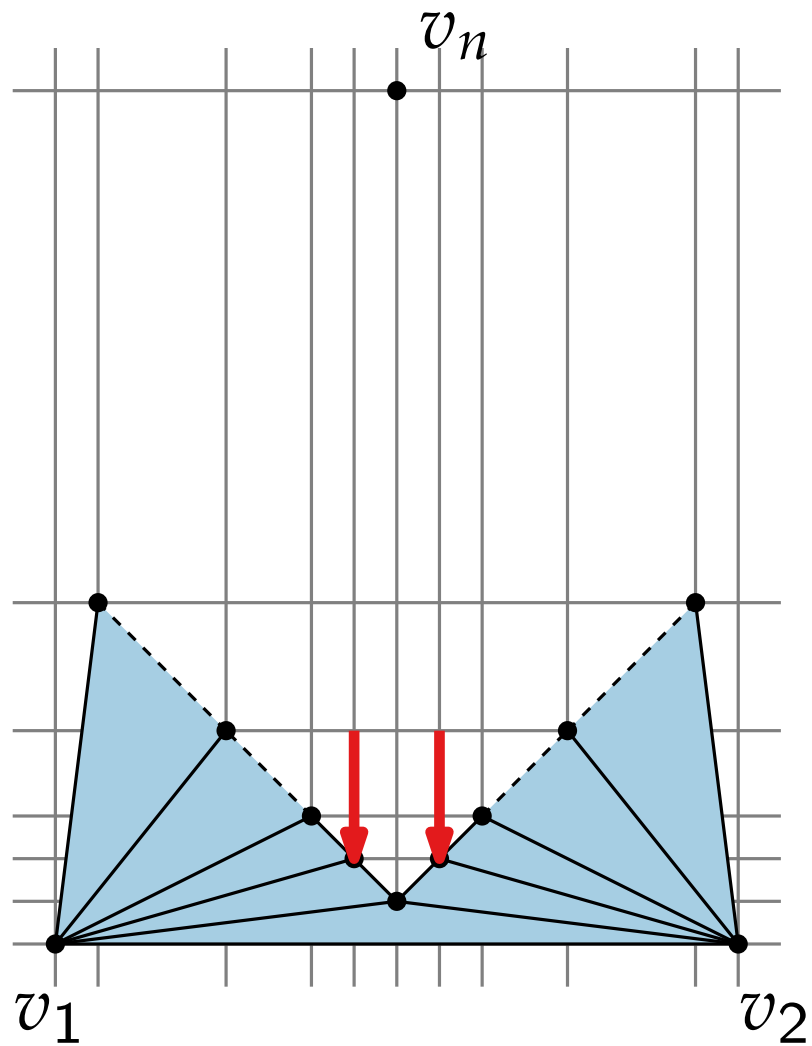


Height



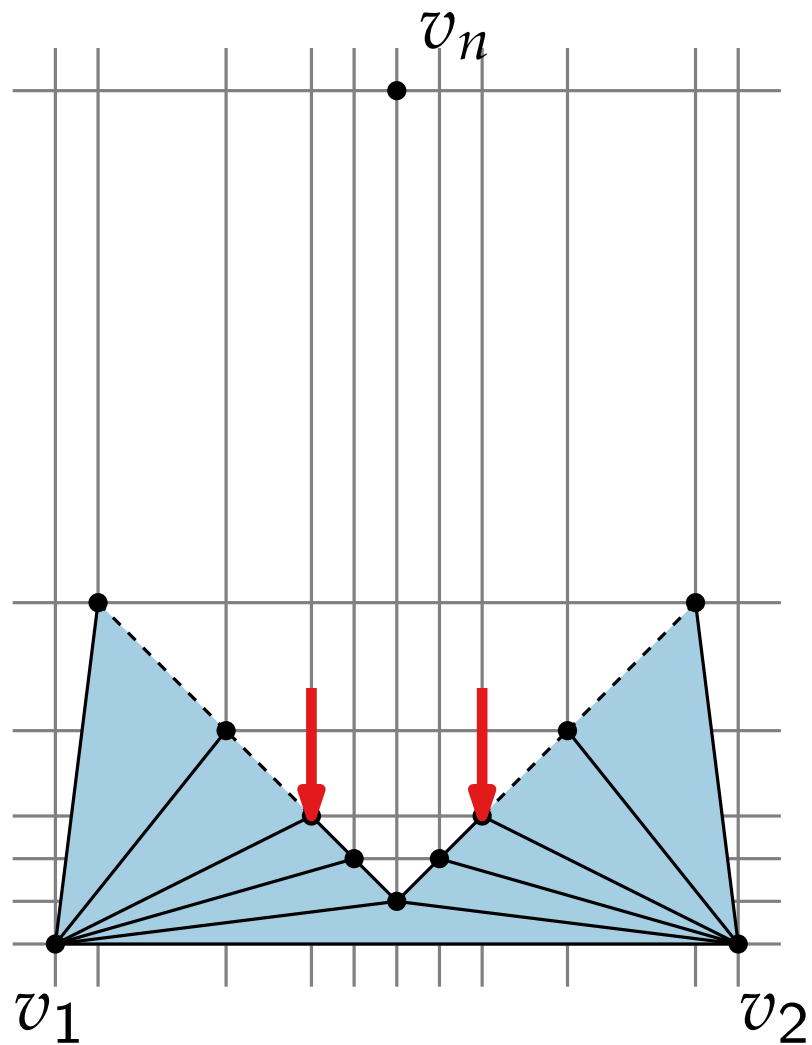
■ v_3 at height 1

Height



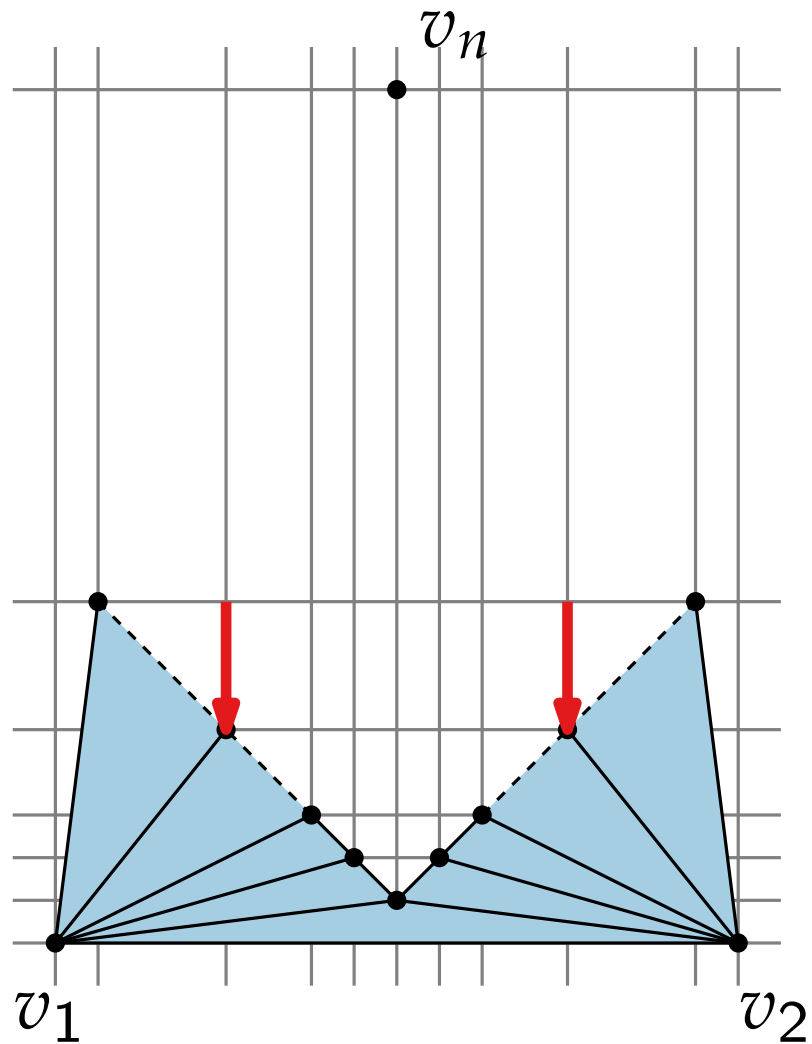
- v_3 at height 1
- v_4, v_5 at height 2

Height



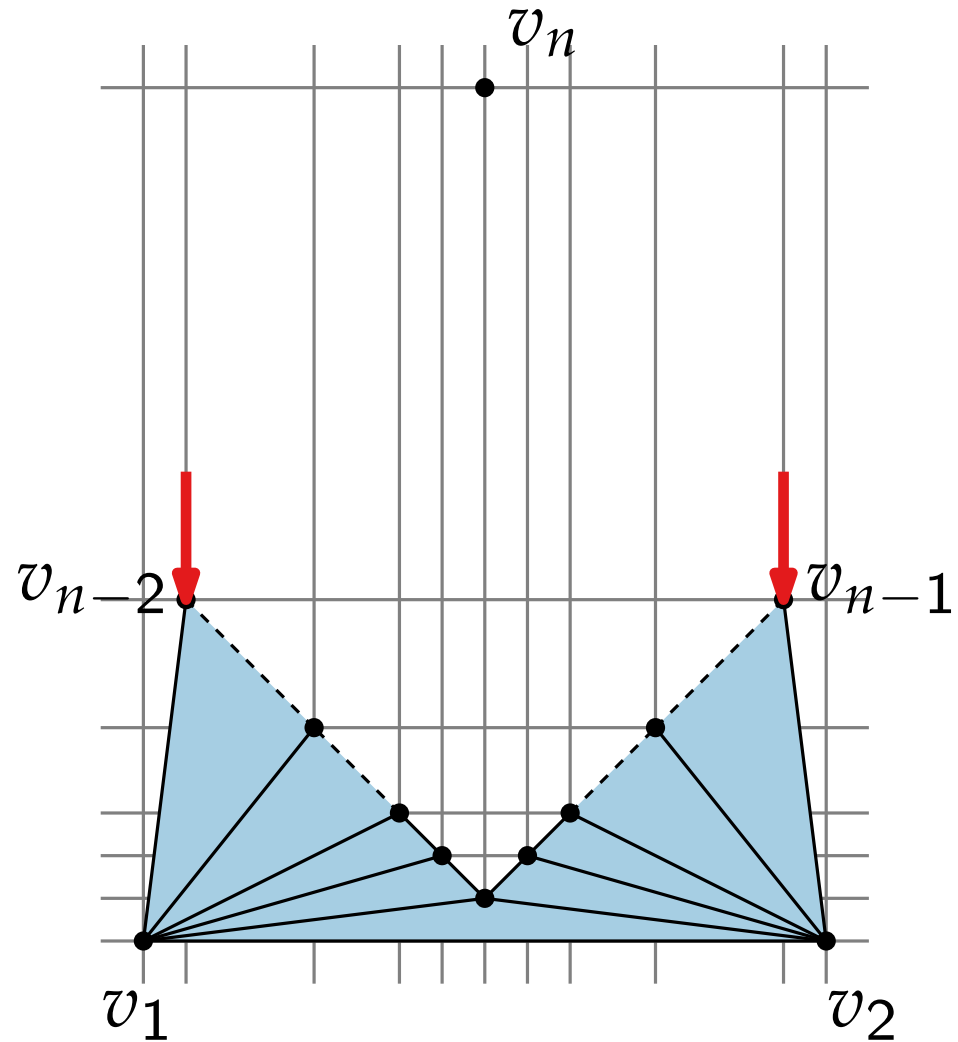
- v_3 at height 1
- v_4, v_5 at height 2
- v_6, v_7 at height 3

Height



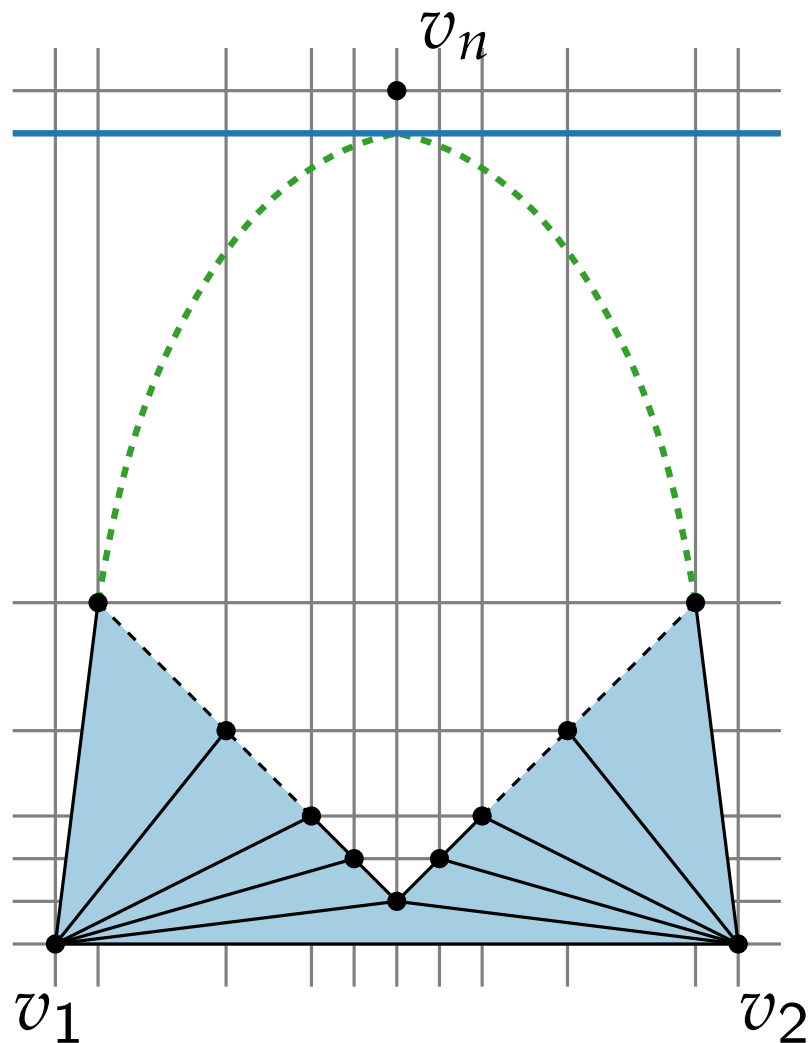
- v_3 at height 1
- v_4, v_5 at height 2
- v_6, v_7 at height 3
- v_{2i}, v_{2i+1} at height i

Height



- v_3 at height 1
- v_4, v_5 at height 2
- v_6, v_7 at height 3
- v_{2i}, v_{2i+1} at height i
- v_{n-2}, v_{n-1} at height $\frac{n-2}{2}$

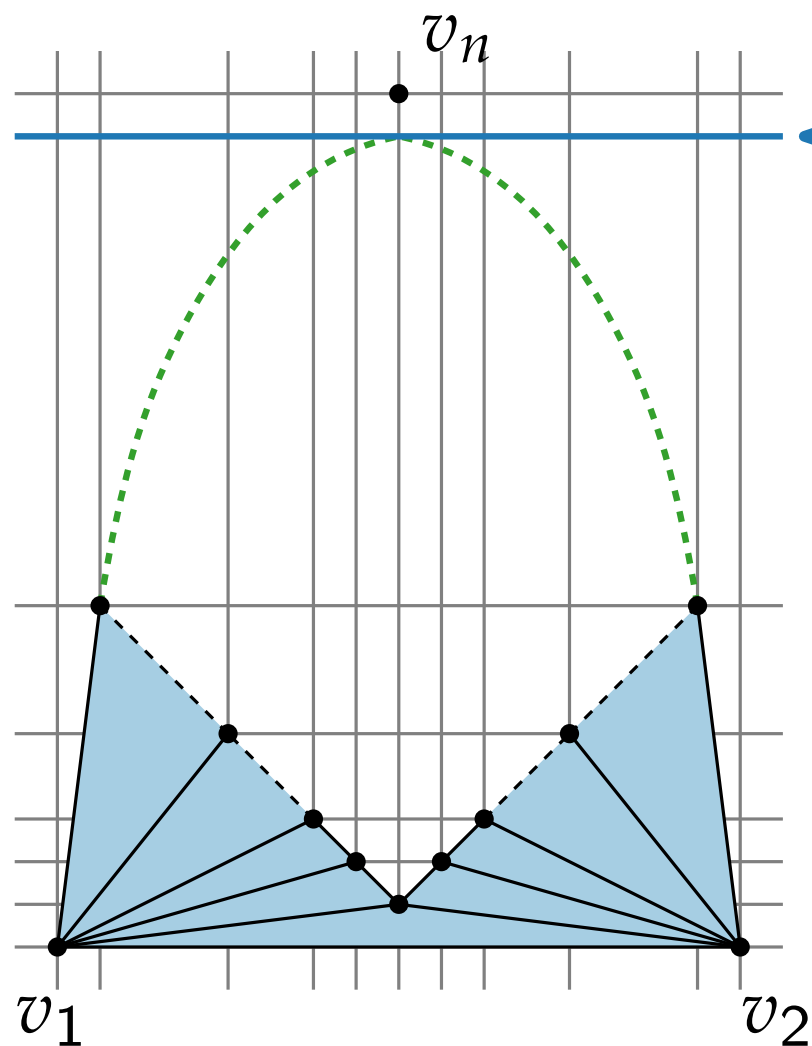
Height



- Slope for $(v_1, v_{n-2}) = \frac{n-2}{2}$
- Slope for $(v_2, v_{n-1}) = -\frac{n-2}{2}$
- Length of $(v_1, v_2) = n - 2$

- v_3 at height 1
- v_4, v_5 at height 2
- v_6, v_7 at height 3
- v_{2i}, v_{2i+1} at height i
- v_{n-2}, v_{n-1} at height $\frac{n-2}{2}$

Height

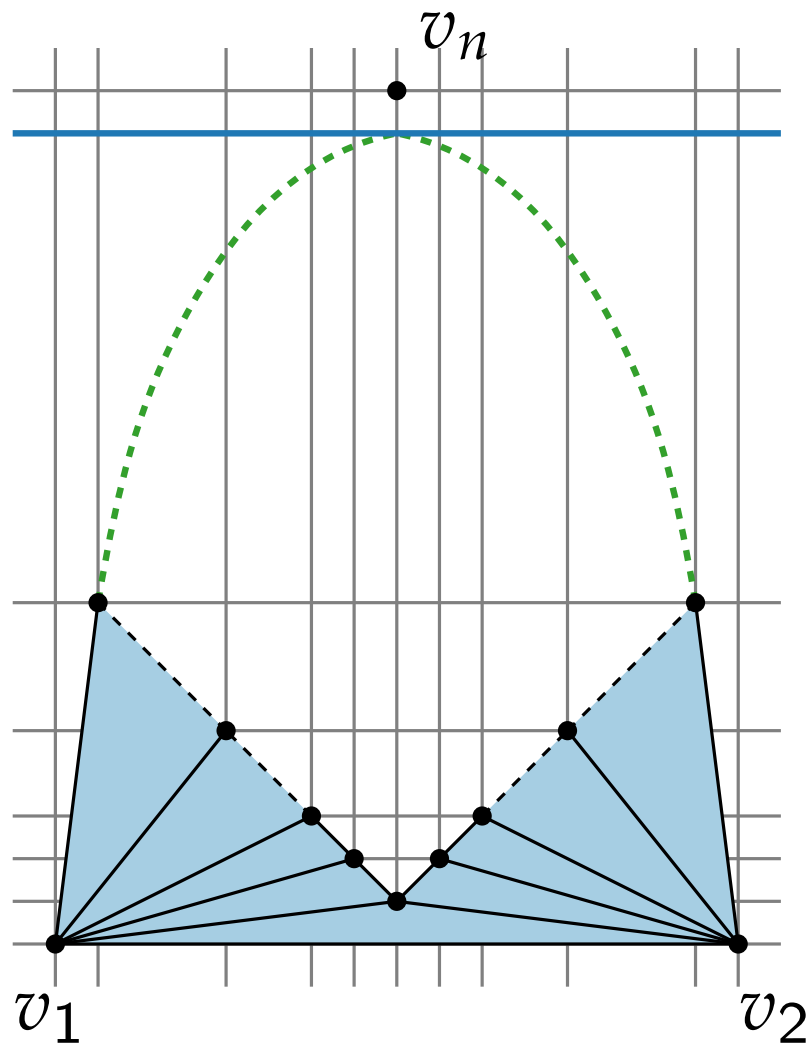


v_n above $\frac{(n-2)^2}{4}$

- Slope for $(v_1, v_{n-2}) = \frac{n-2}{2}$
- Slope for $(v_2, v_{n-1}) = -\frac{n-2}{2}$
- Length of $(v_1, v_2) = n - 2$

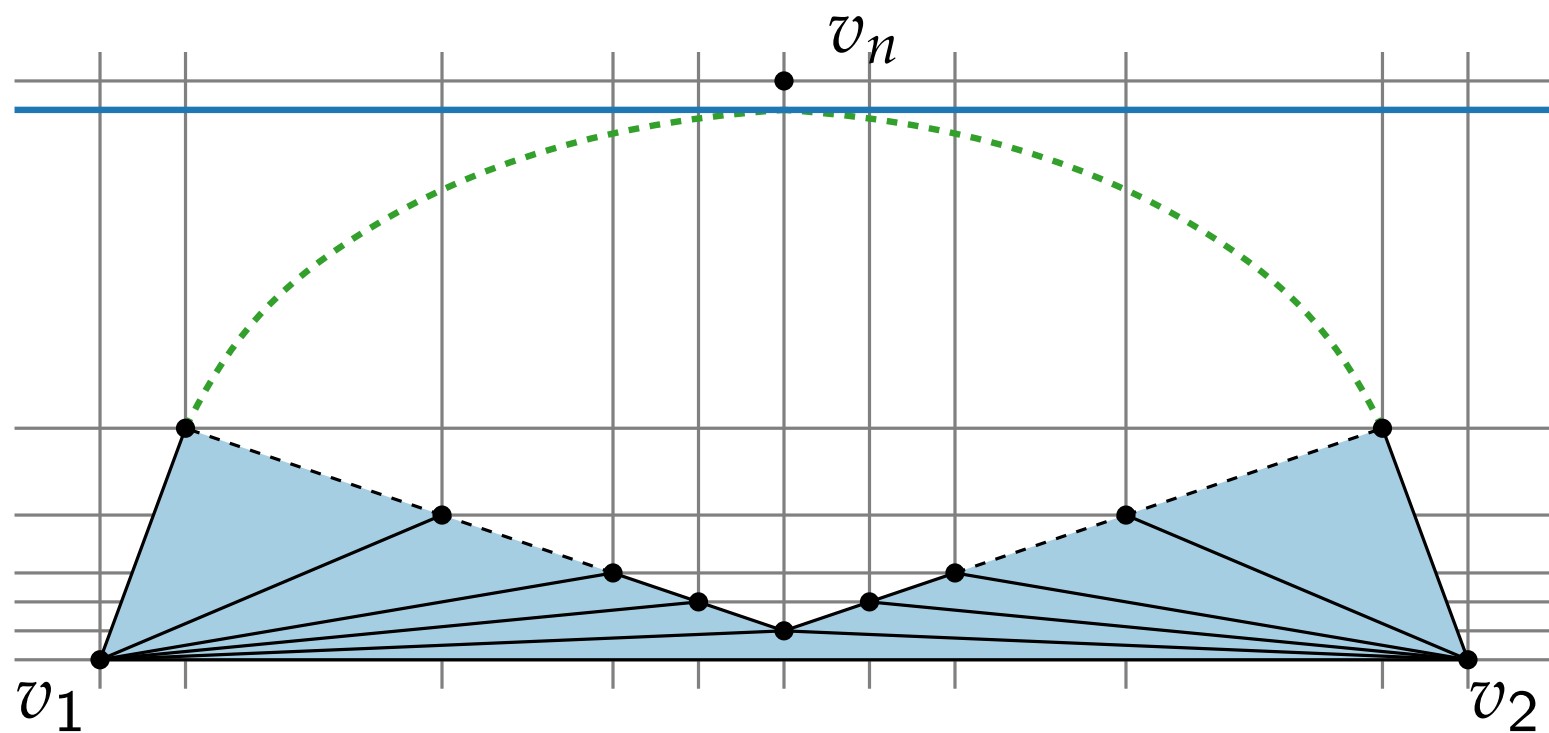
- v_3 at height 1
- v_4, v_5 at height 2
- v_6, v_7 at height 3
- v_{2i}, v_{2i+1} at height i
- v_{n-2}, v_{n-1} at height $\frac{n-2}{2}$

Height

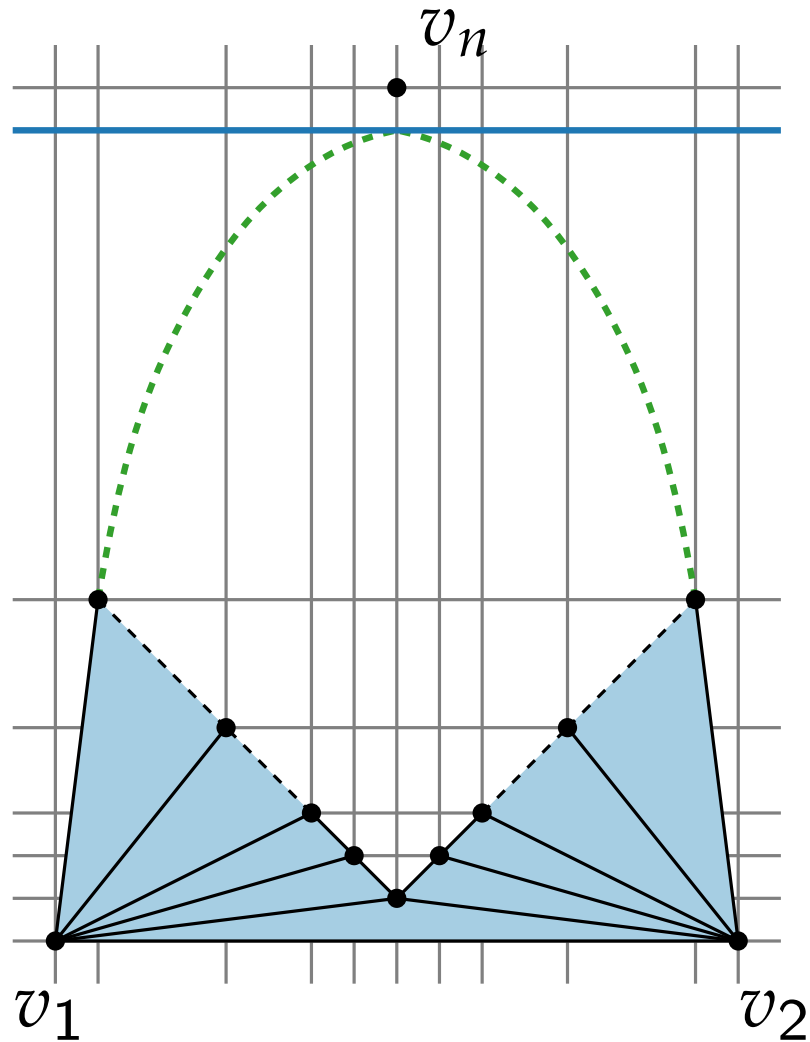


Stretching?

- decrease the height
- increase the width
- vertices on the grid?



Height



Stretching?

- decrease the height
- increase the width
- vertices on the grid?

Shifting

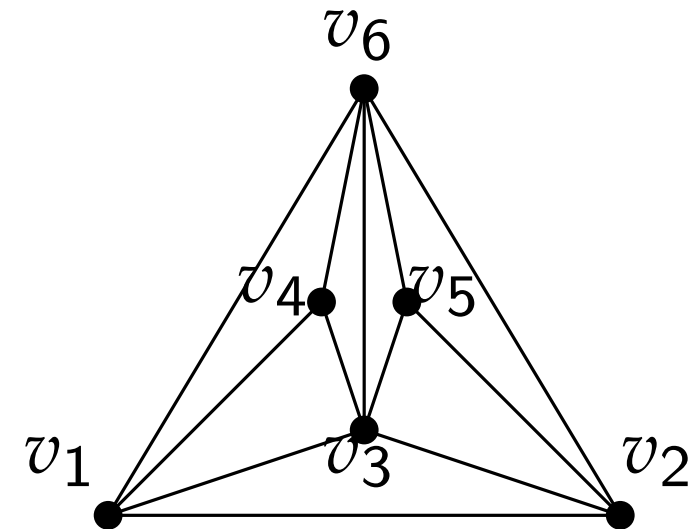
- control slopes
- additional shifting at each step

Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

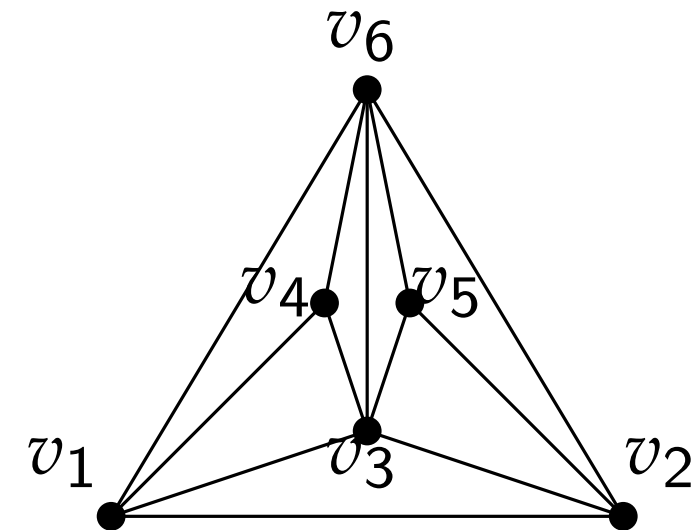
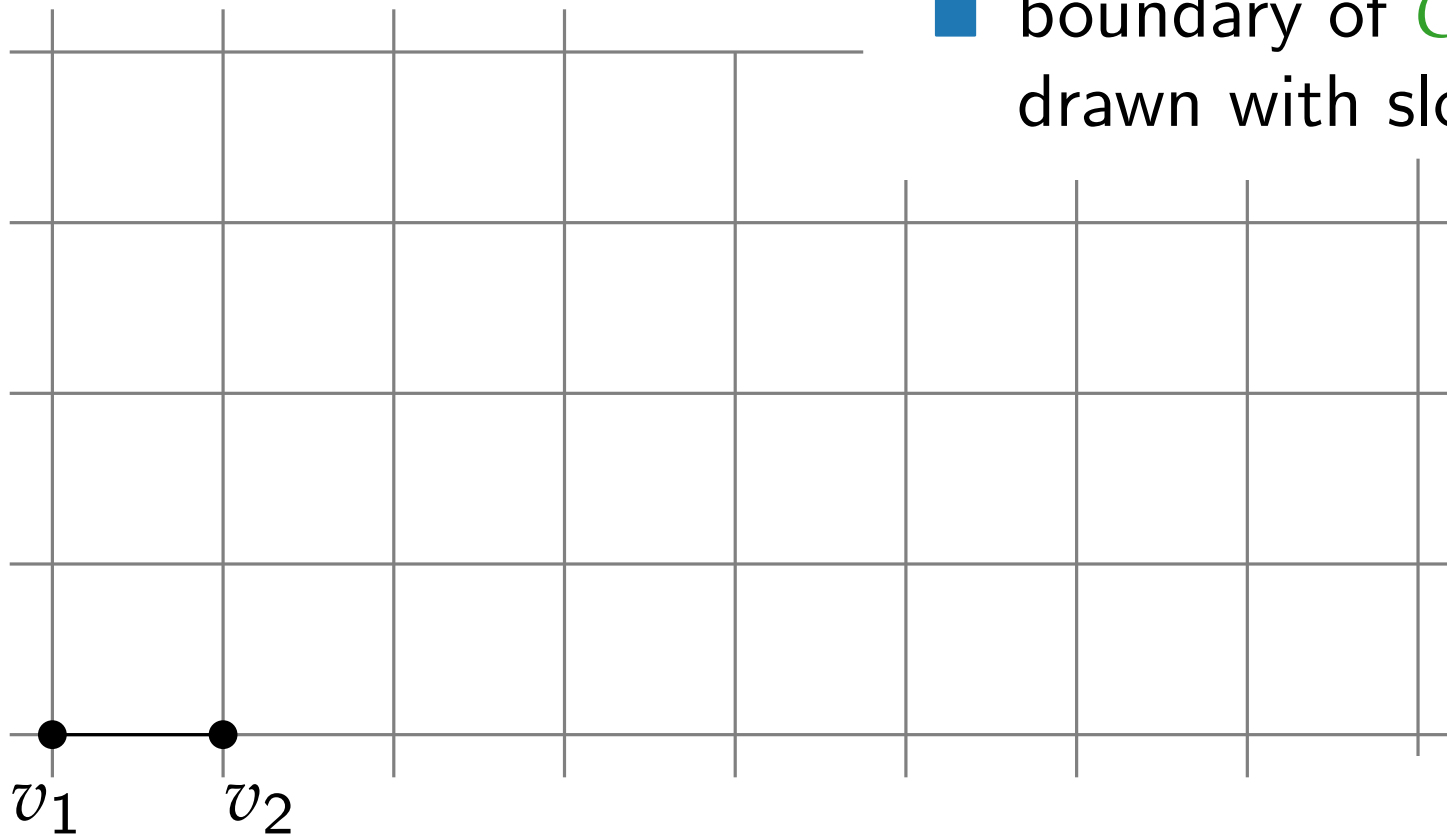


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
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- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

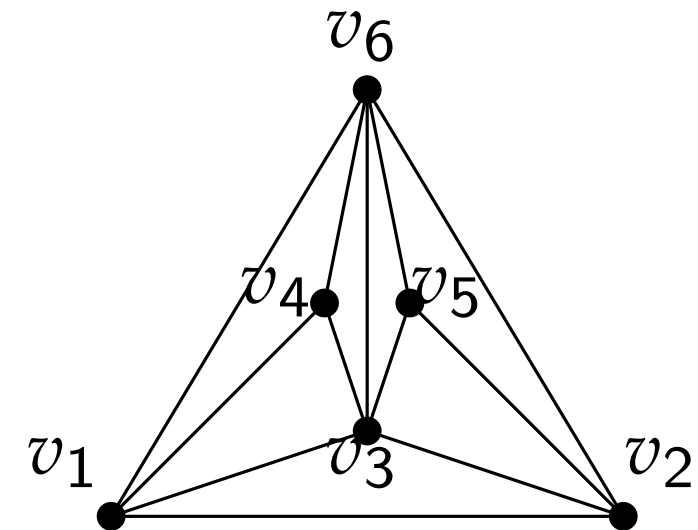
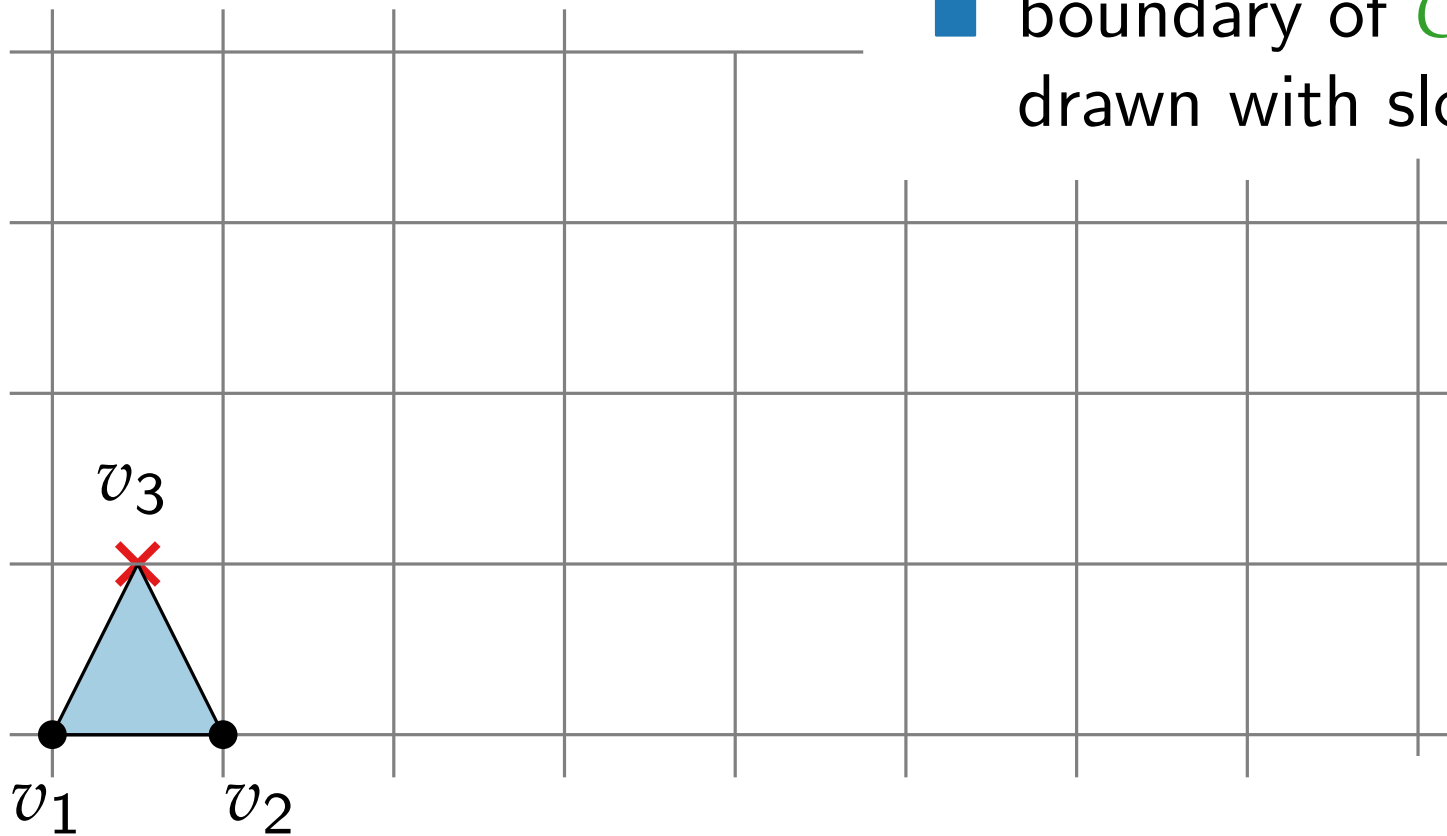


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

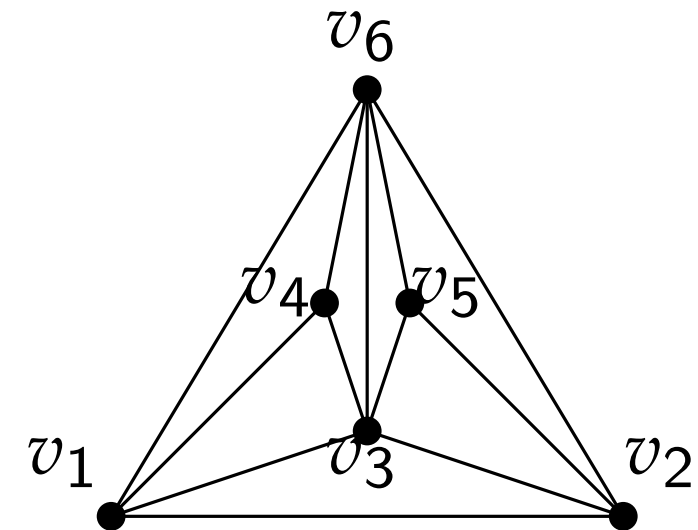
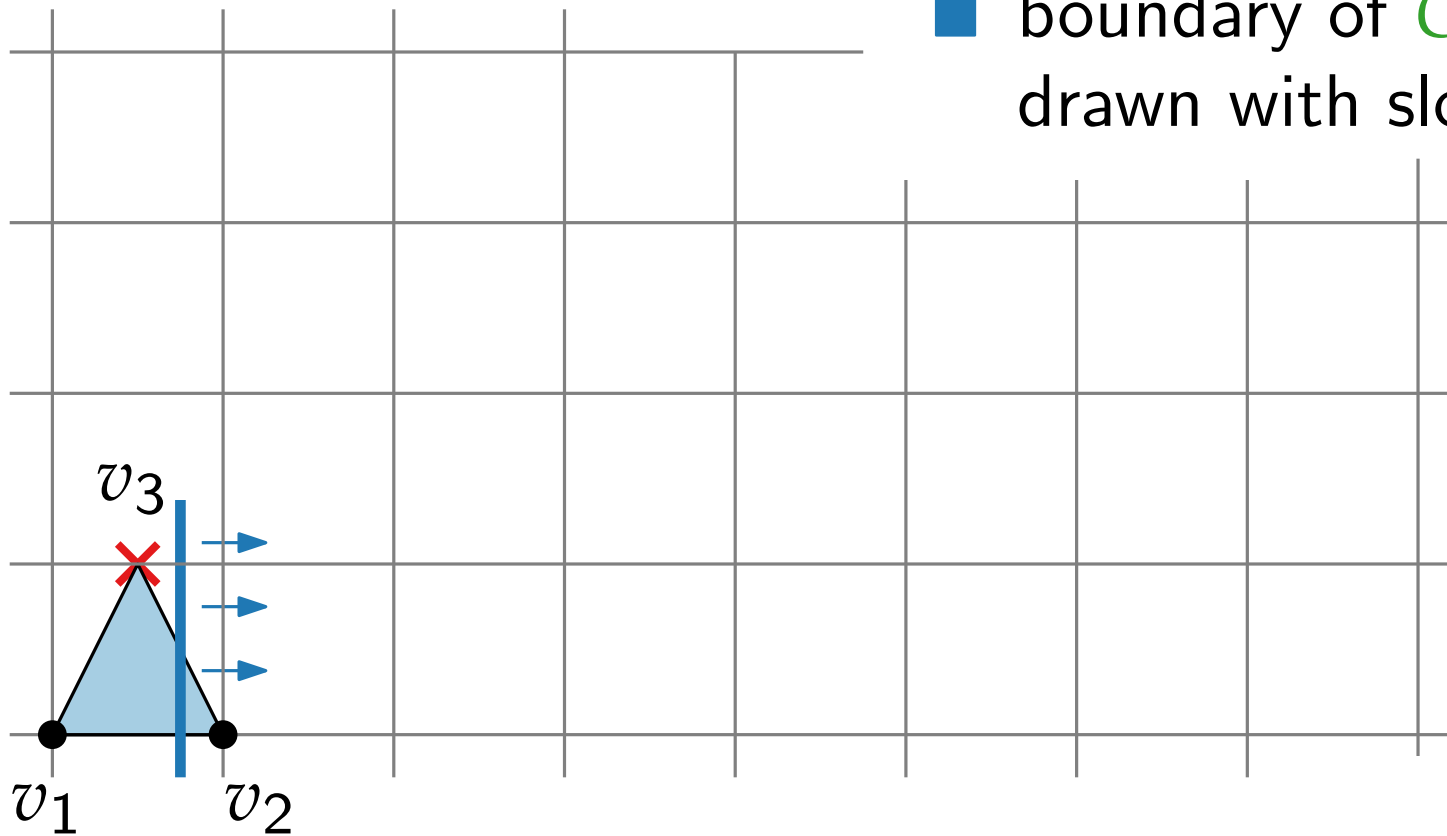


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

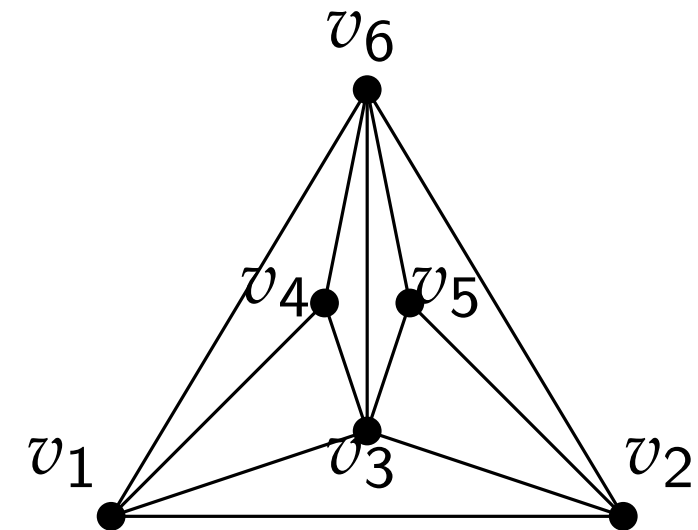
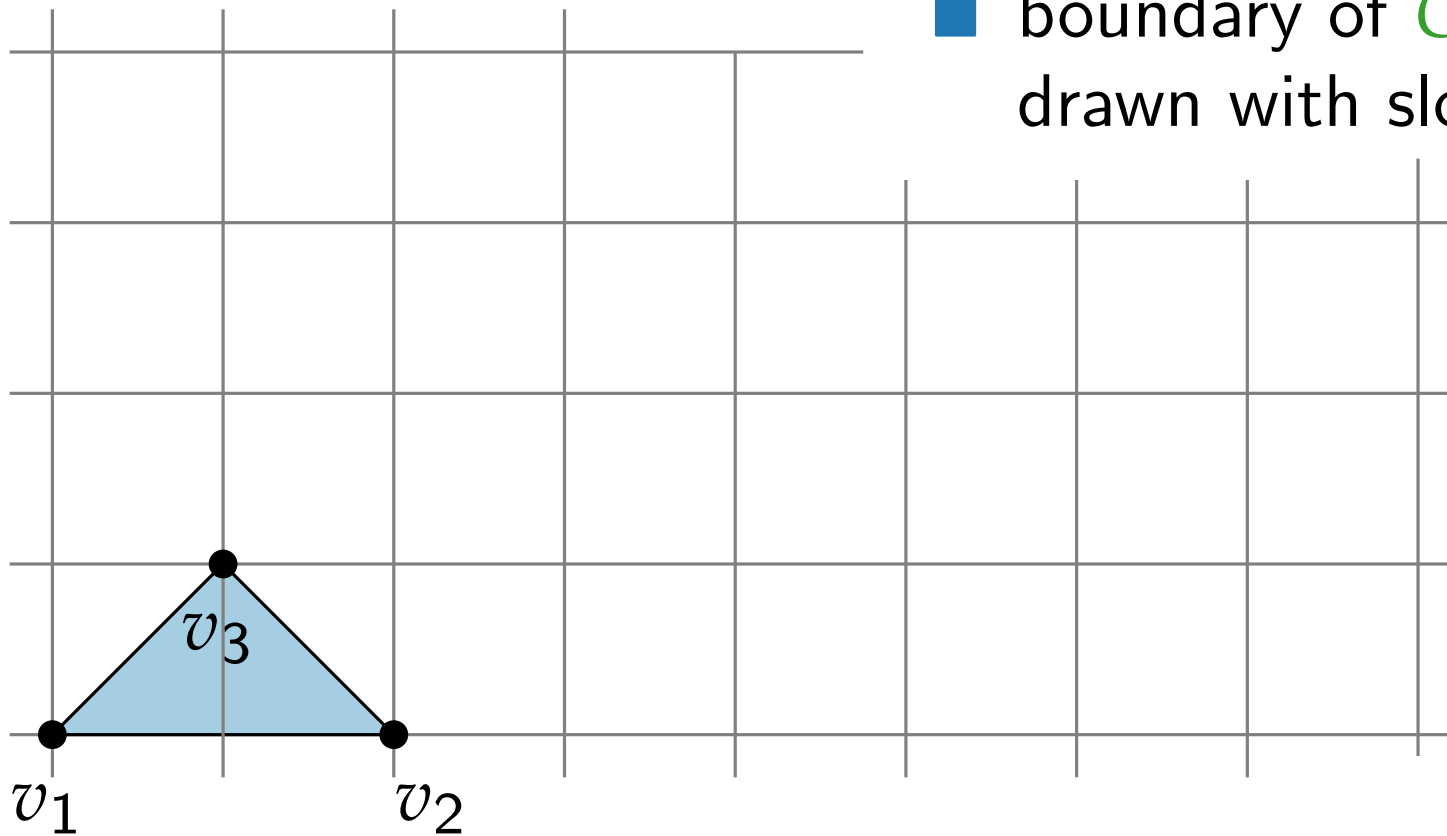


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

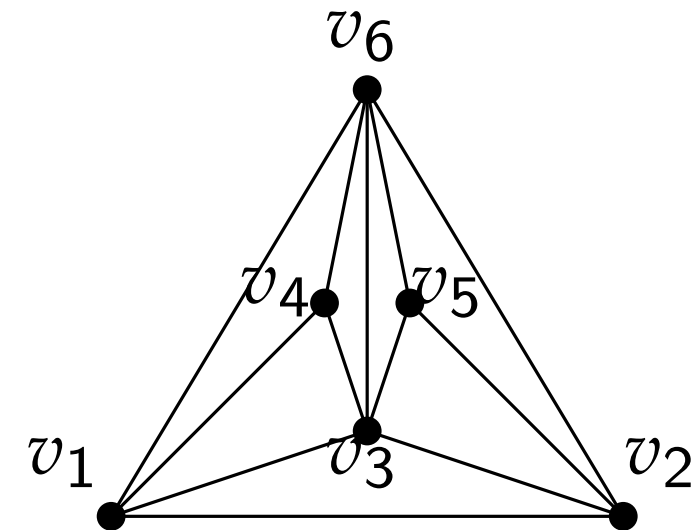
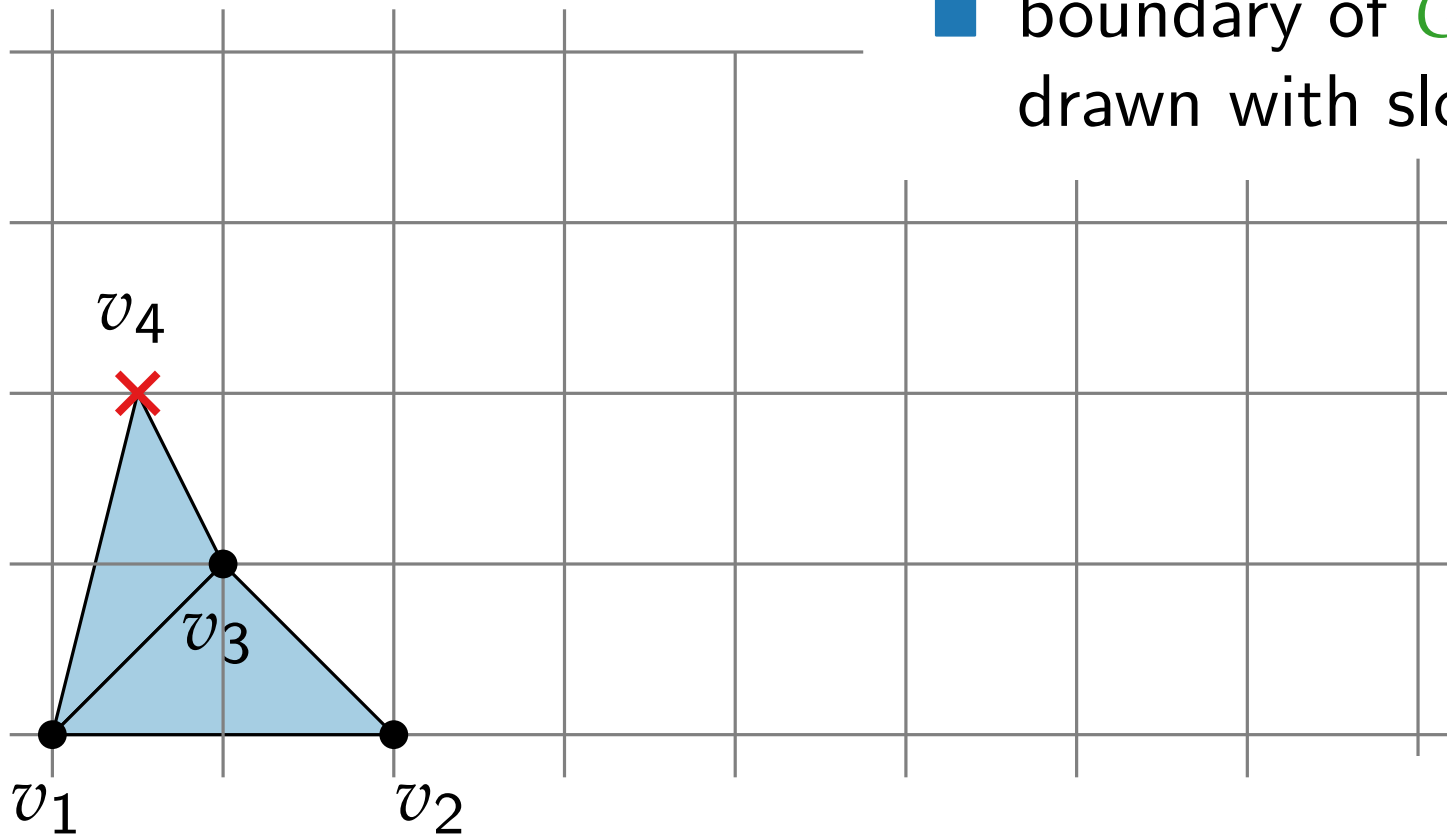


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

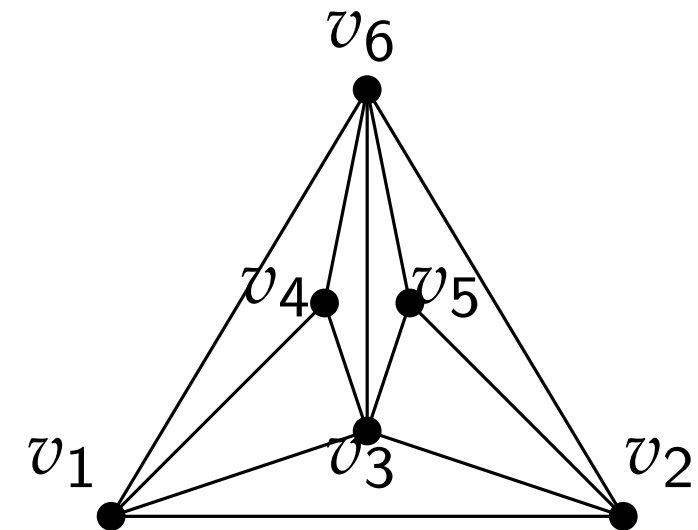
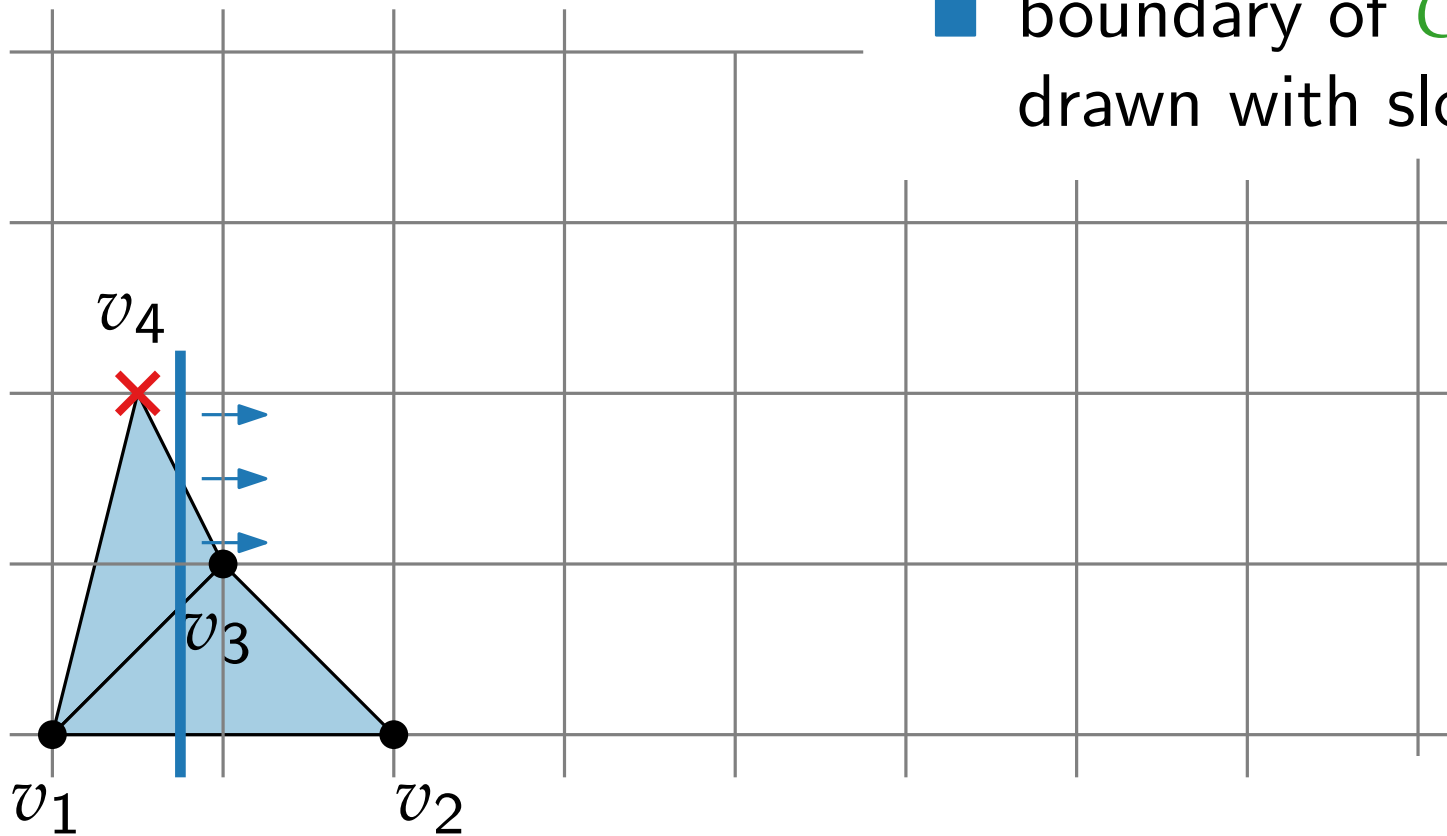


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

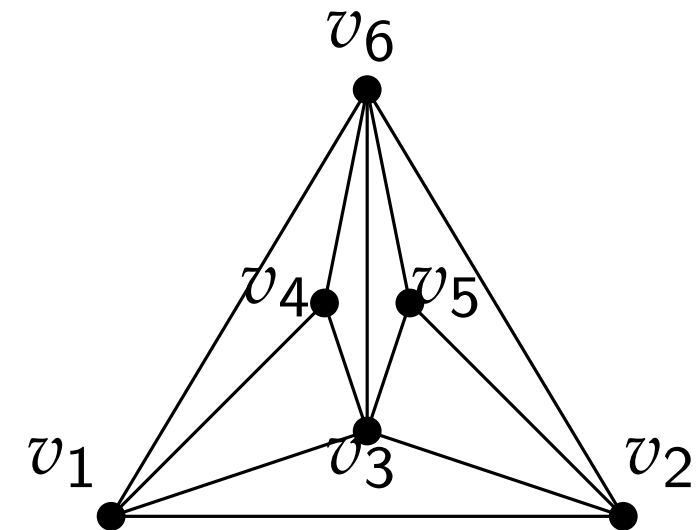
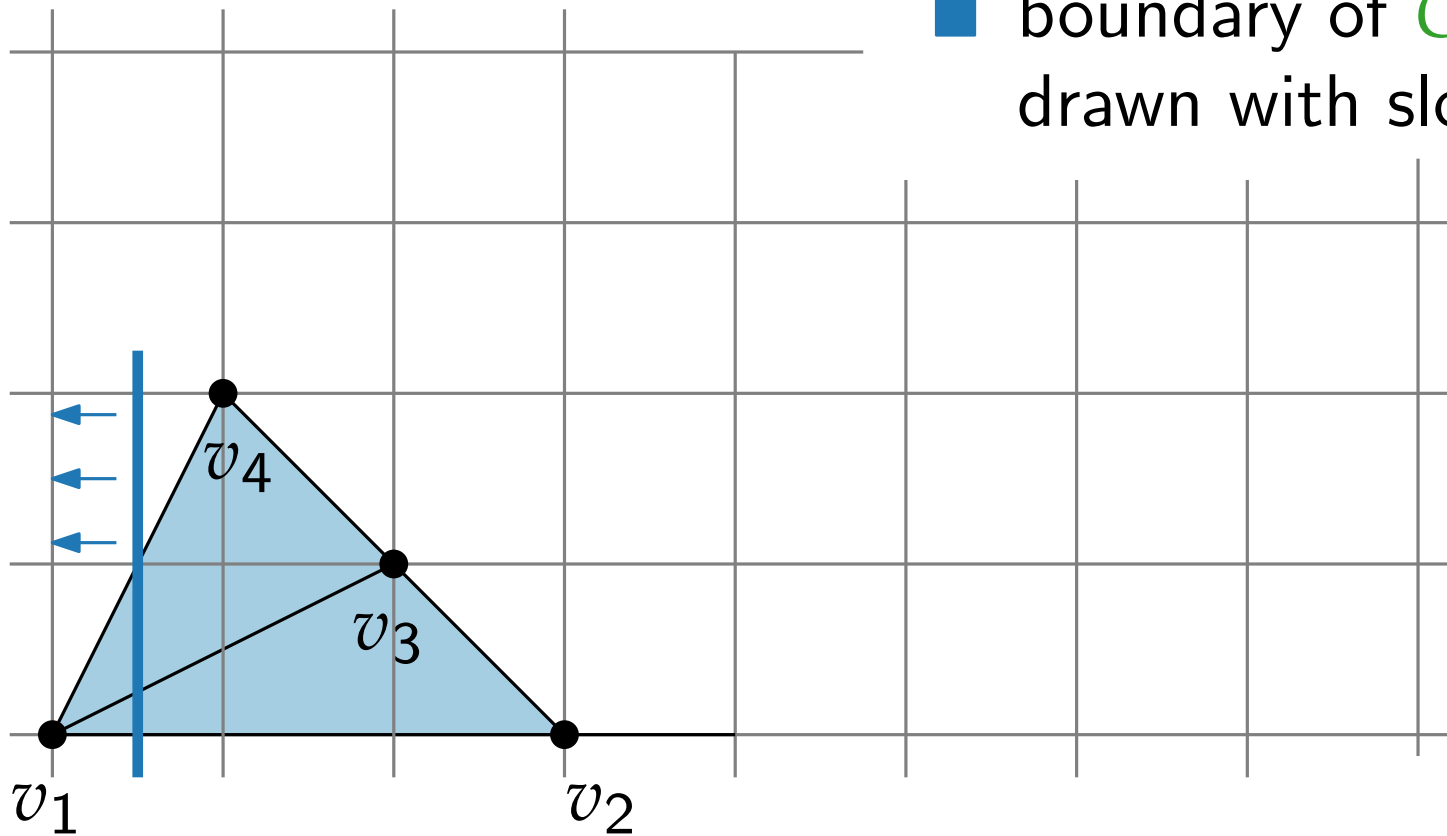


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

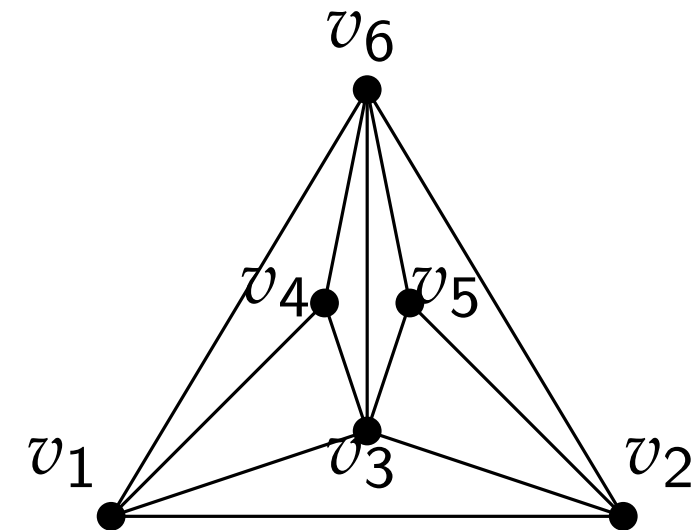
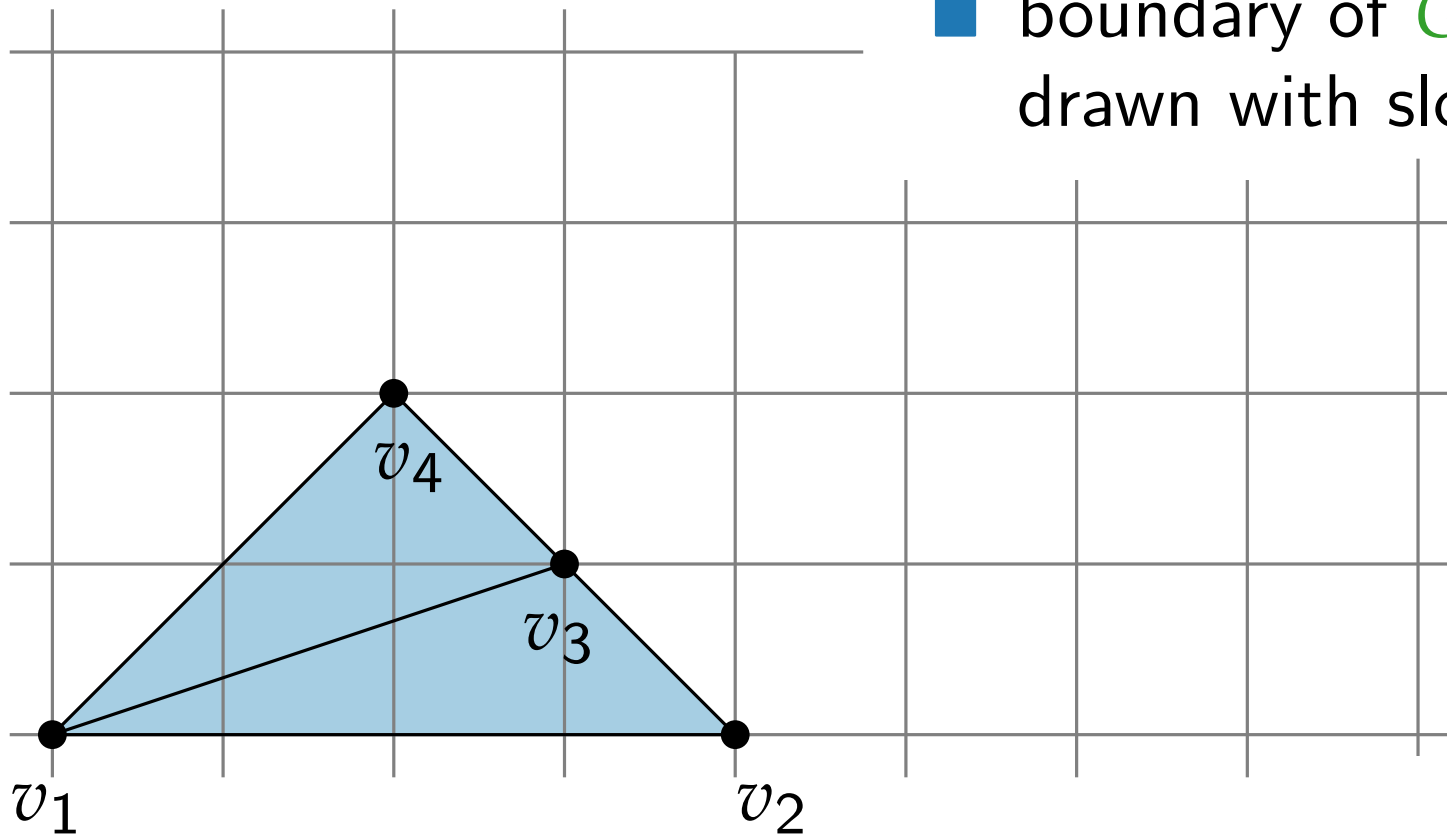


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

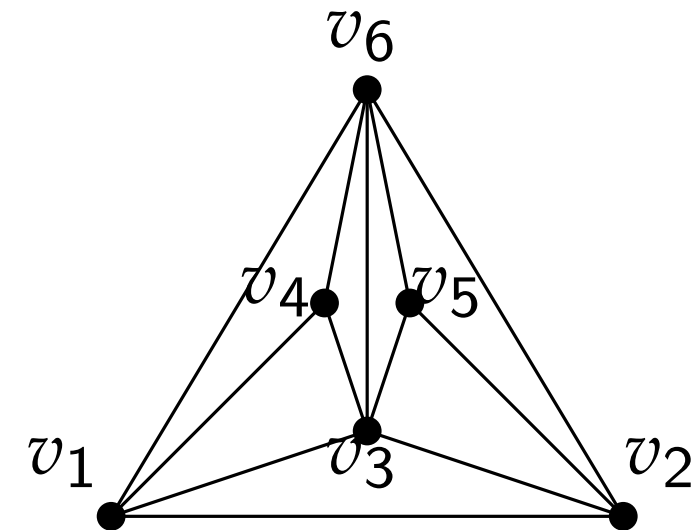
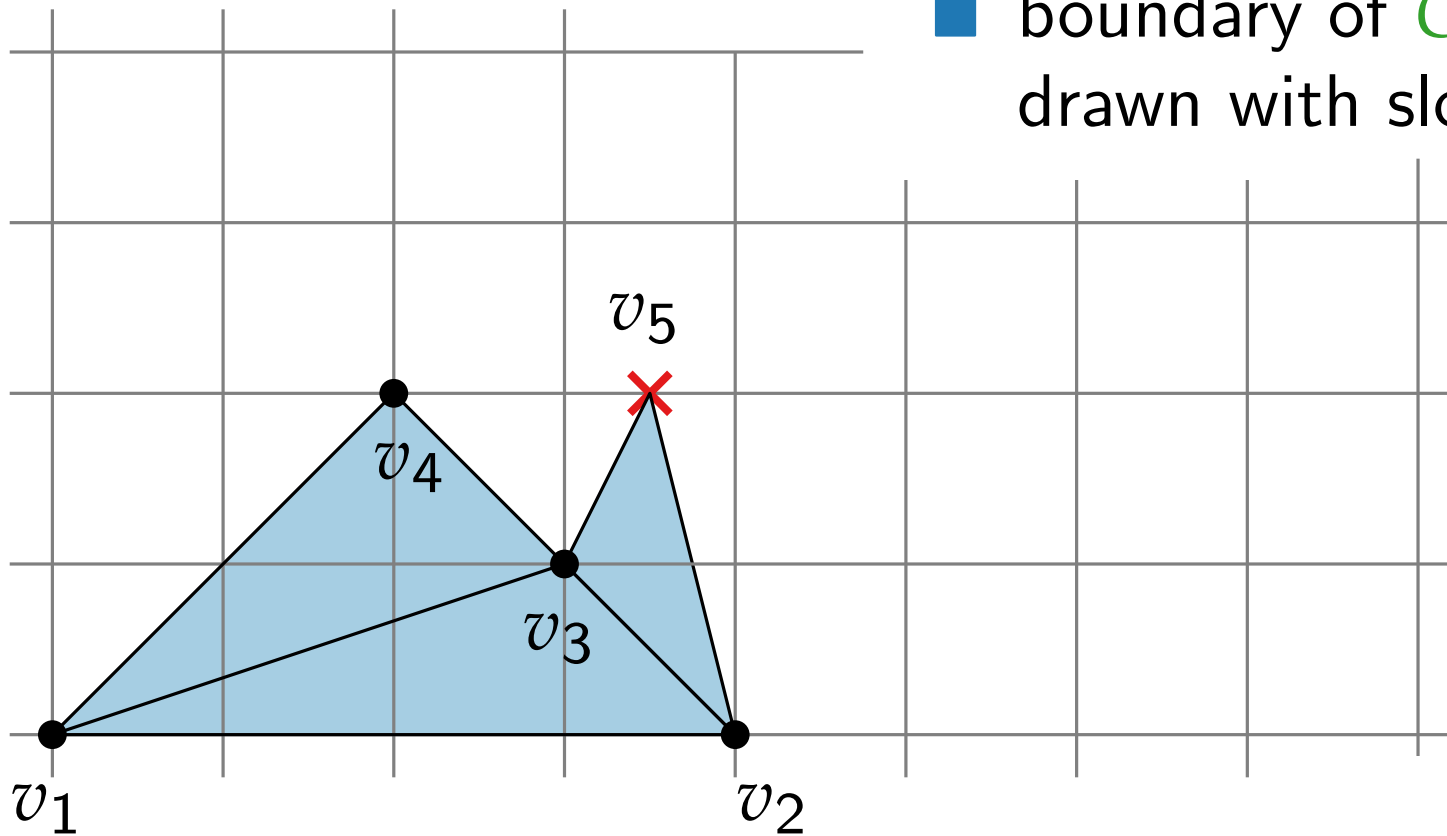


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
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- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

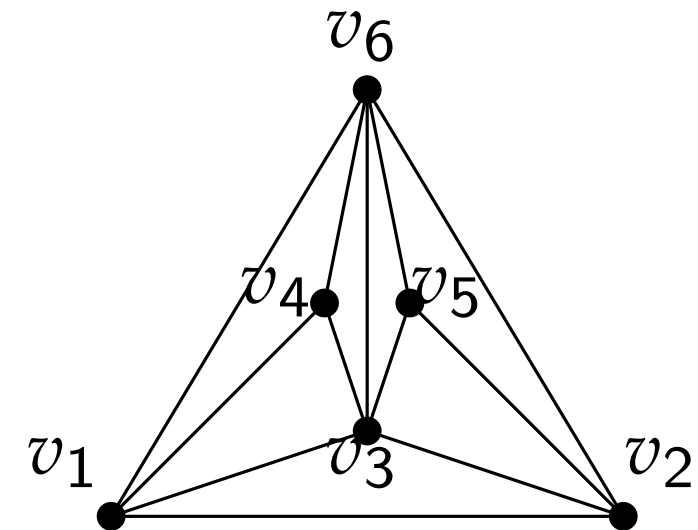
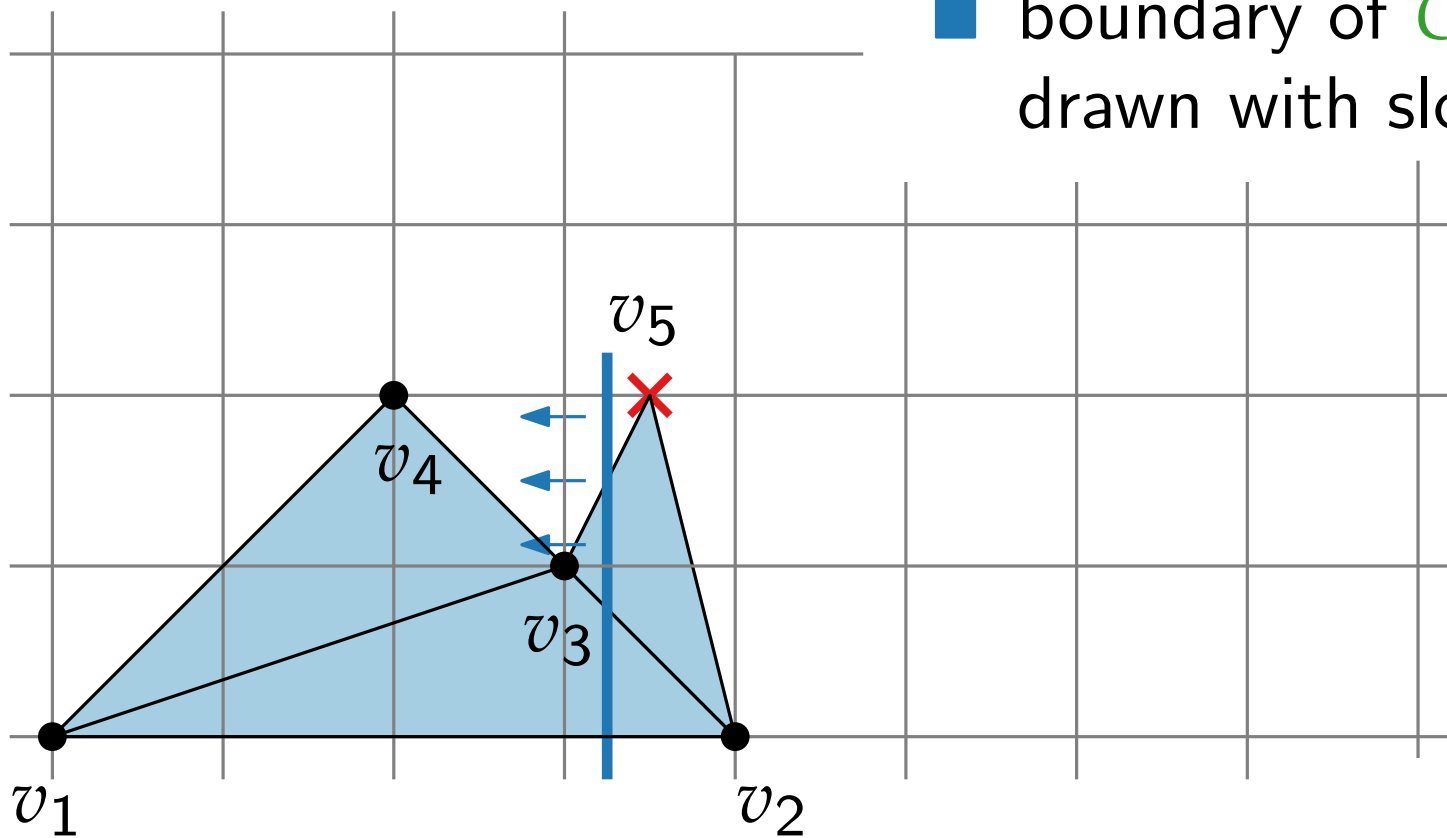


Constraints

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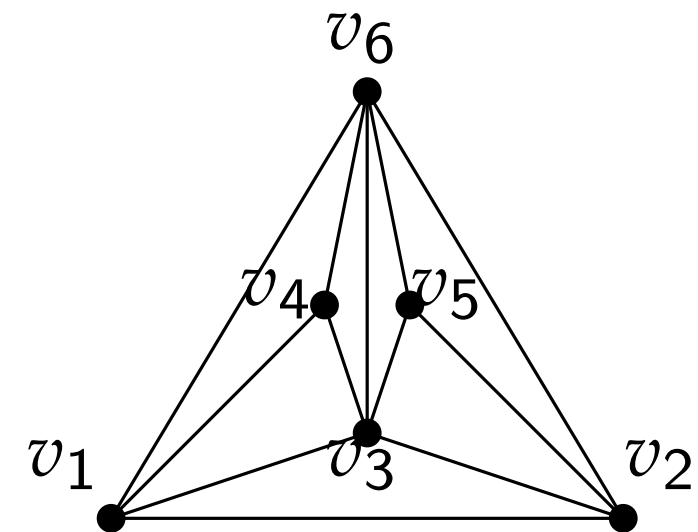
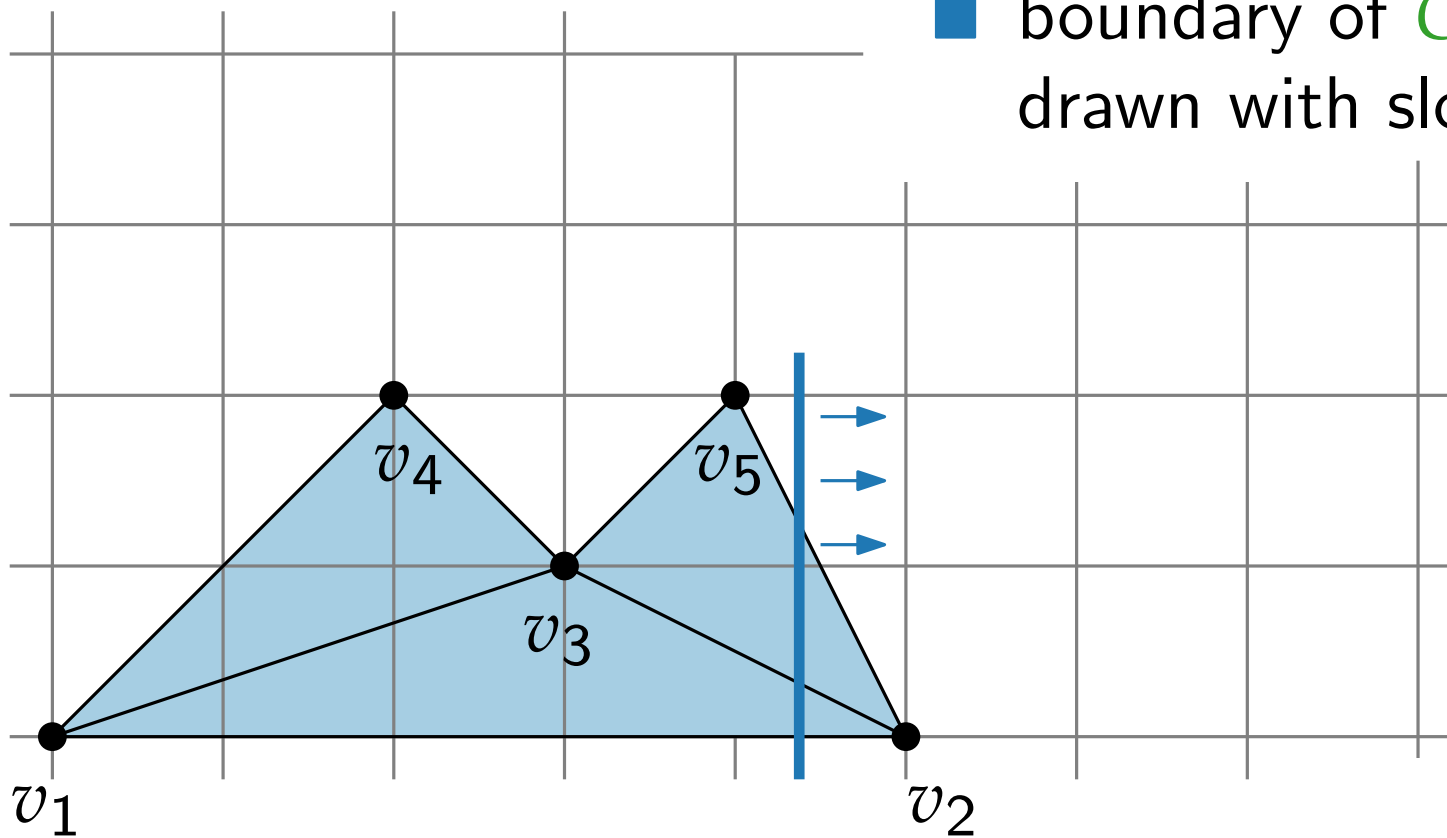


Constraints

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- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

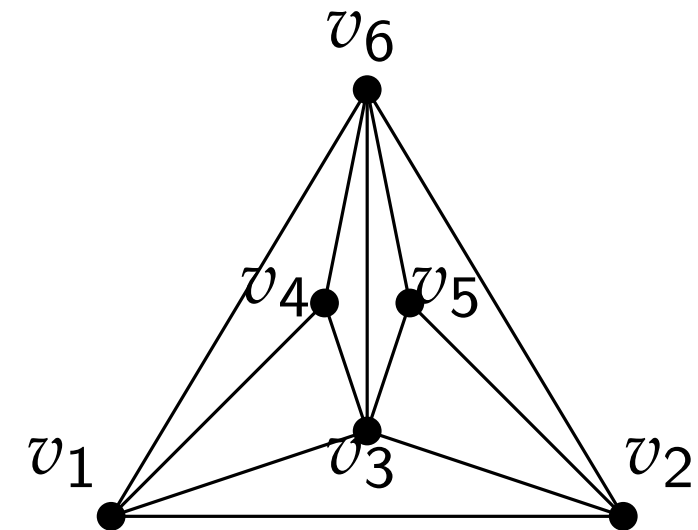
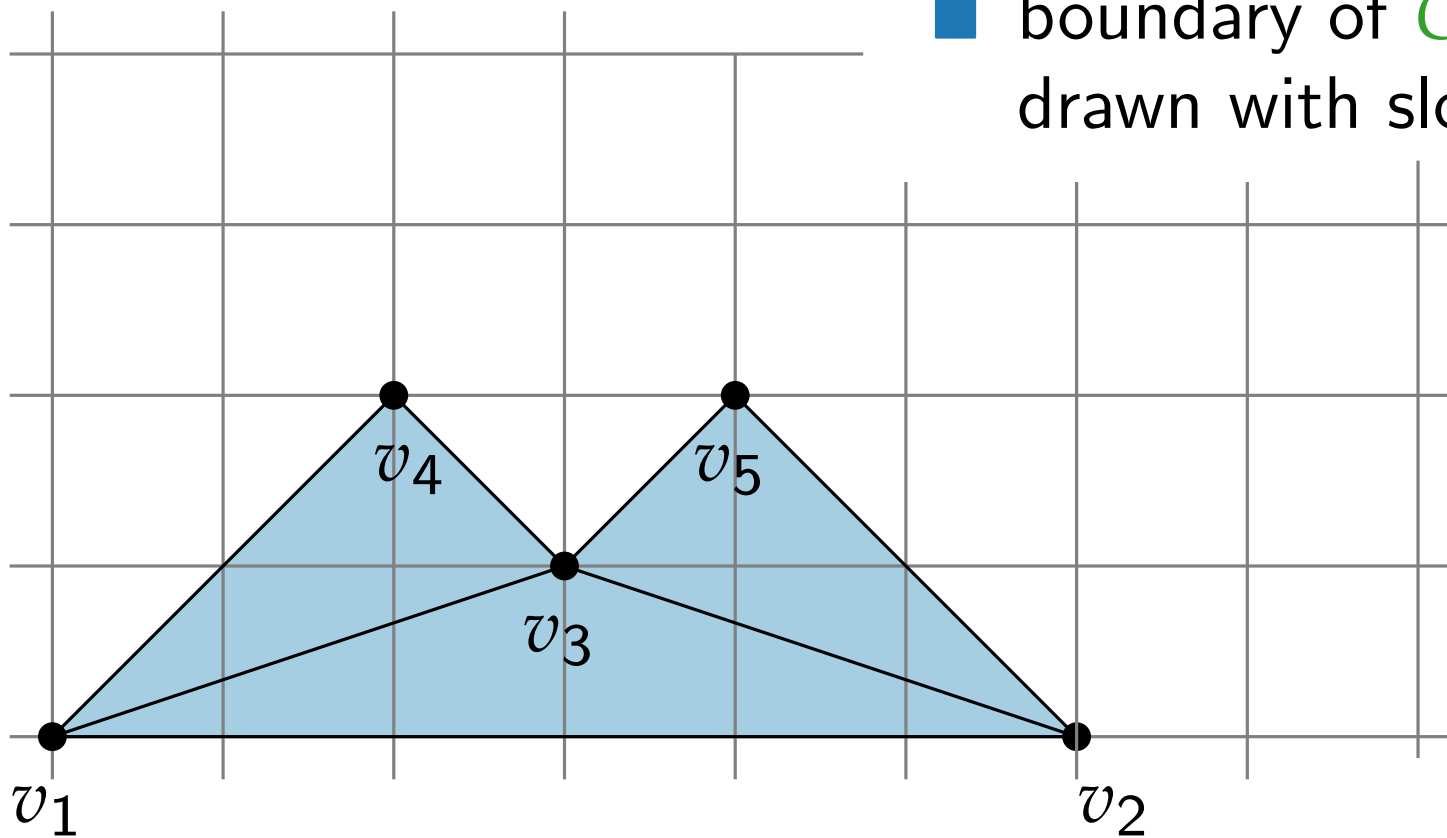


Constraints

Constraints:

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- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

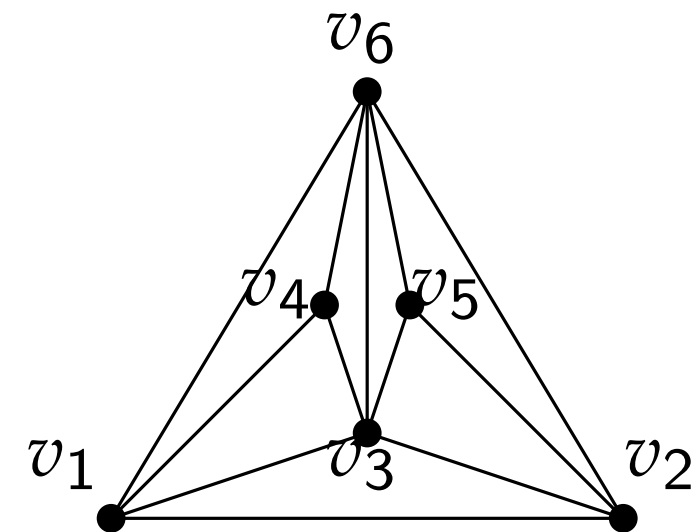
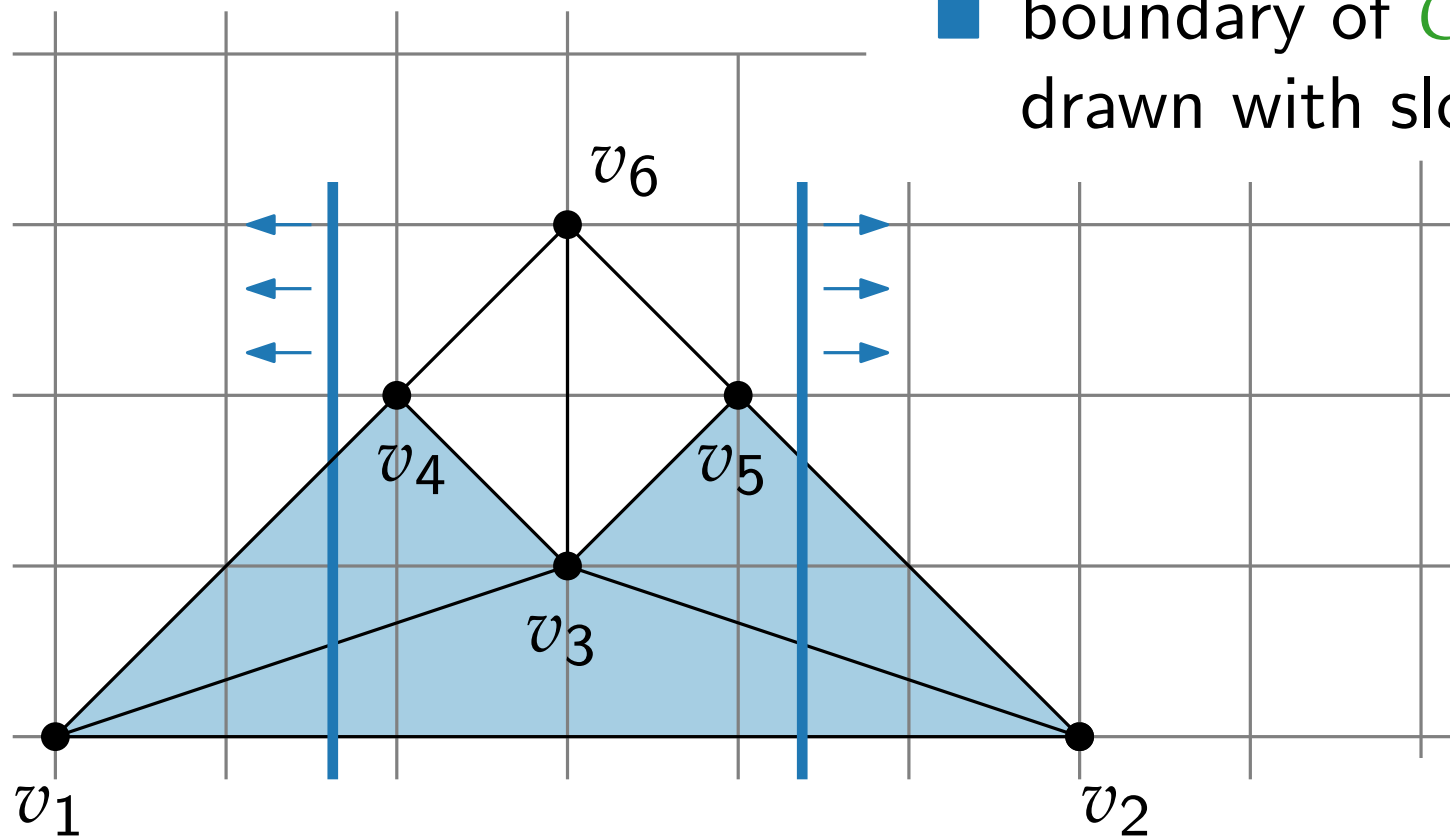


Constraints

Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

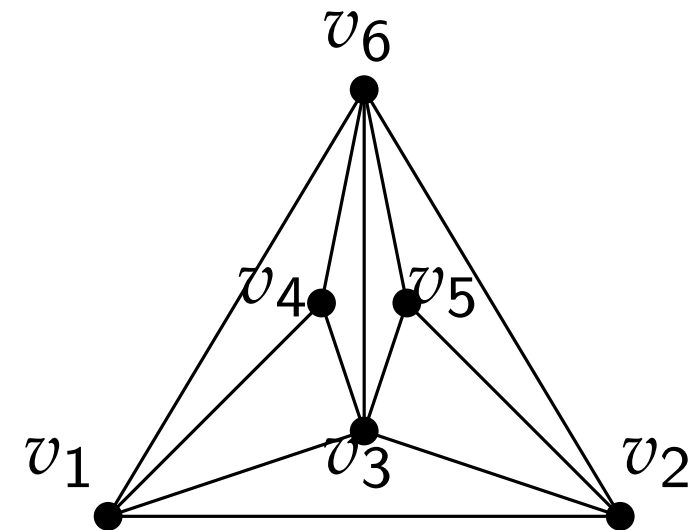
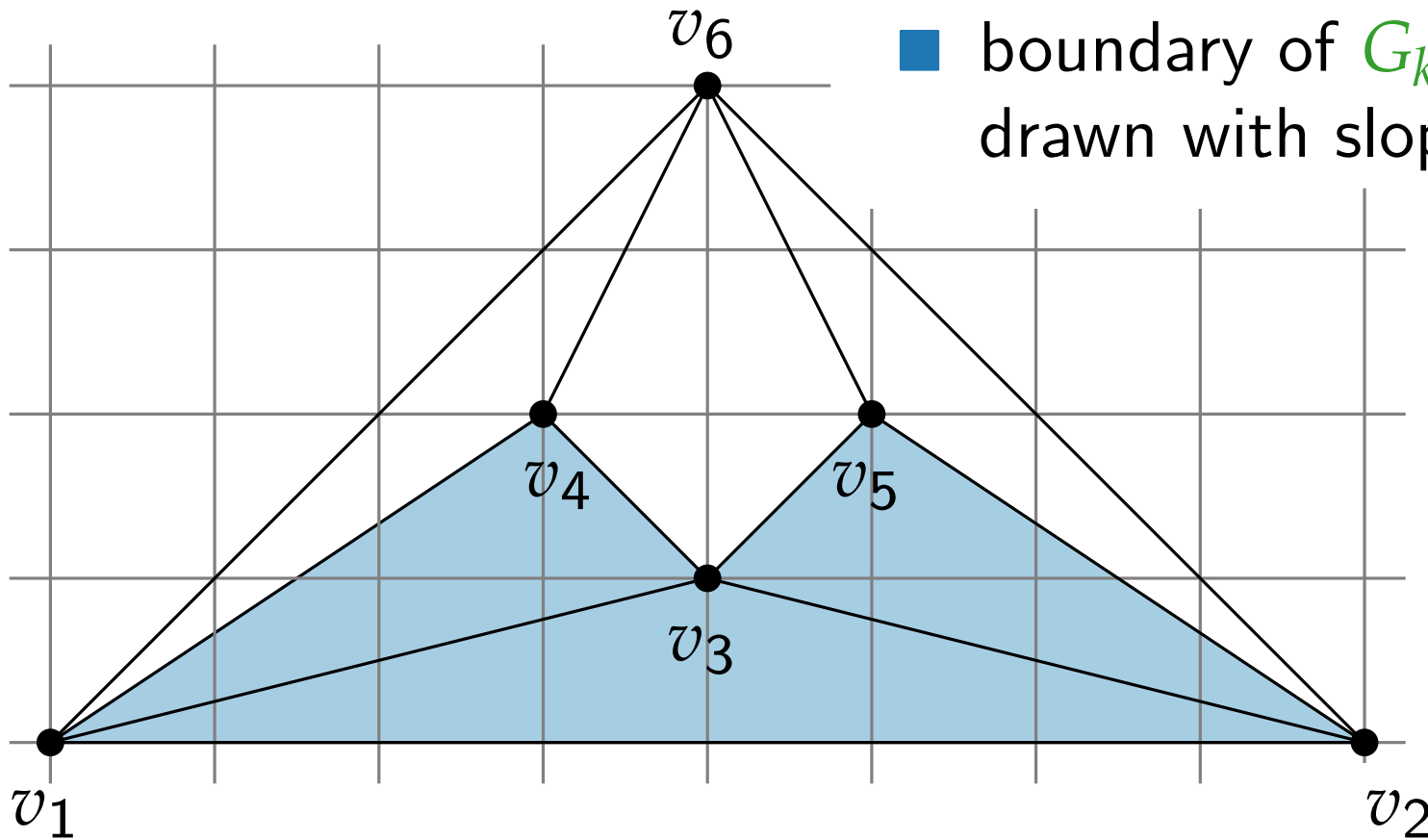


Constraints

Constraints:

G_{k-1} is drawn such that

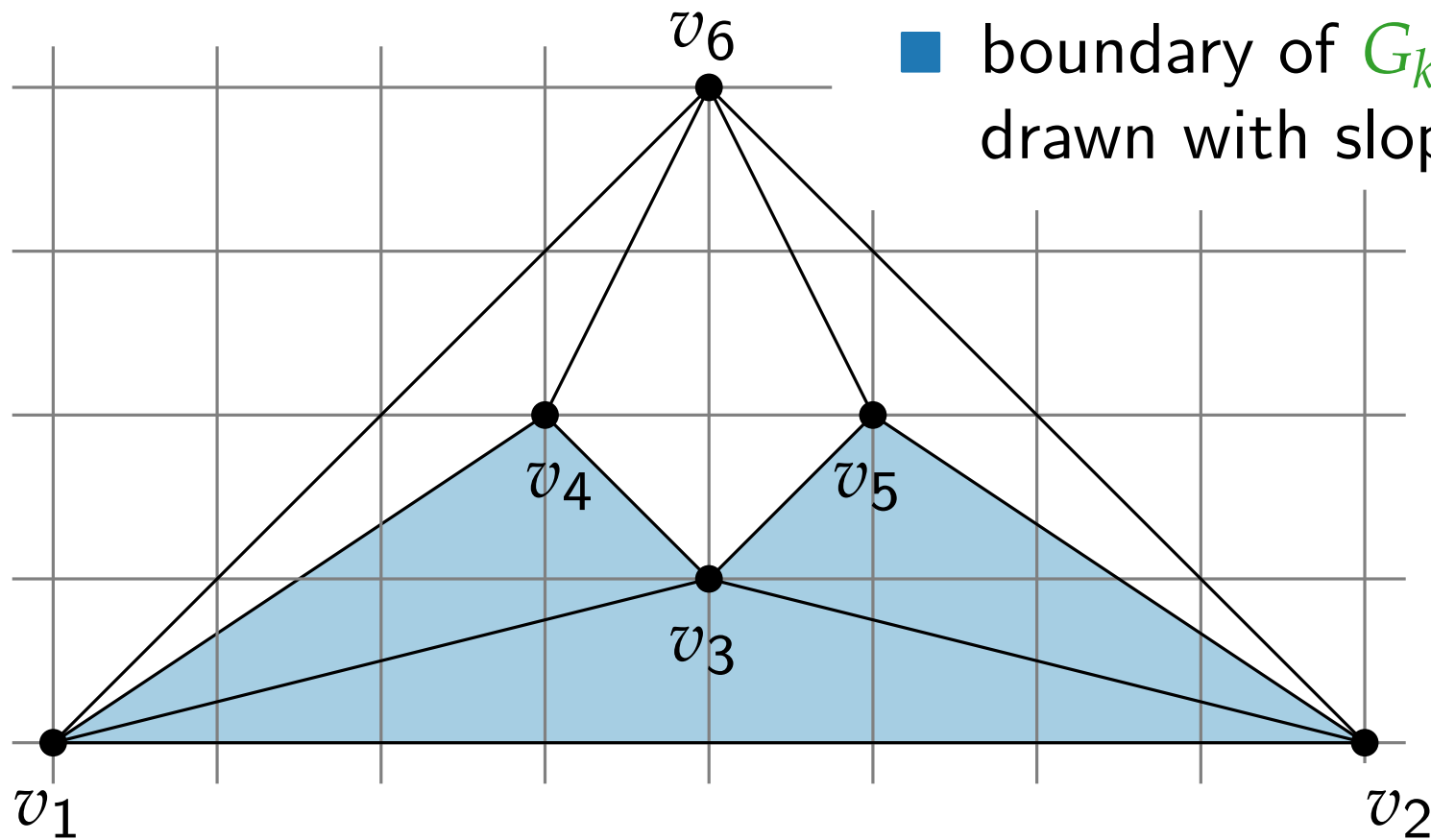
- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,



Constraints

Remarks:

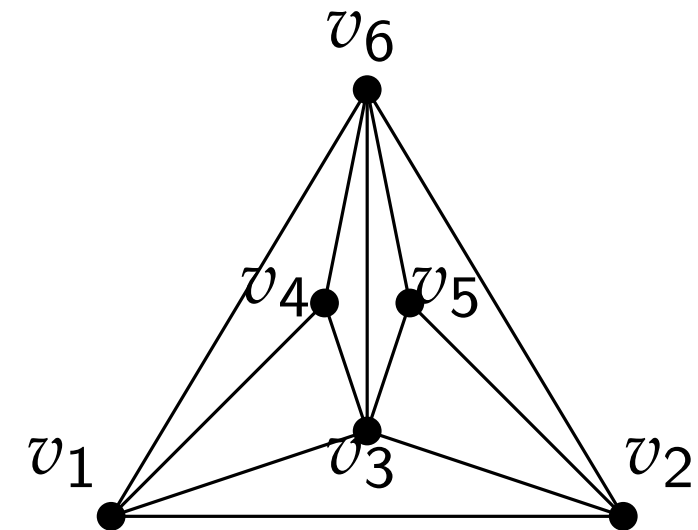
- 2 shifts per step
- width $< 2n$
- height $< n$



Constraints:

G_{k-1} is drawn such that

- v_1 is leftmost vertex, v_2 is rightmost vertex,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slope ± 1 ,

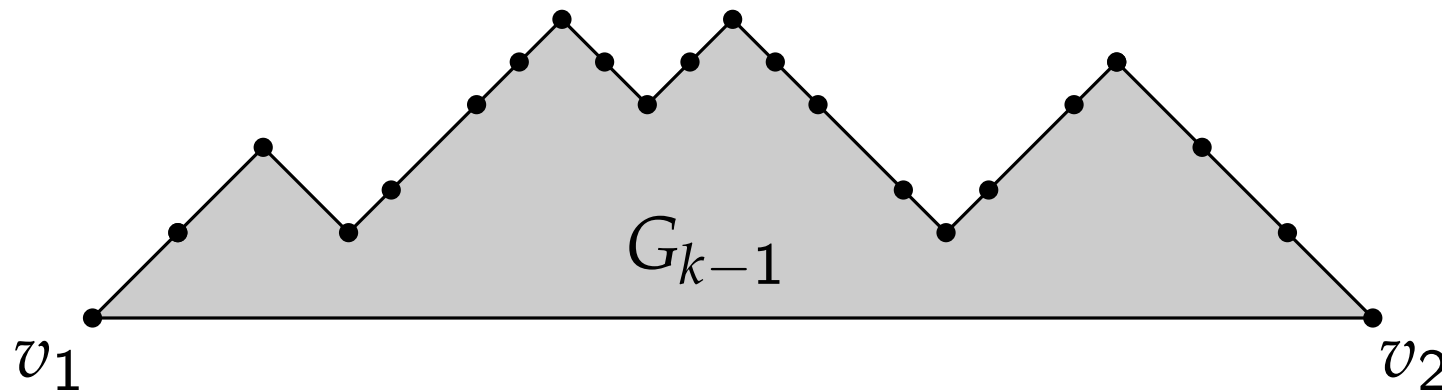


Shift method

Algorithm invariants/constraints:

G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 4, 0)$,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1 .

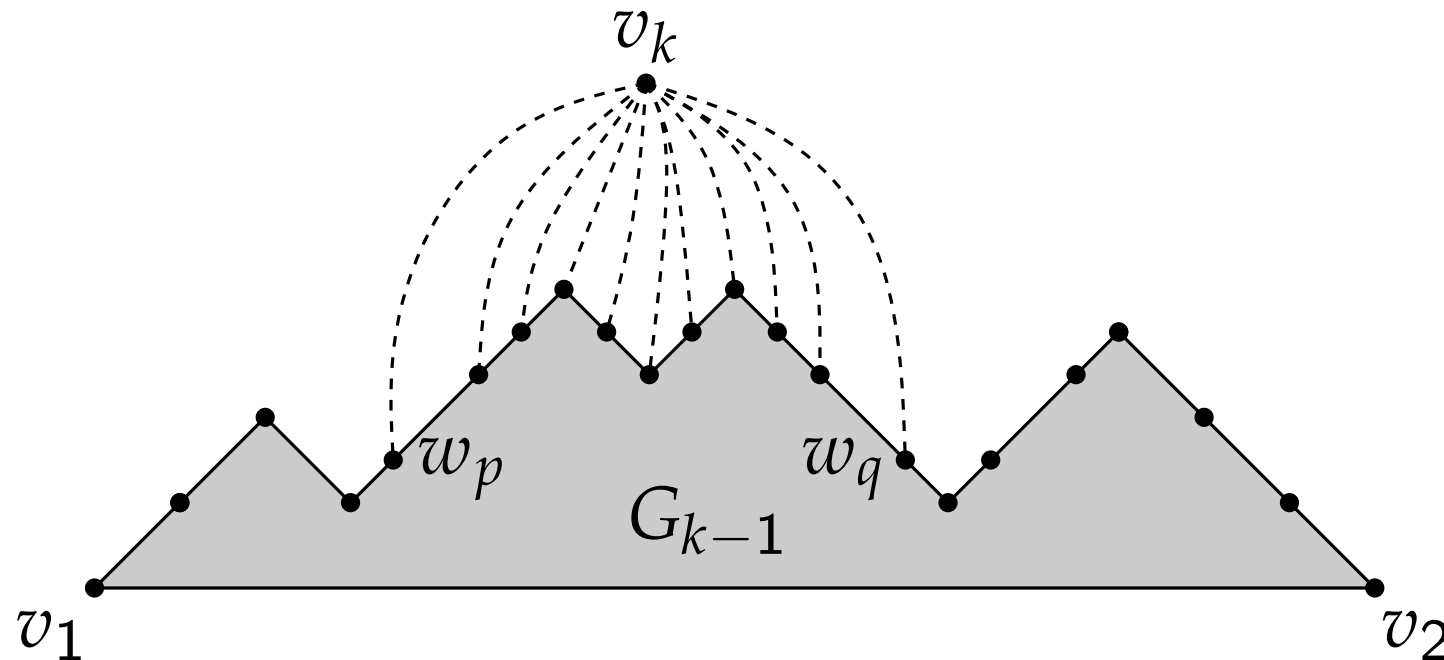


Shift method

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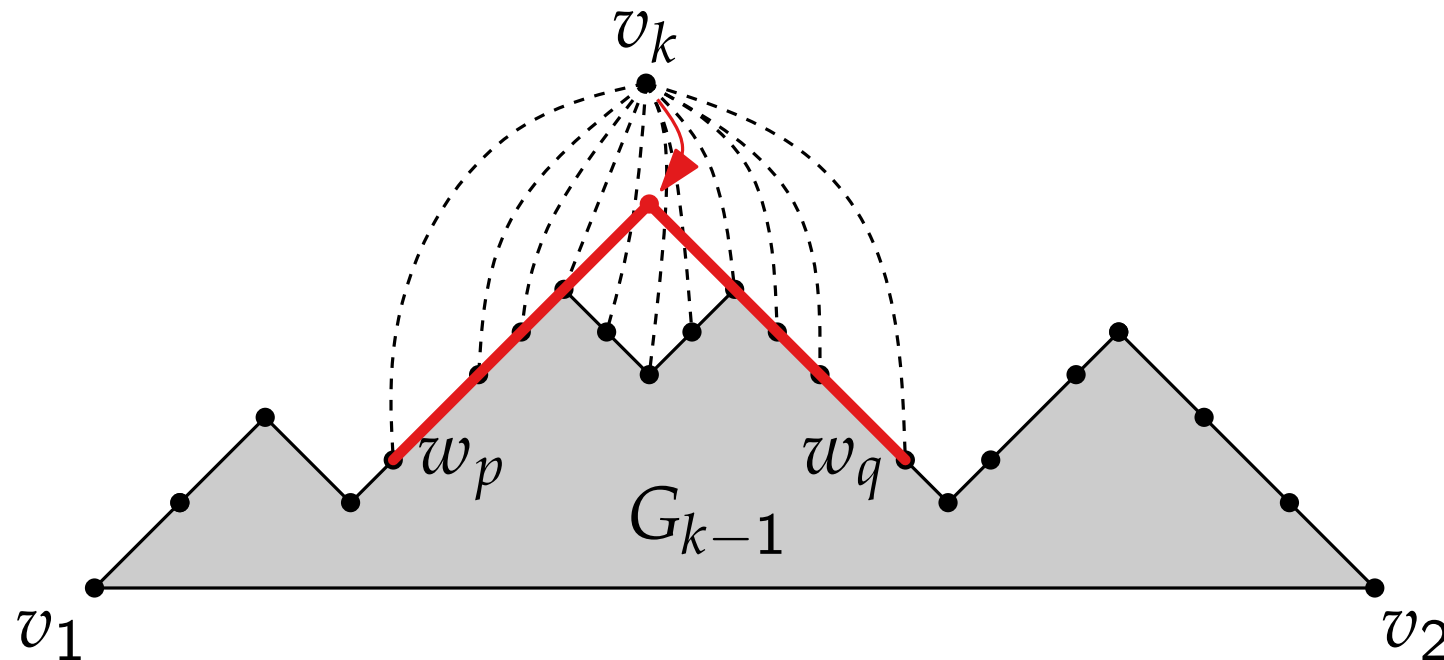


Shift method

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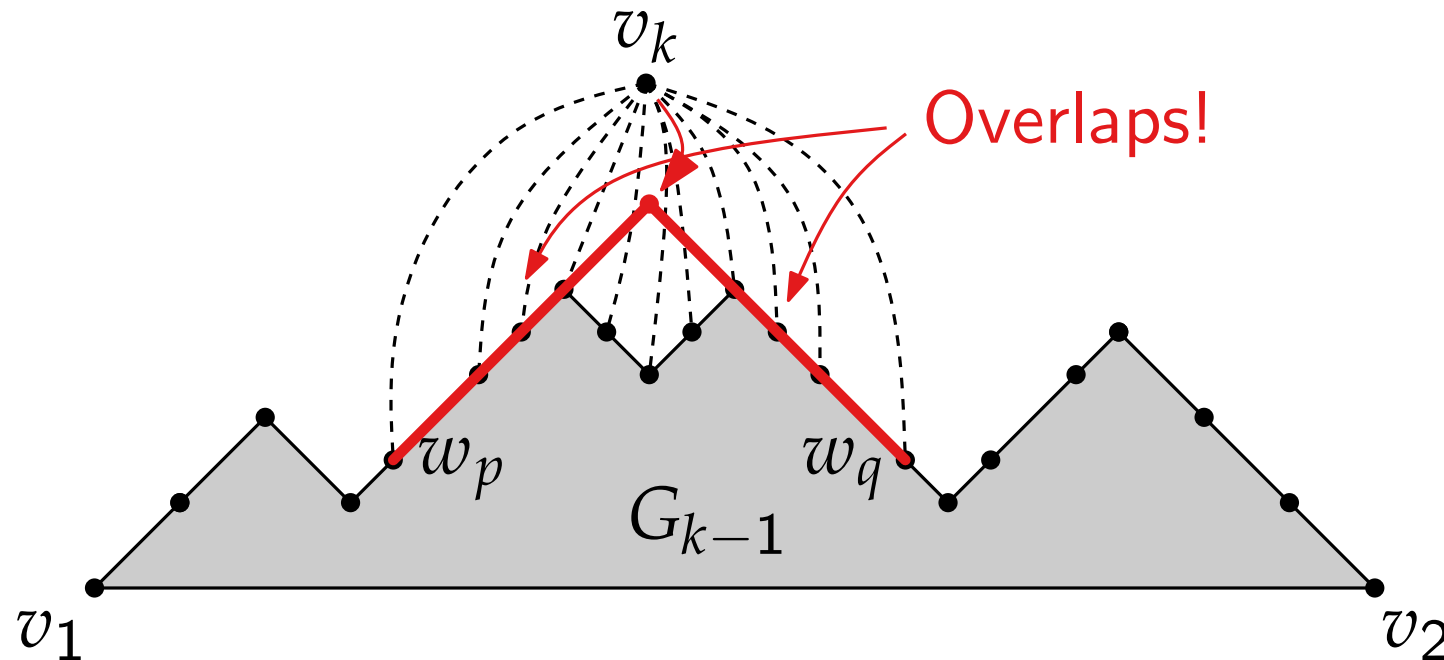


Shift method

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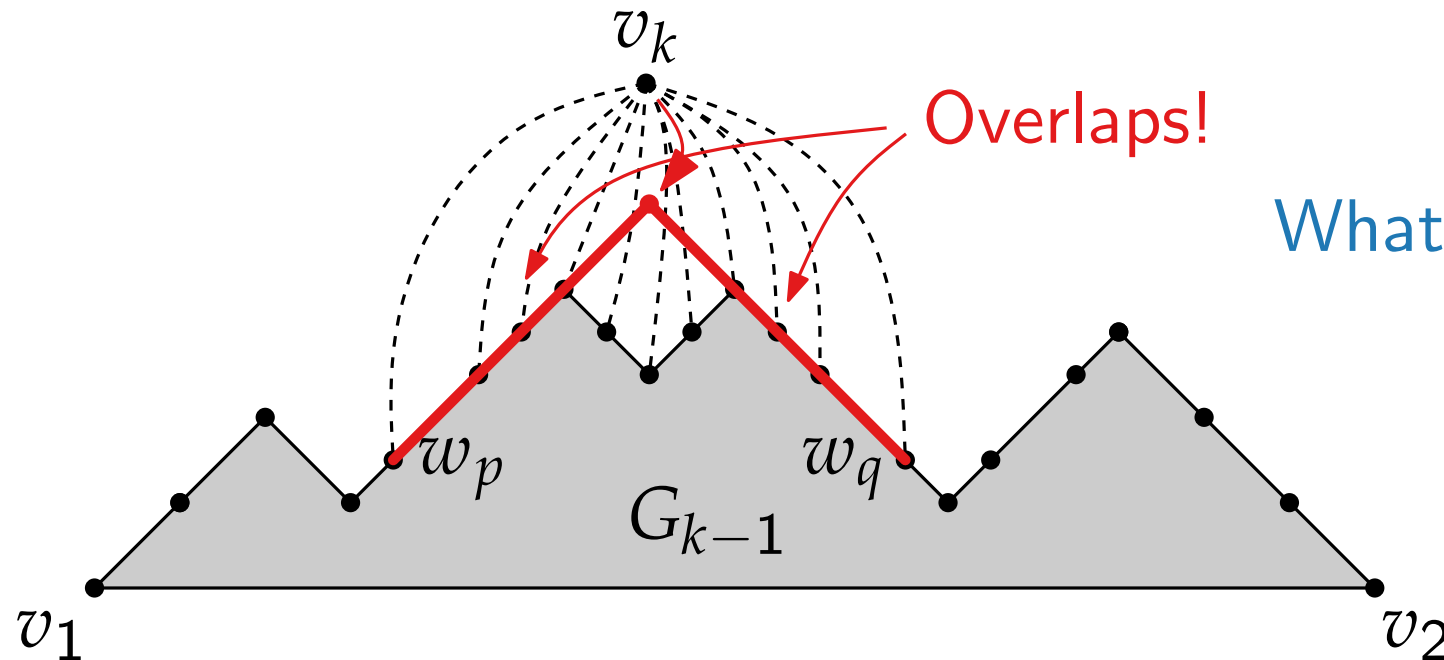


Shift method

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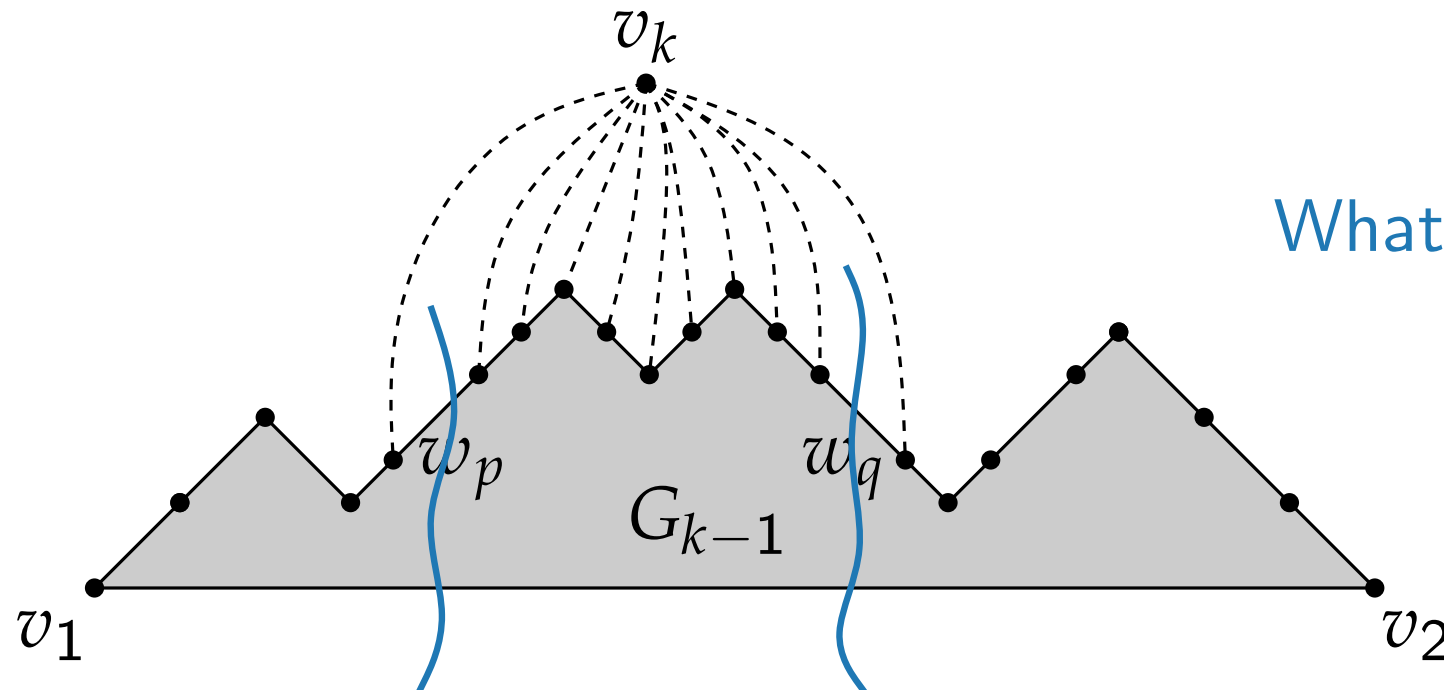


Shift method

Algorithm invariants/constraints:

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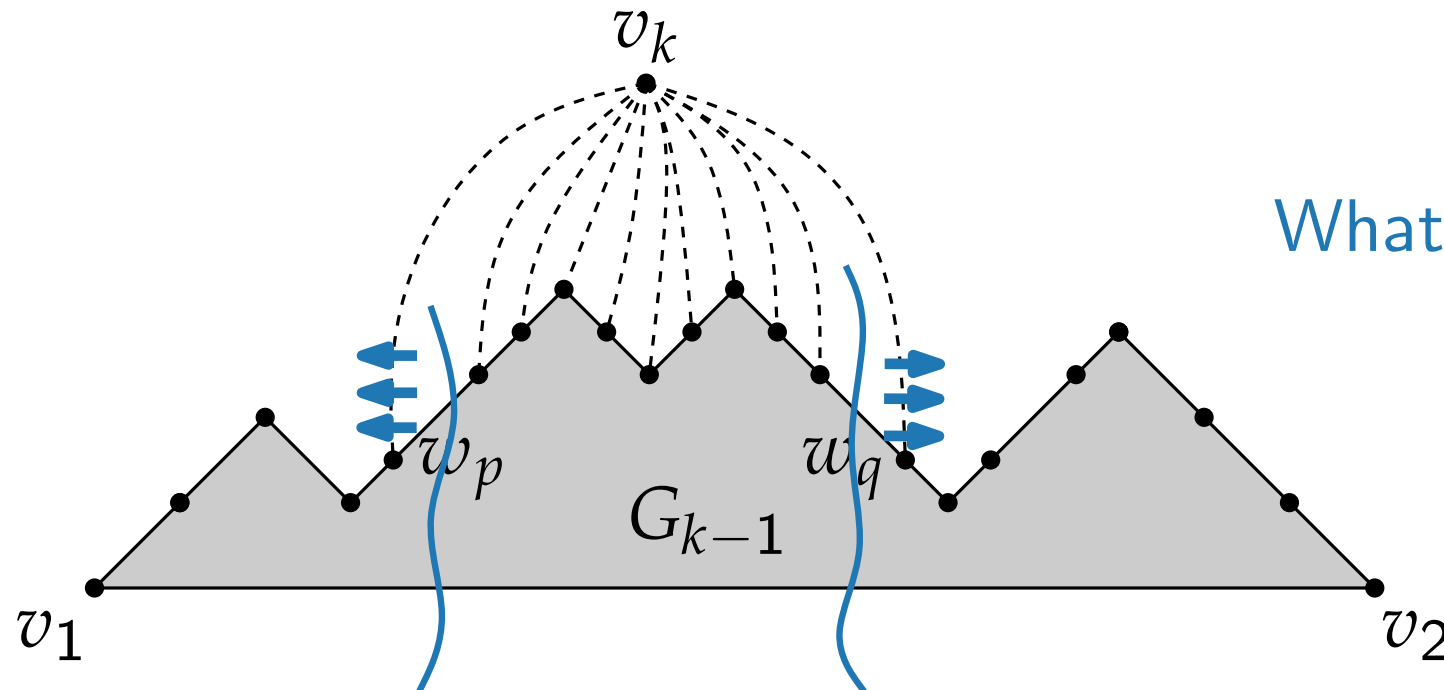
What is the solution?

Shift method

Algorithm invariants/constraints:

G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 4, 0)$,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1 .



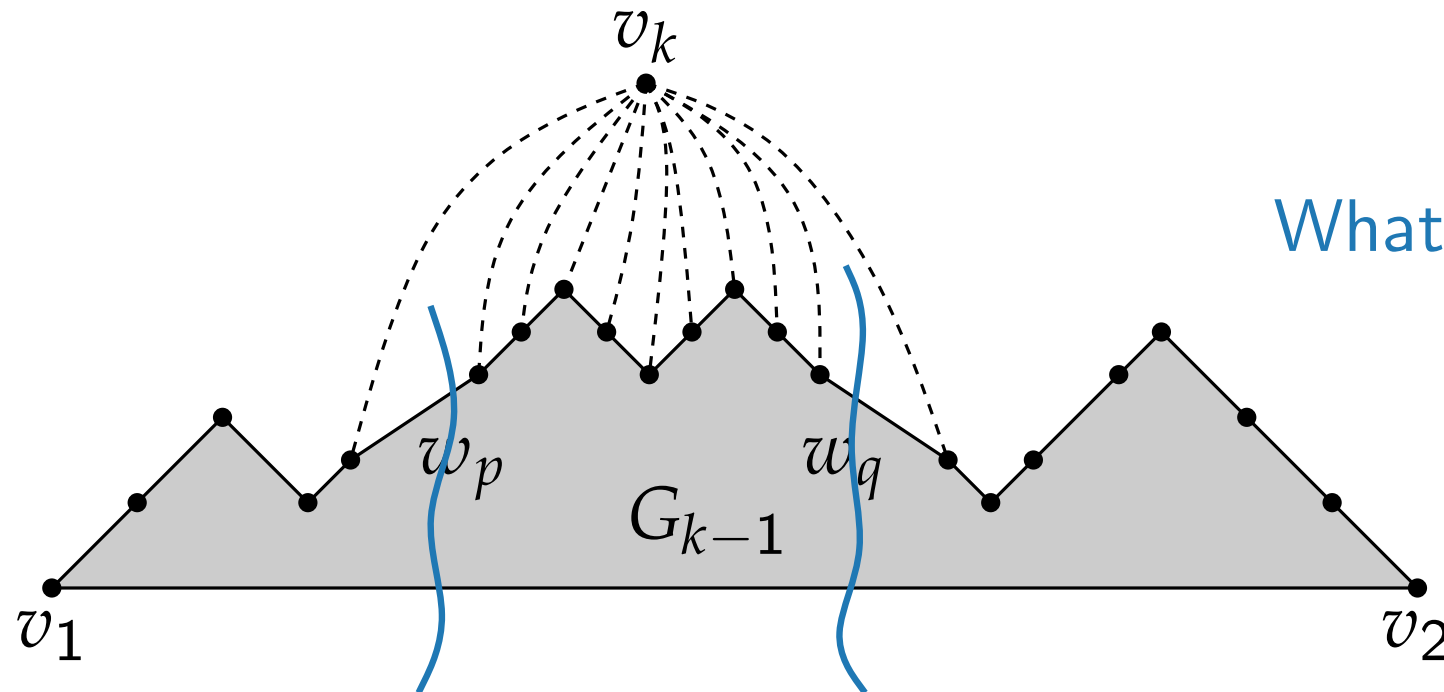
What is the solution?

Shift method

Algorithm invariants/constraints:

G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 4, 0)$,
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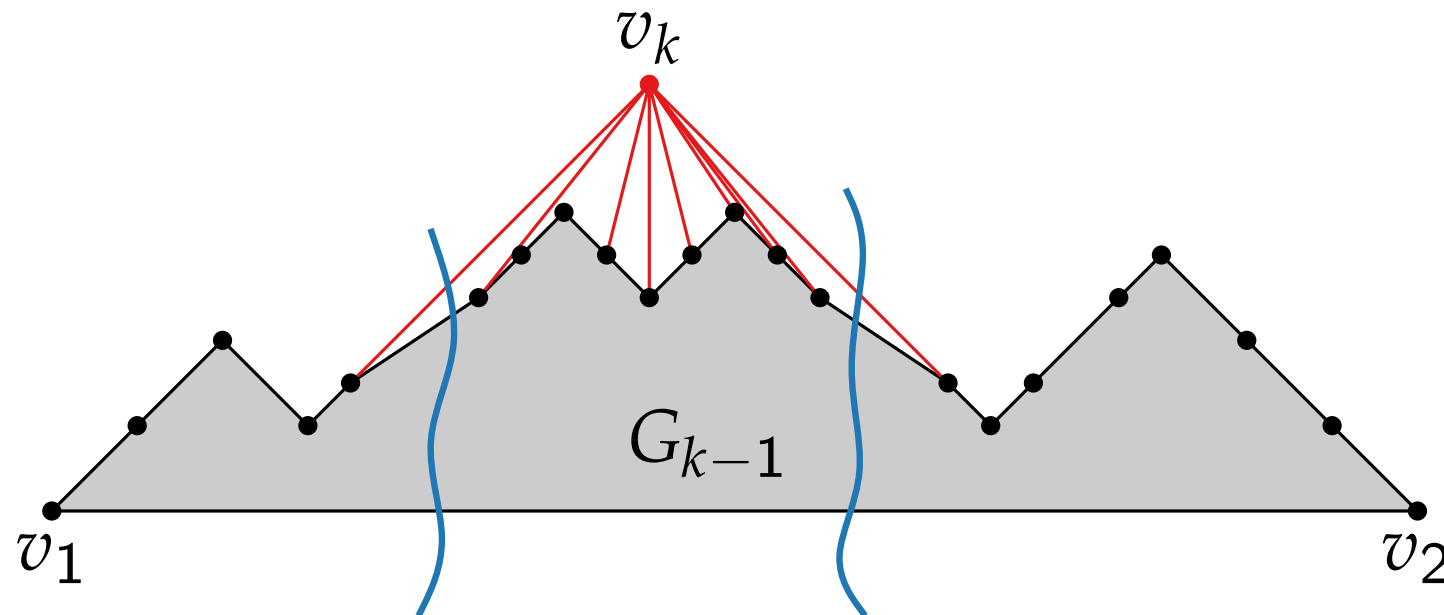
What is the solution?

Shift method

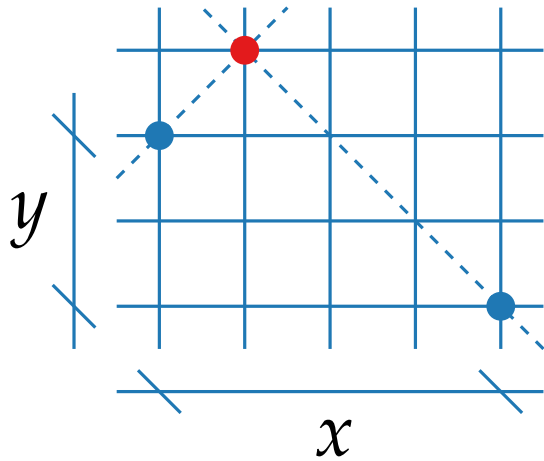
Algorithm invariants/constraints:

G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 4, 0)$,
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- each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1 .



Shift method

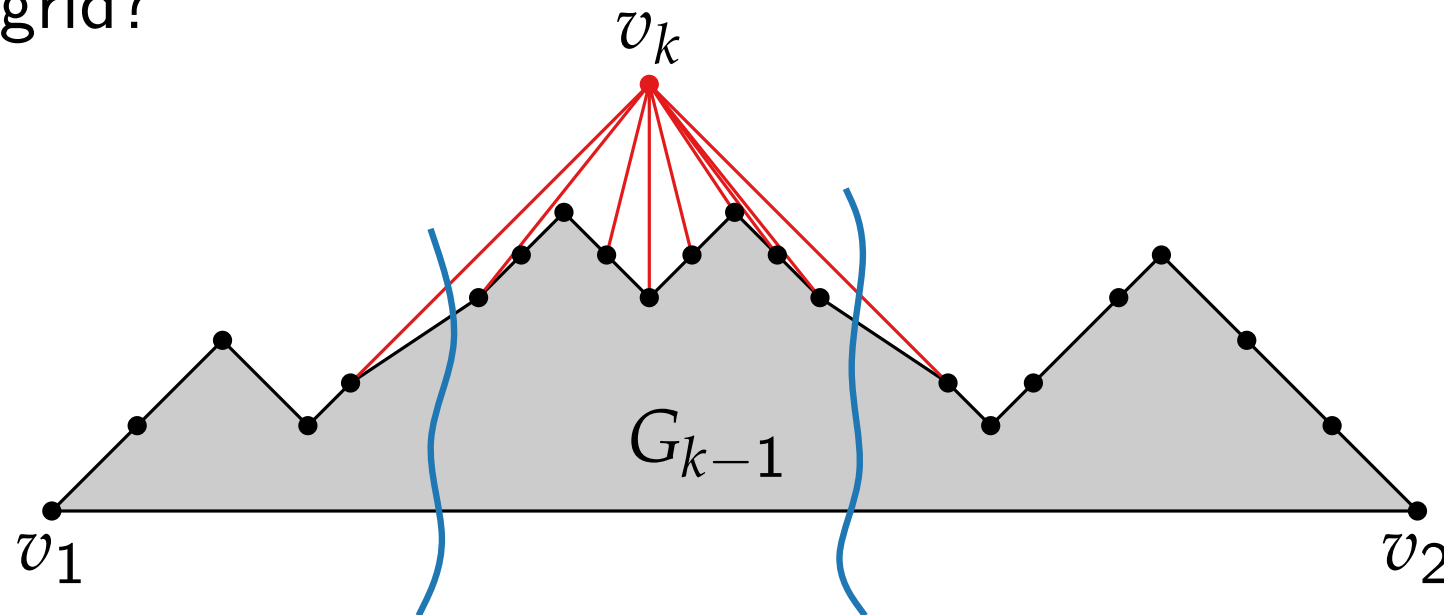


Algorithm invariants/constraints:

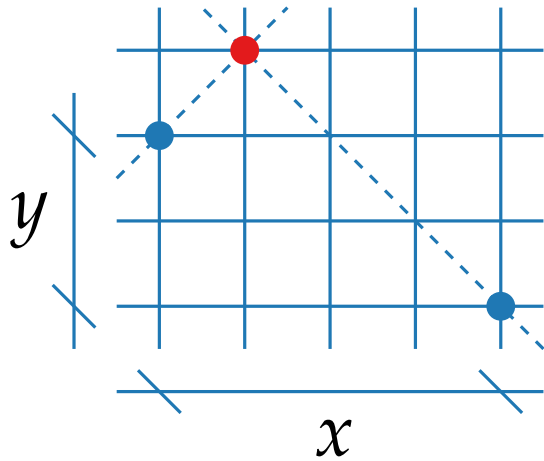
G_{k-1} is drawn such that

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- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1 .

- Why is v_k on grid?



Shift method

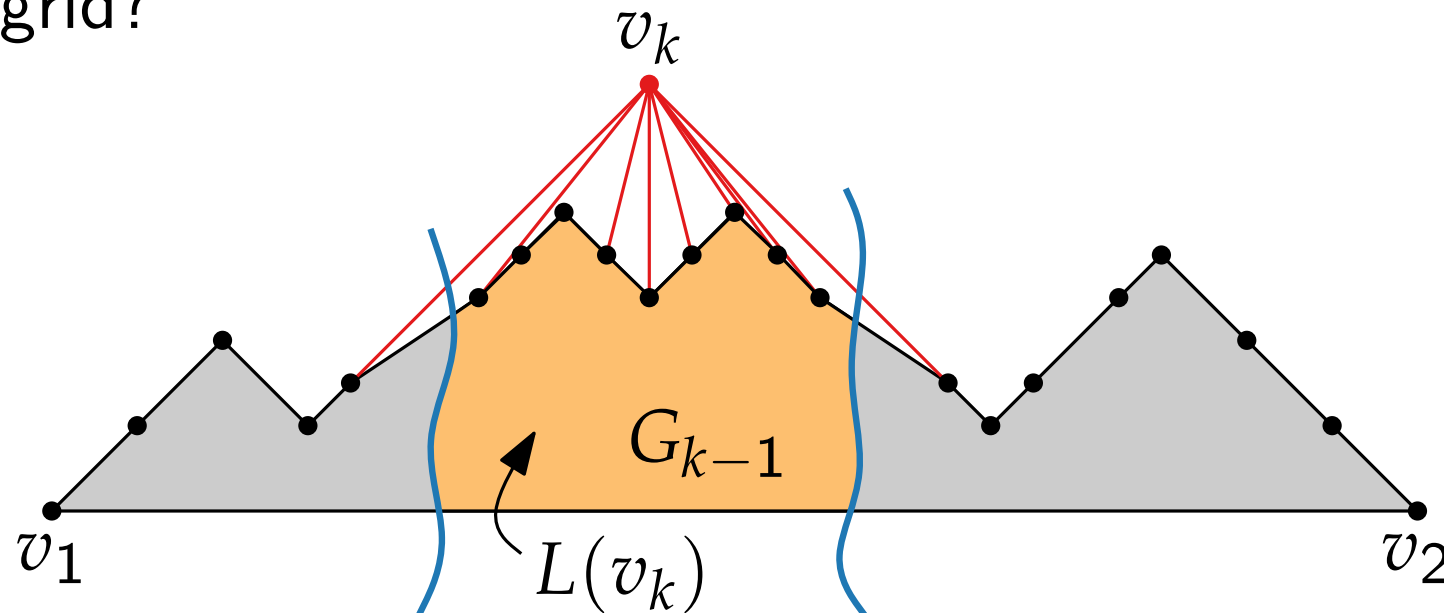


Algorithm invariants/constraints:

G_{k-1} is drawn such that

- v_1 is on $(0, 0)$, v_2 is on $(2k - 4, 0)$,
- boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn x -monotone,
- each edge of the boundary of G_{k-1} (minus edge (v_1, v_2)) is drawn with slopes ± 1 .

- Why is v_k on grid?



Shift method

Lemma.

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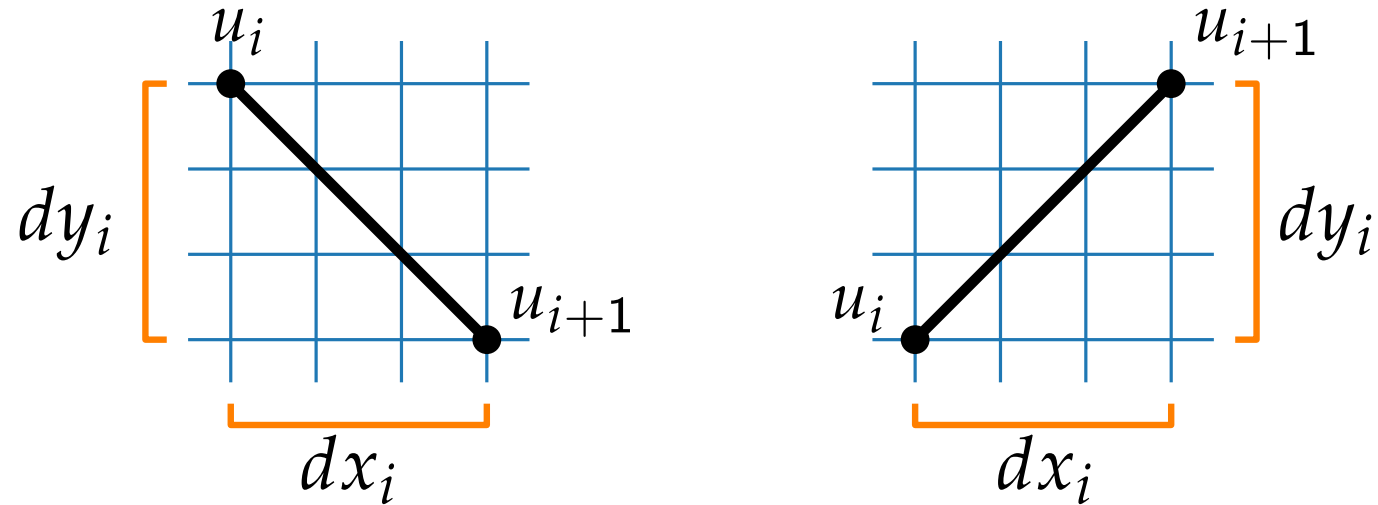
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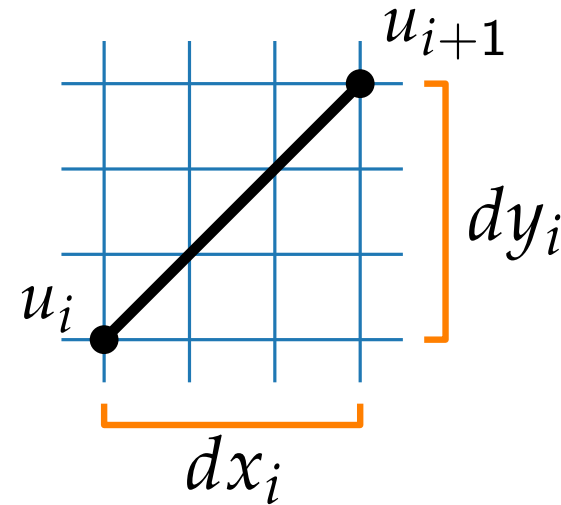
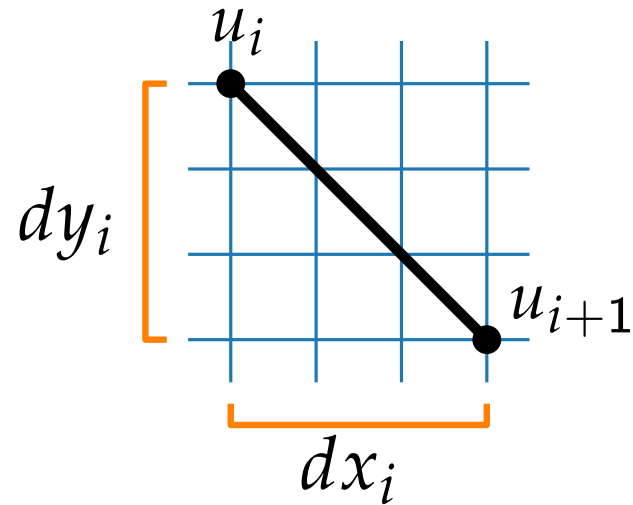


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$$d(u_i, u_{i+1}) = |dx_i| + |dy_i| \text{ even}$$

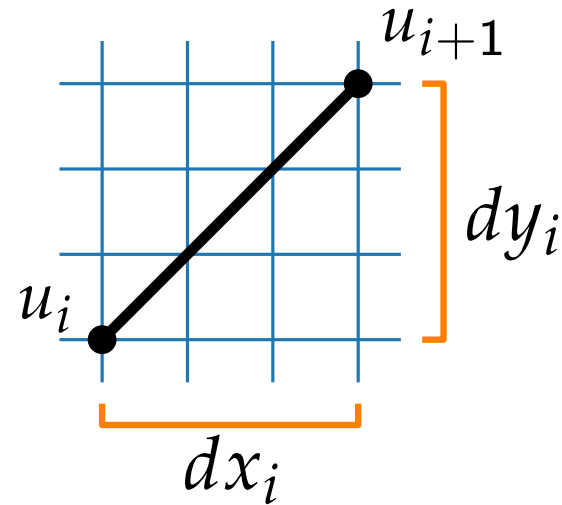
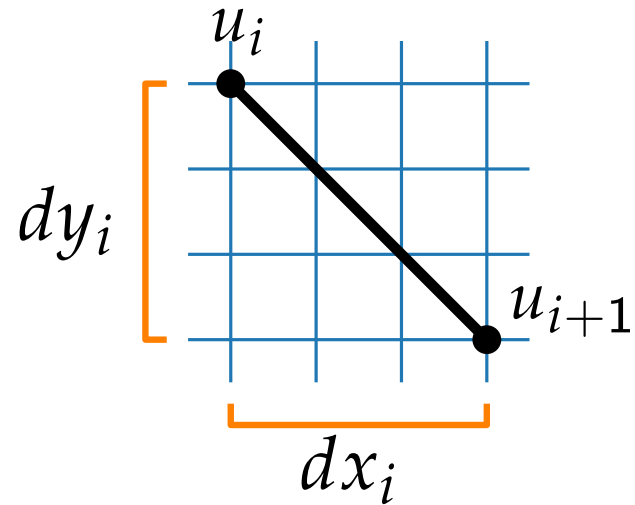
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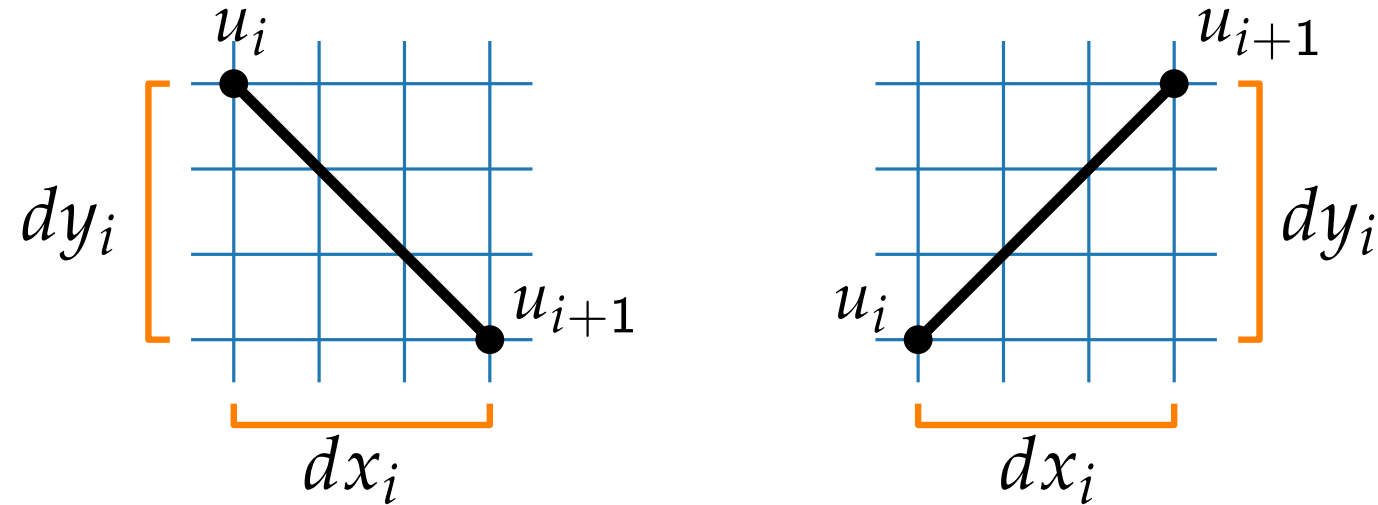
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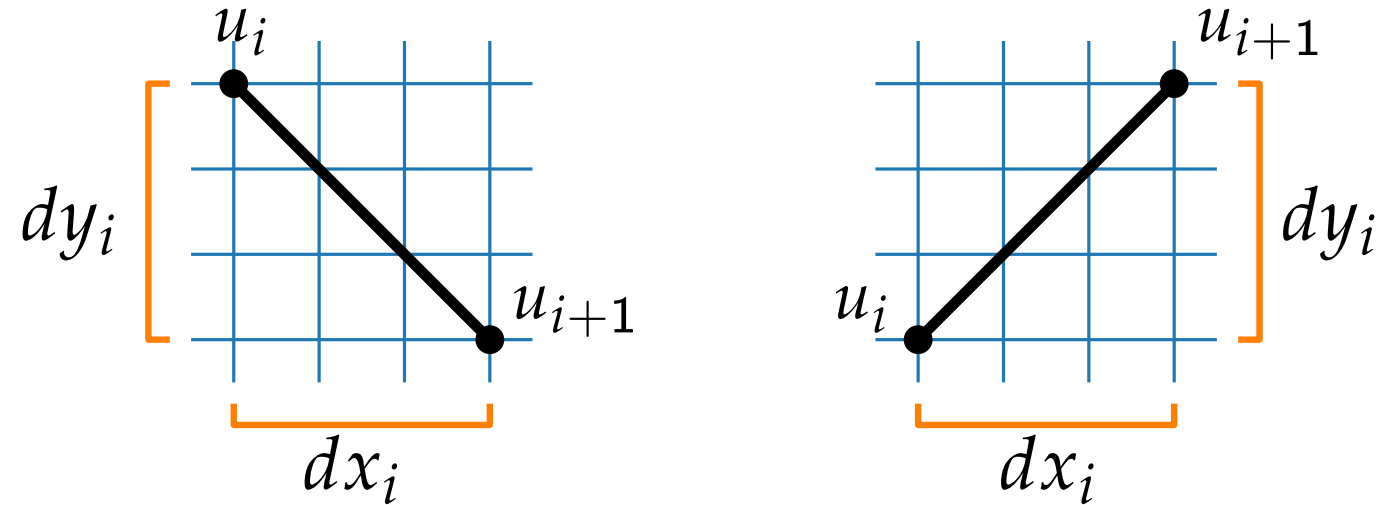
$$d(u_i, u_{i+l}) = \sum_{j=i}^{i+l-1} |dx_j| + \lambda_j |dy_j|, \lambda_j = \pm 1 \quad \text{even}$$

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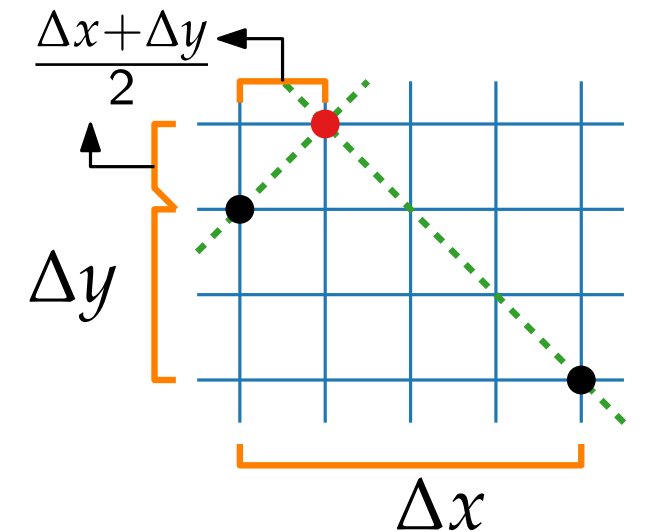


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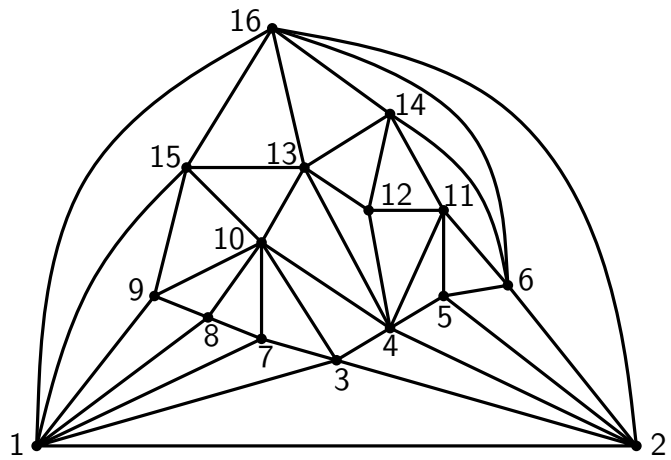
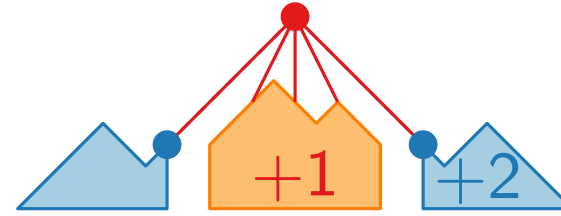
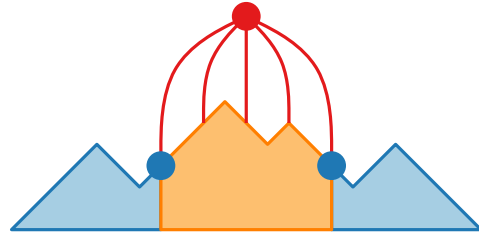
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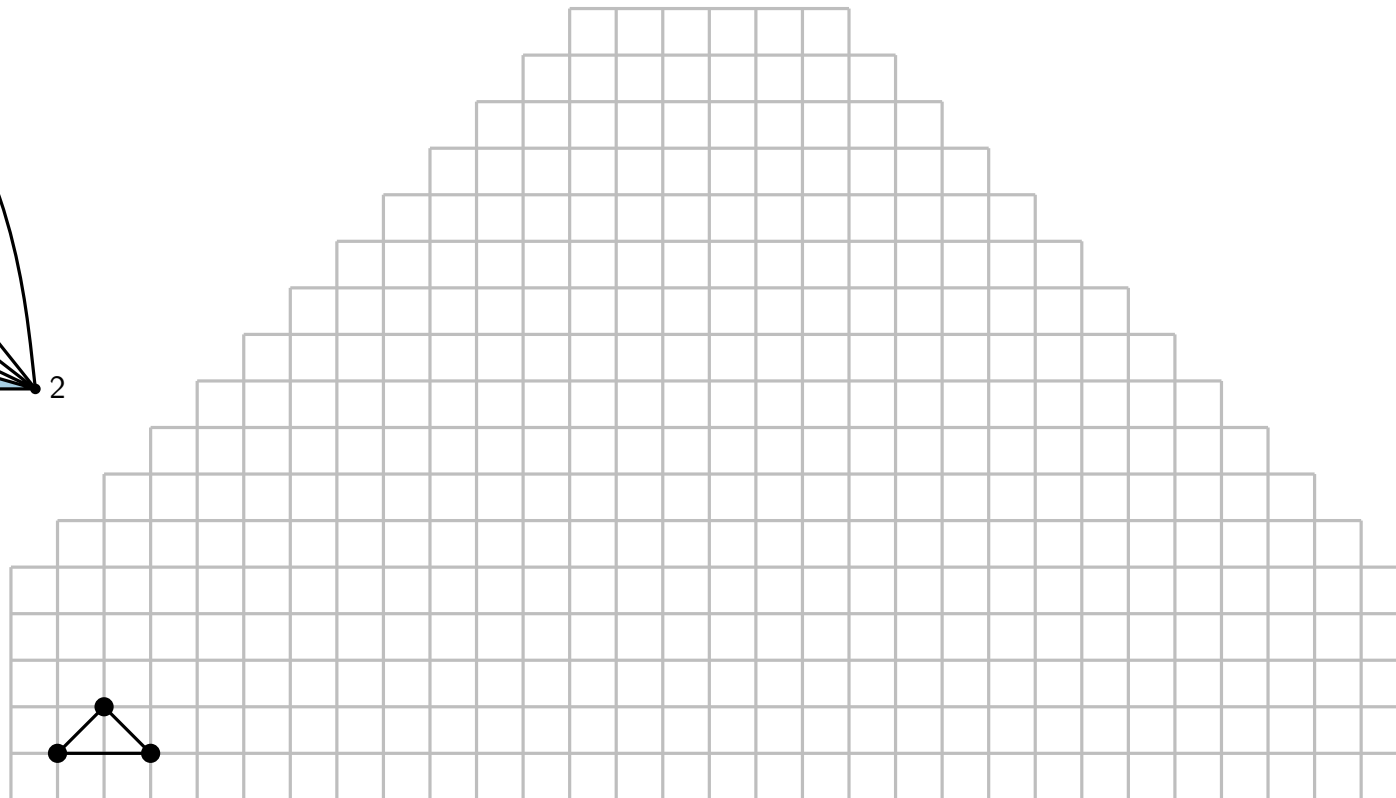
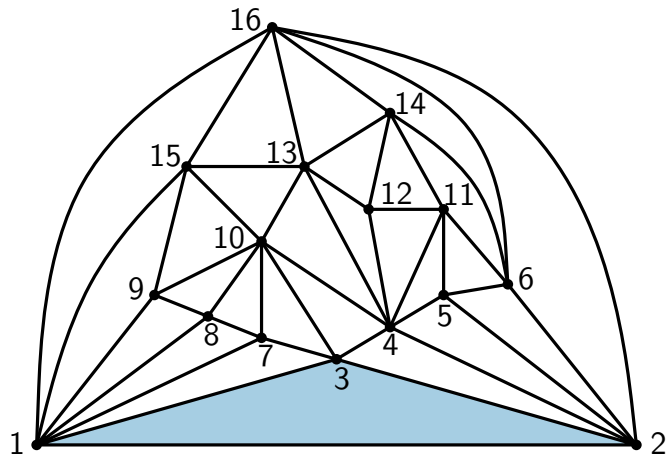
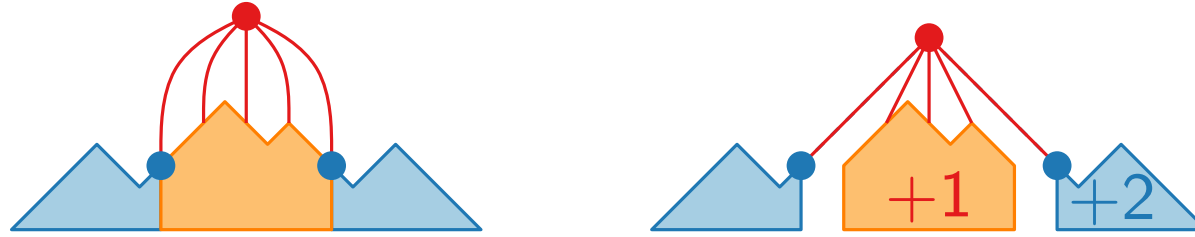
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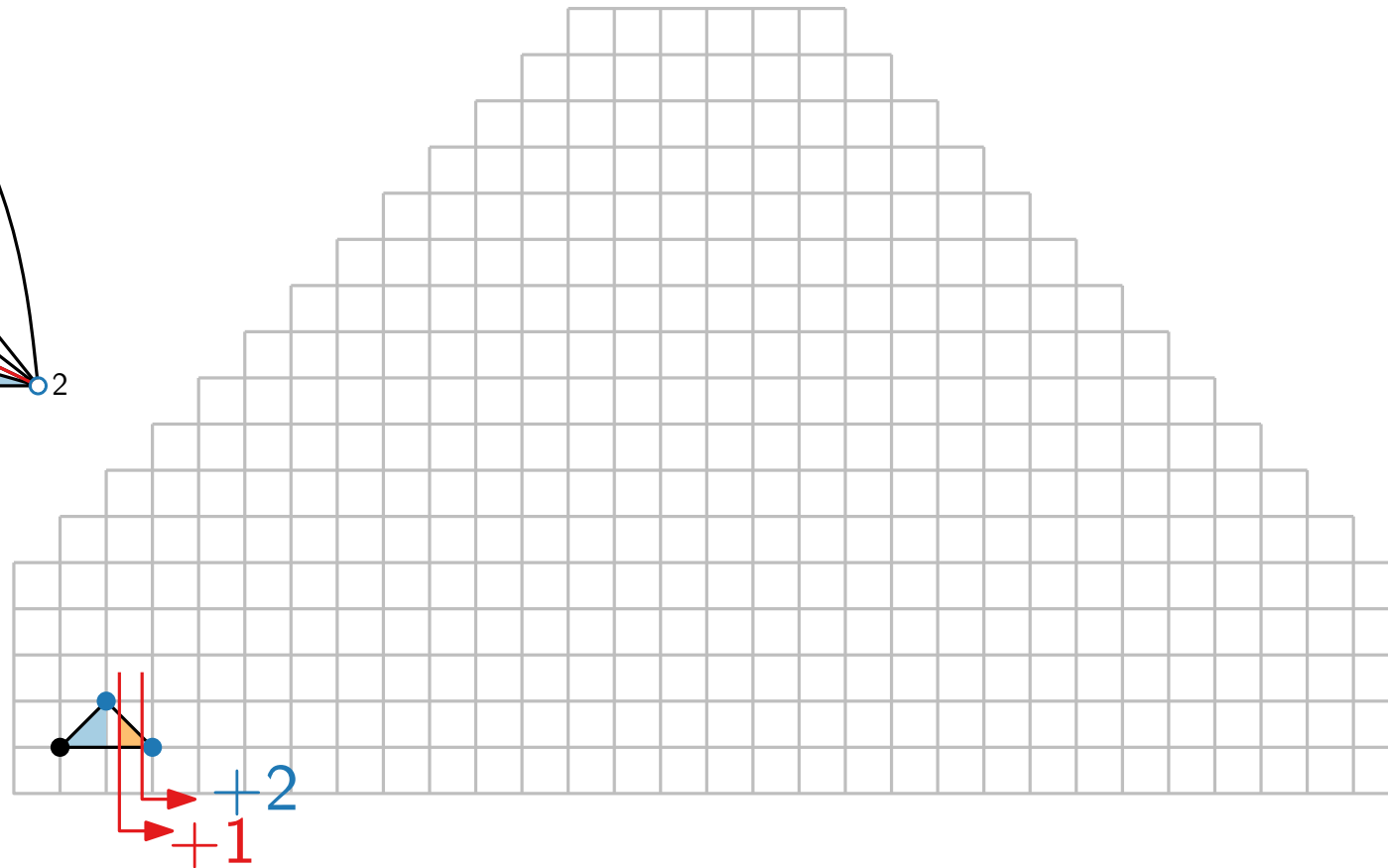
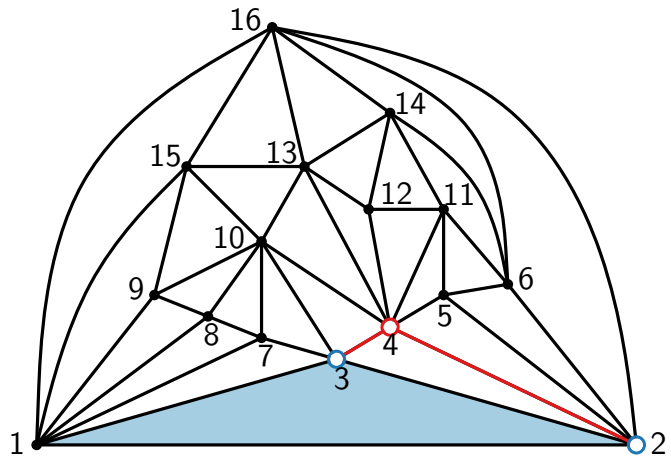
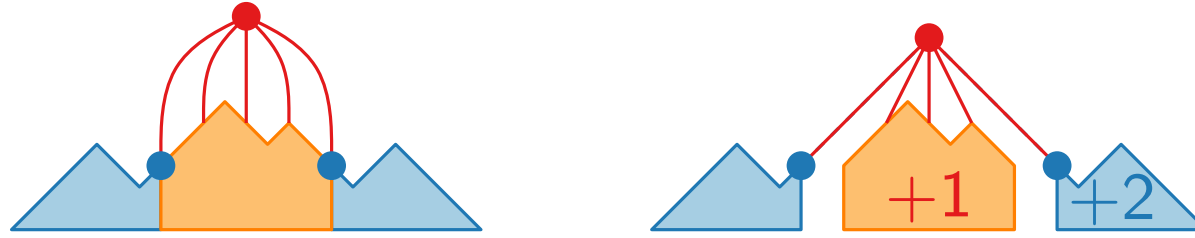
Shift method – example



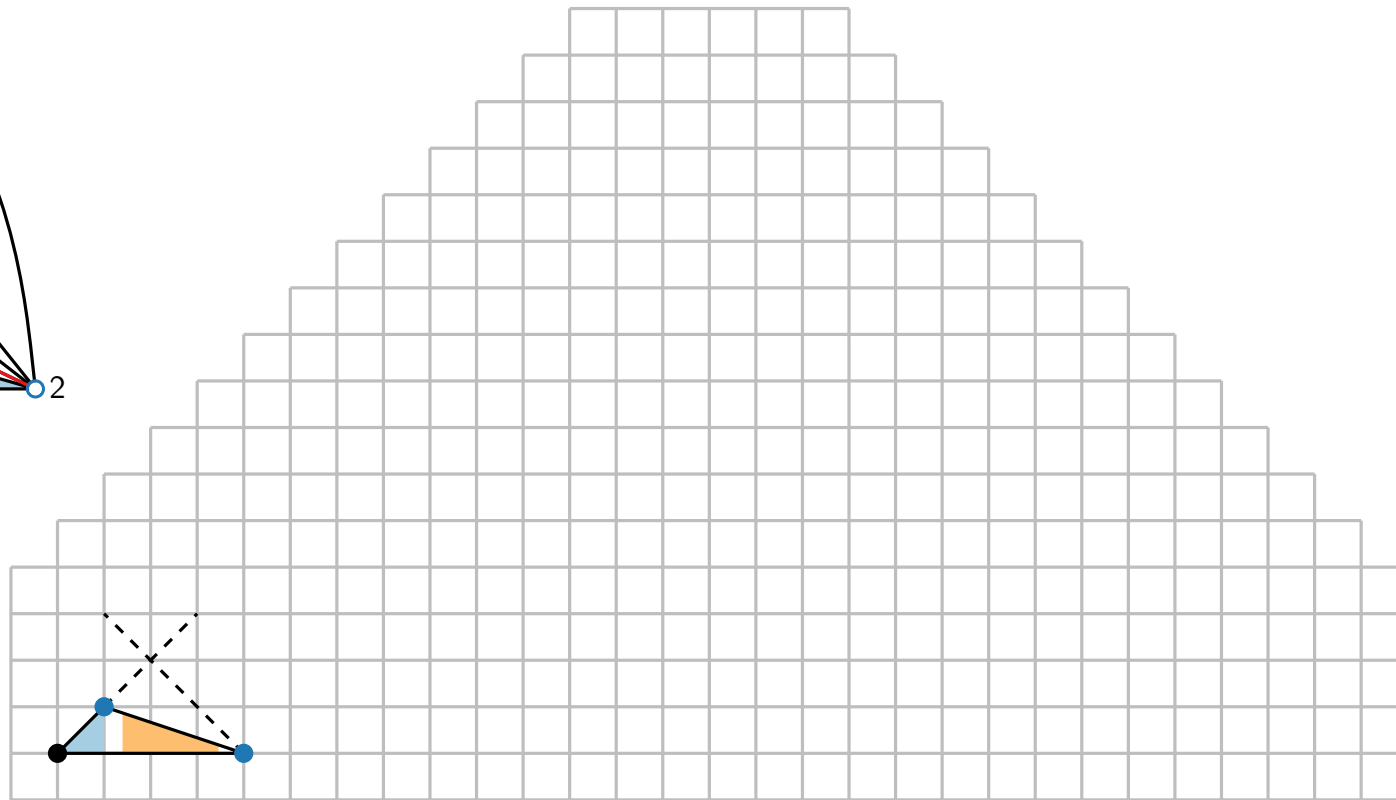
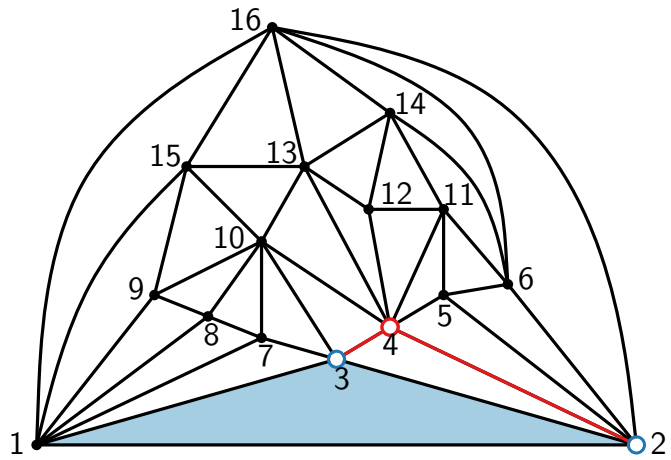
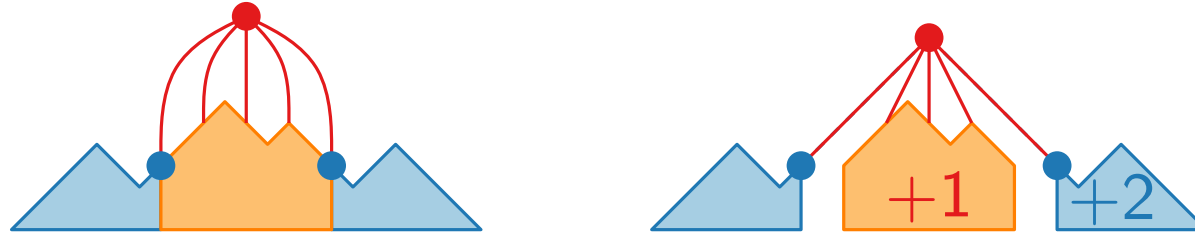
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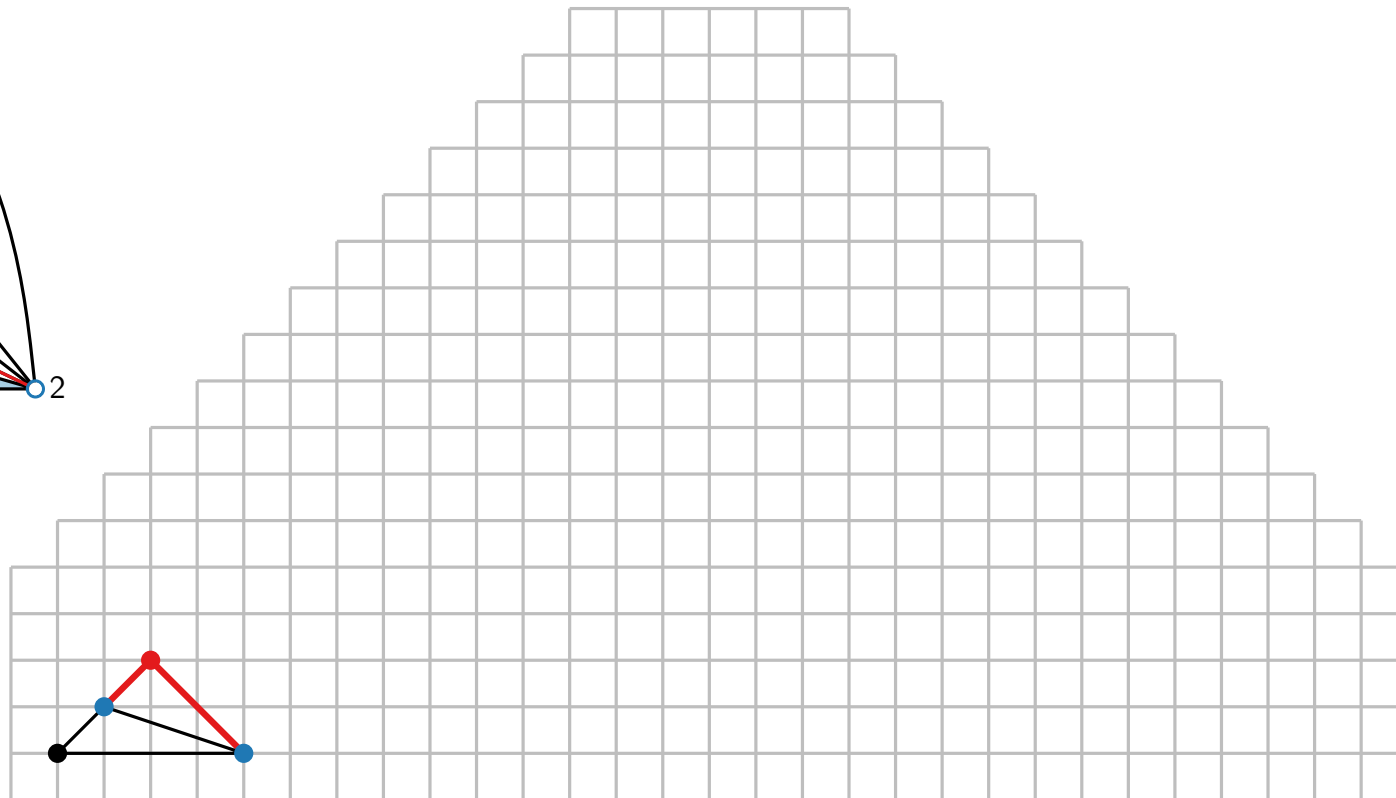
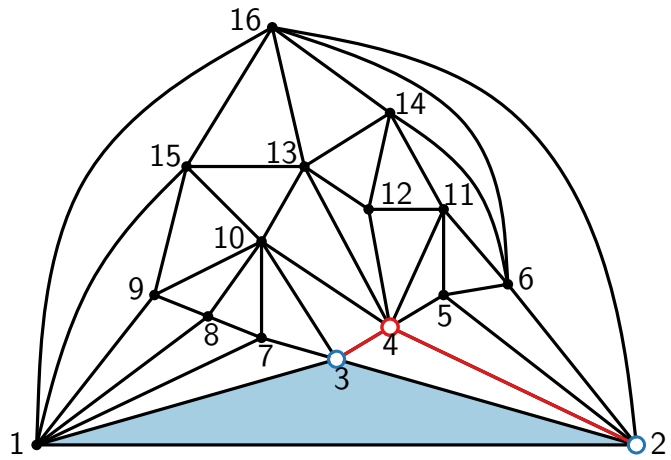
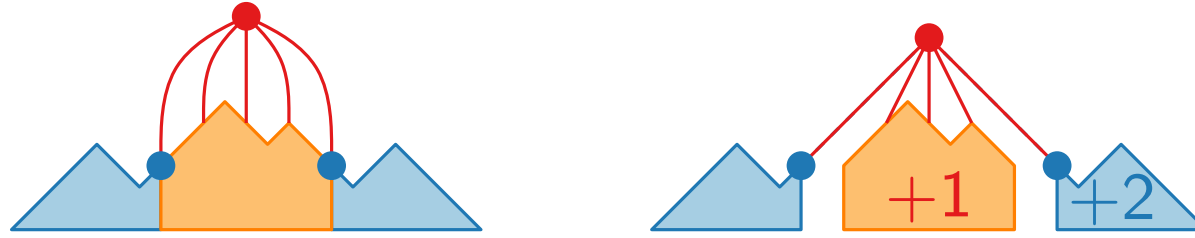
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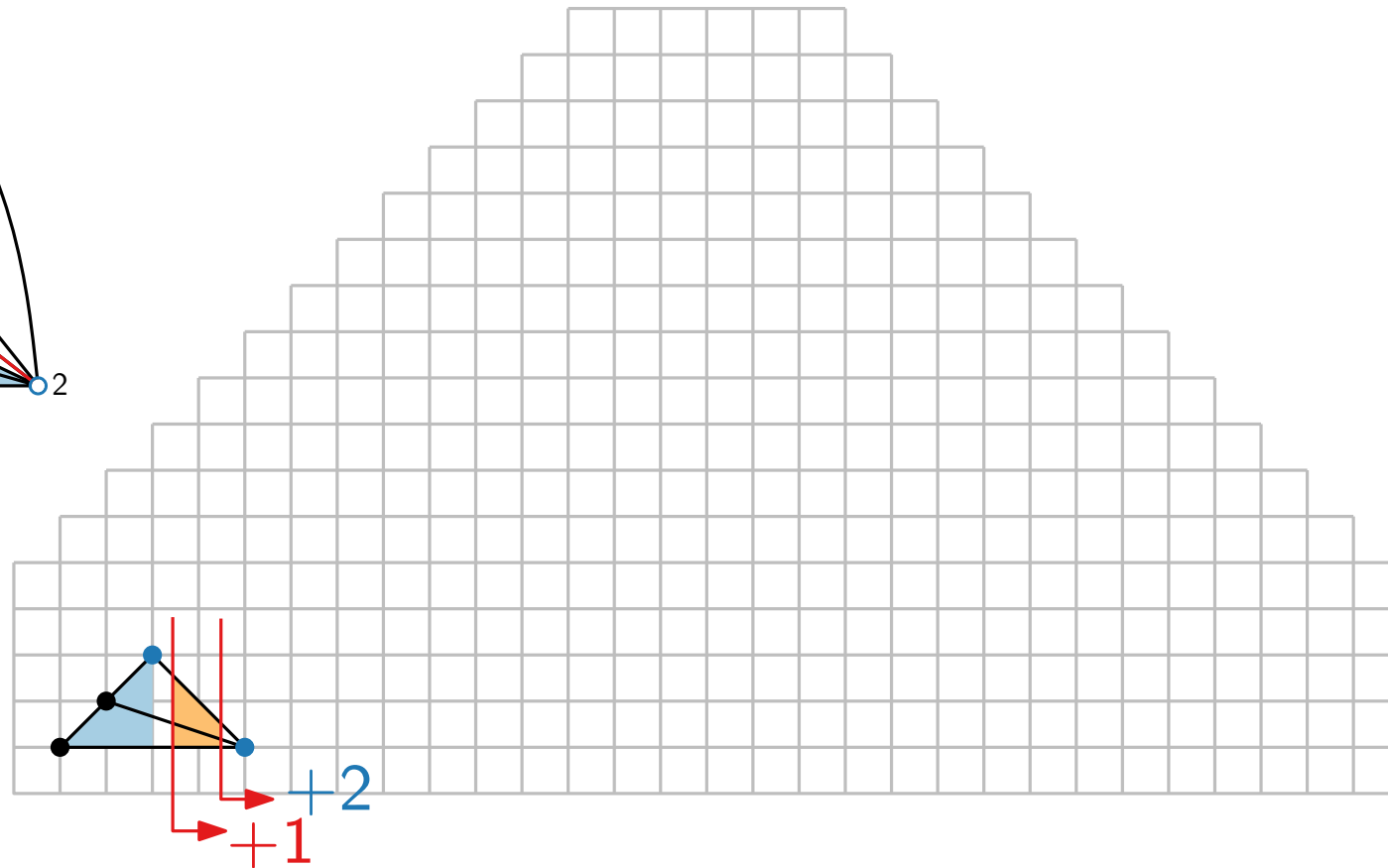
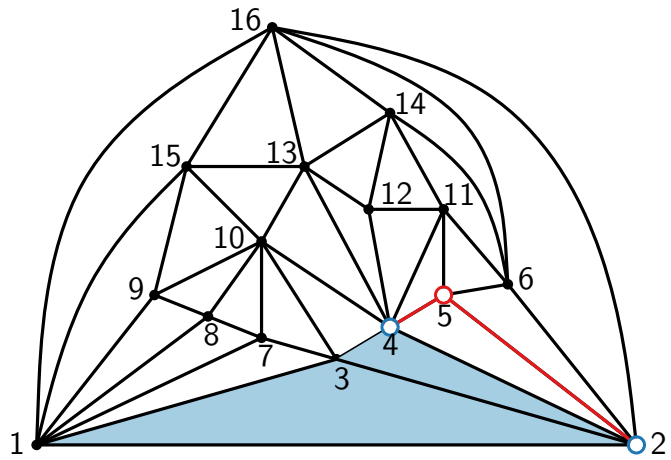
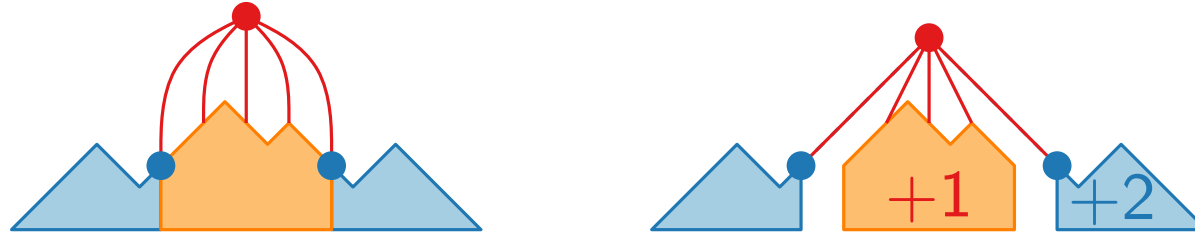
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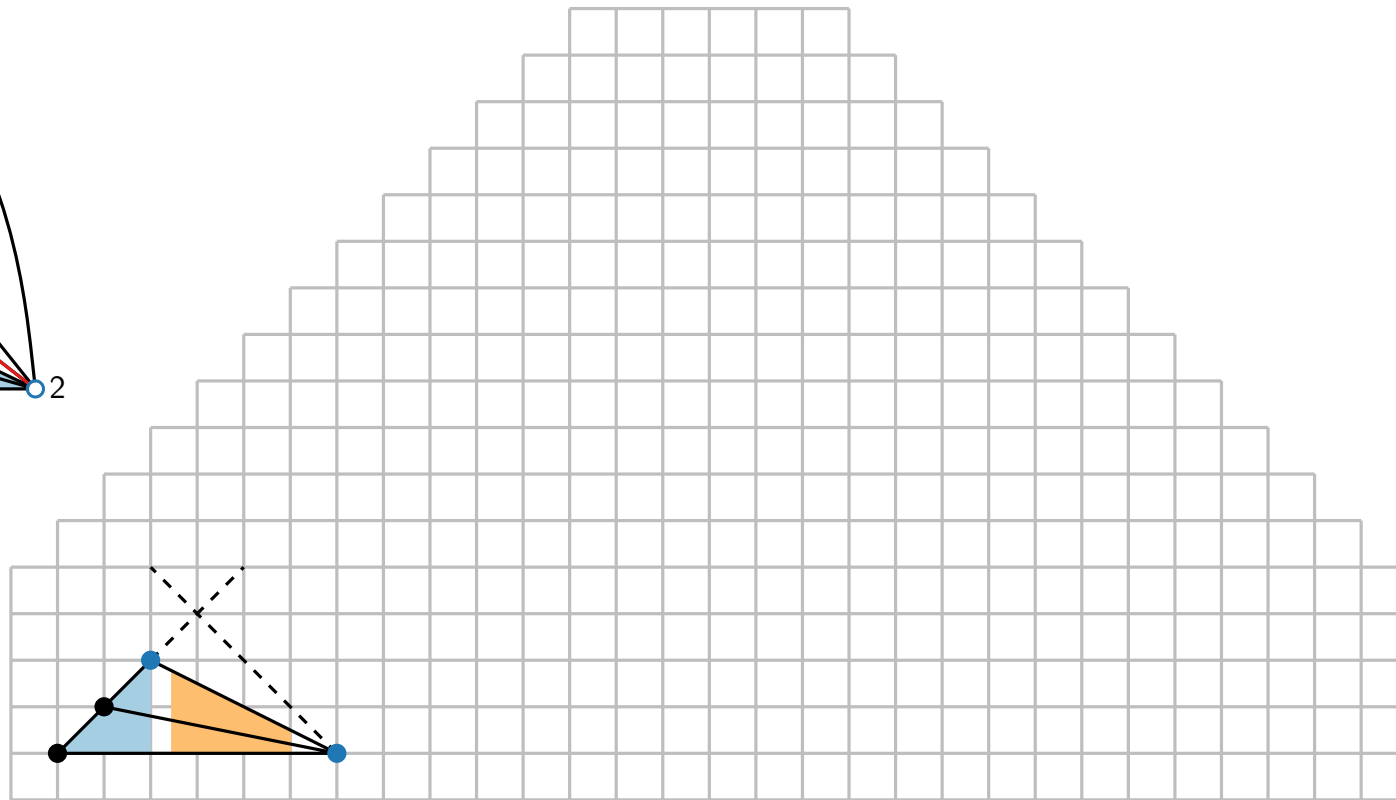
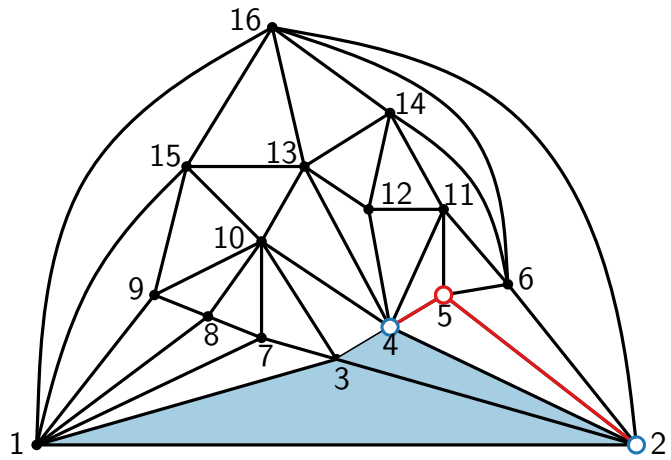
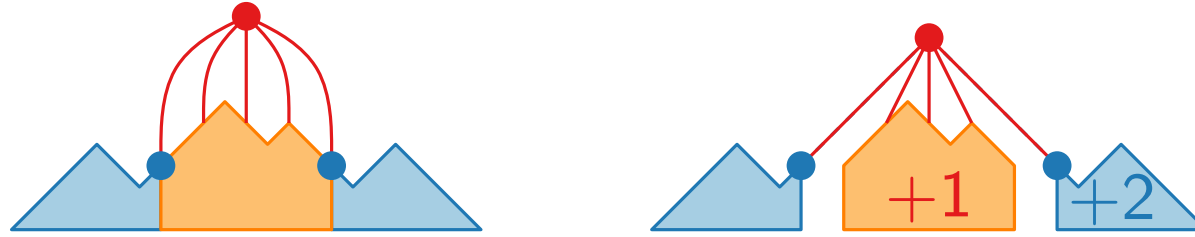
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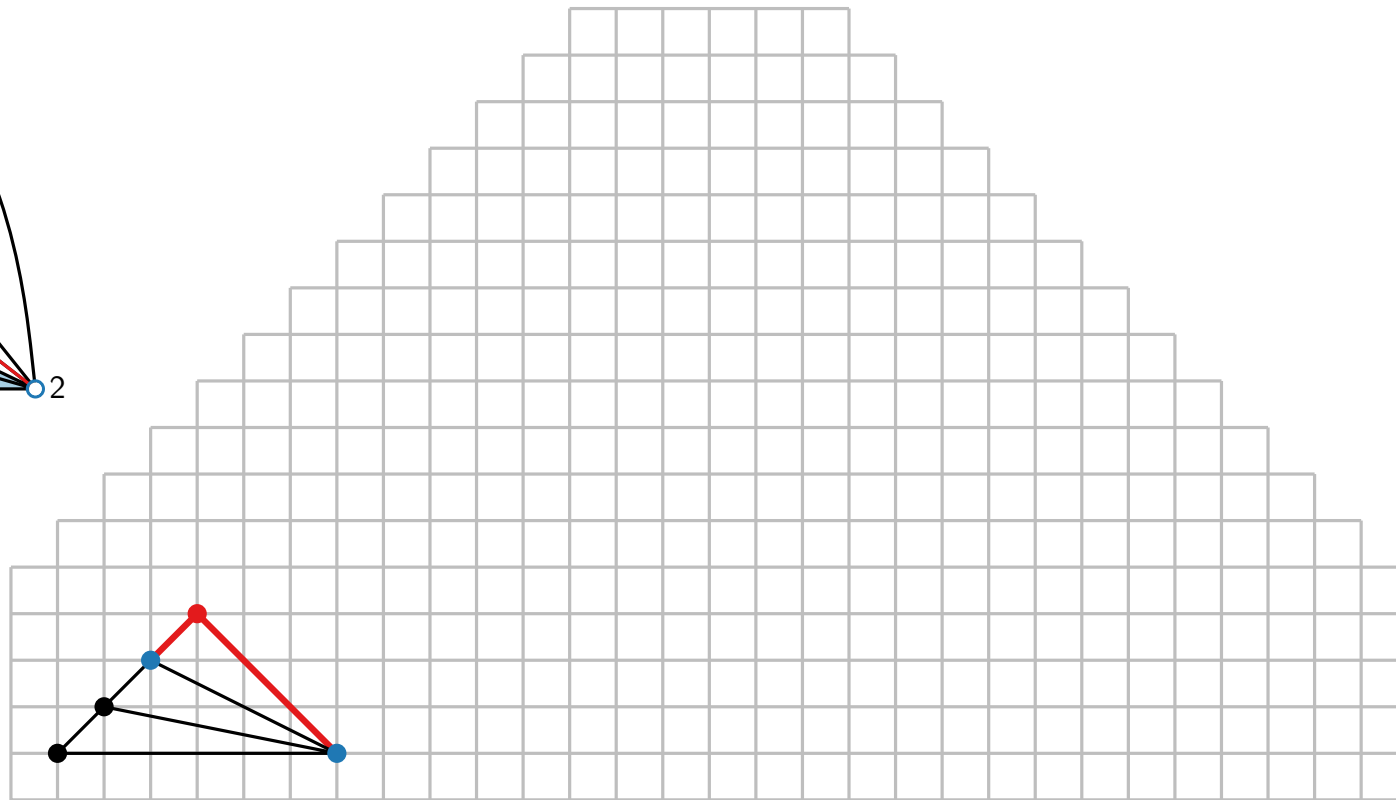
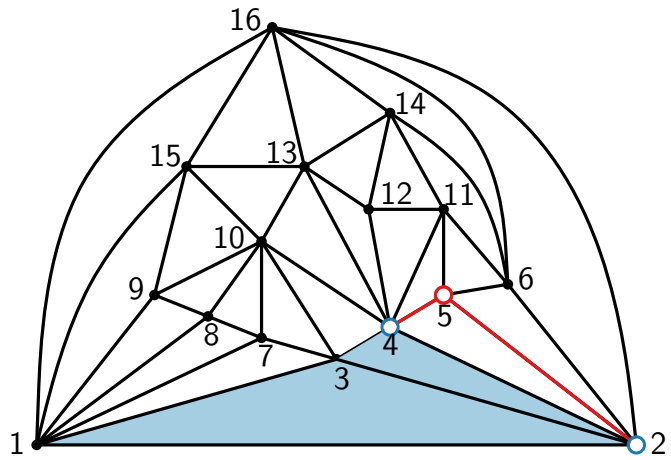
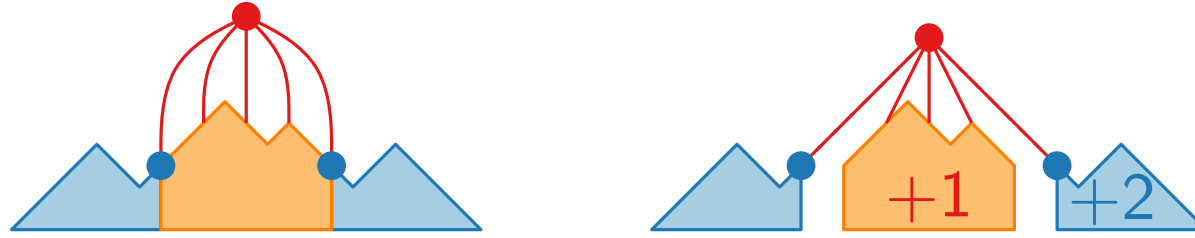
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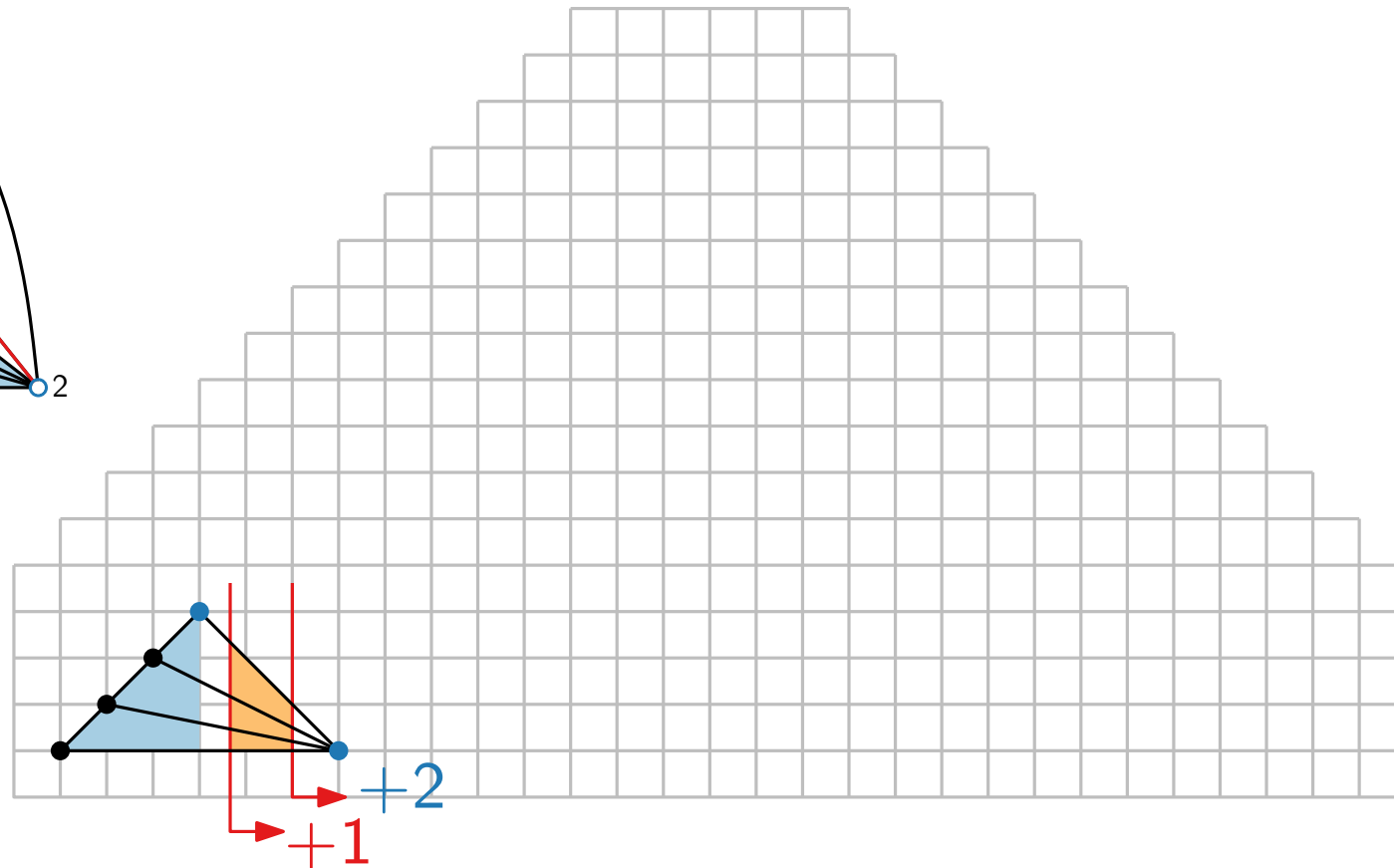
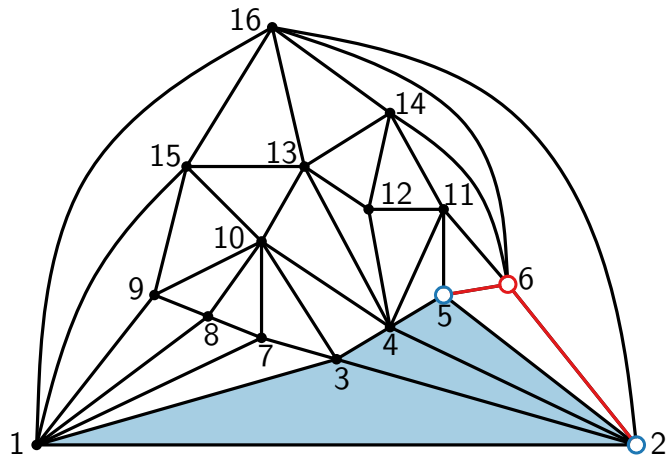
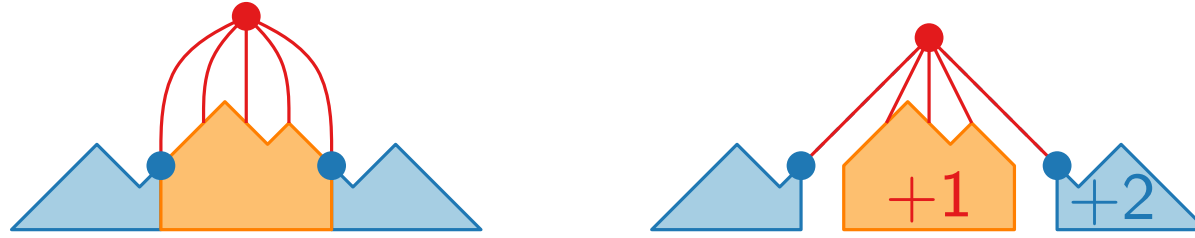
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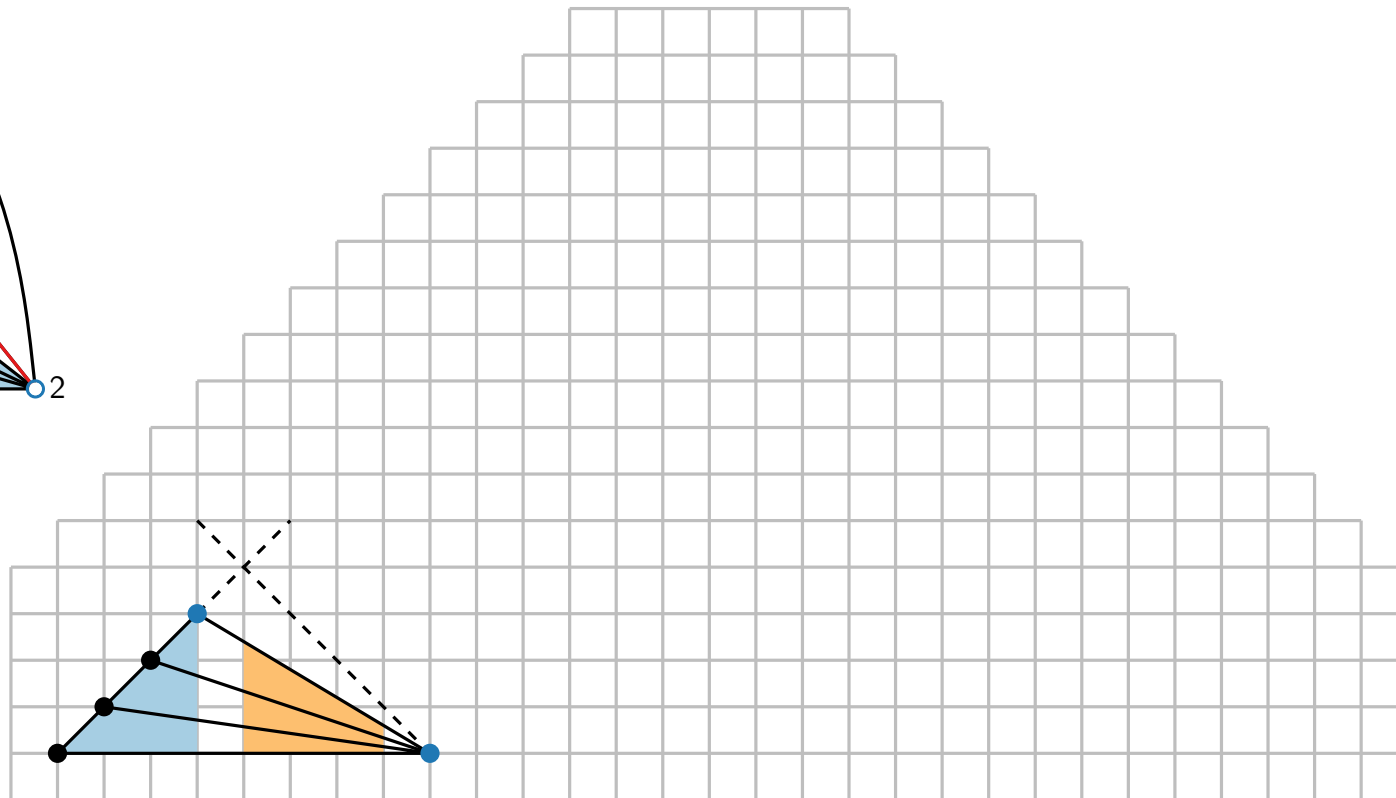
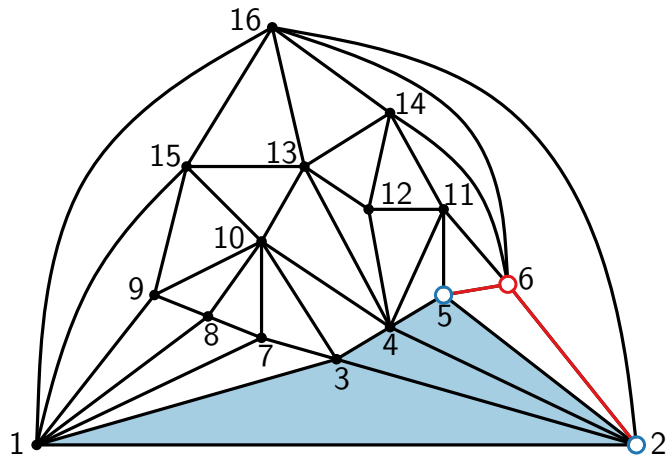
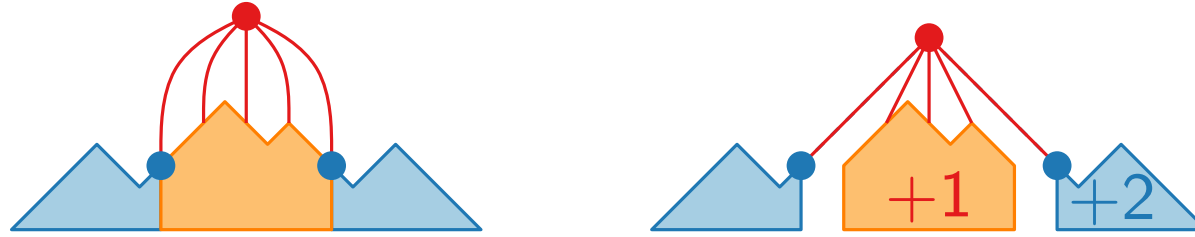
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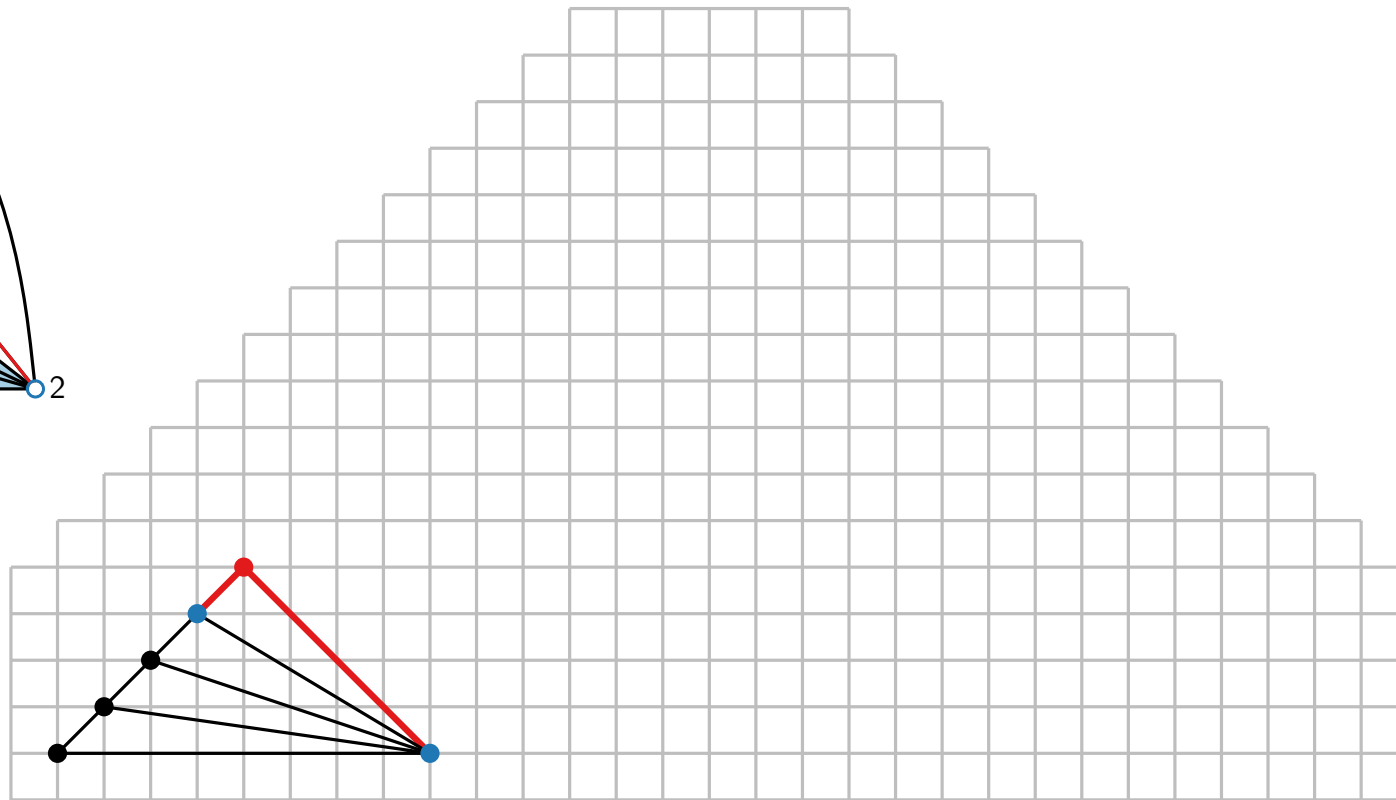
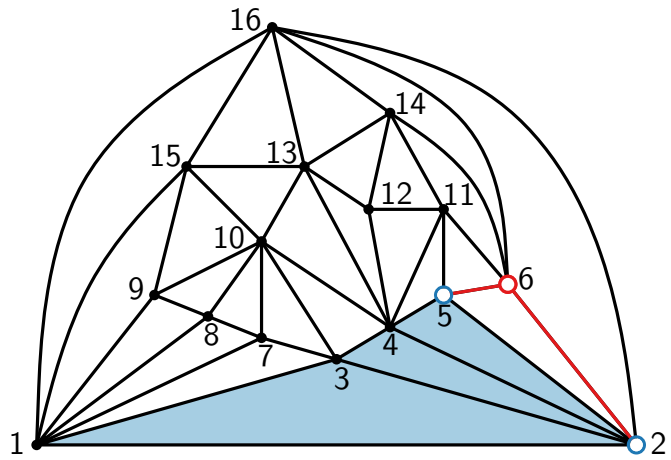
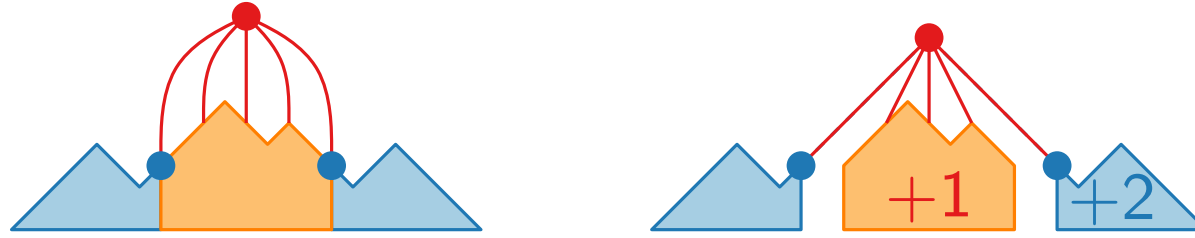
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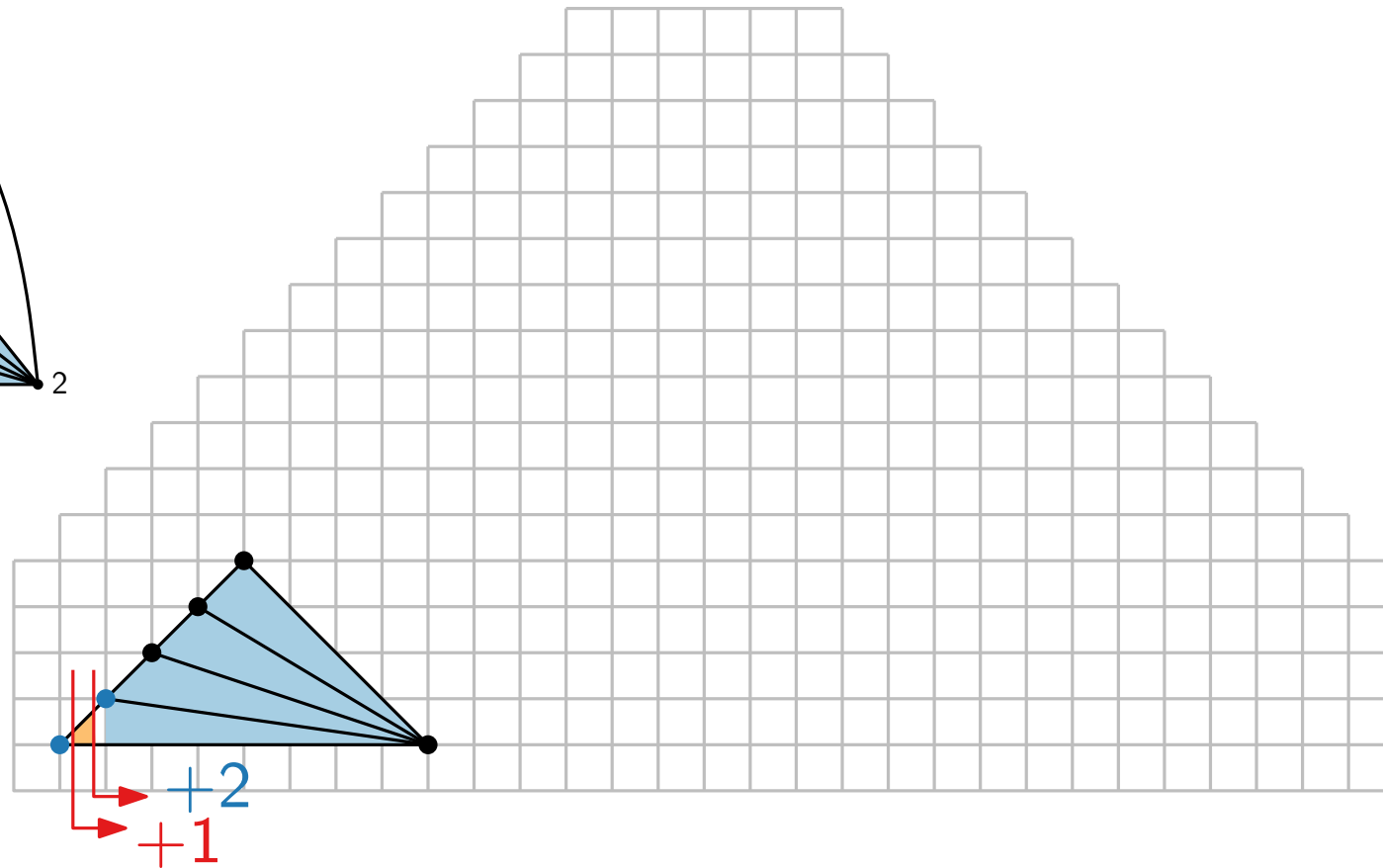
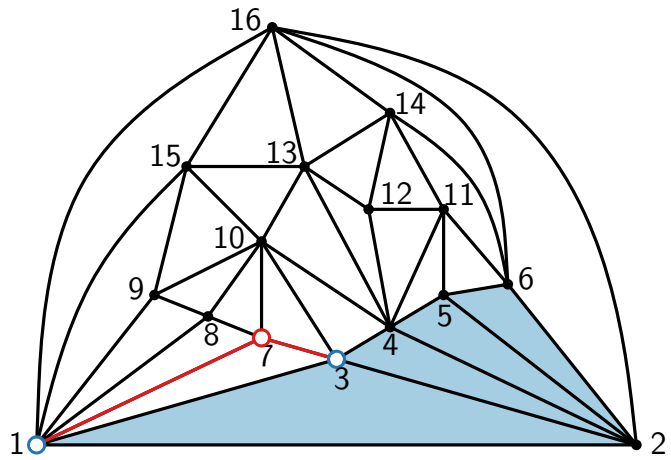
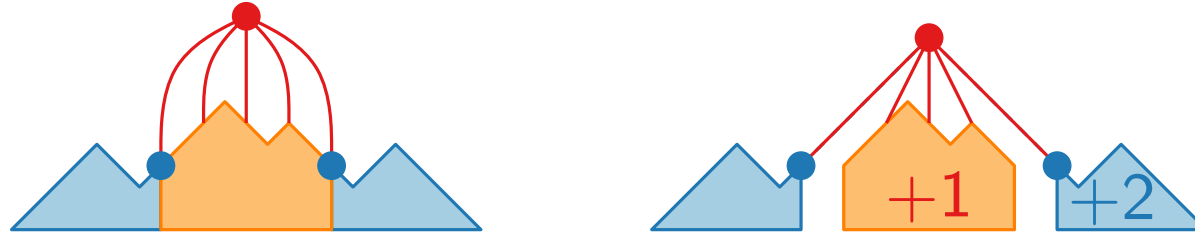
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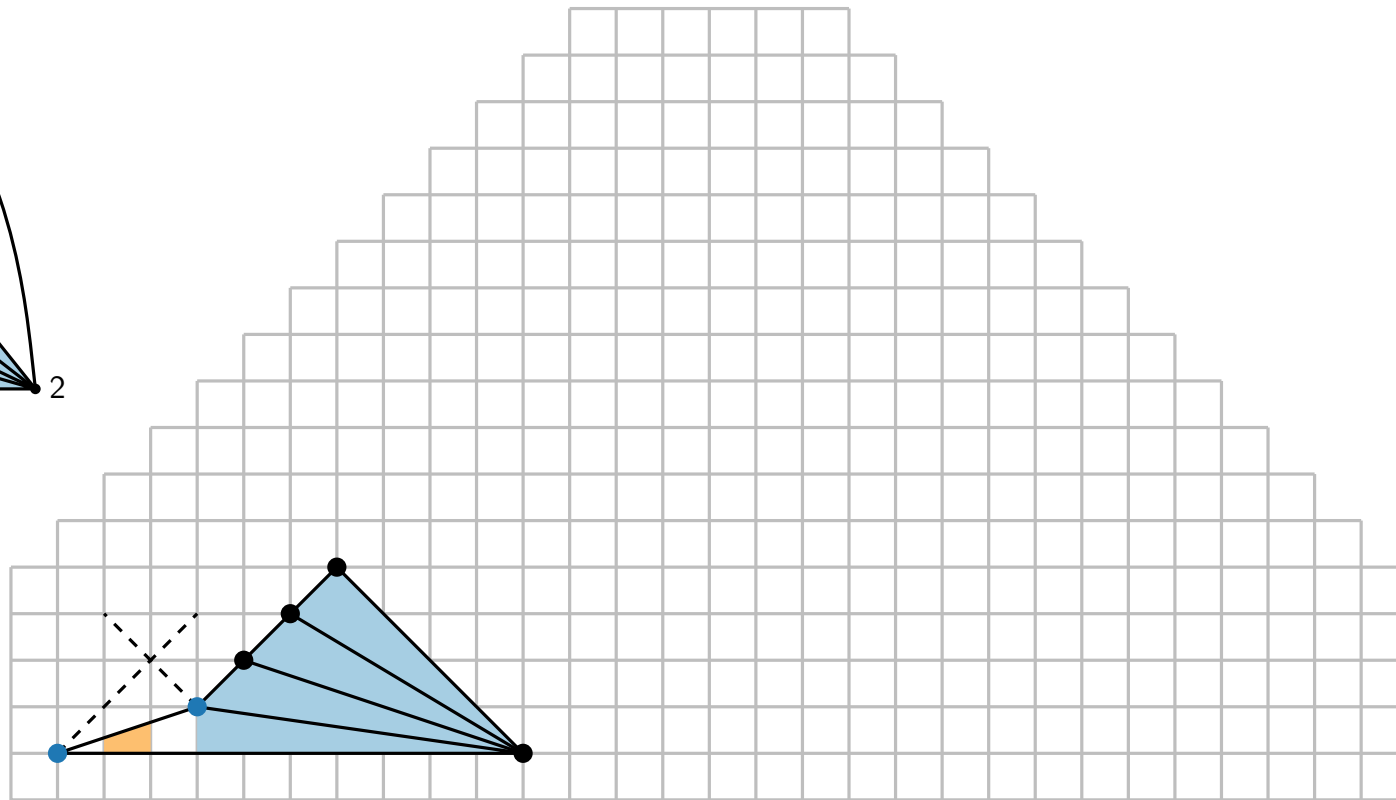
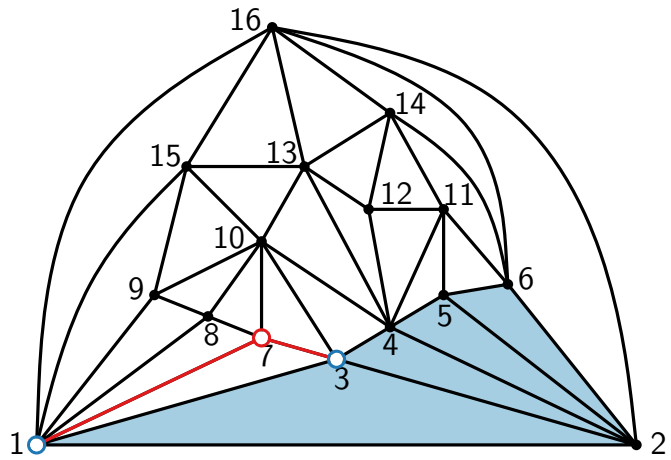
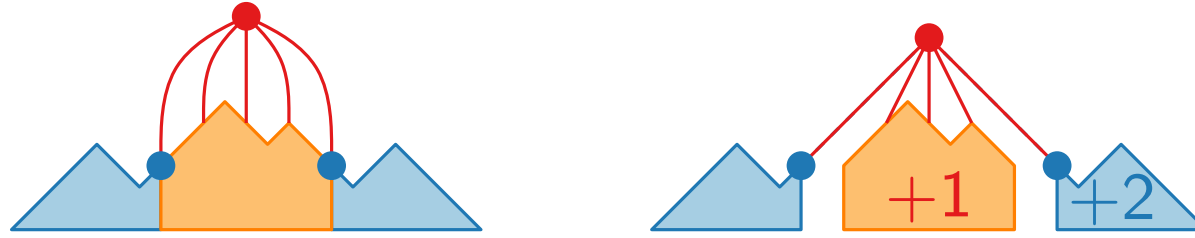
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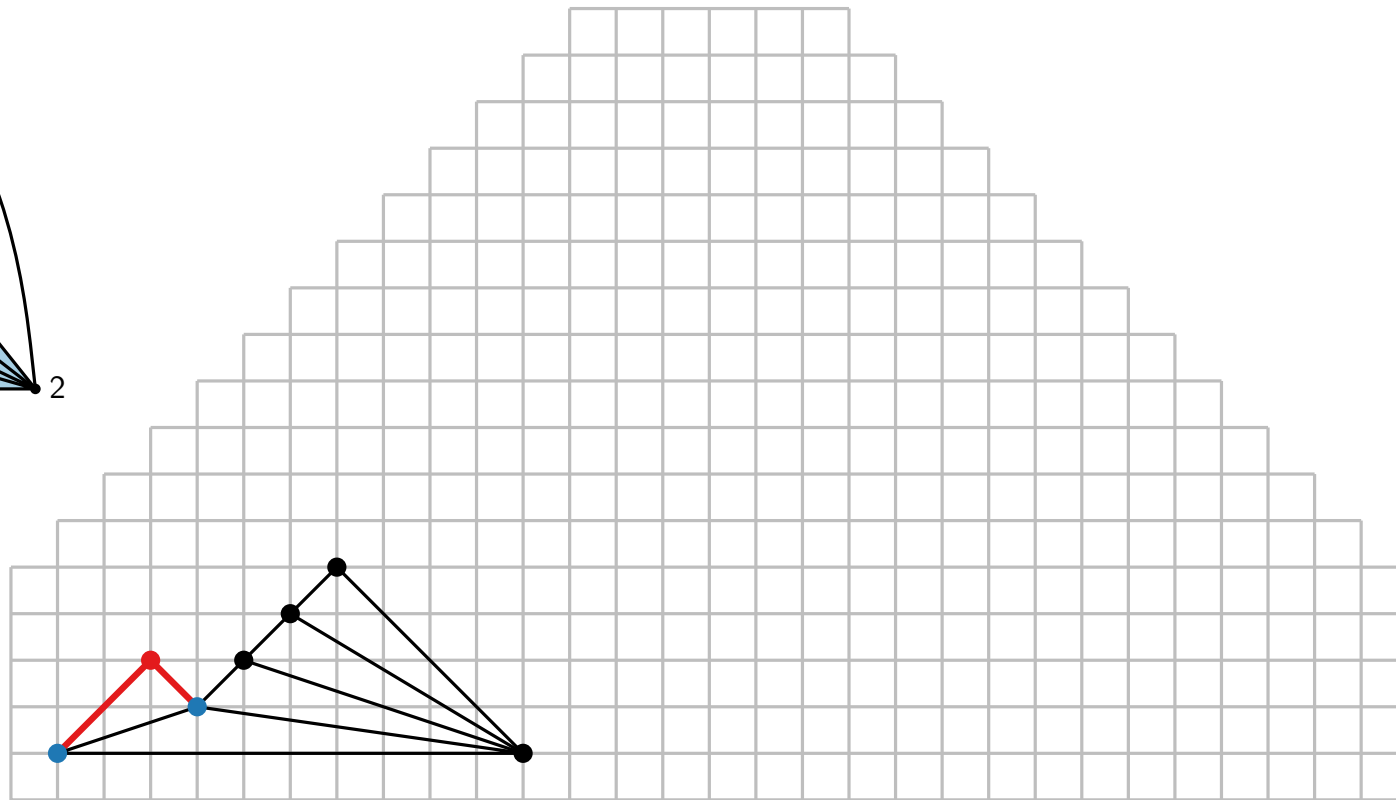
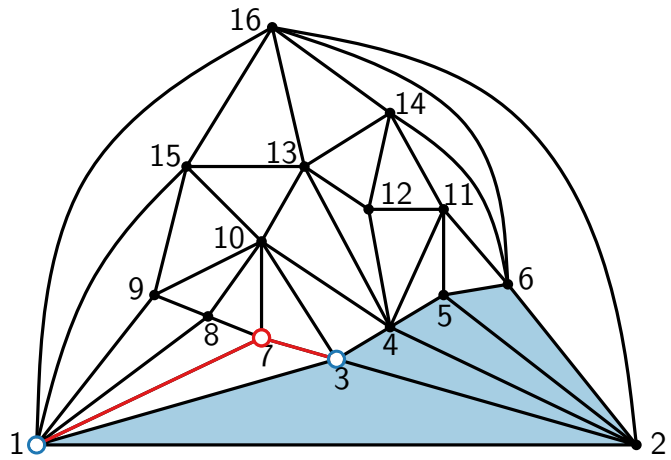
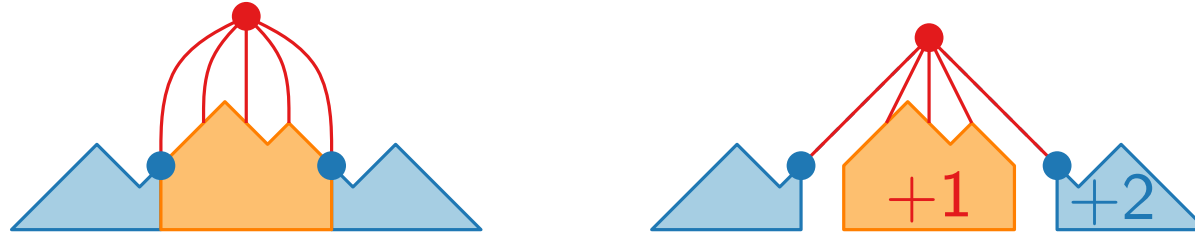
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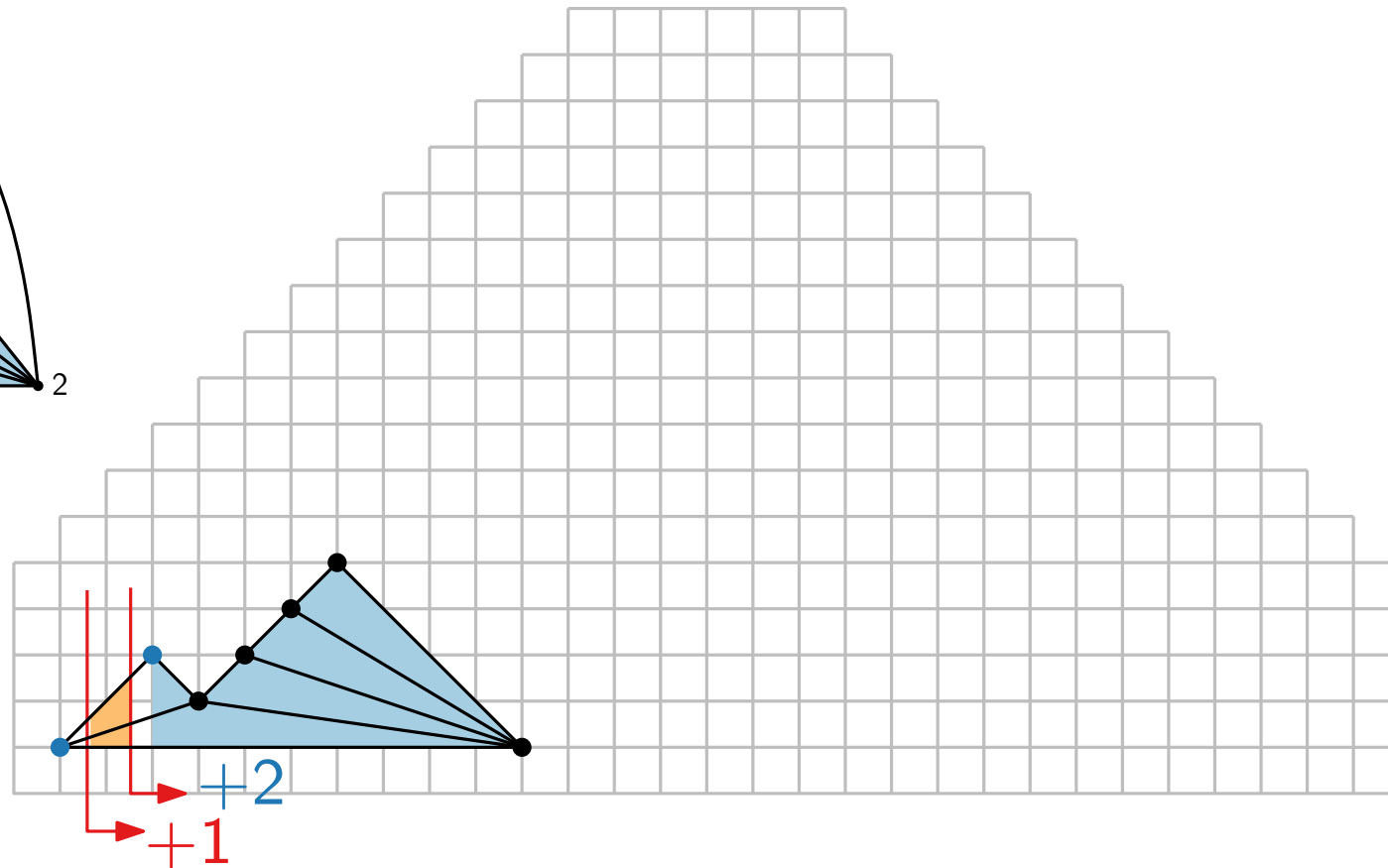
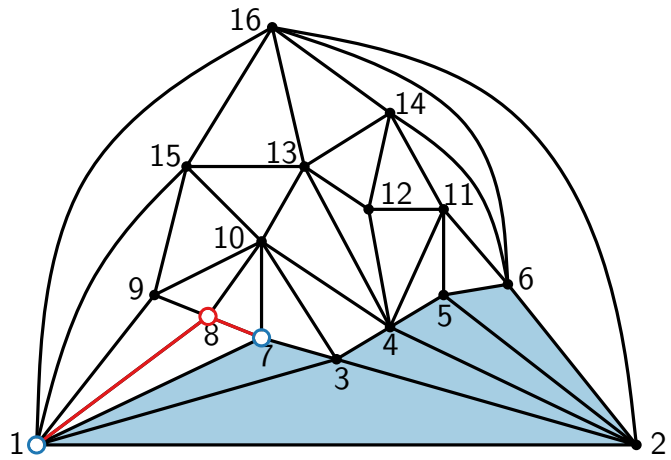
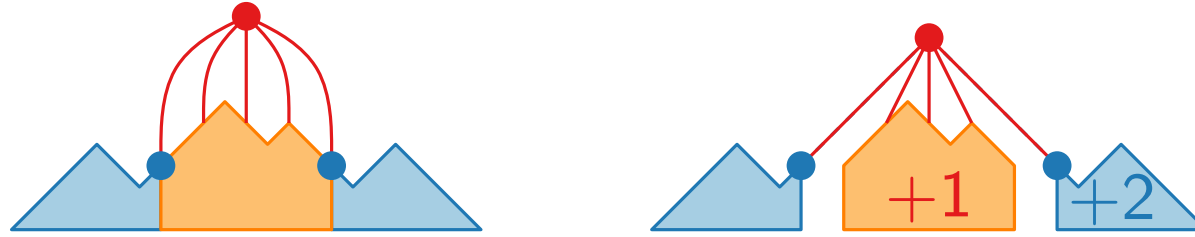
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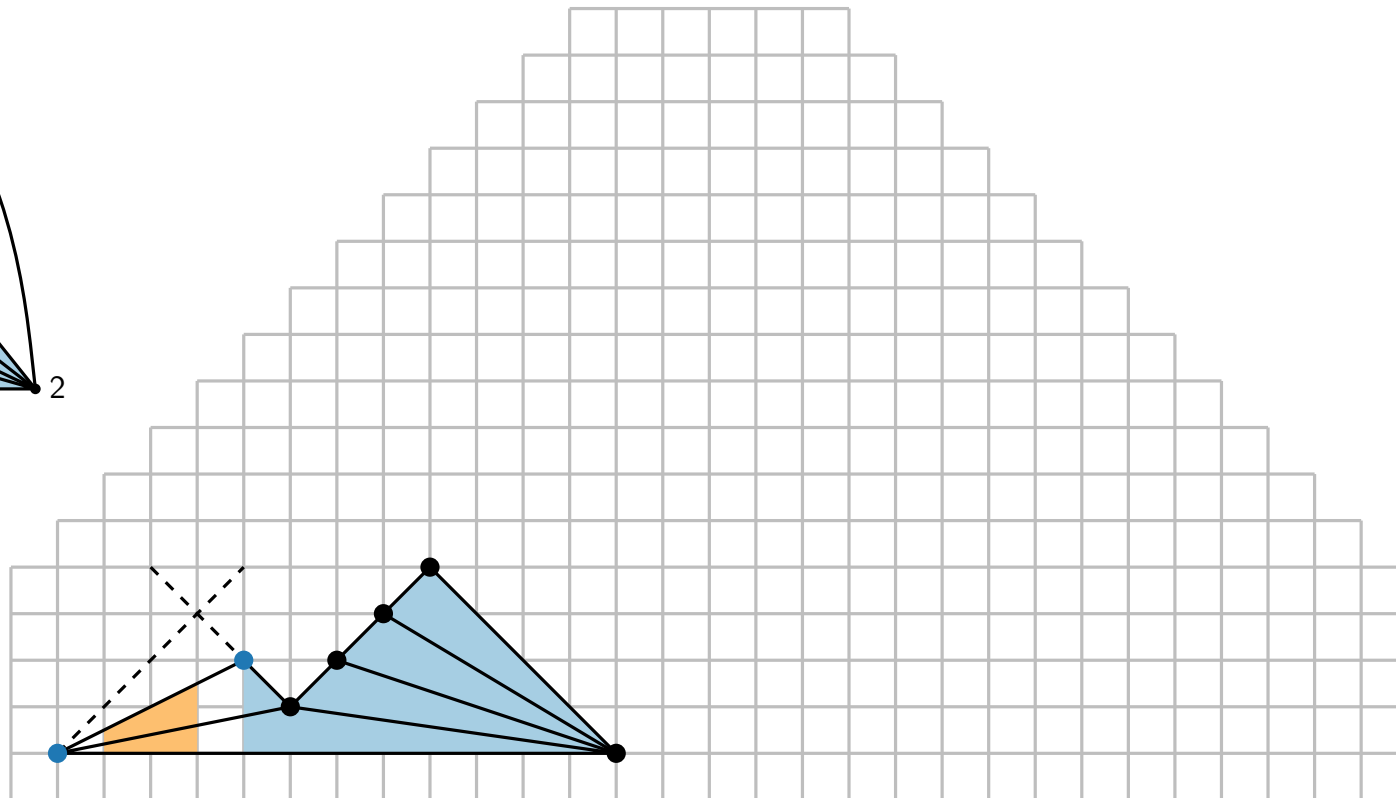
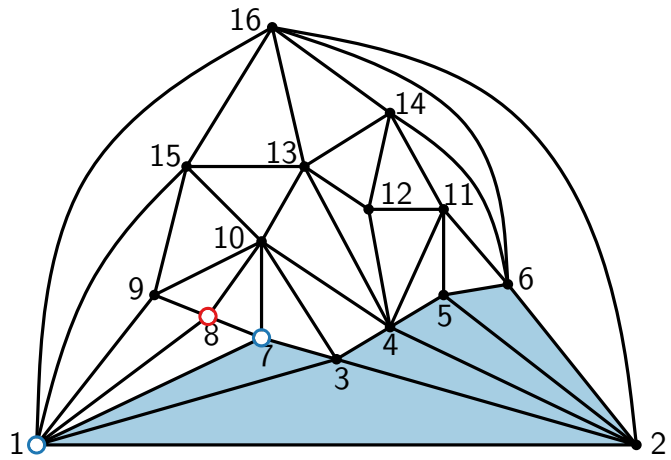
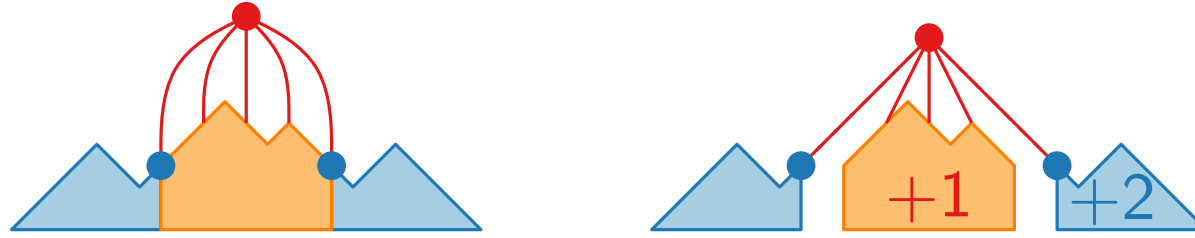
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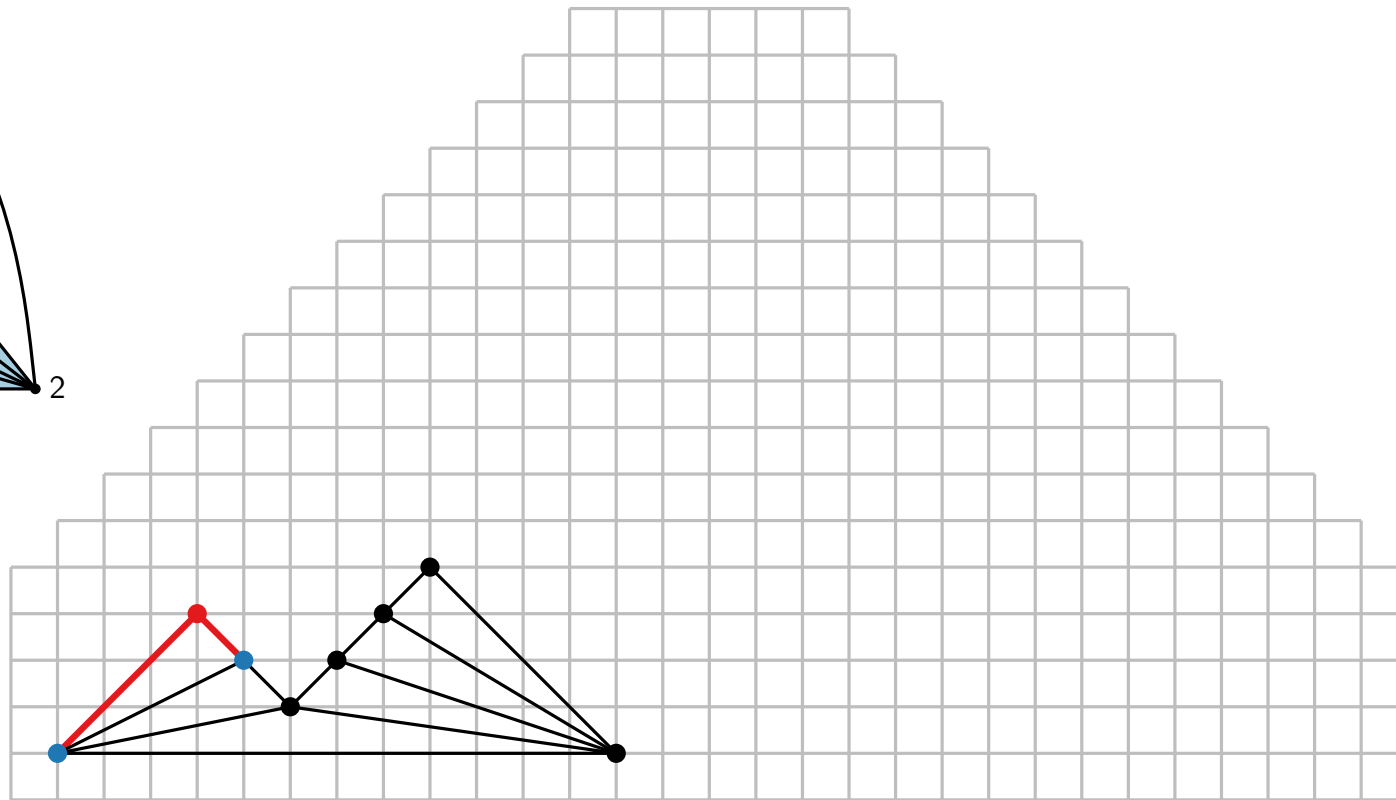
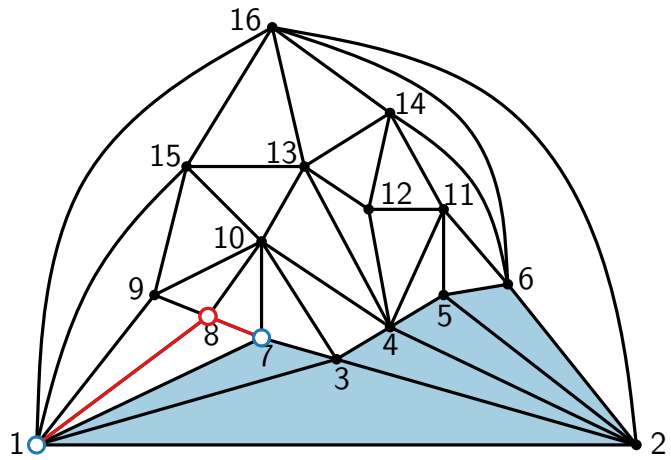
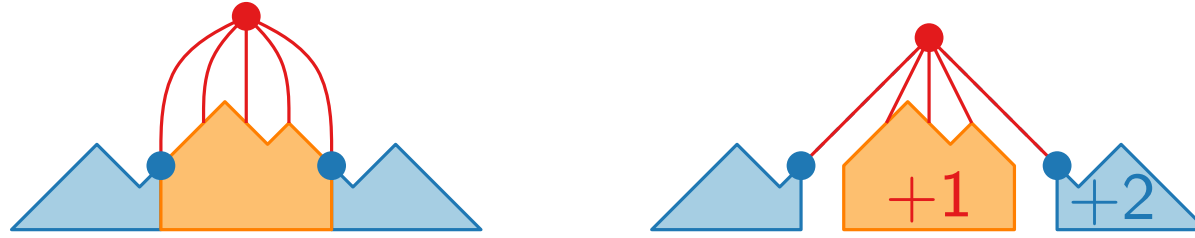
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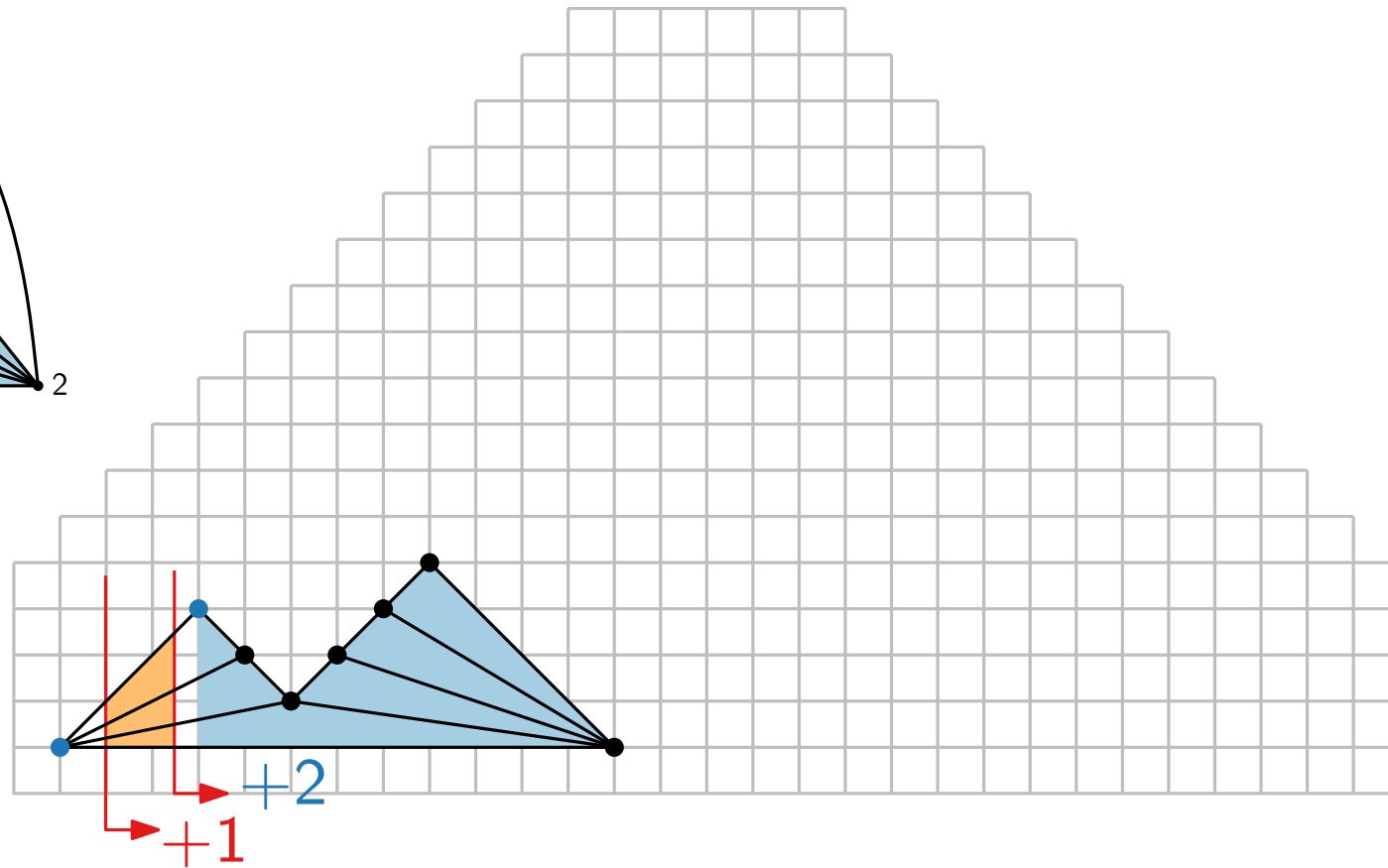
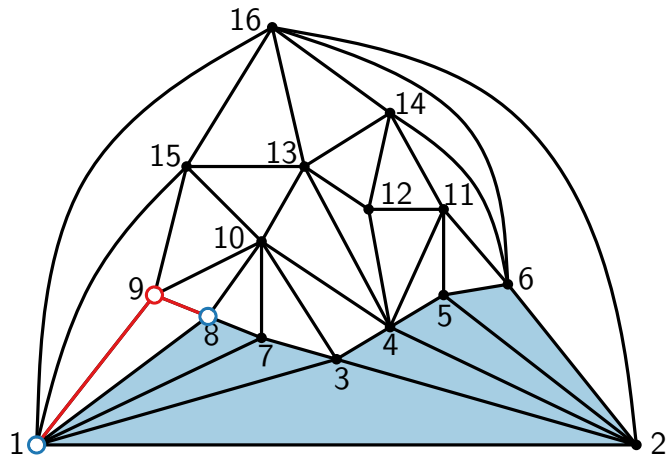
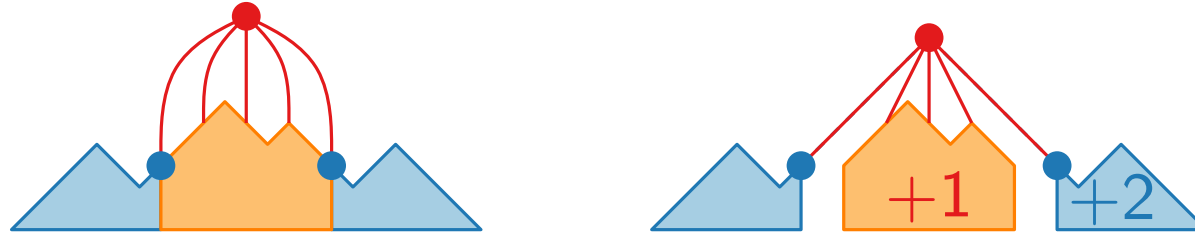
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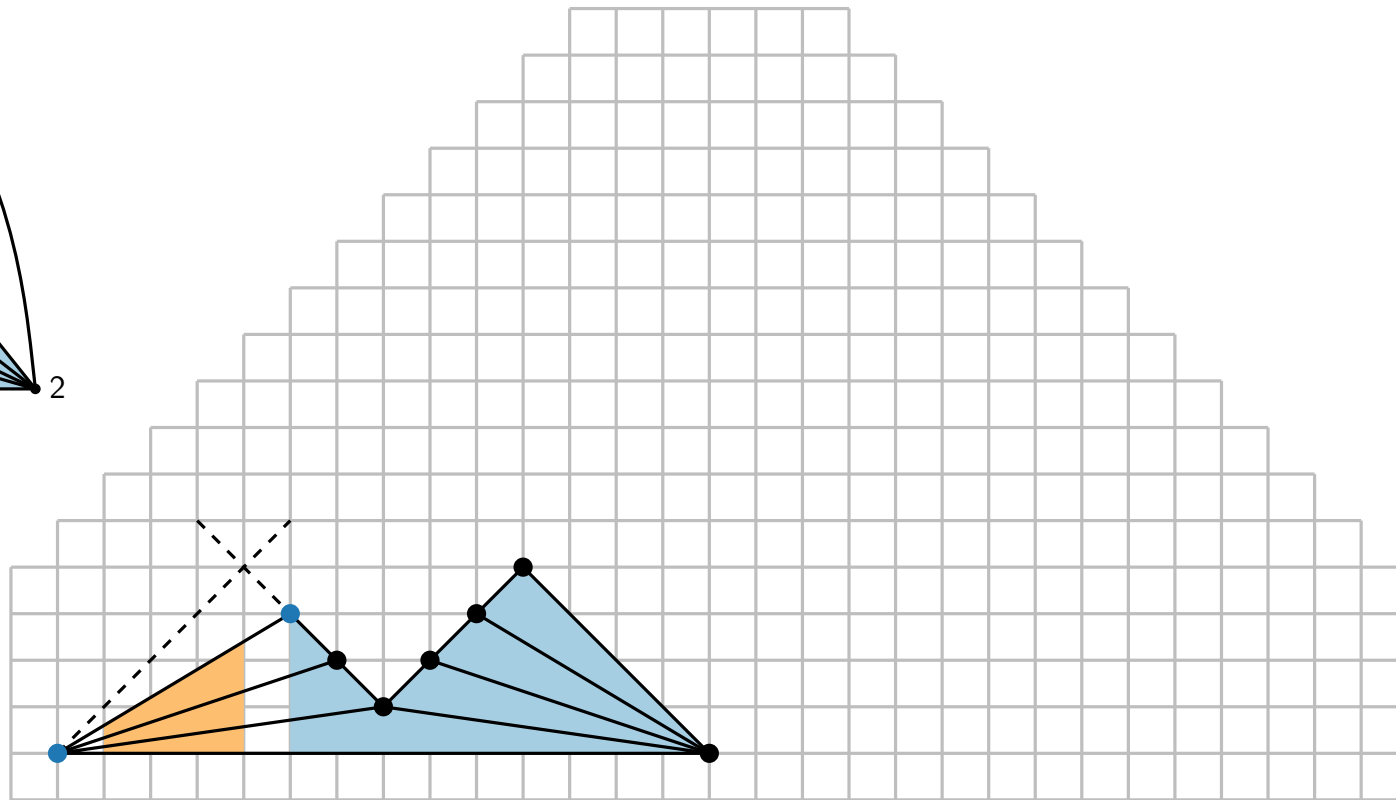
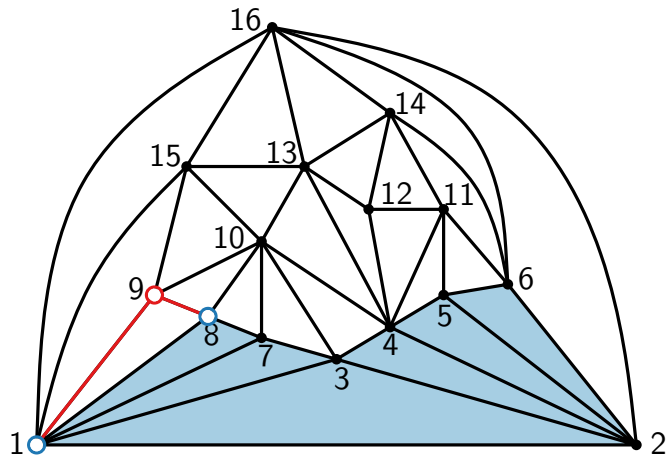
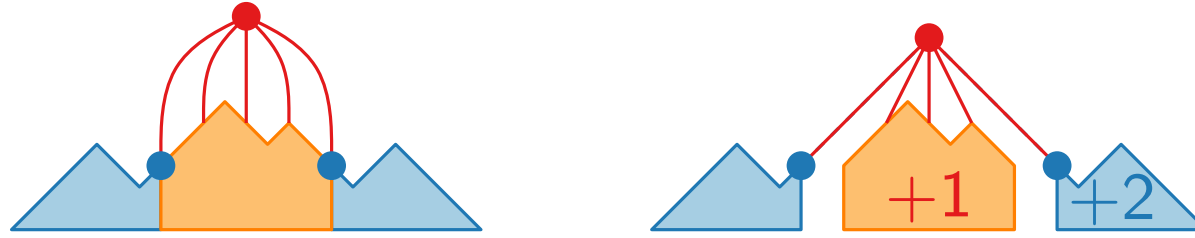
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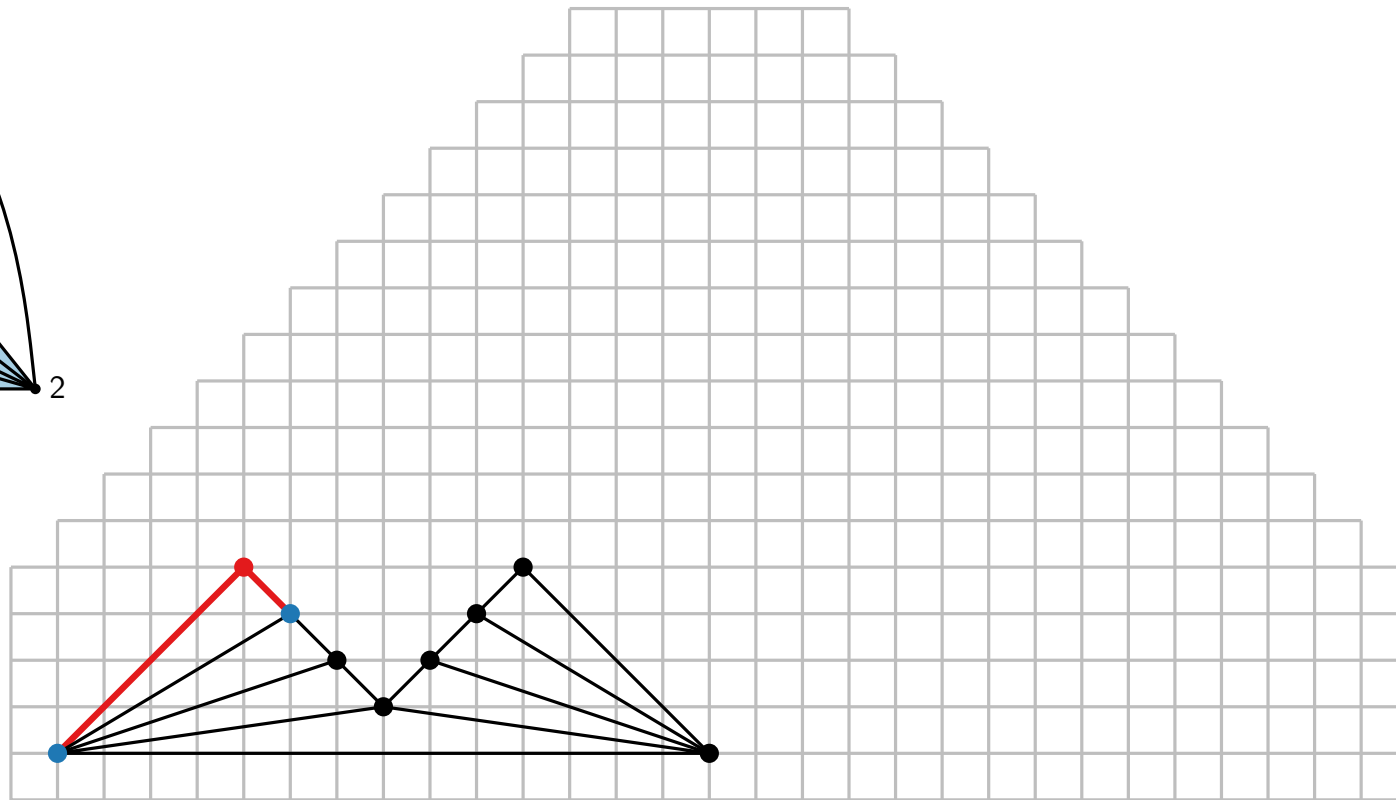
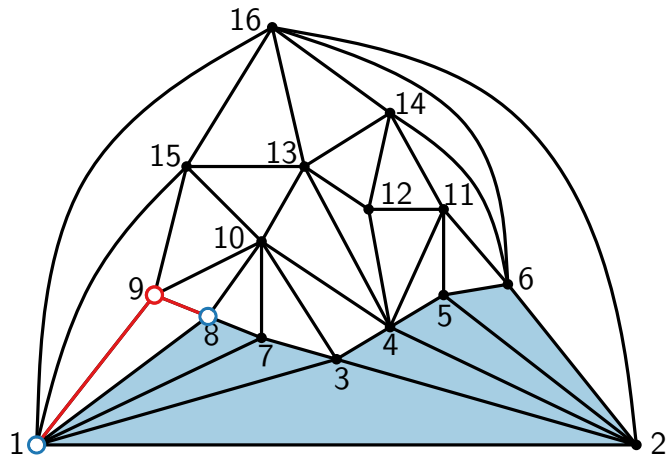
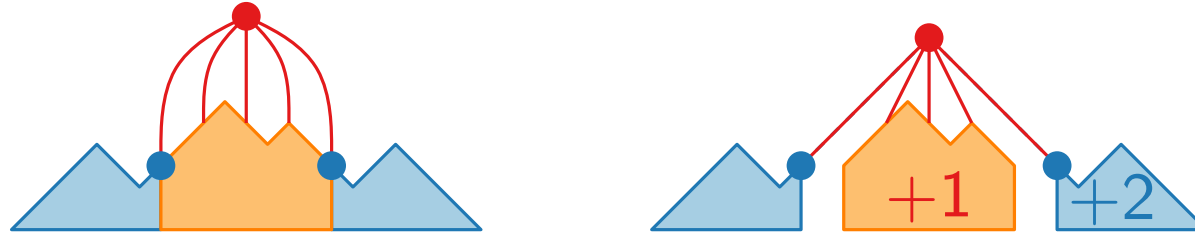
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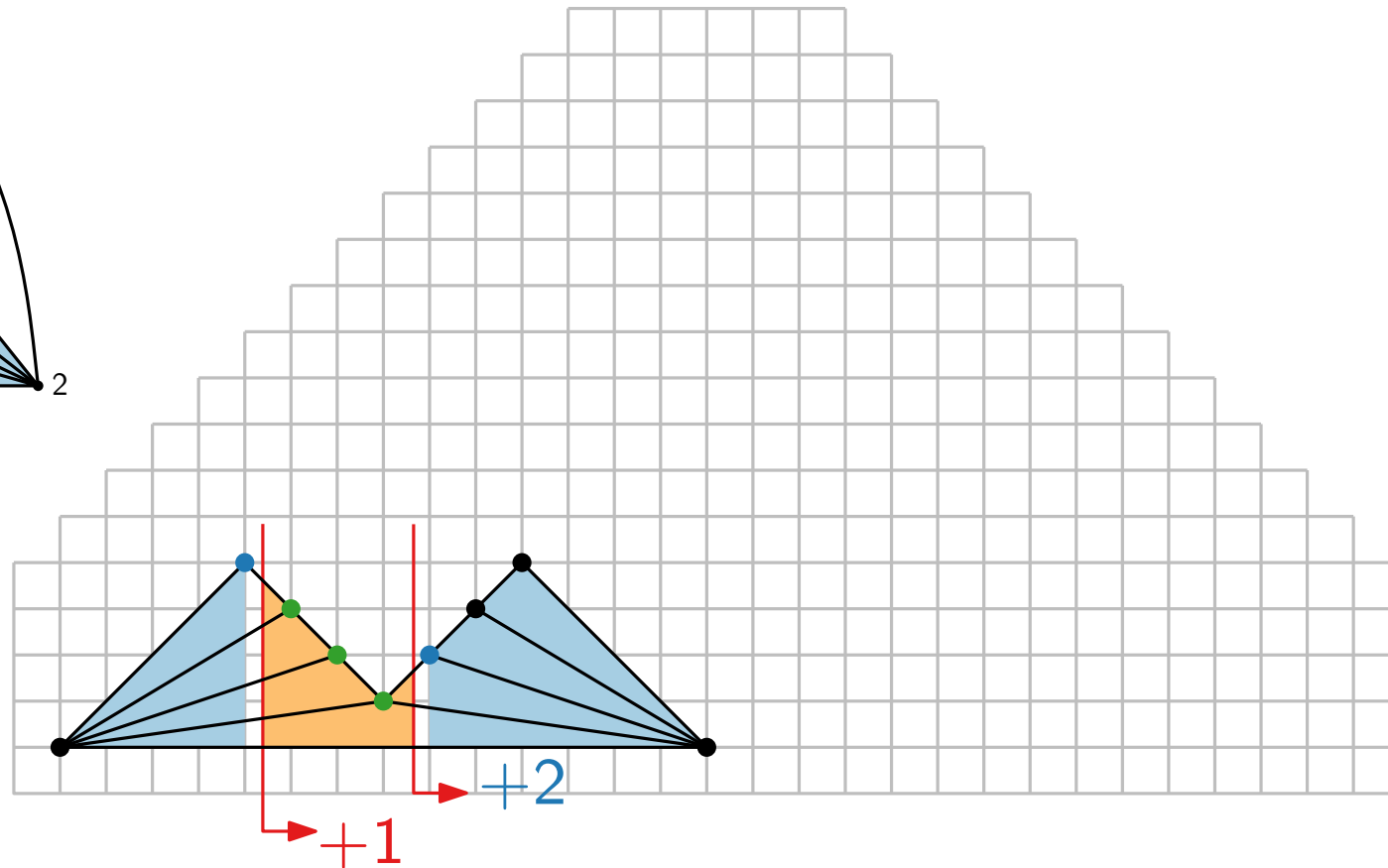
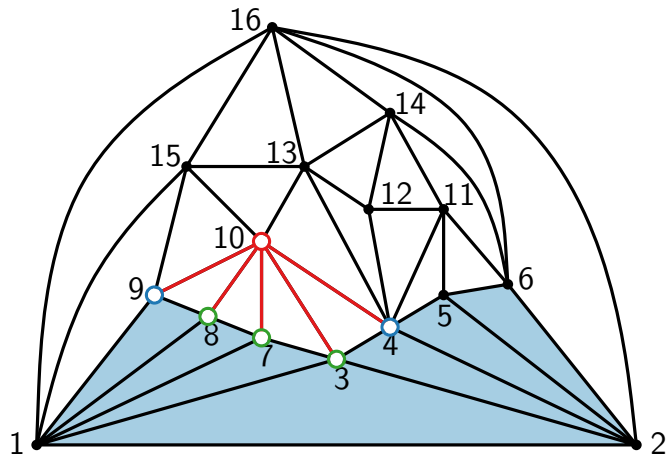
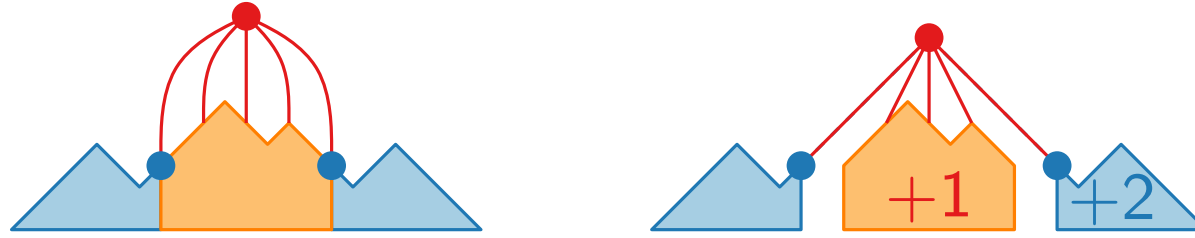
Shift method – example



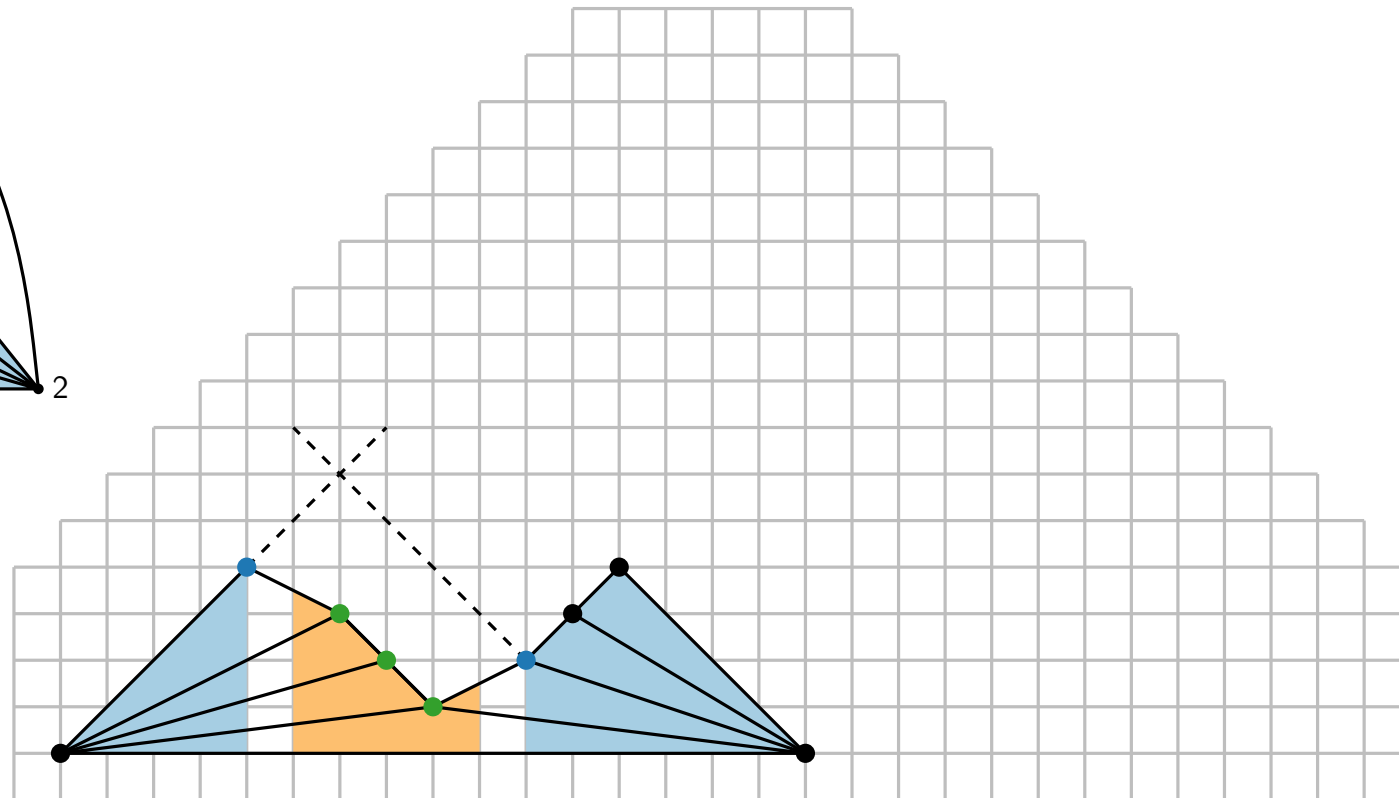
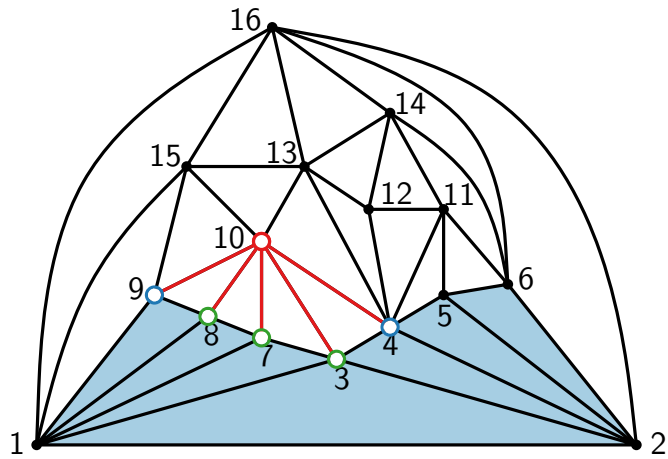
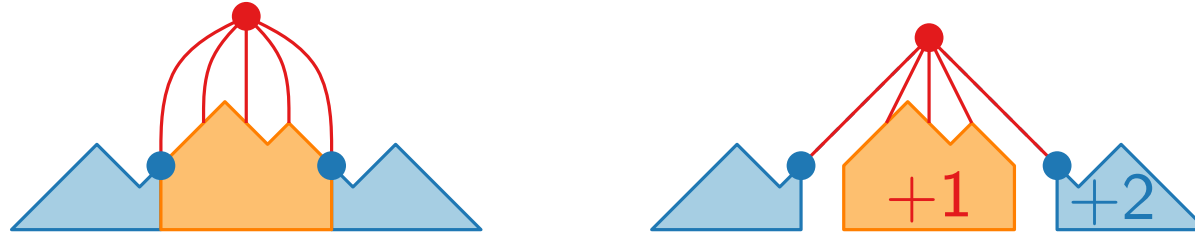
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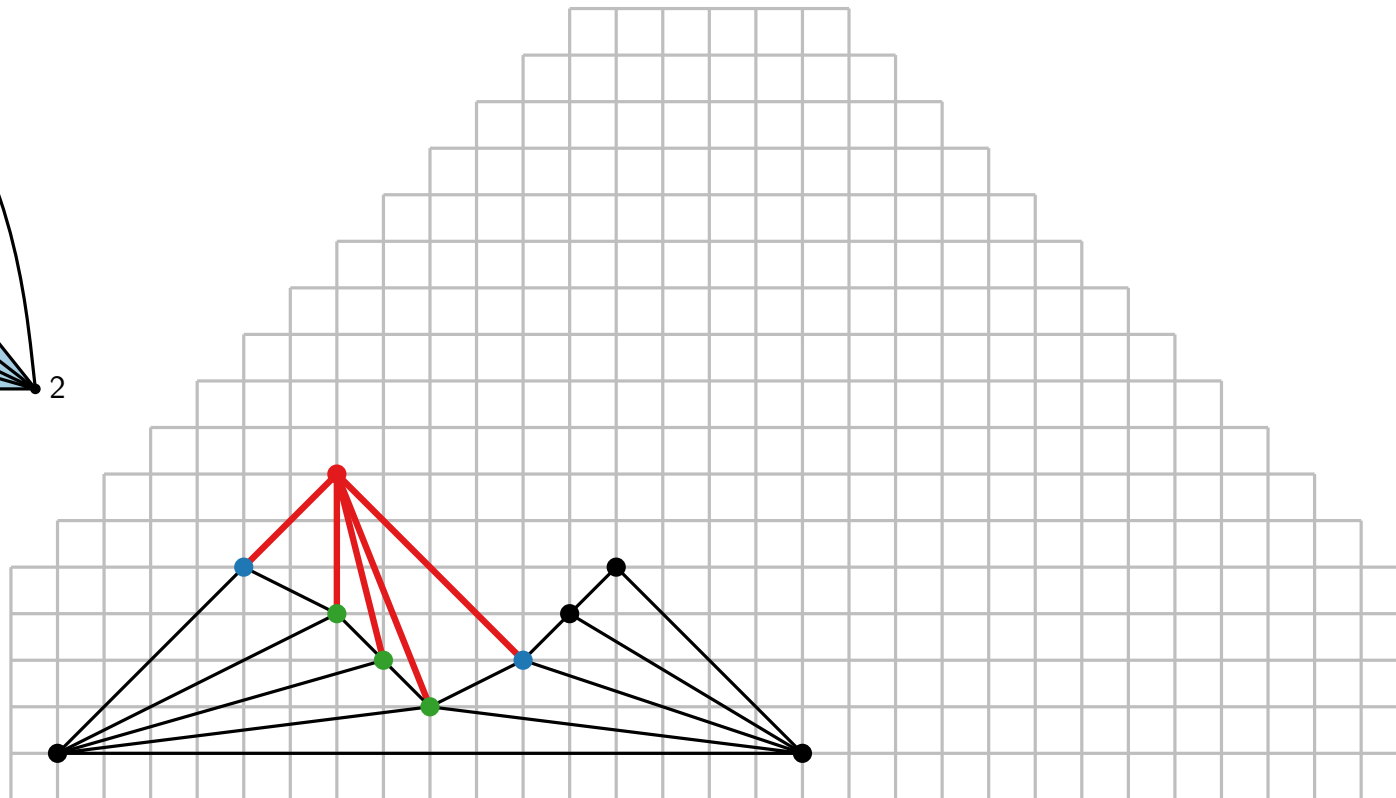
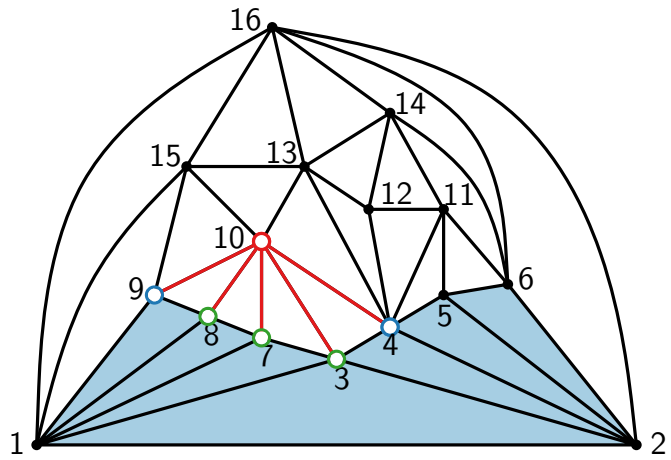
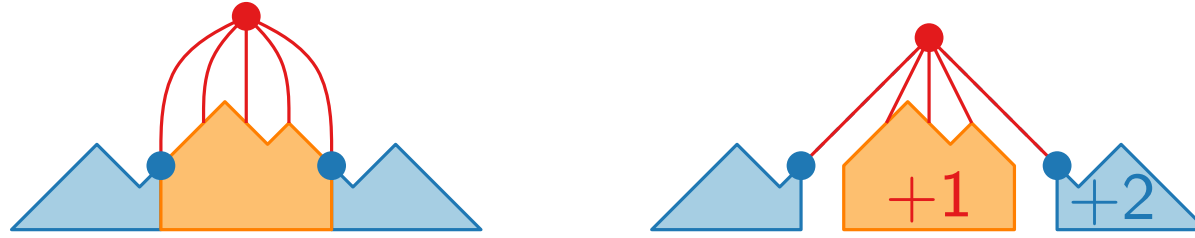
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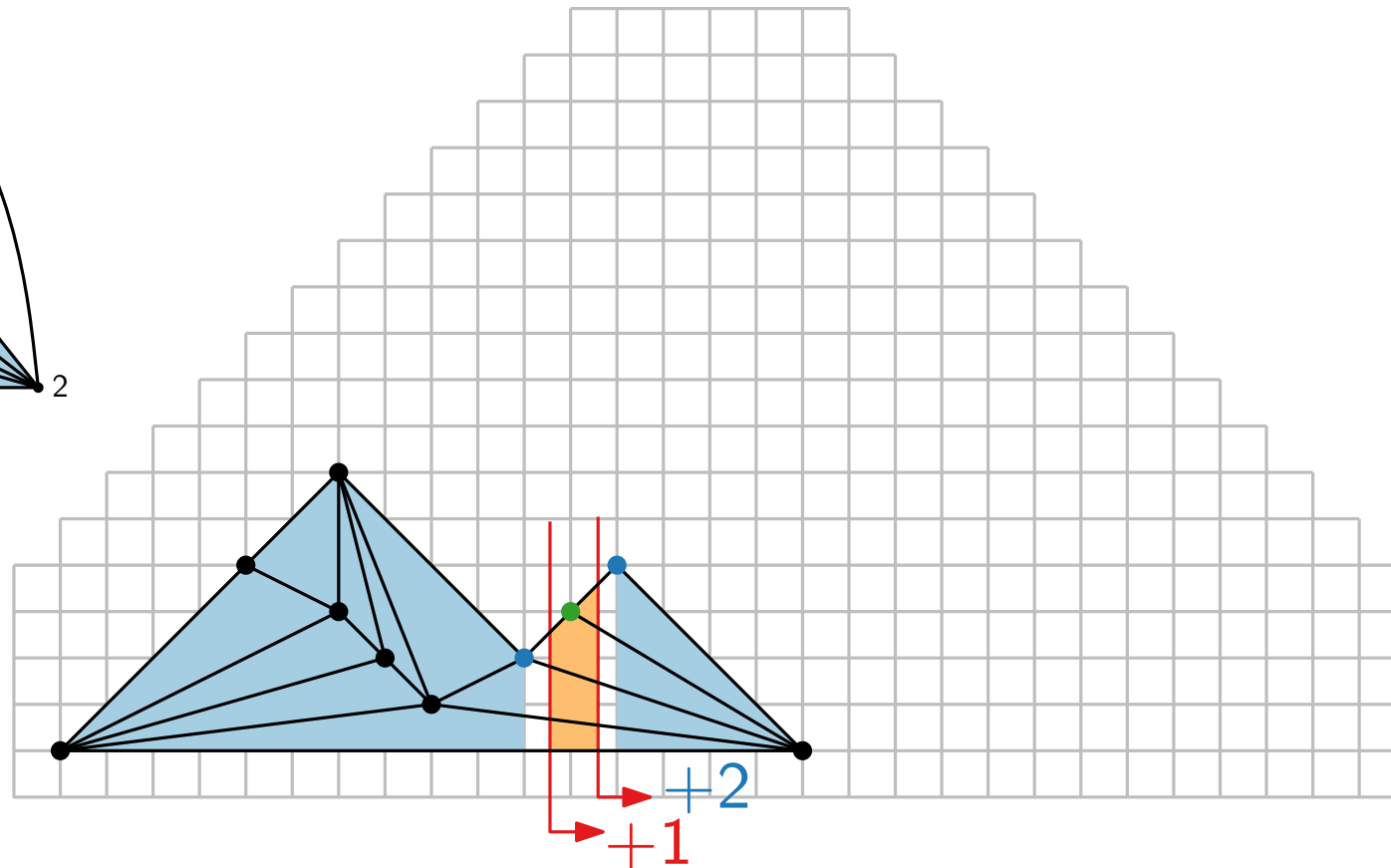
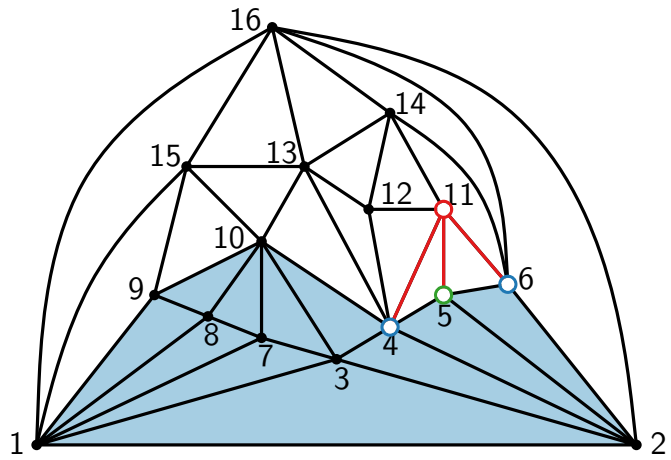
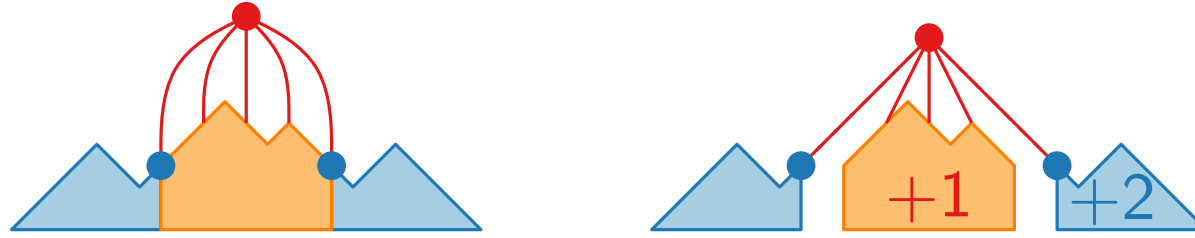
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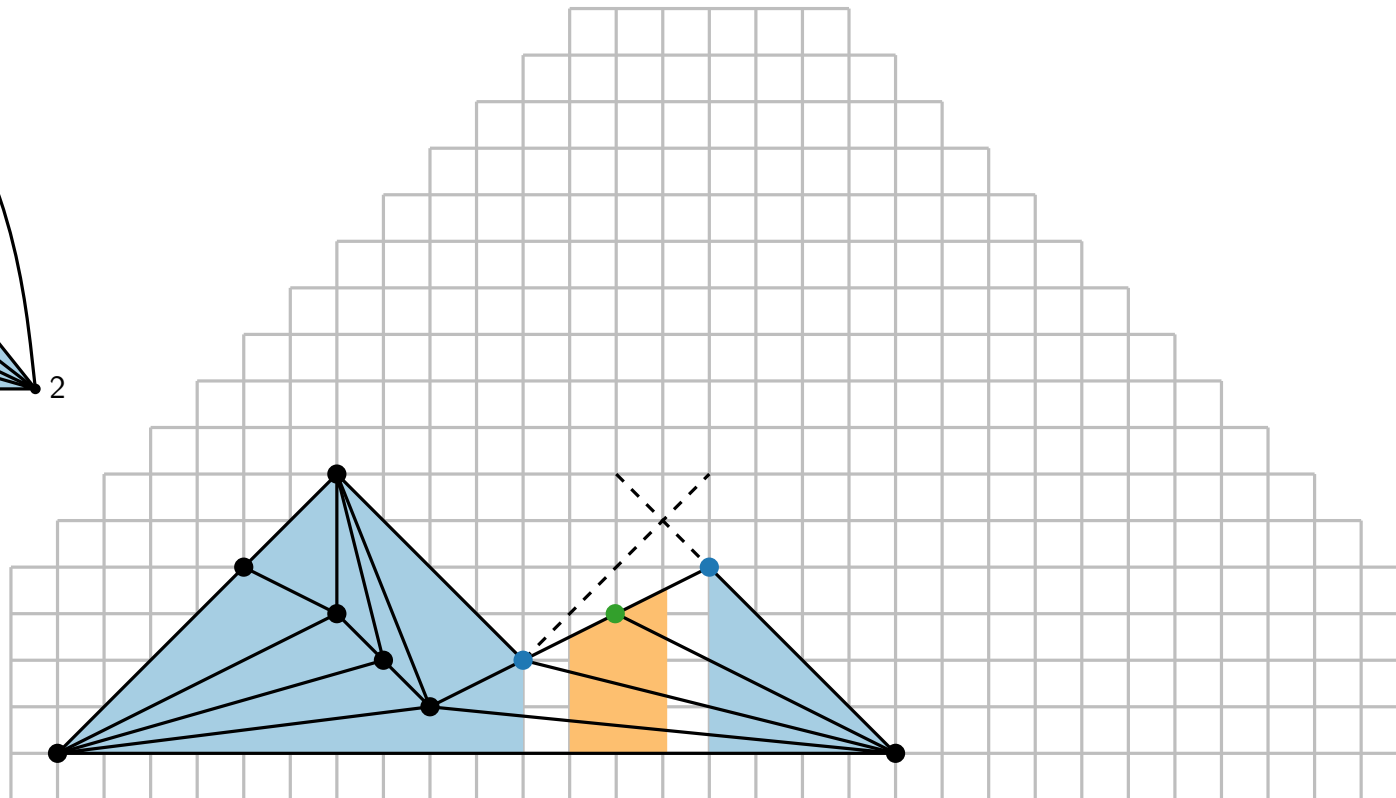
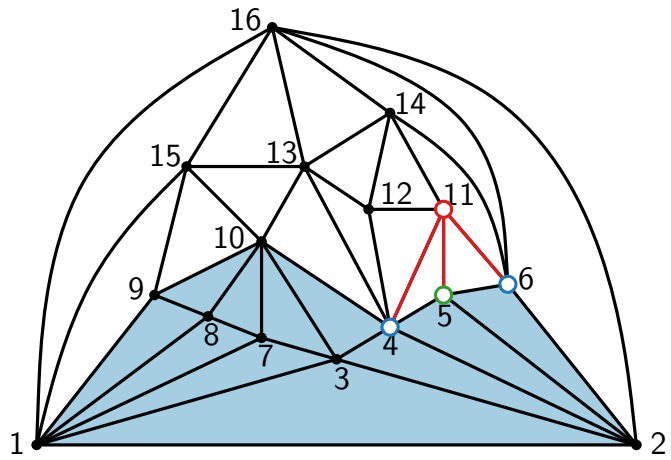
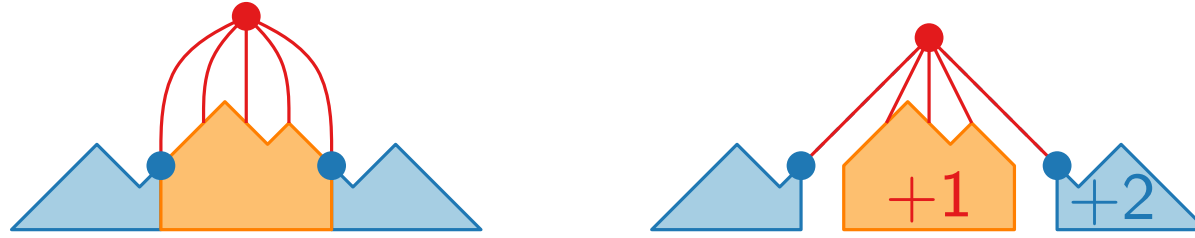
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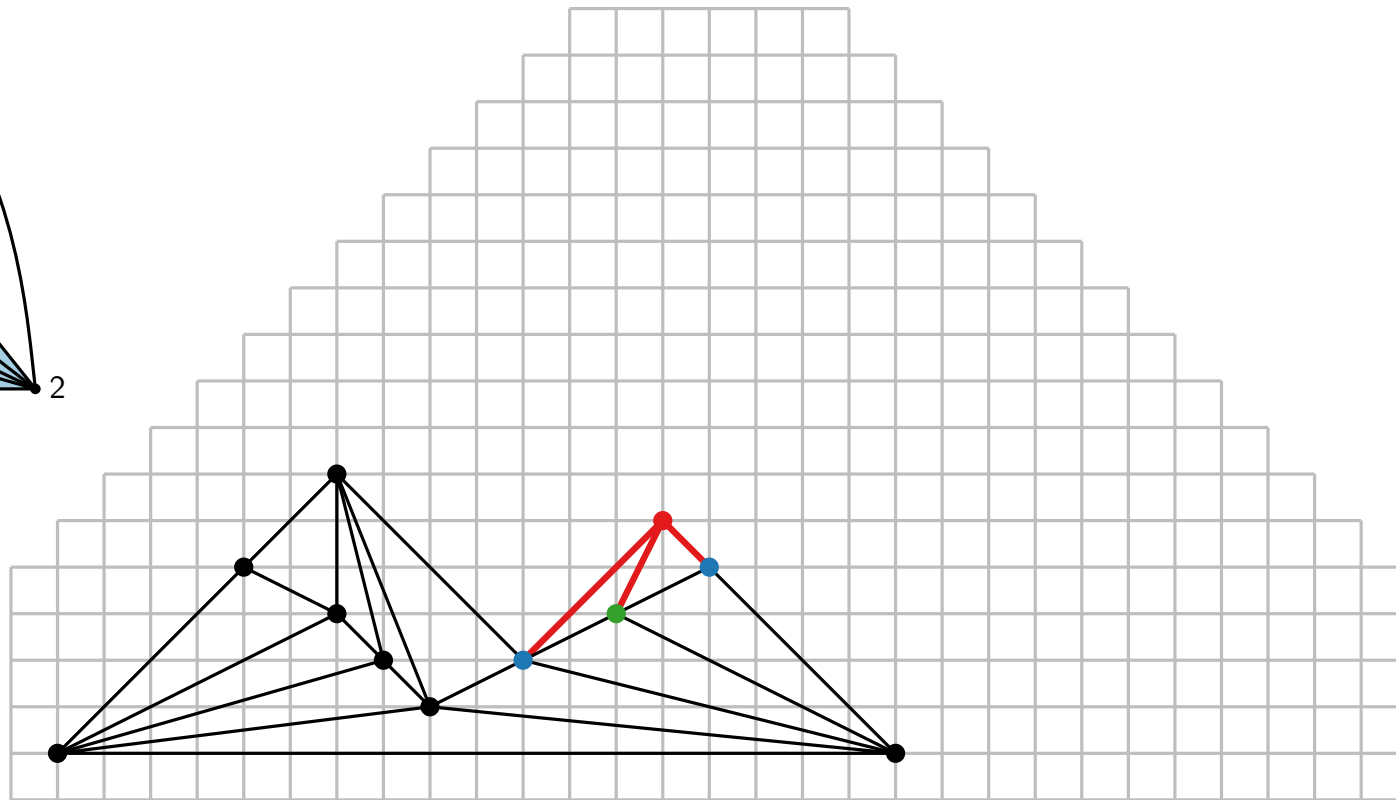
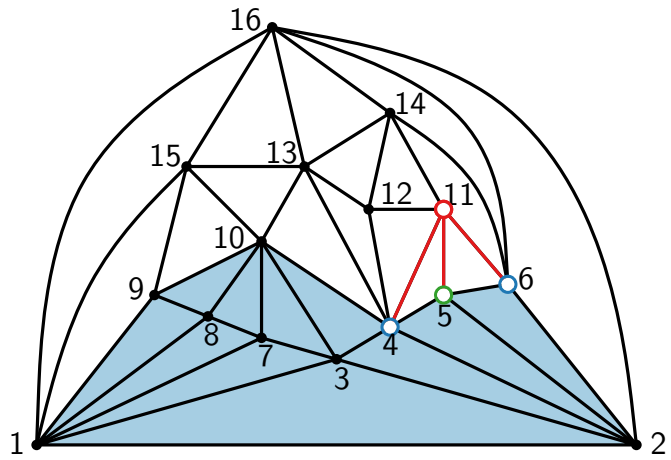
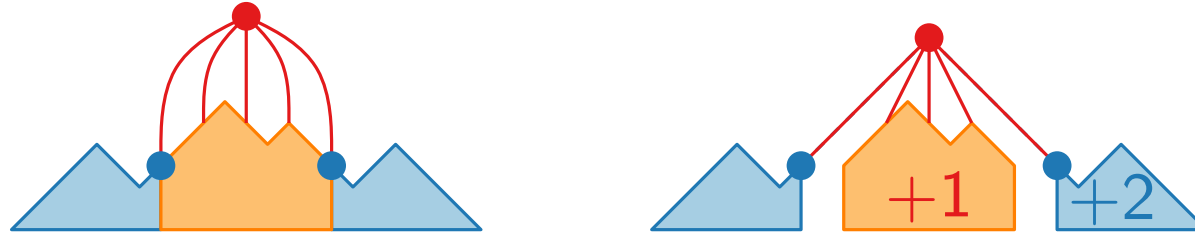
Shift method – example



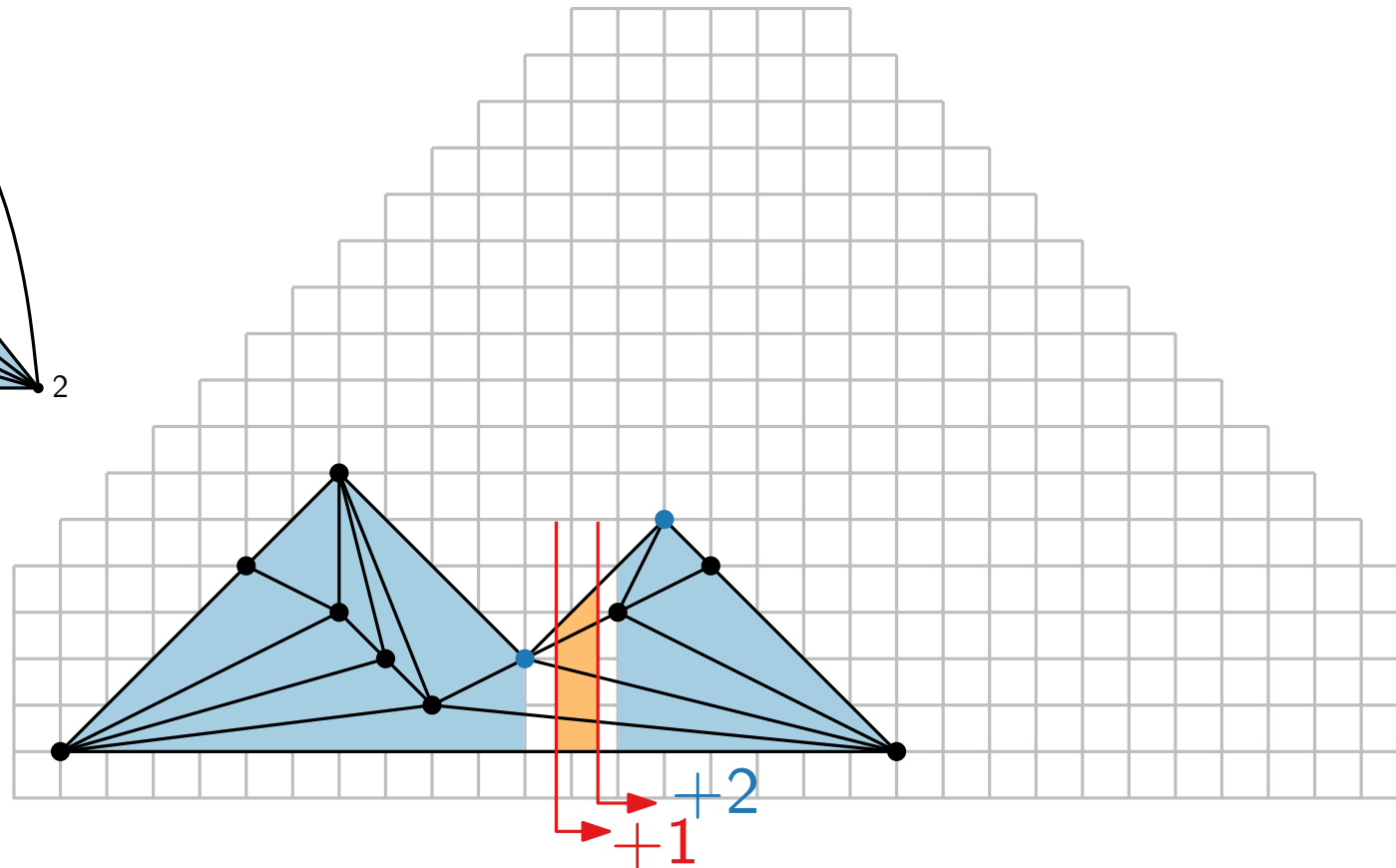
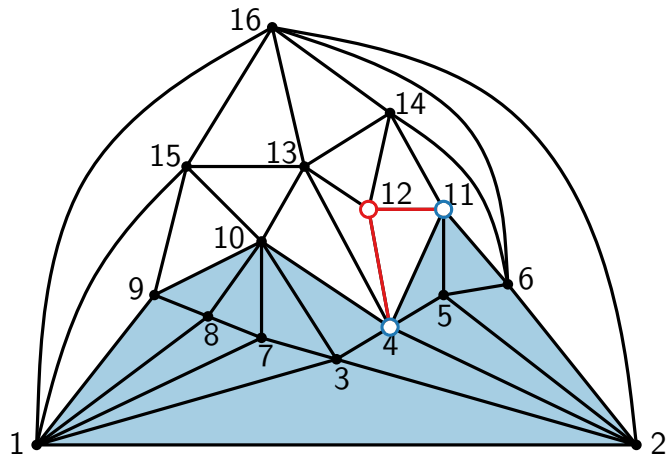
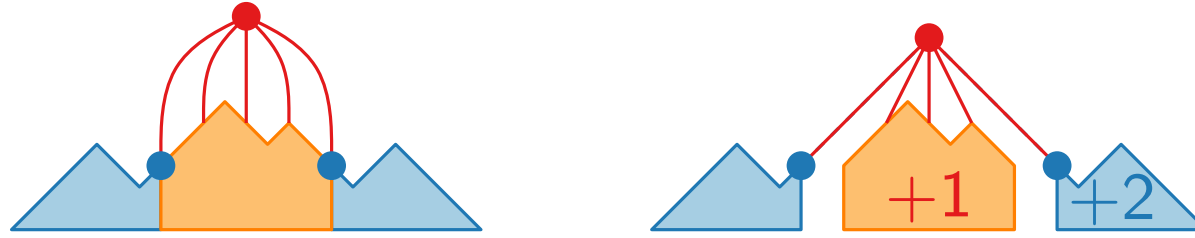
Shift method – example



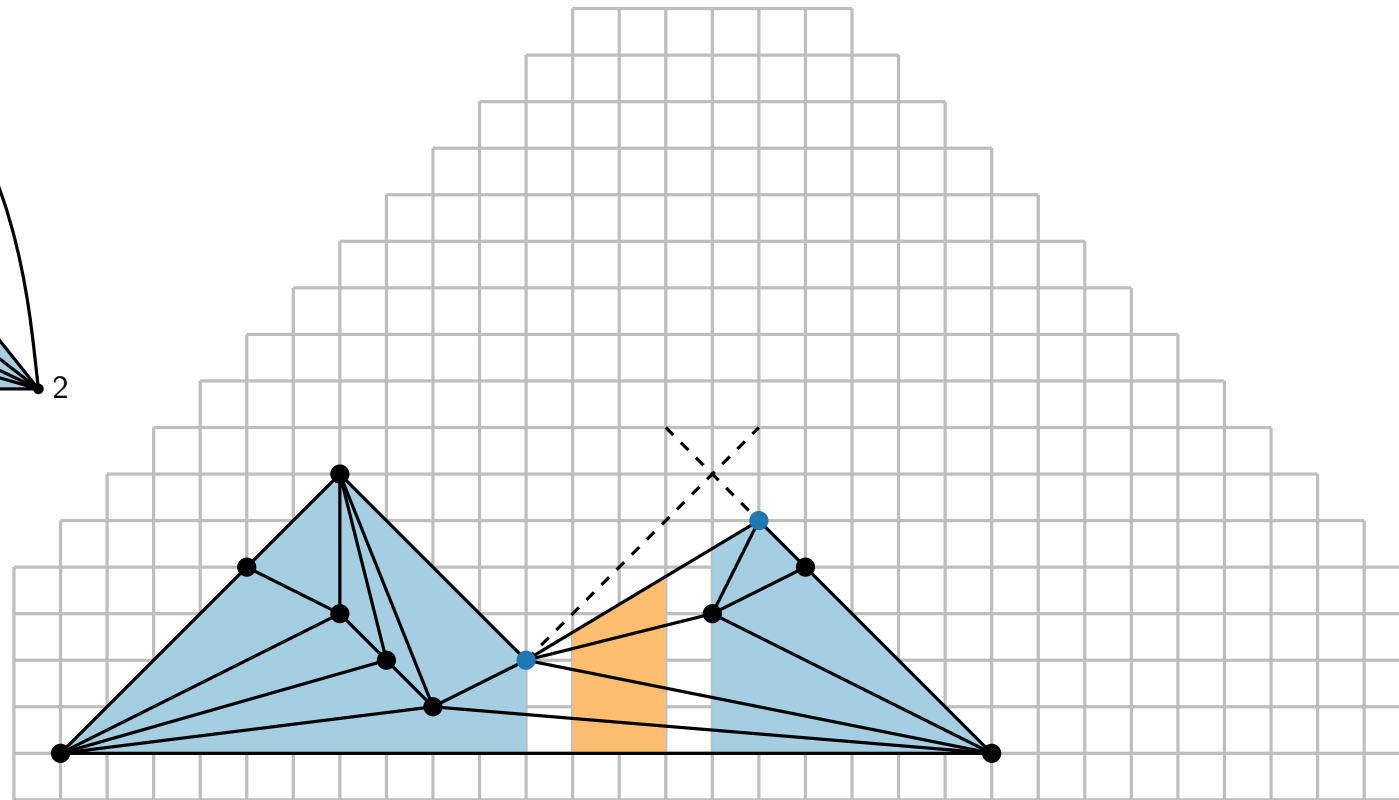
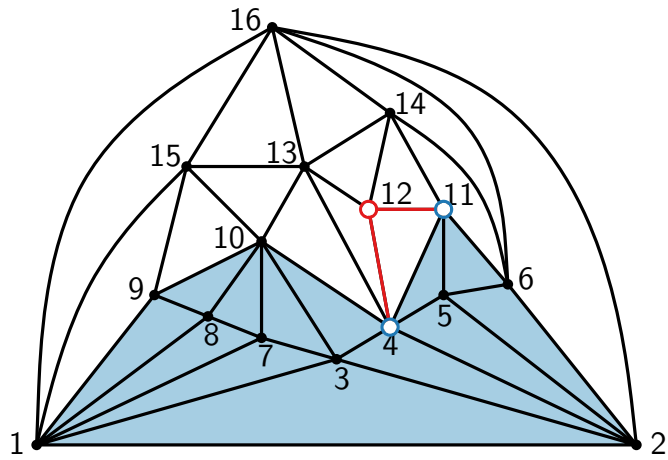
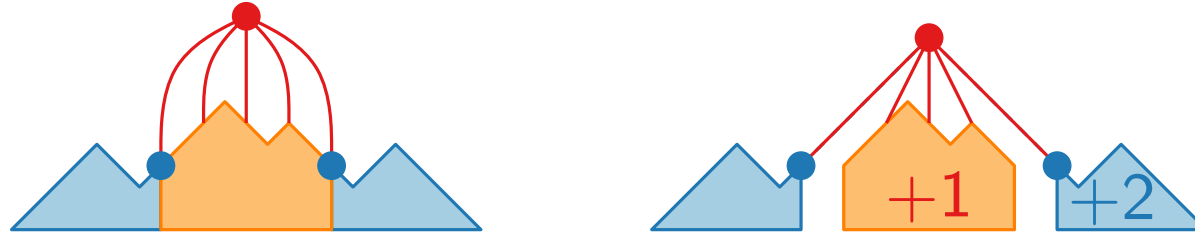
Shift method – example



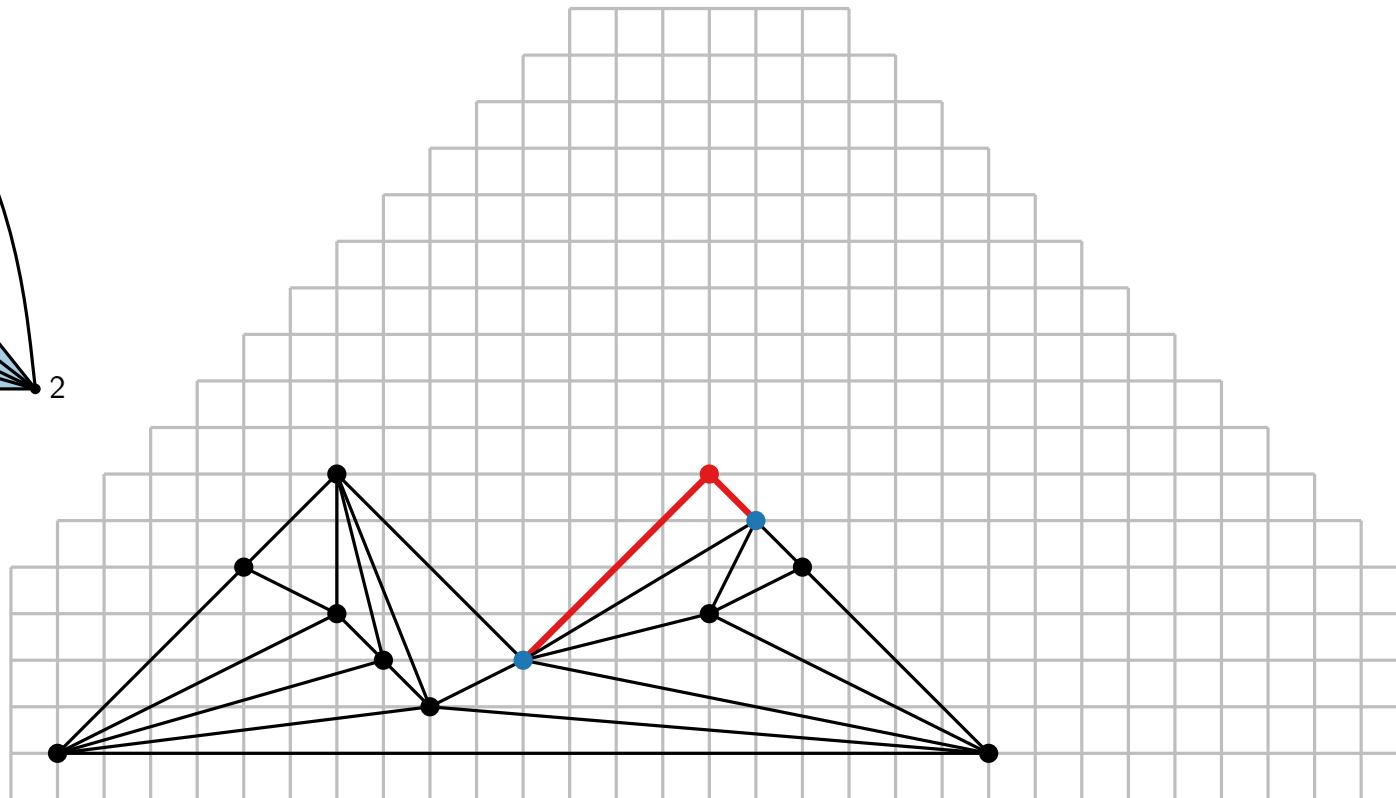
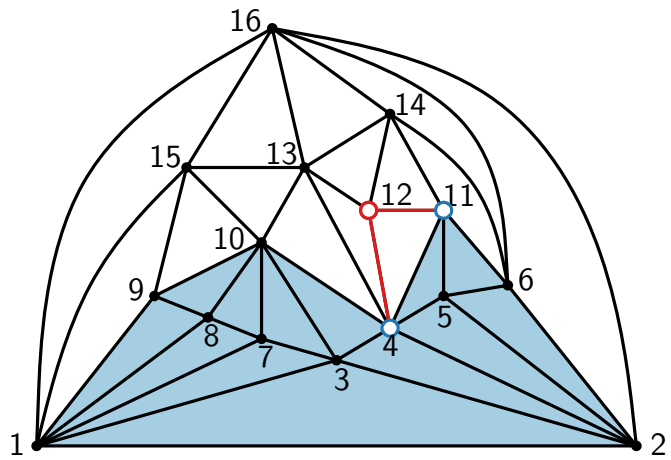
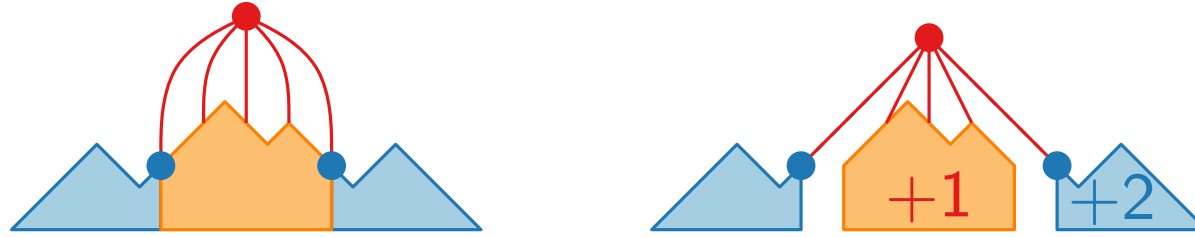
Shift method – example



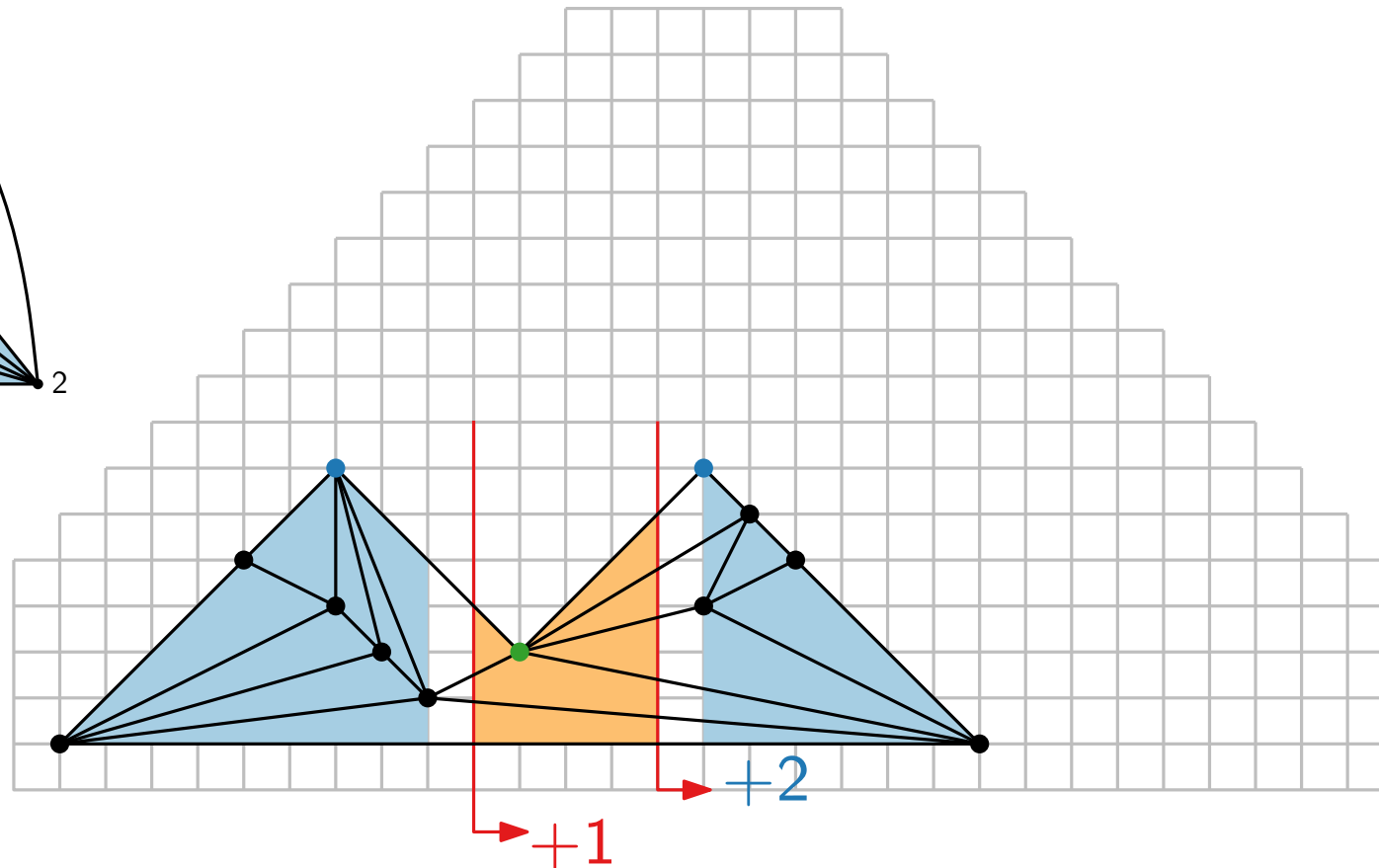
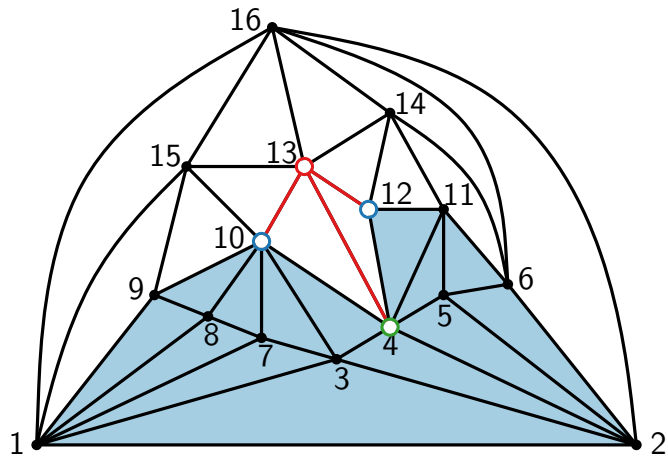
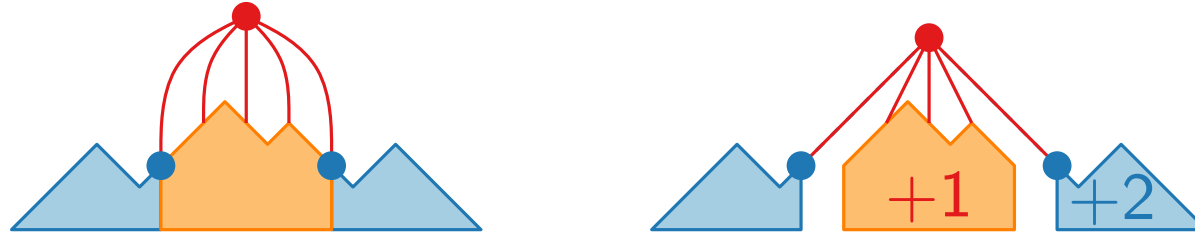
Shift method – example



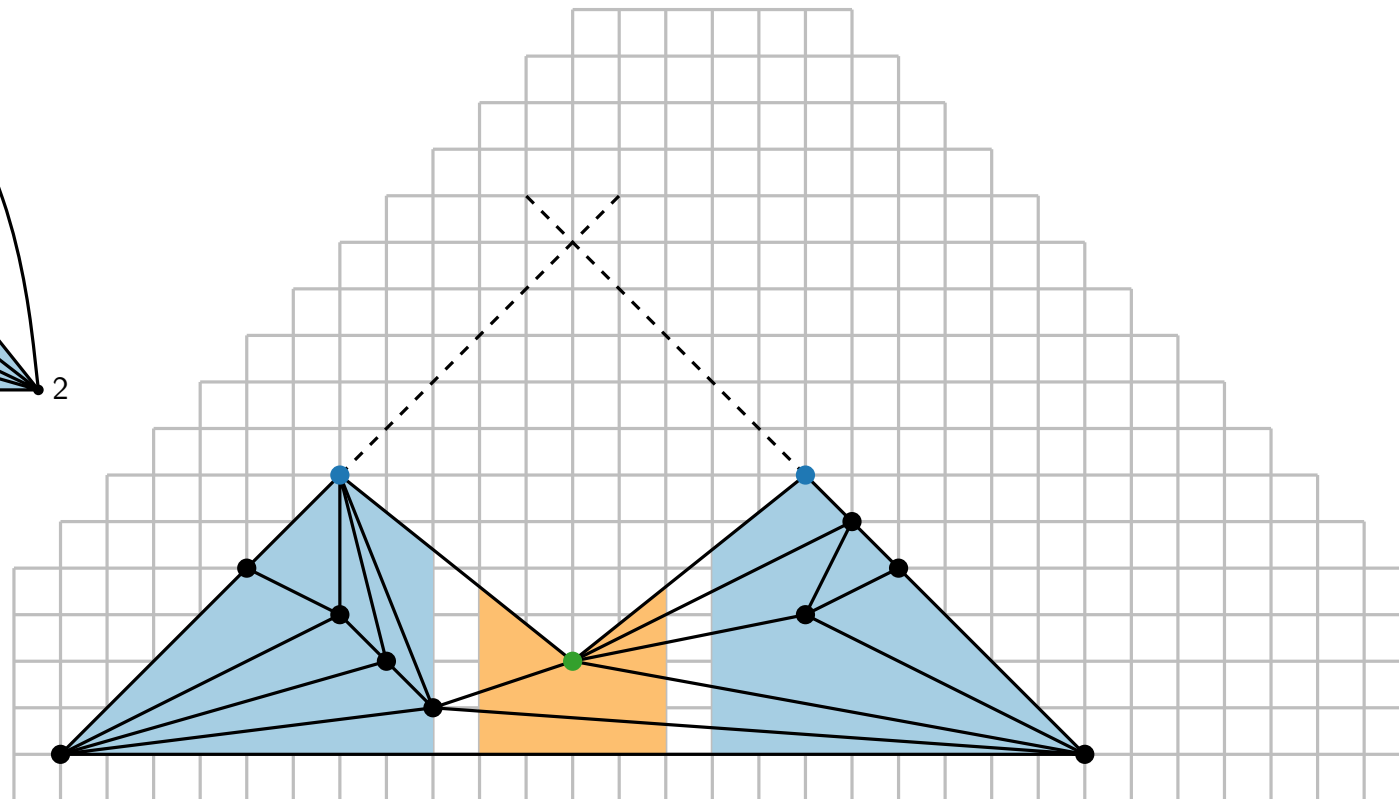
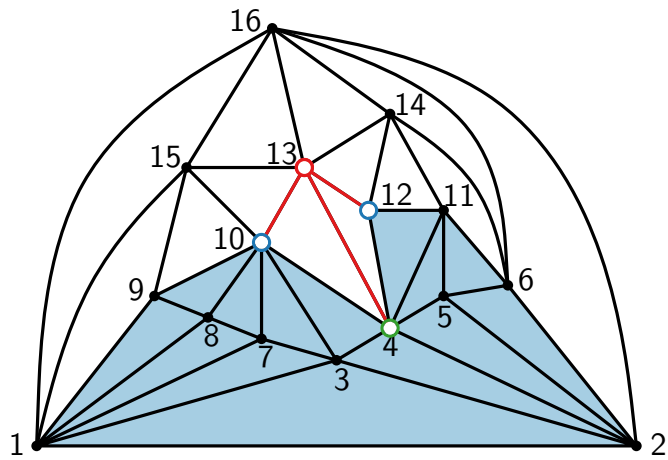
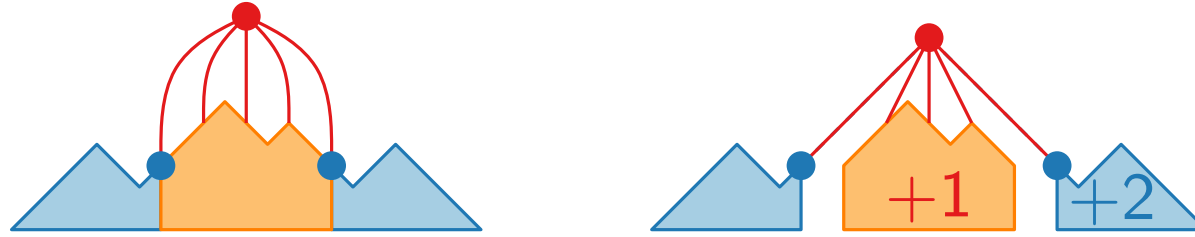
Shift method – example



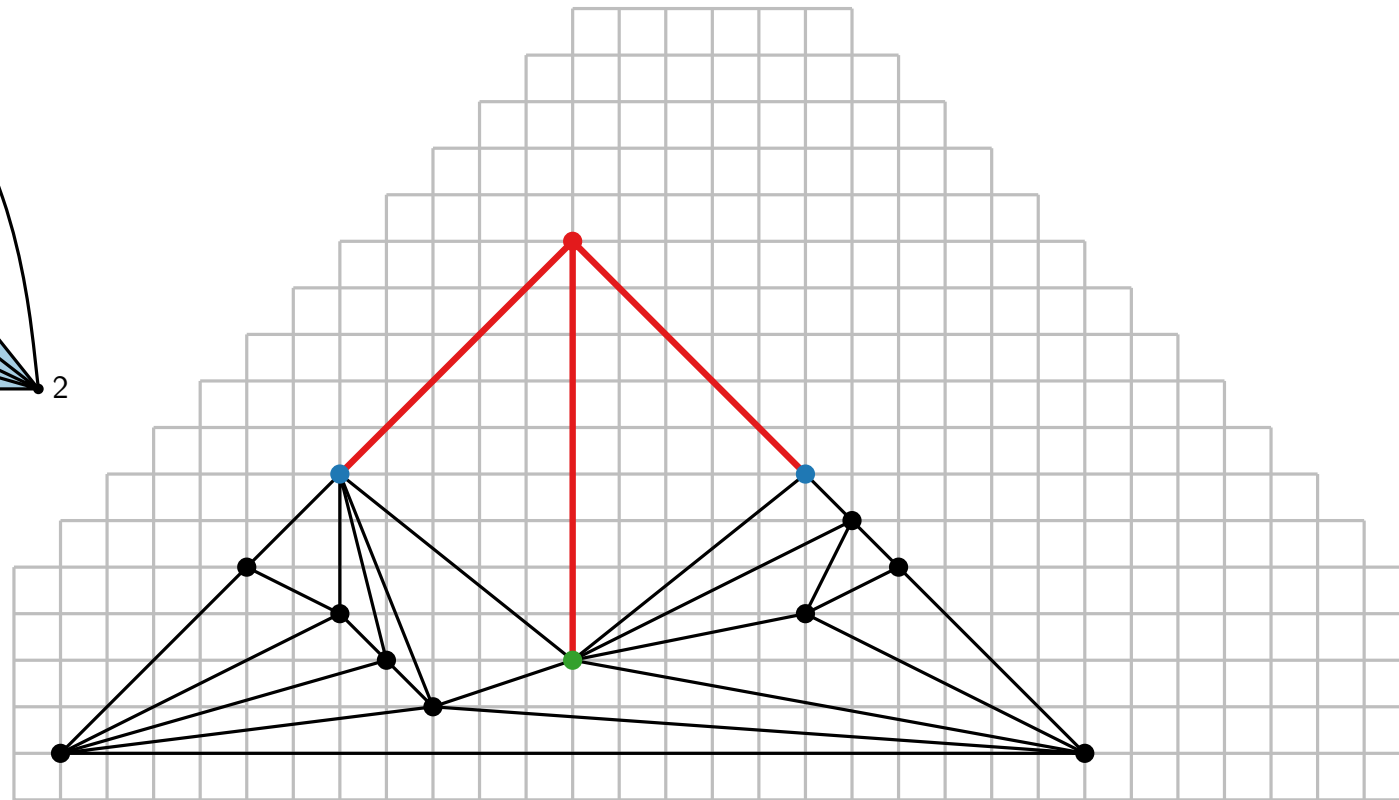
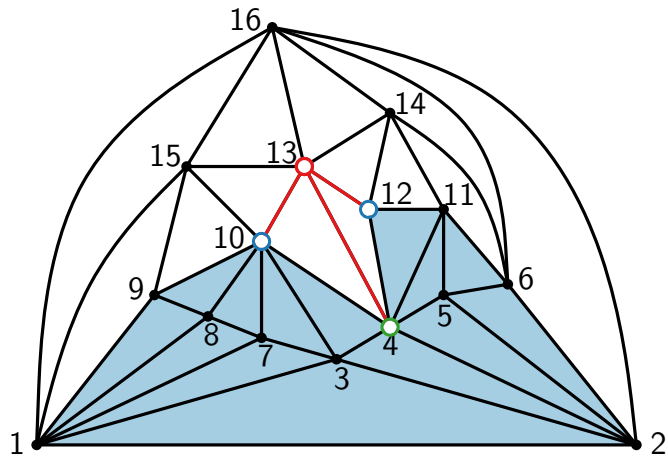
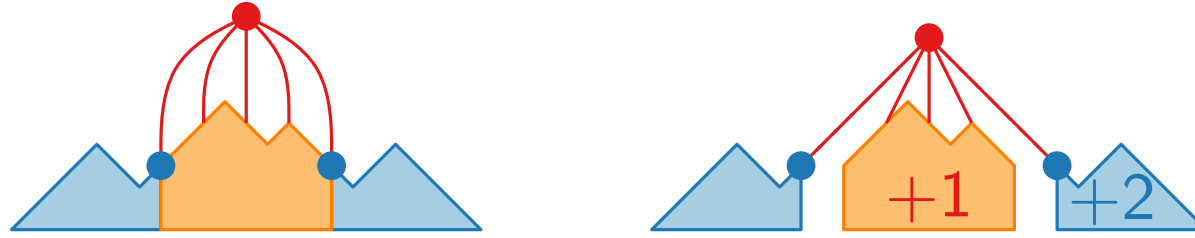
Shift method – example



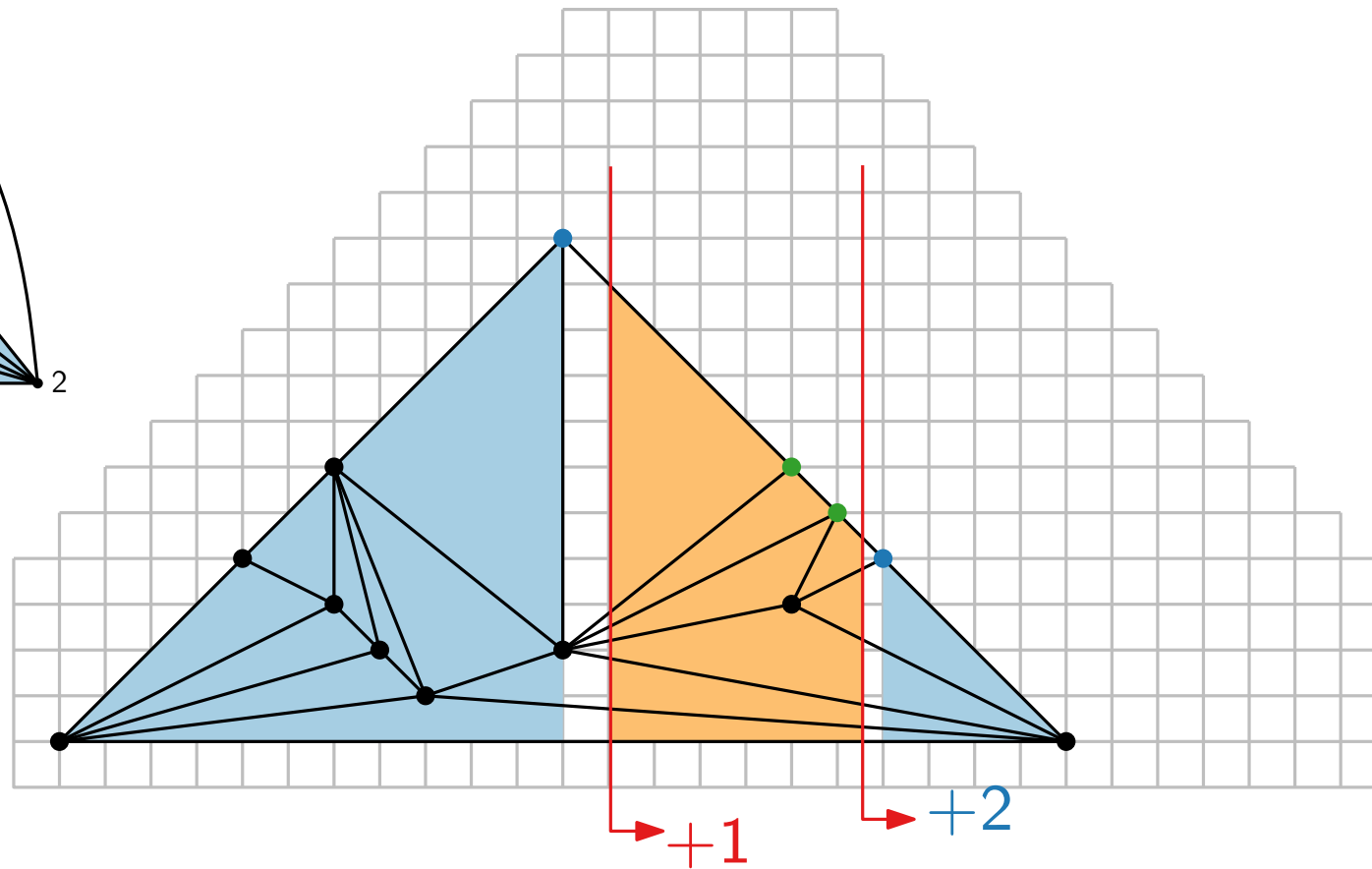
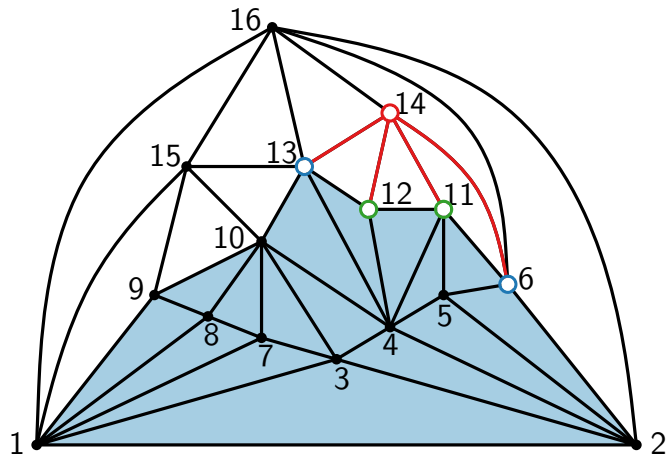
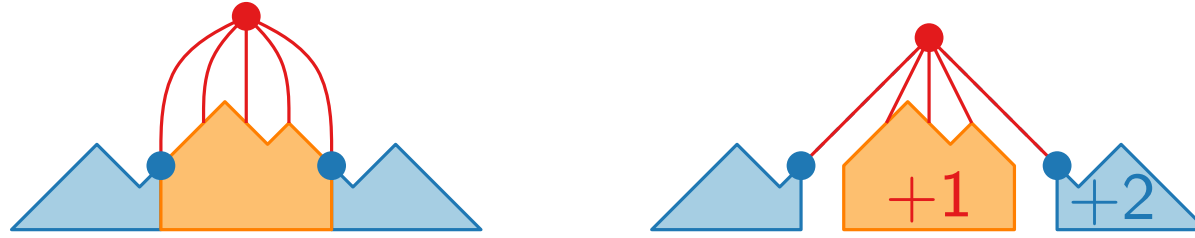
Shift method – example



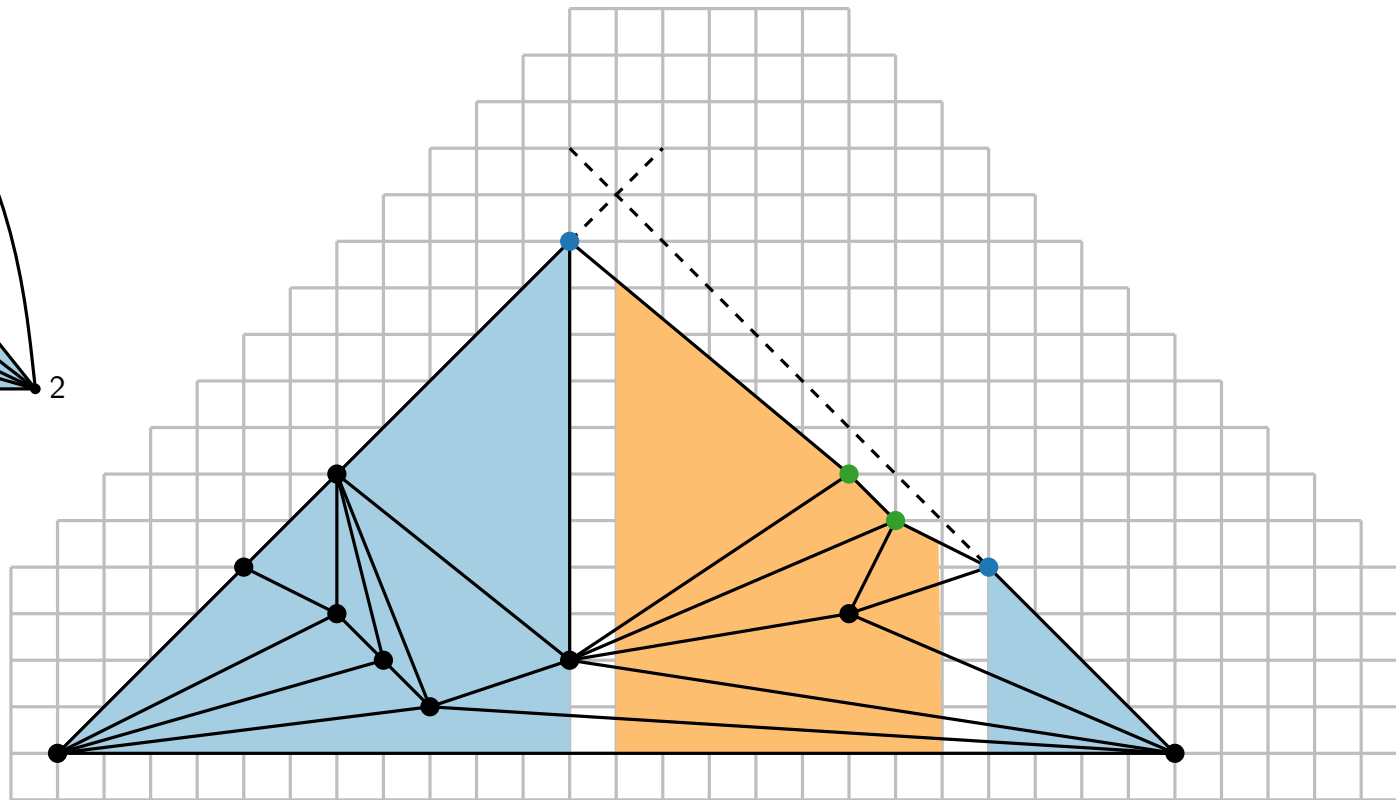
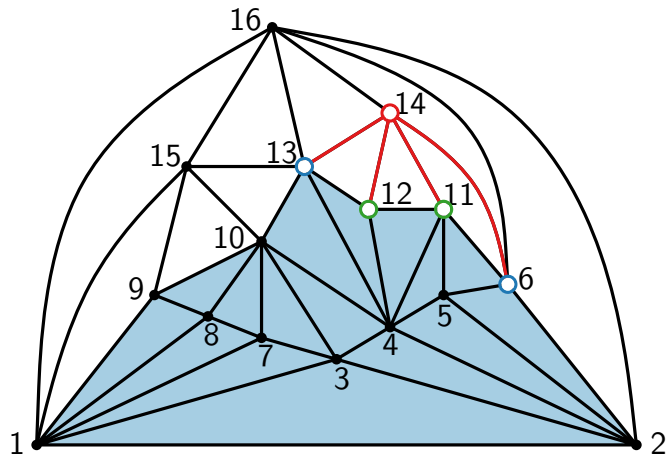
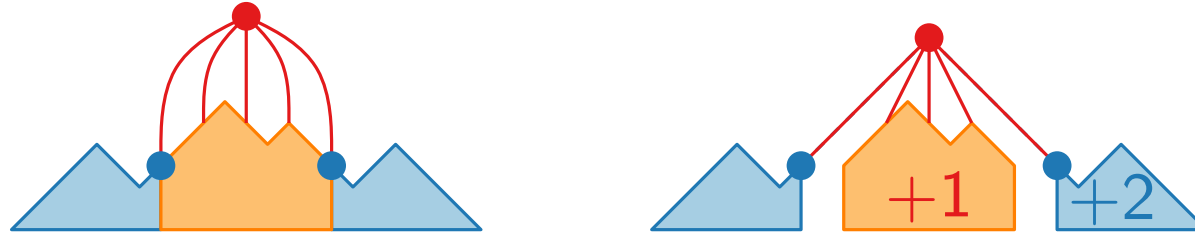
Shift method – example



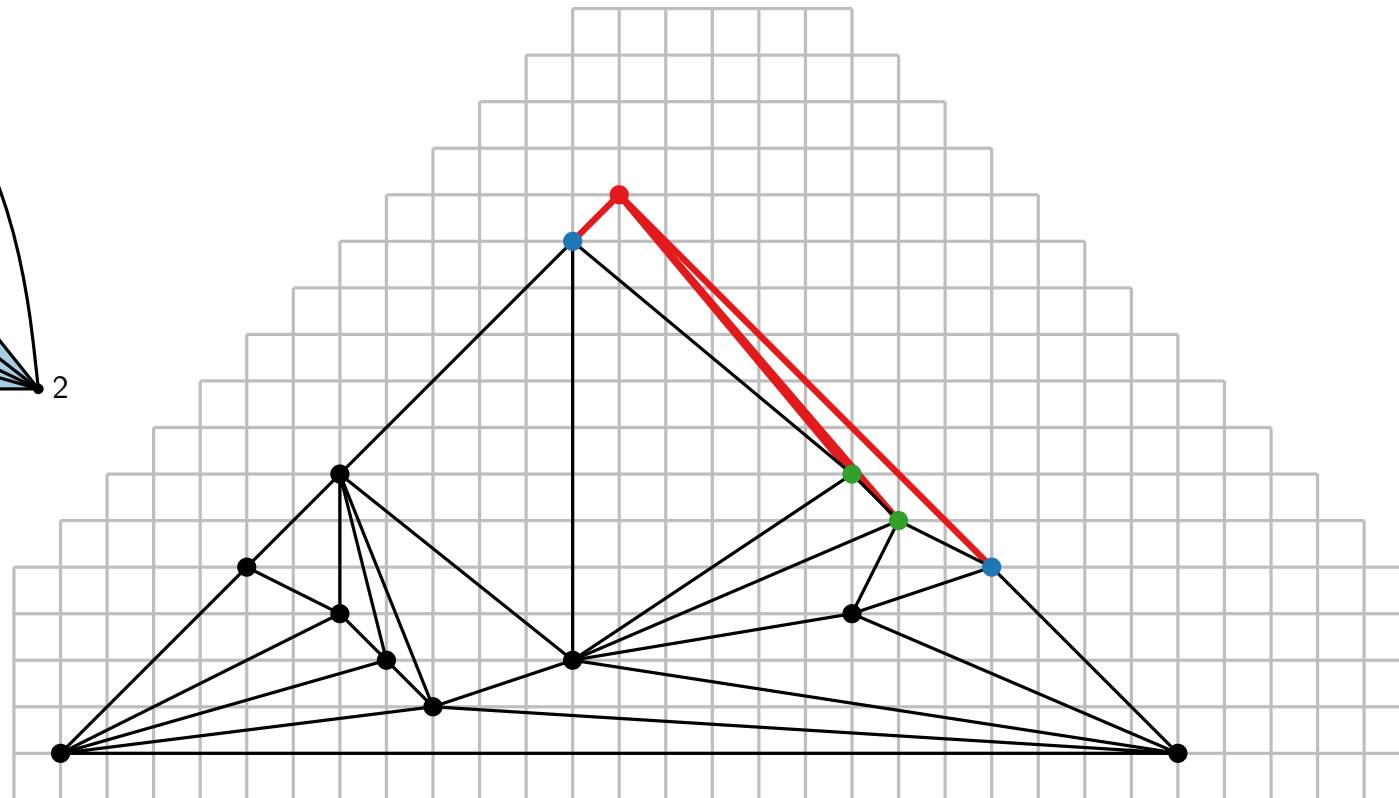
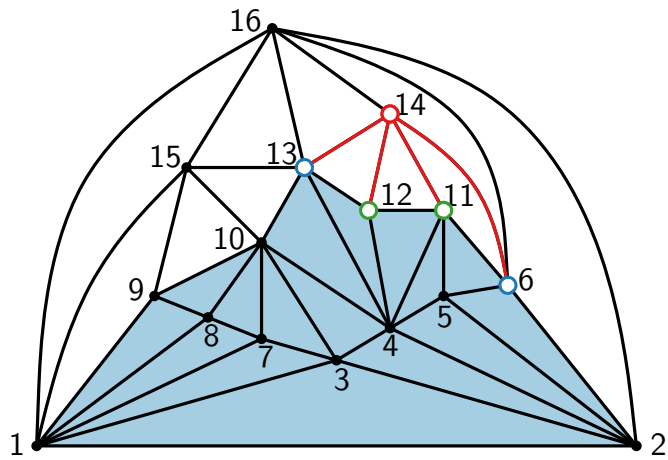
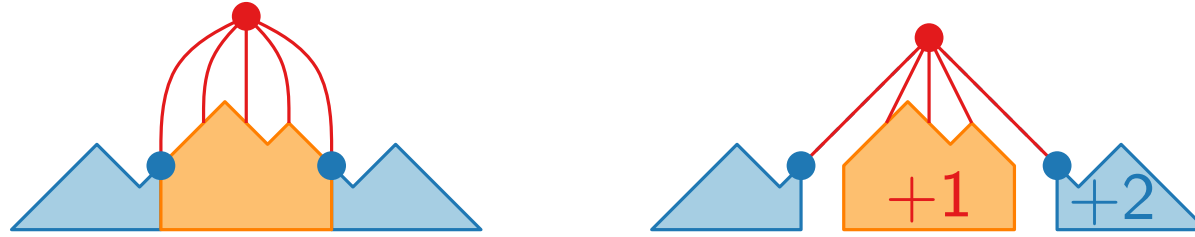
Shift method – example



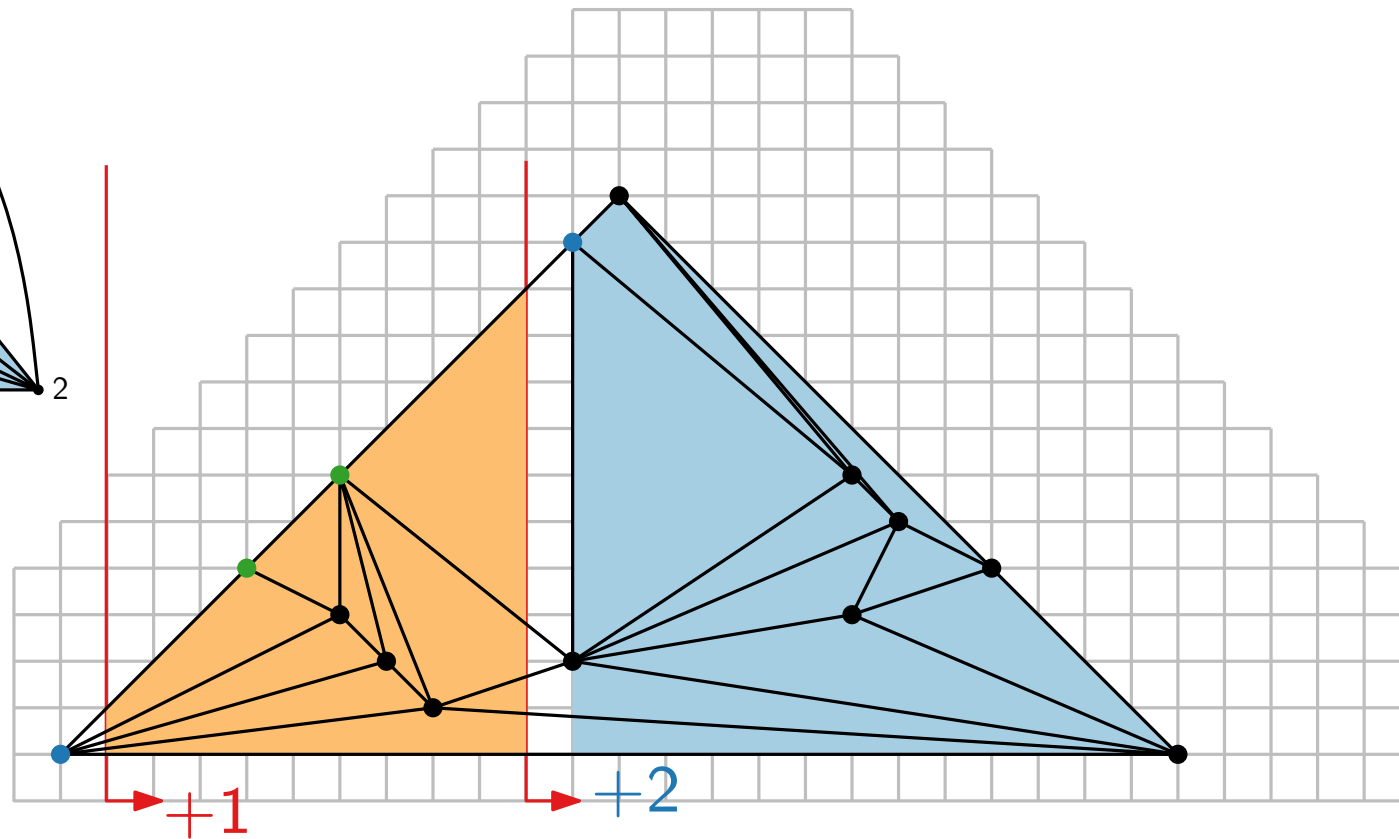
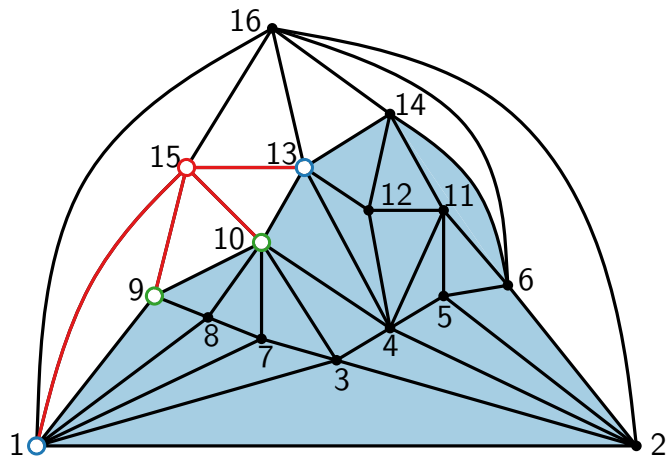
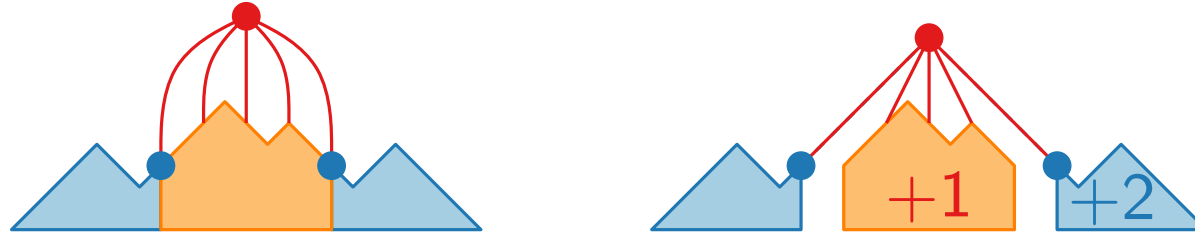
Shift method – example



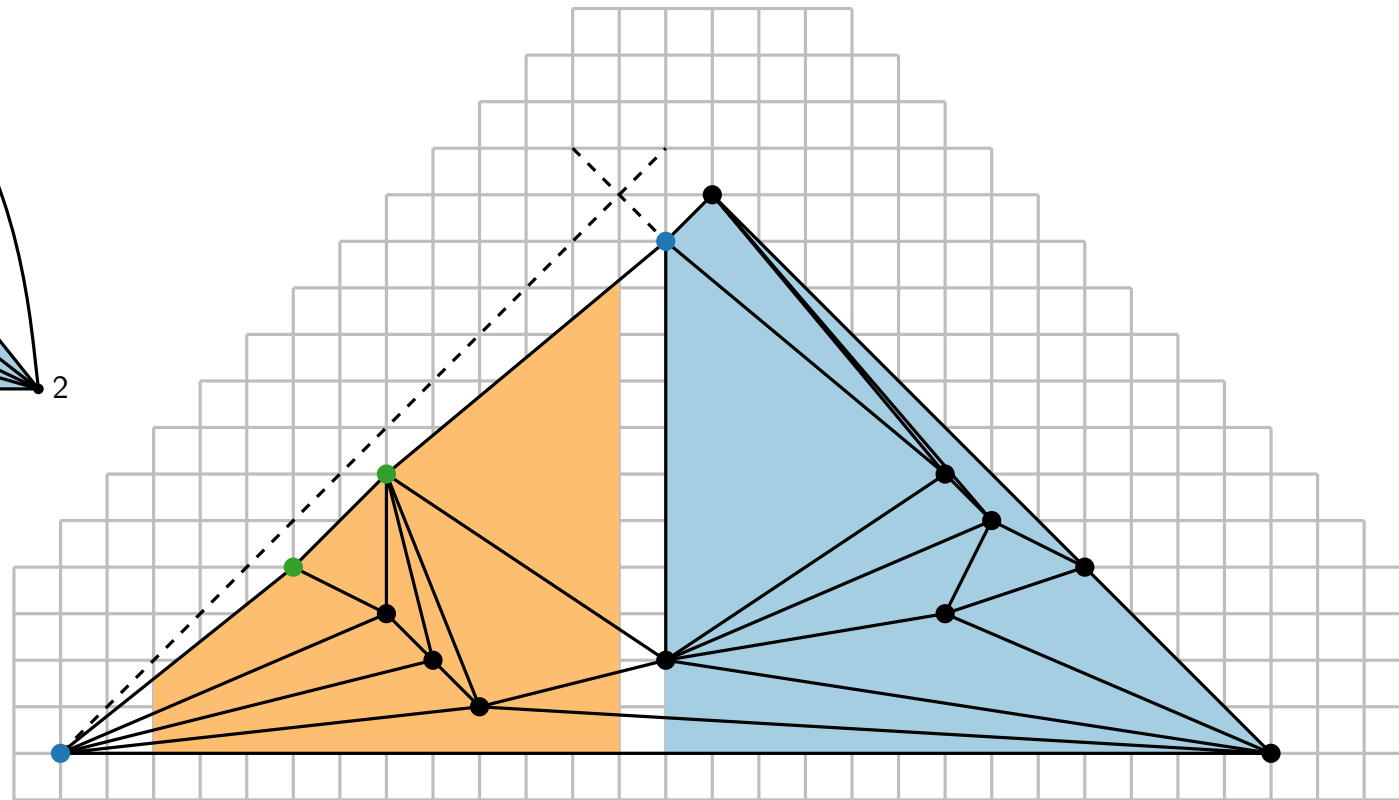
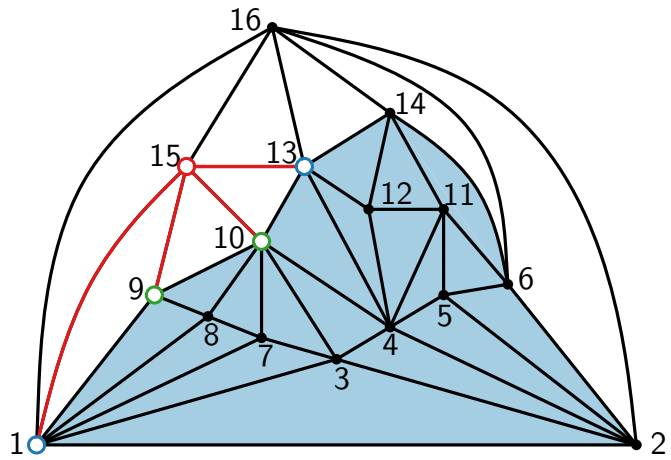
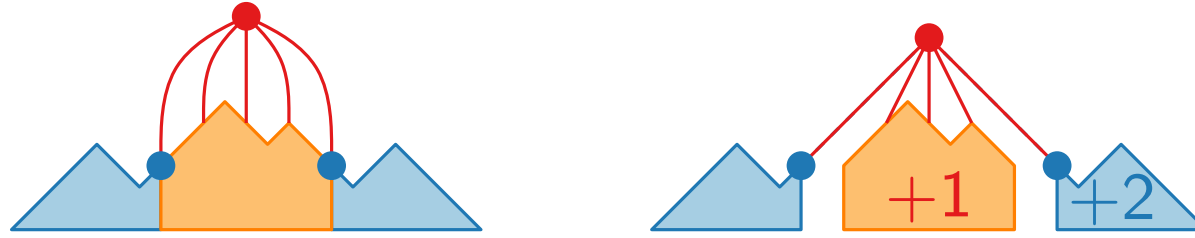
Shift method – example



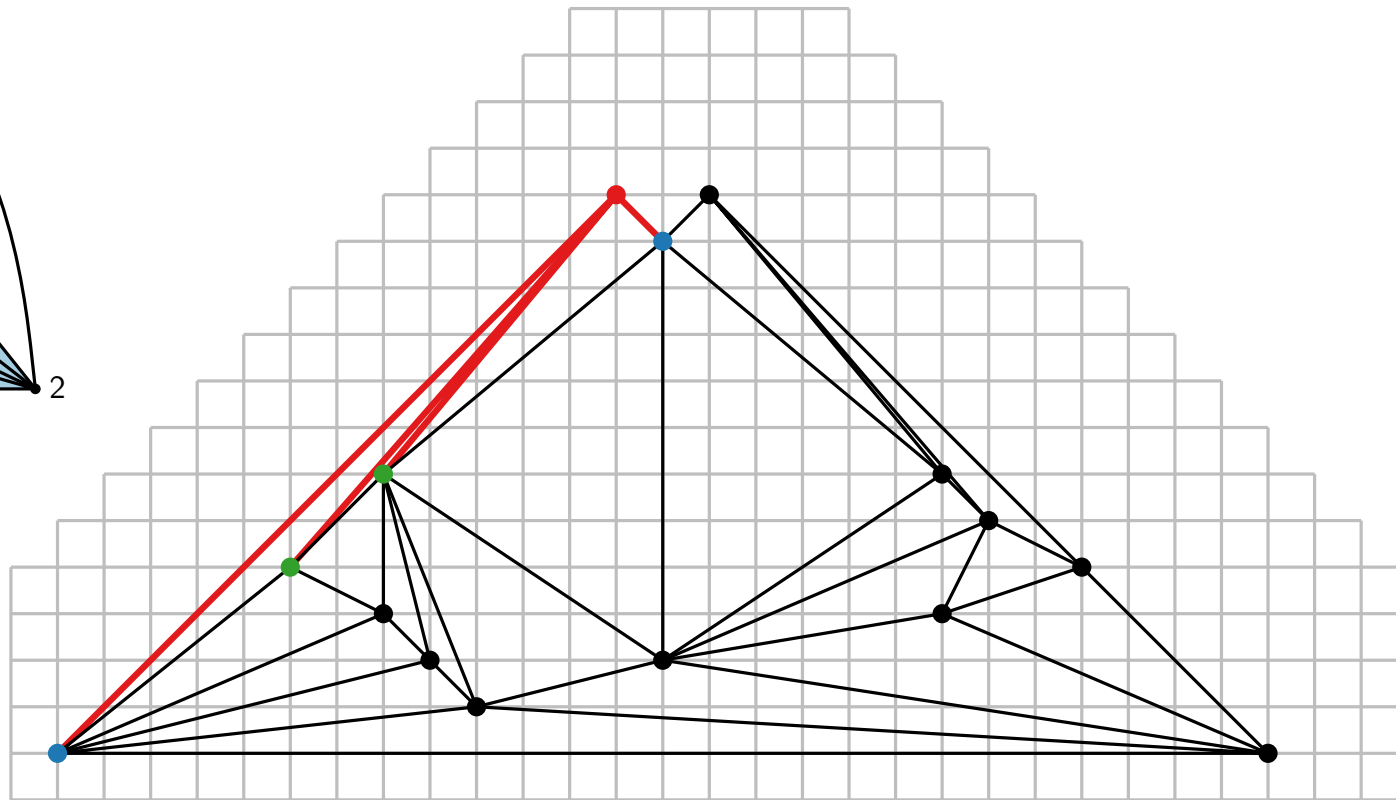
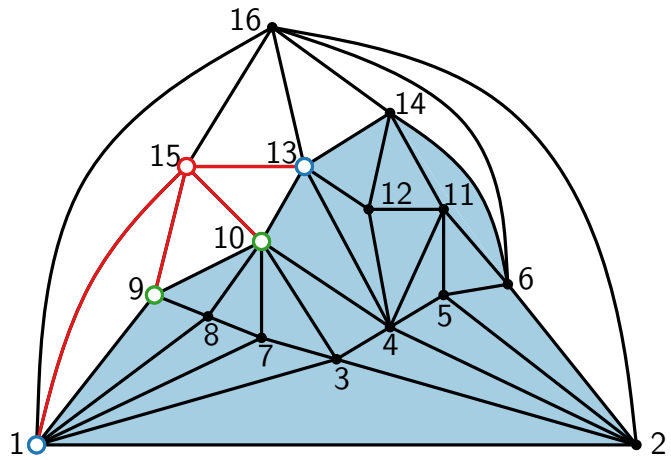
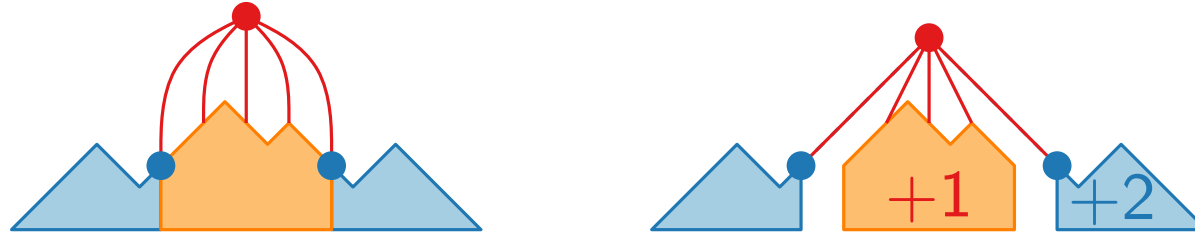
Shift method – example



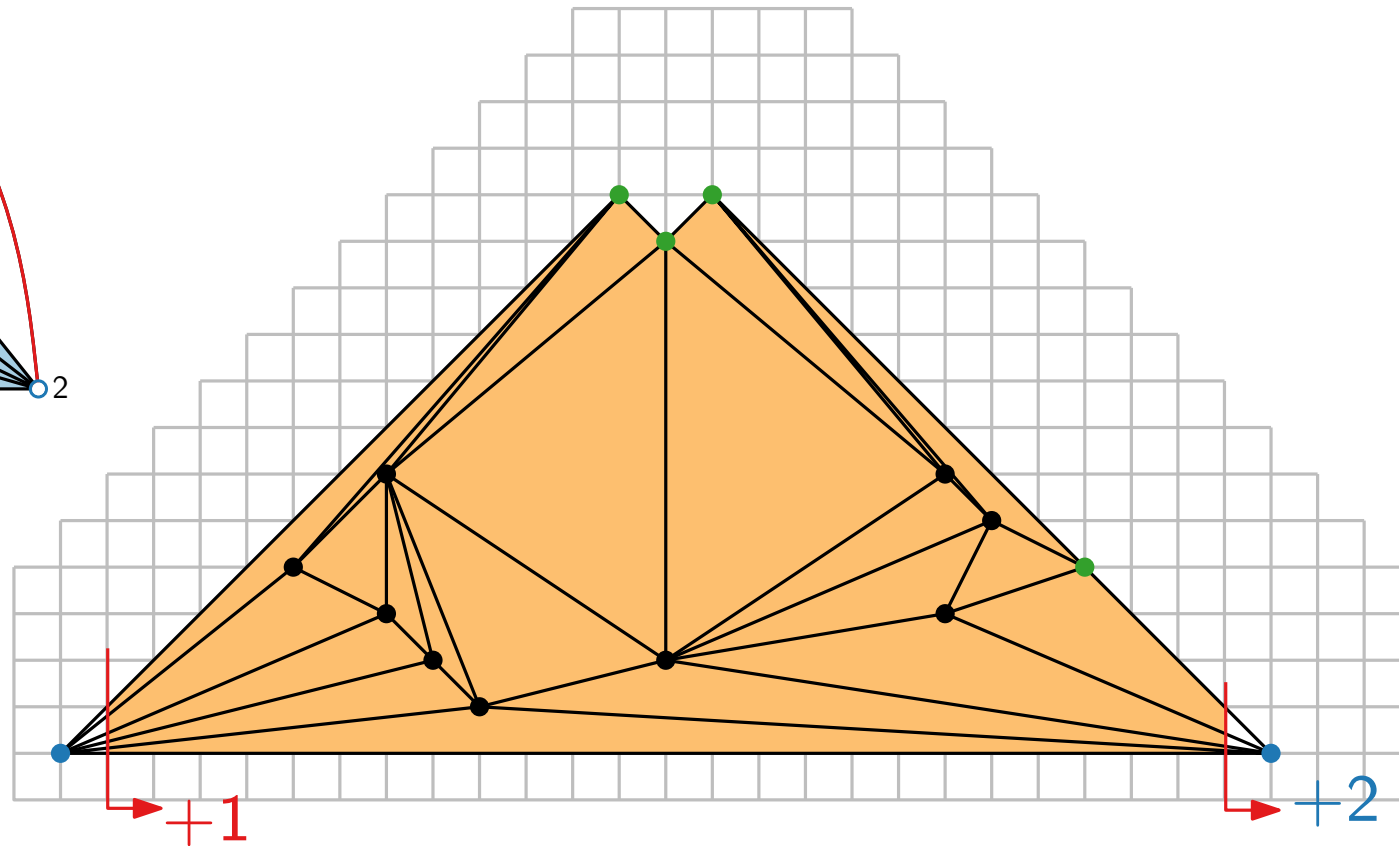
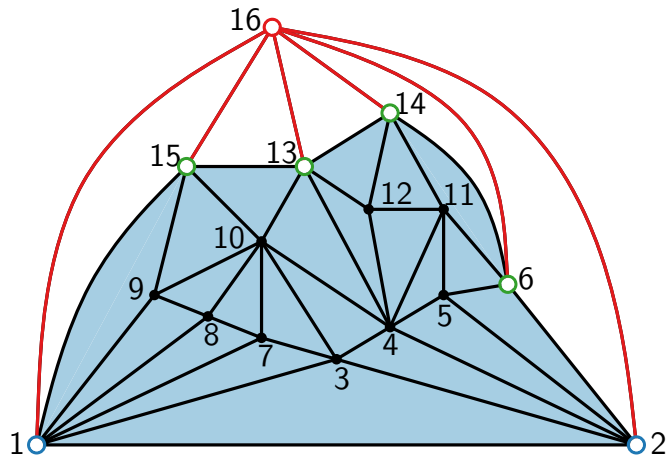
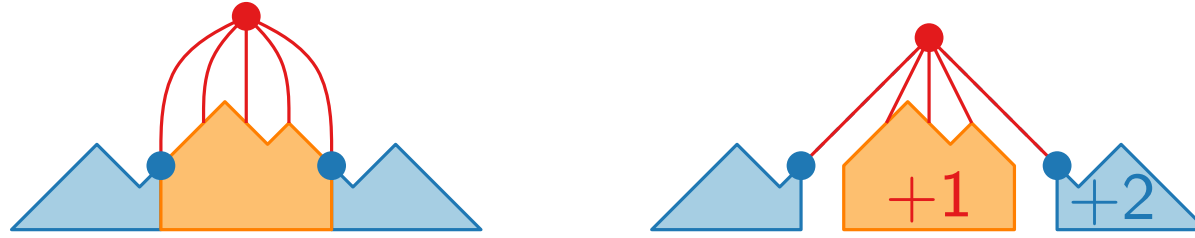
Shift method – example



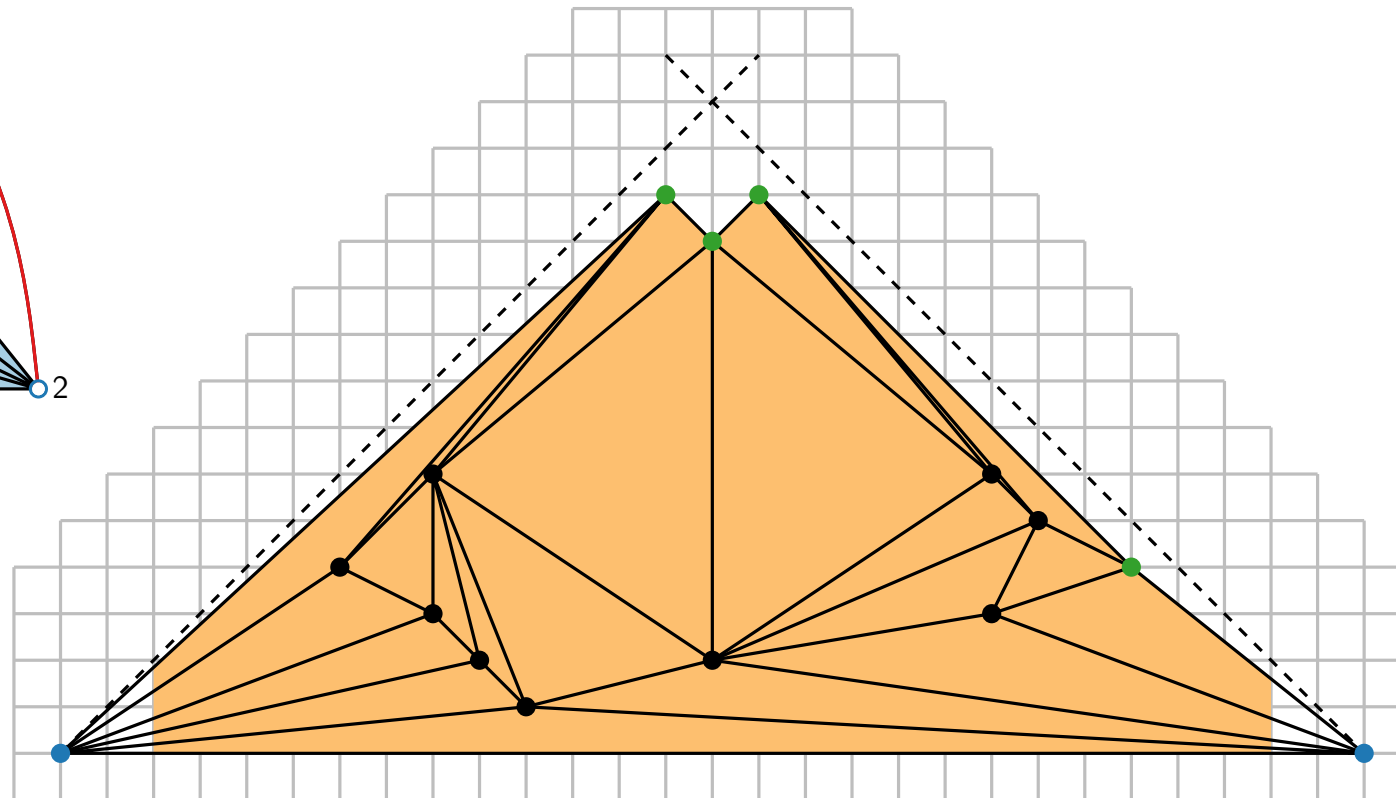
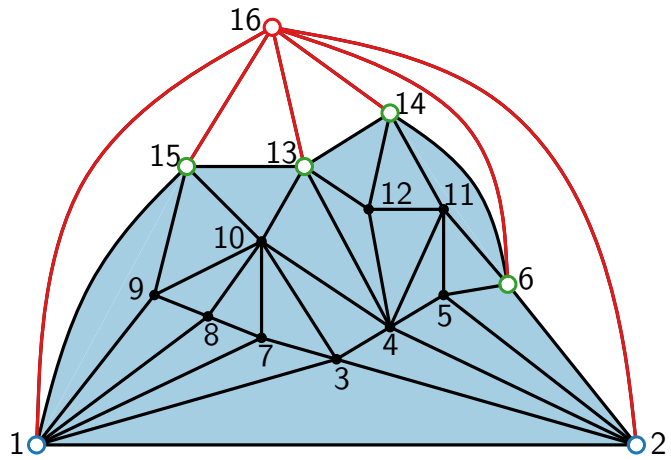
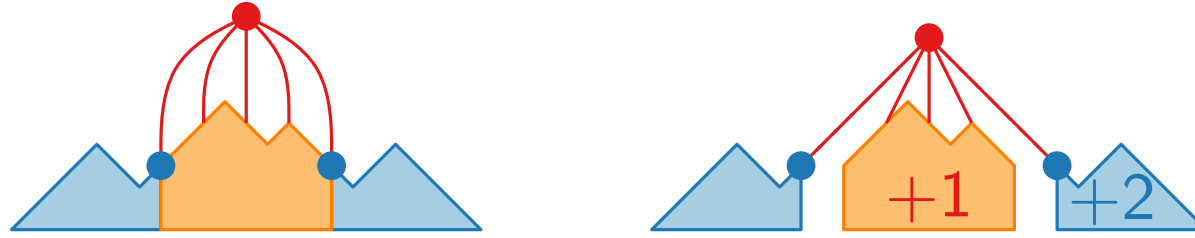
Shift method – example



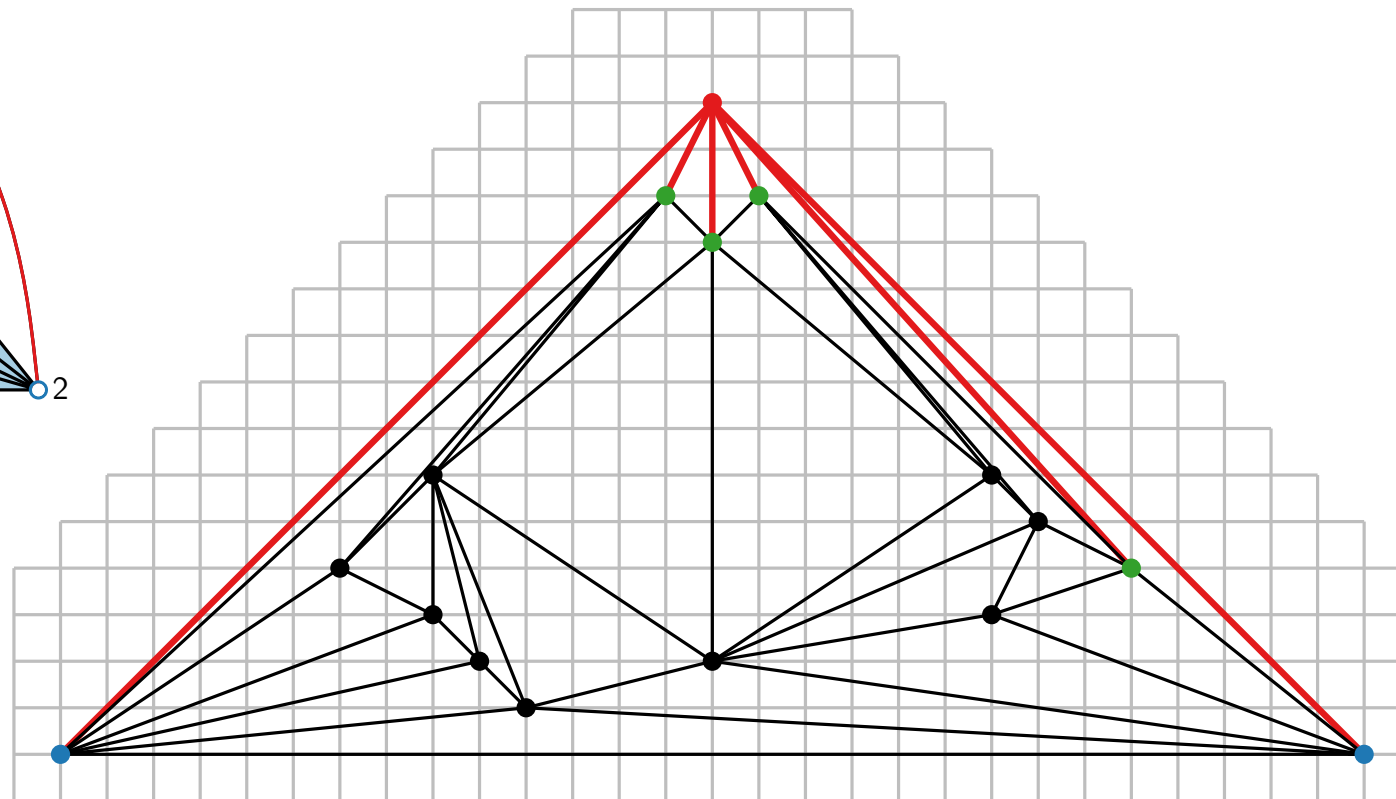
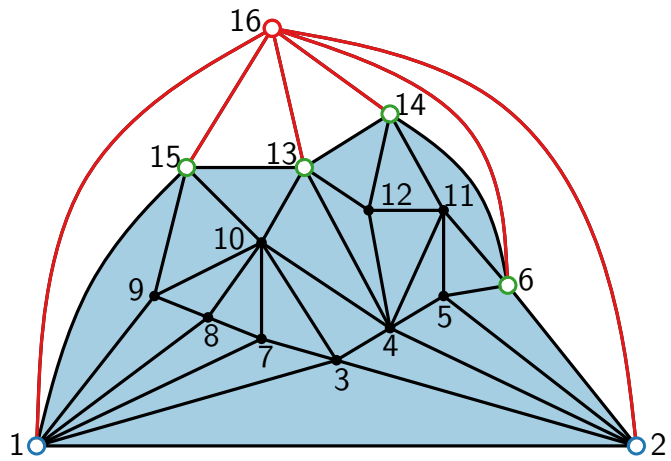
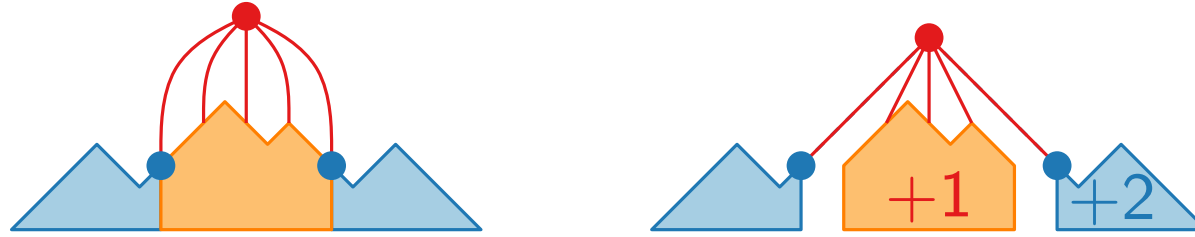
Shift method – example



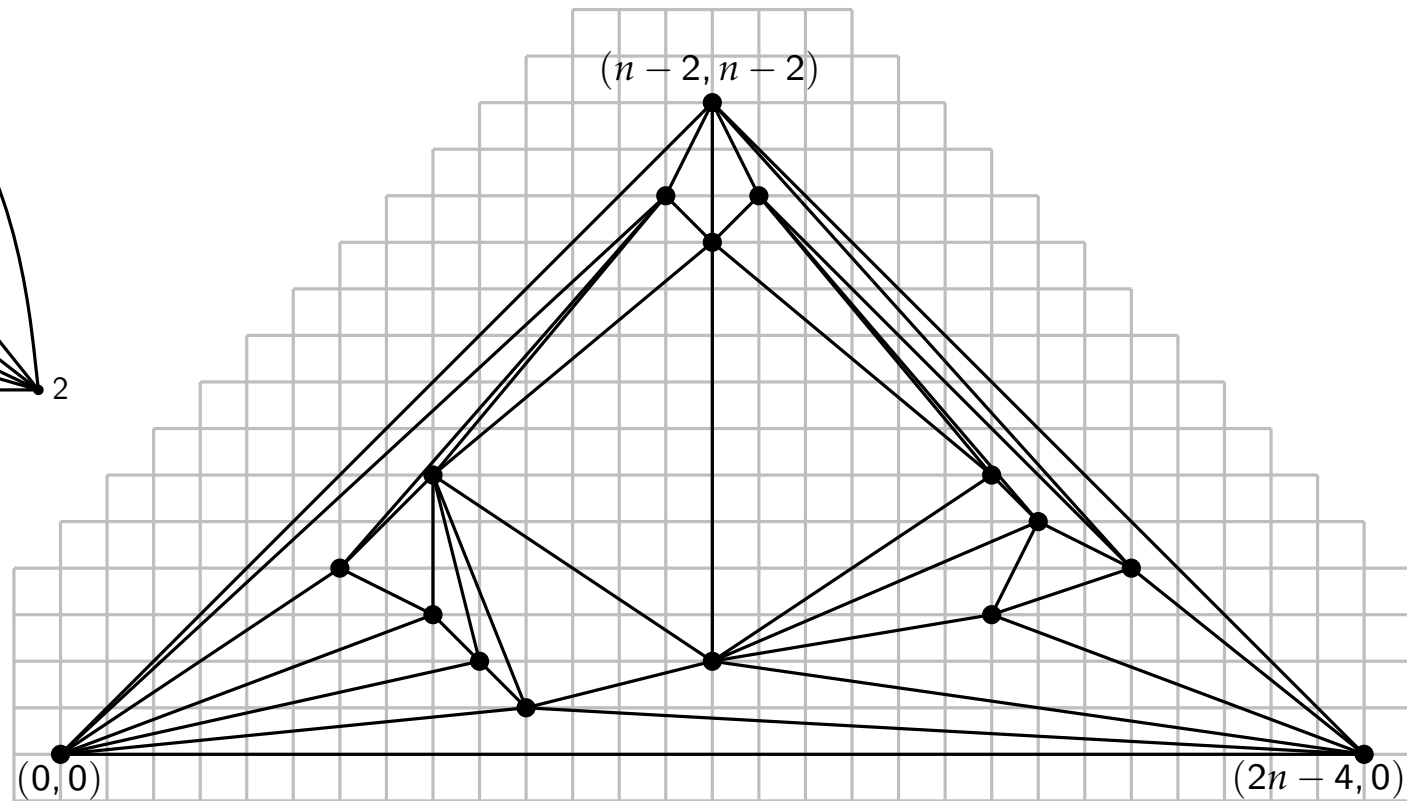
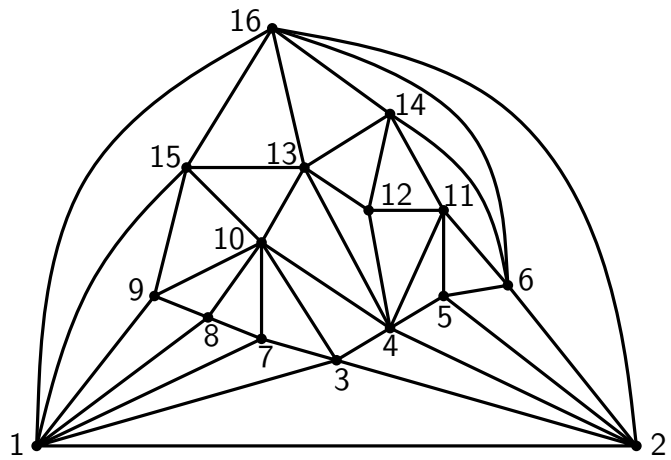
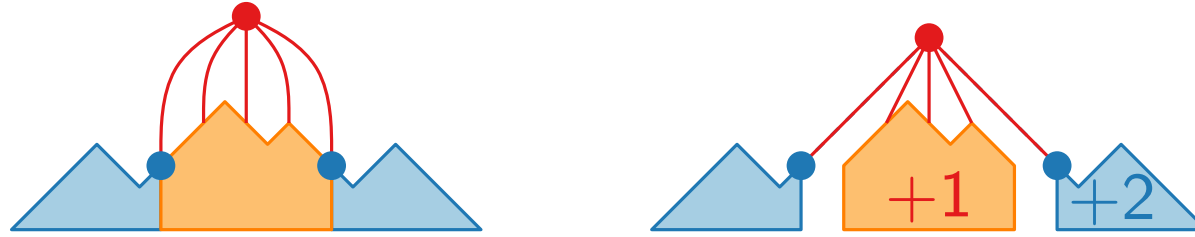
Shift method – example



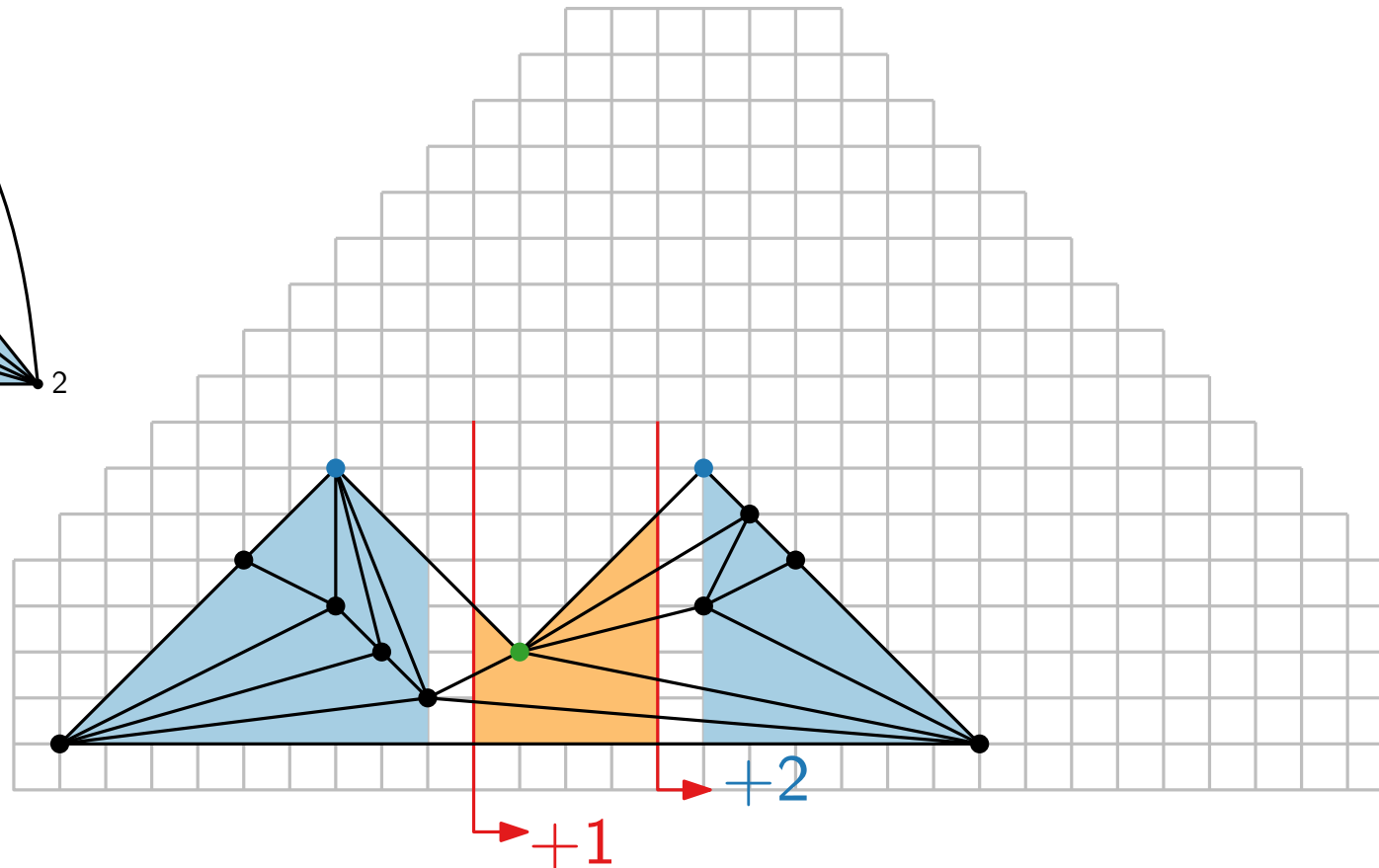
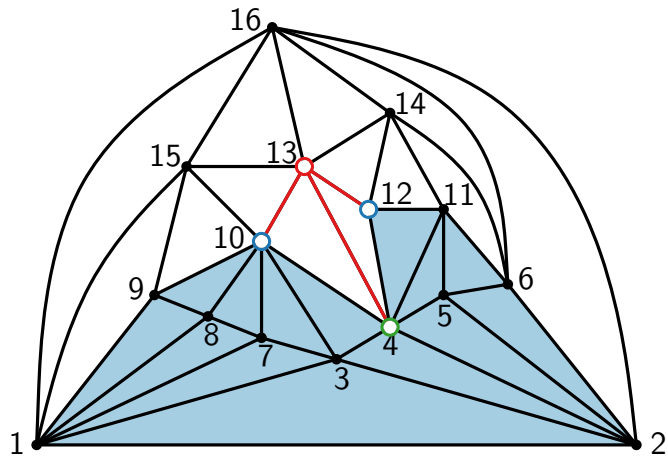
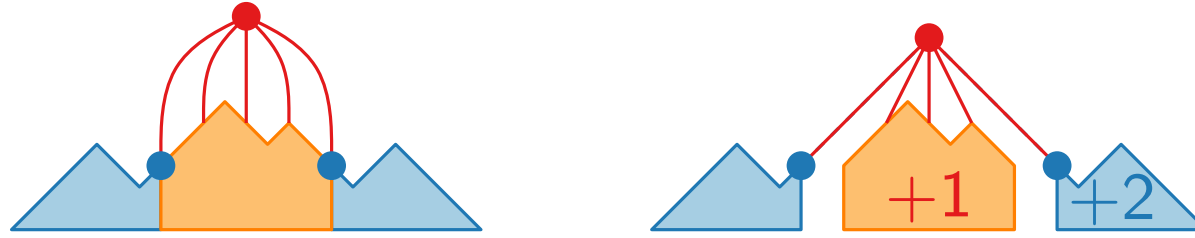
Shift method – example



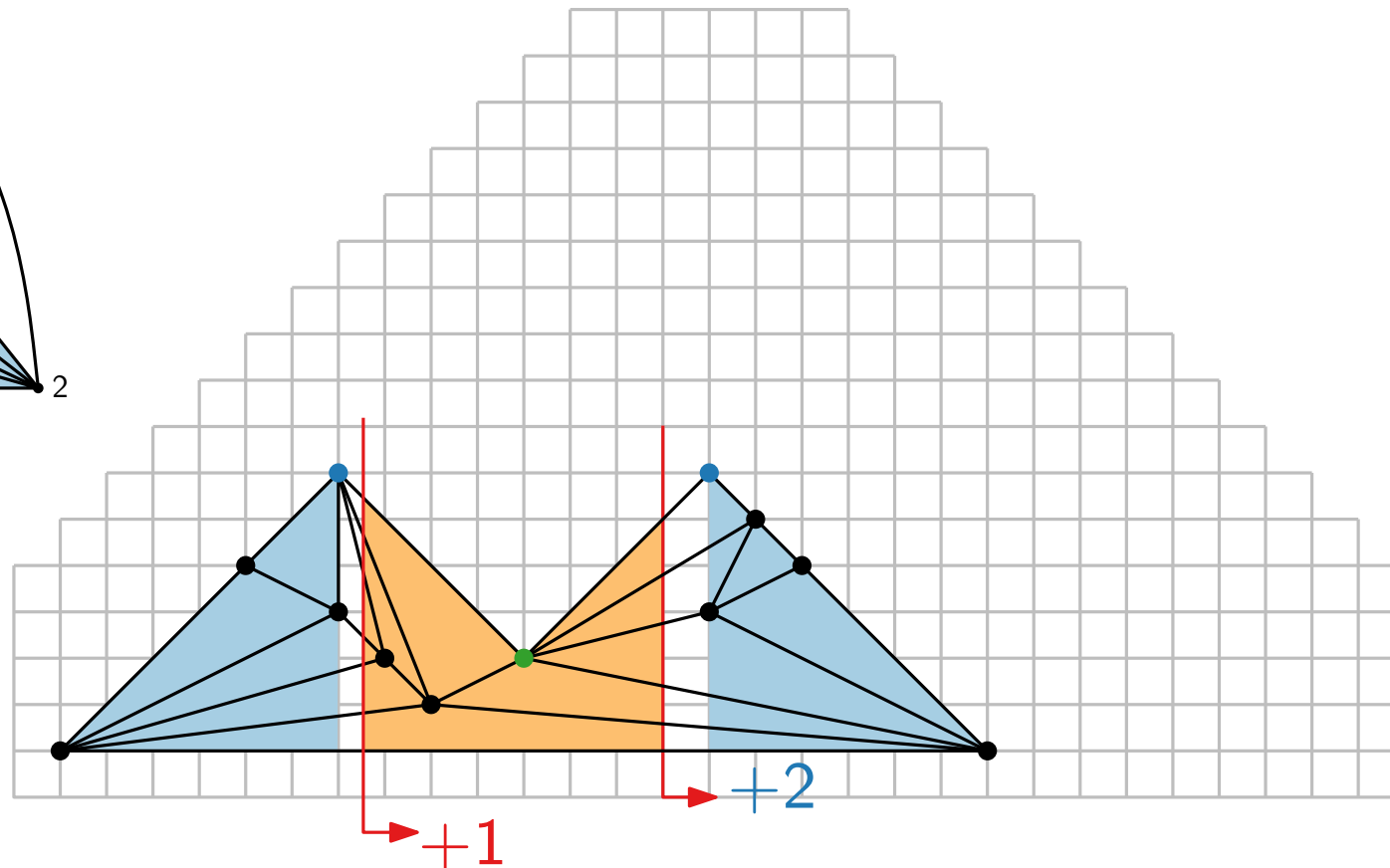
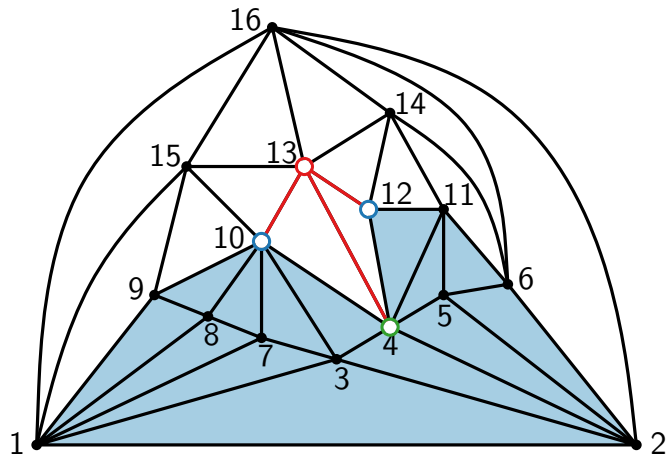
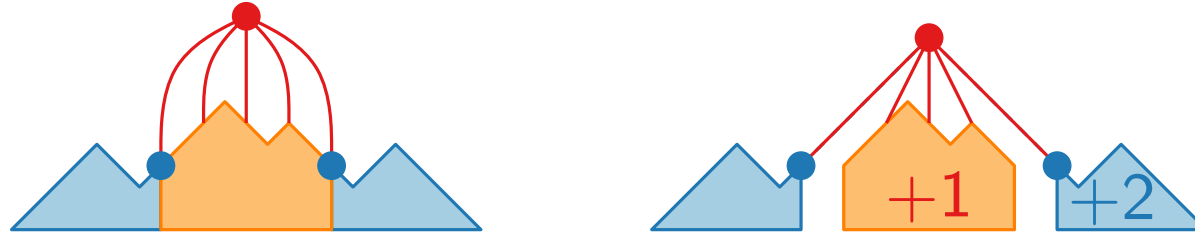
Shift method – example



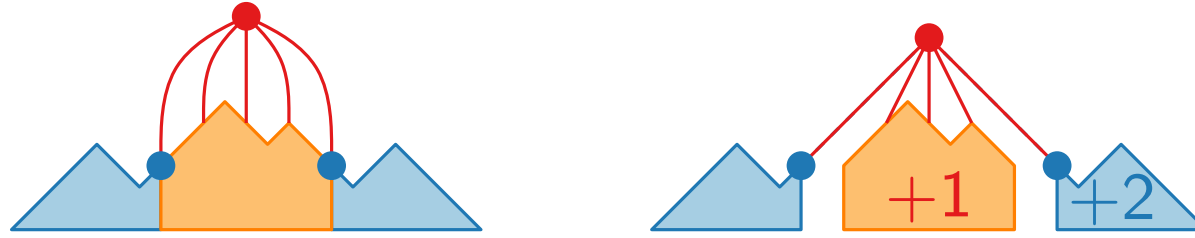
Shift method – example



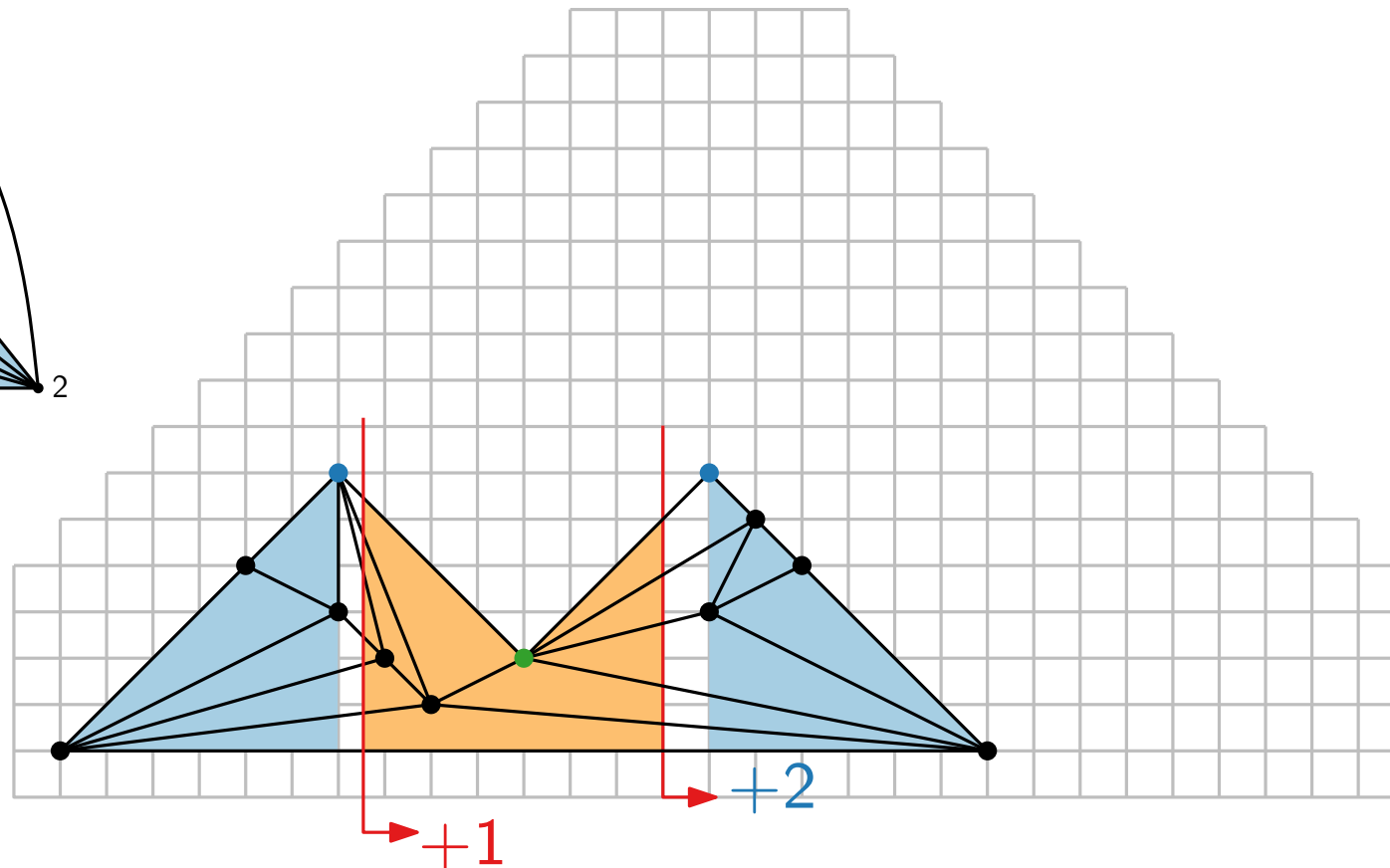
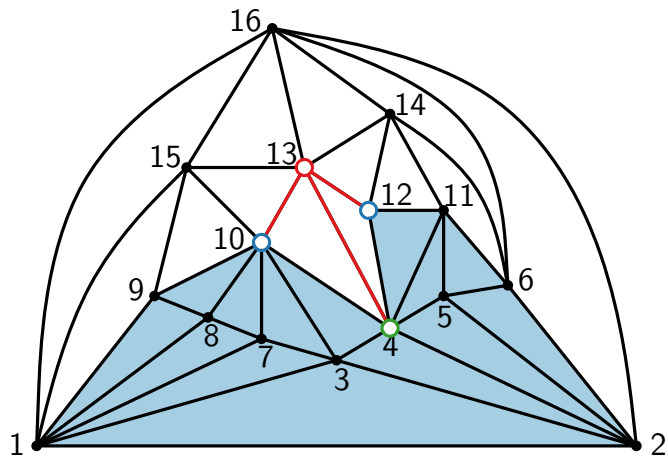
Shift method – example



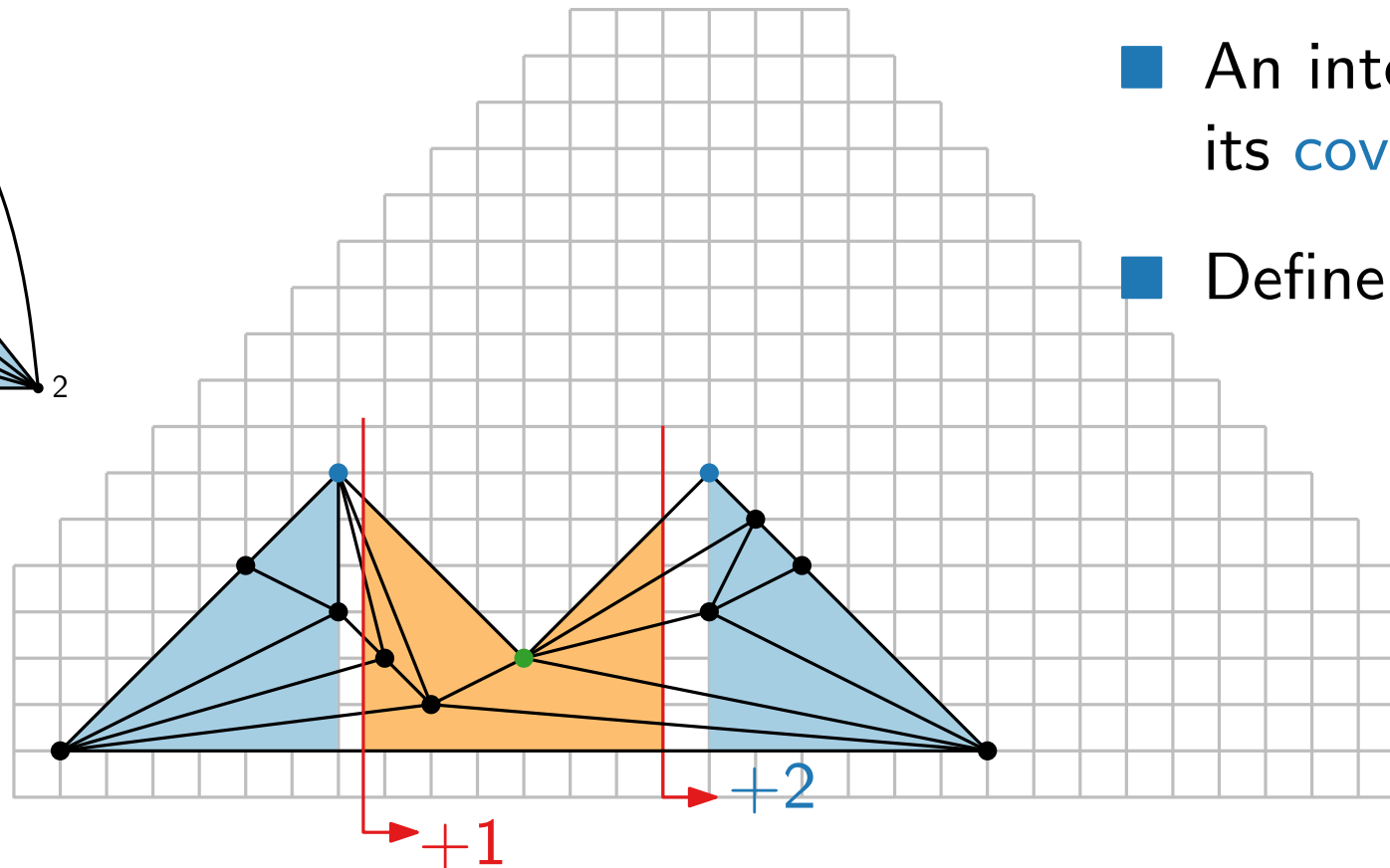
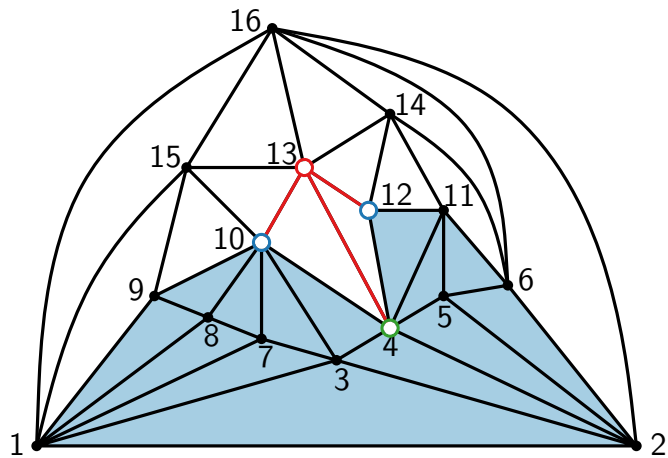
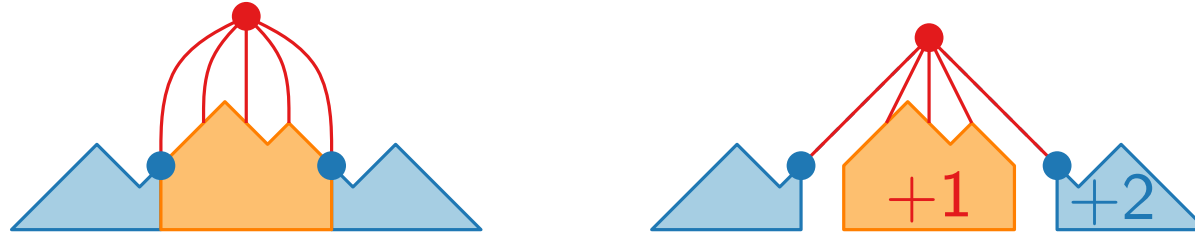
Shift method – example



Which internal nodes are shifted?



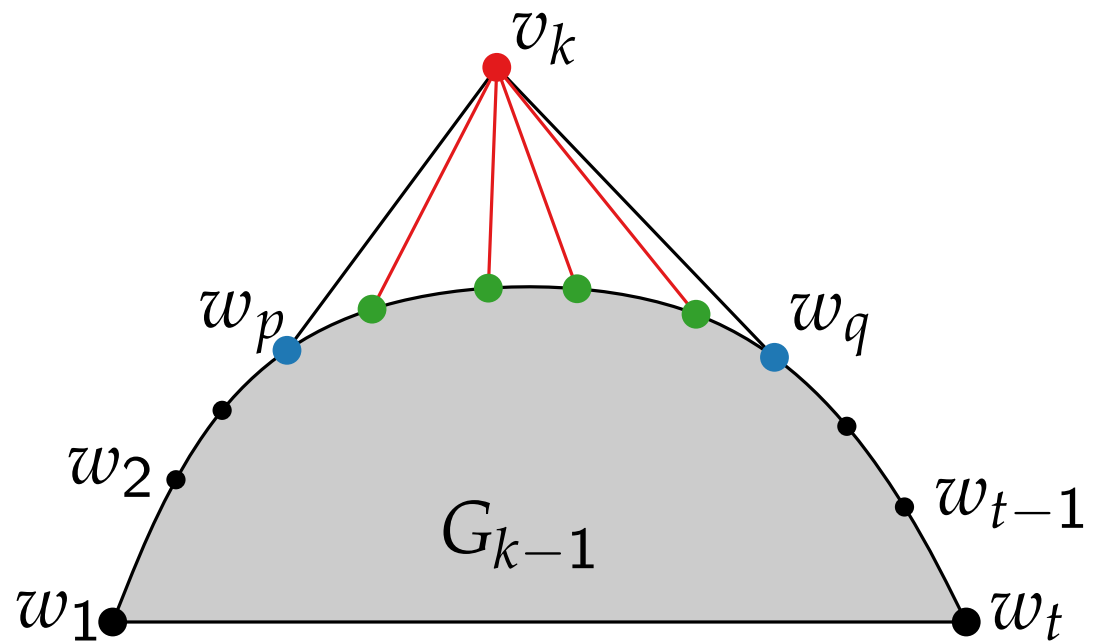
Shift method – example



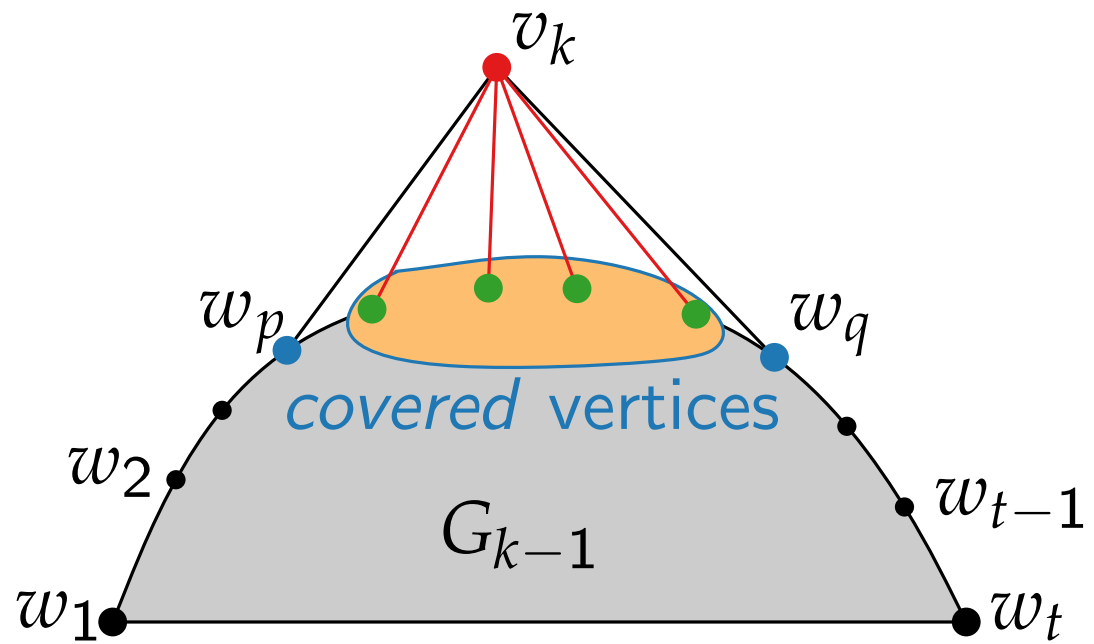
Which internal nodes are shifted?

- An internal node shifts with its **covering** outer vertex
- Define **covering**

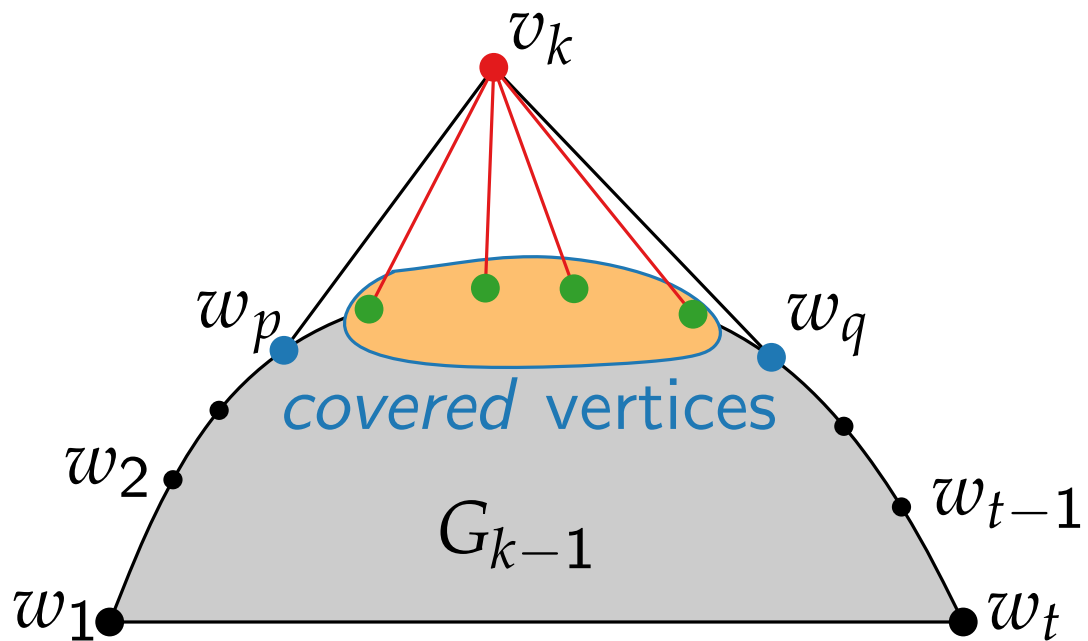
Shift method – dominating



Shift method – dominating



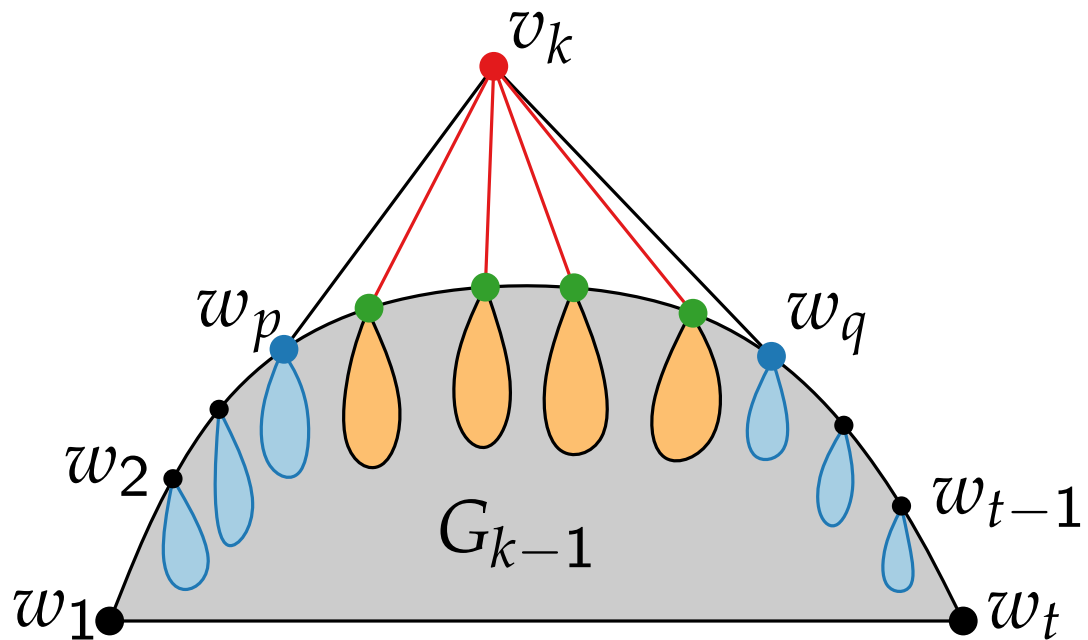
Shift method – dominating



Observations.

- Each internal vertex is **covered** exactly once.
- **Covering relation** defines a tree in G
- and a forest in $G_i, 1 \leq i \leq n - 1$.

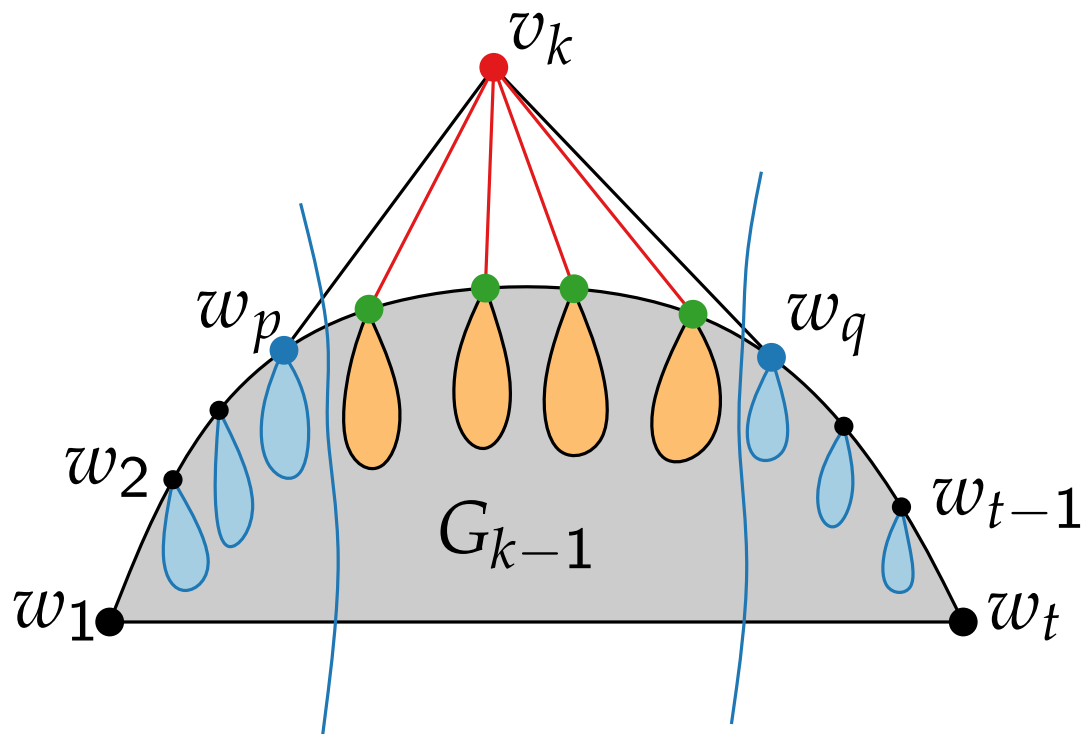
Shift method – dominating



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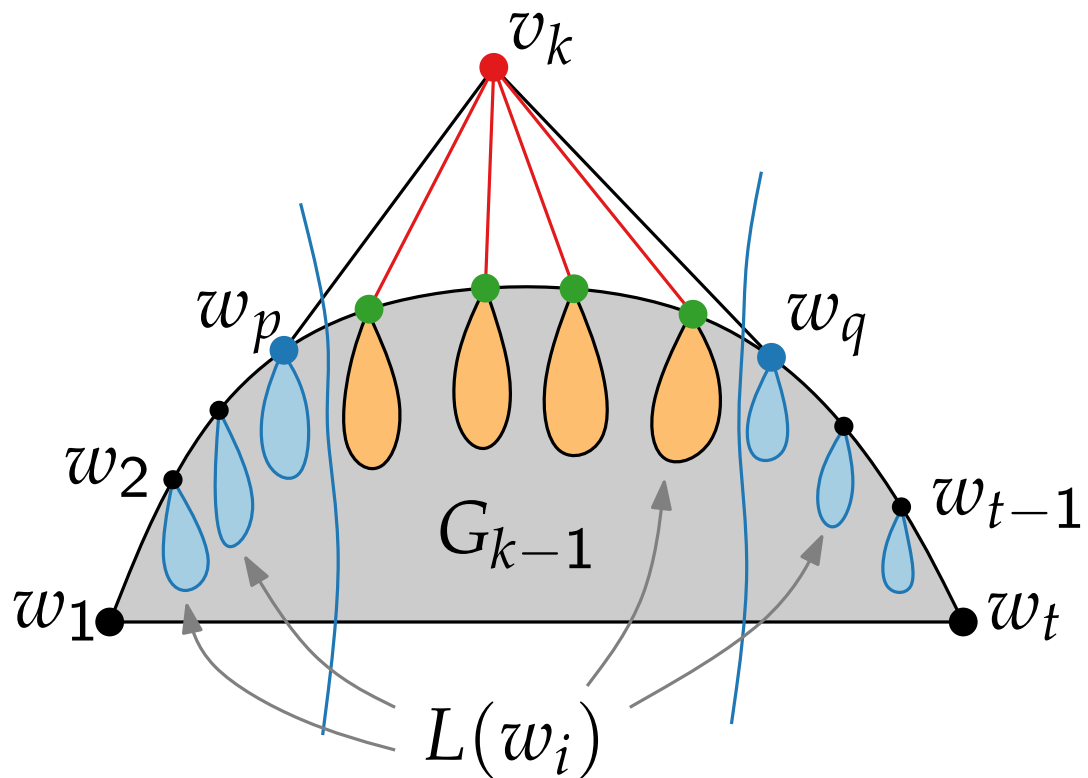
Shift method – dominating



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Shift method – dominating



Observations.

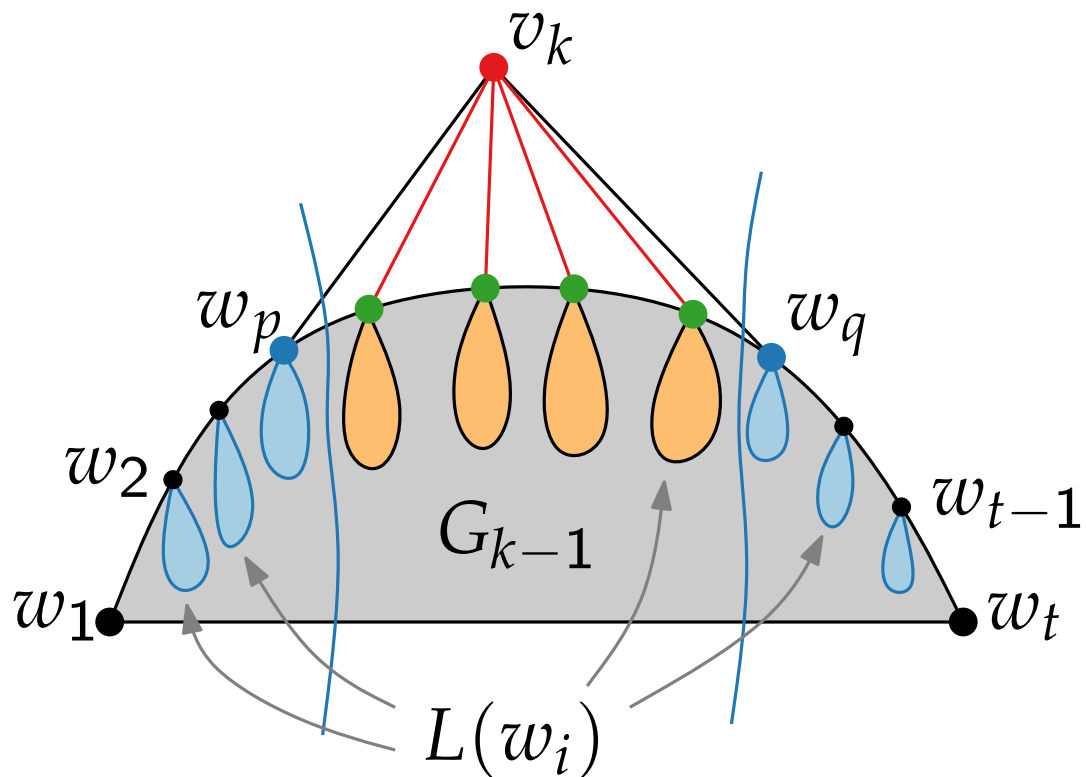
- Each internal vertex is **covered** exactly once.
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Shift method – dominating

Definition.

$L(w_i)$ is the set of vertices covered by w_i

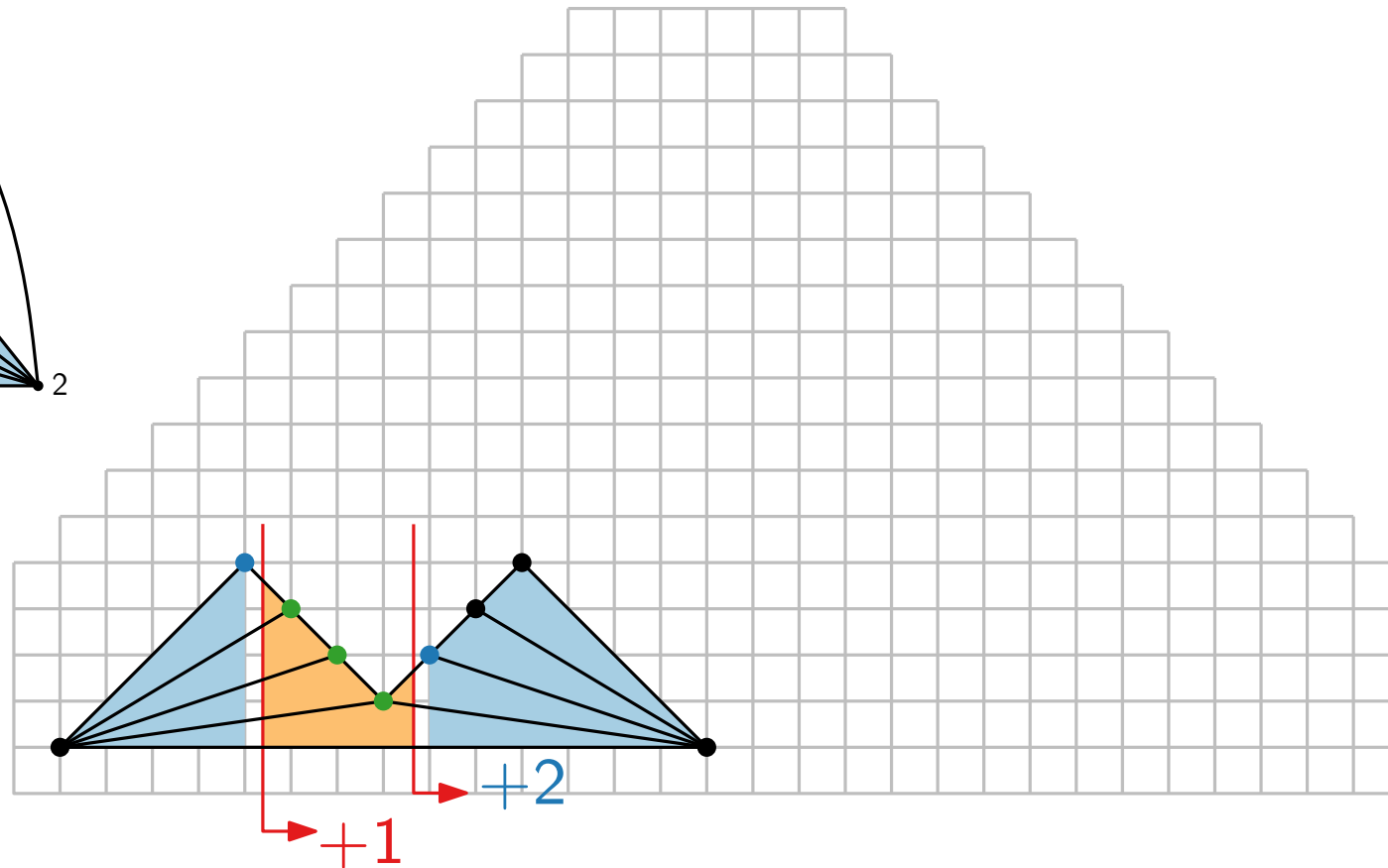
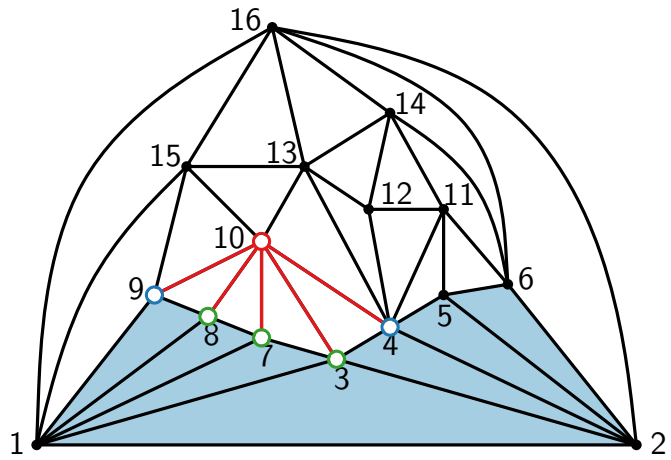
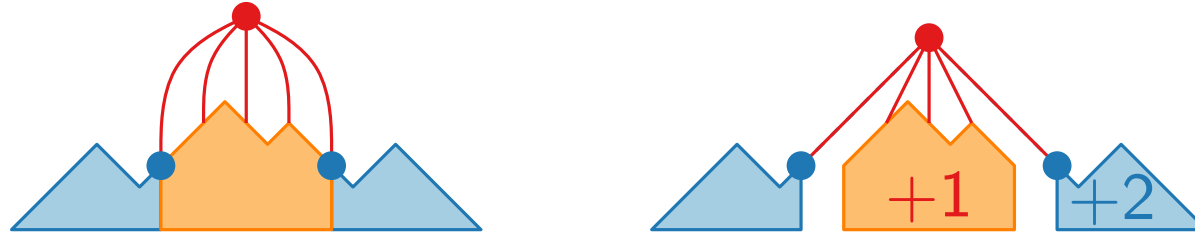
$L(w_i)$ is the subtree of the covering tree rooted at w_i



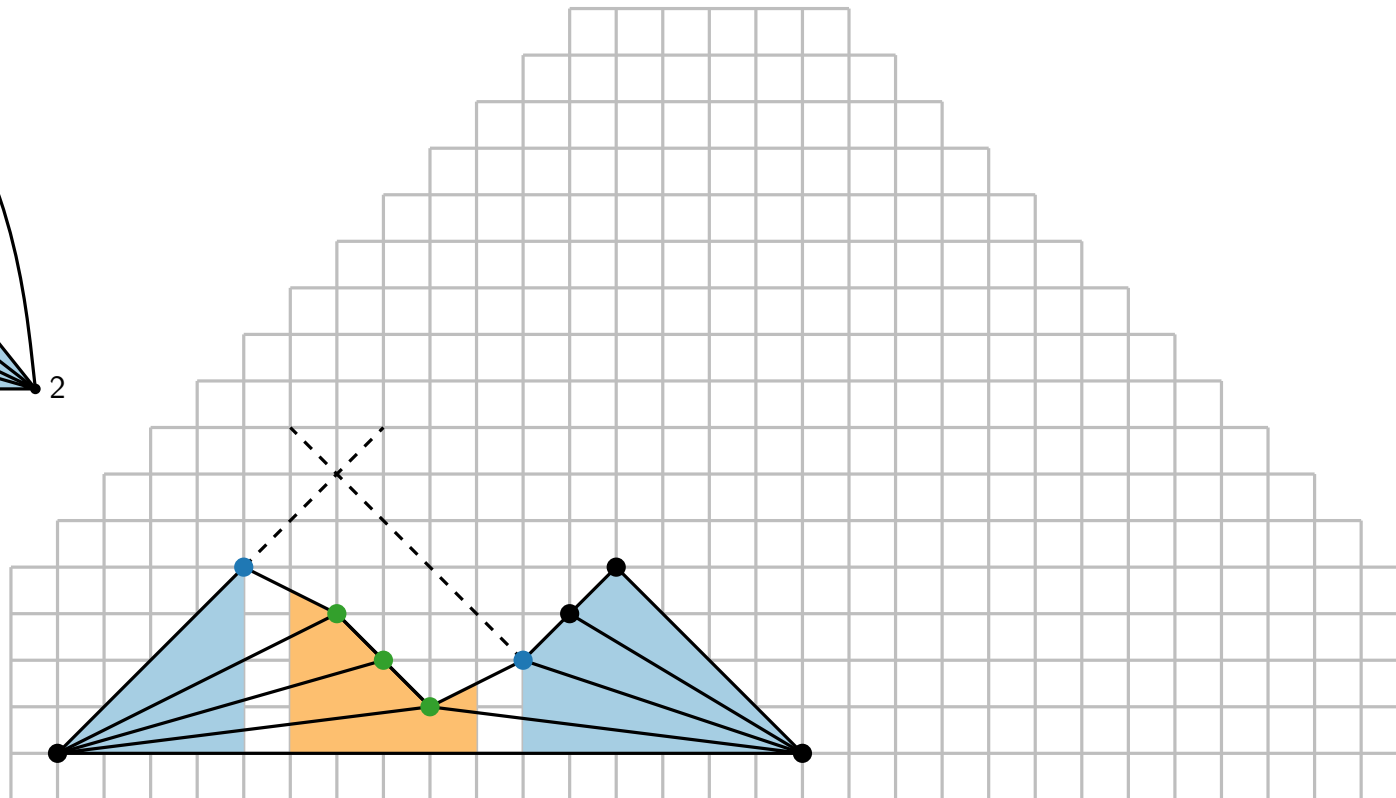
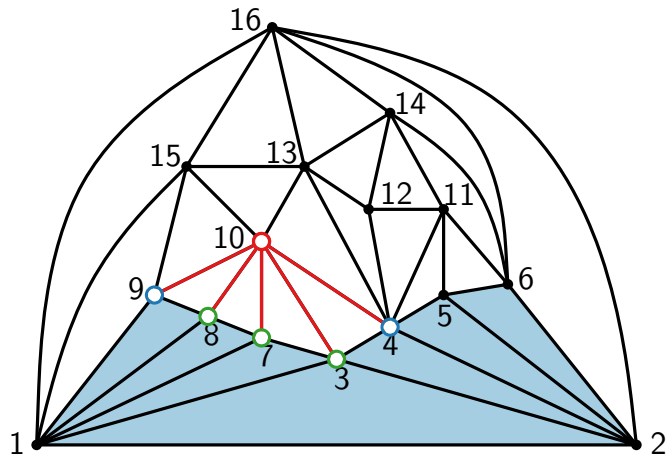
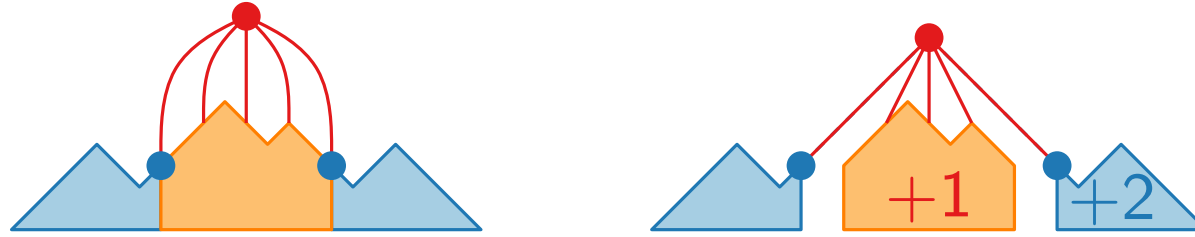
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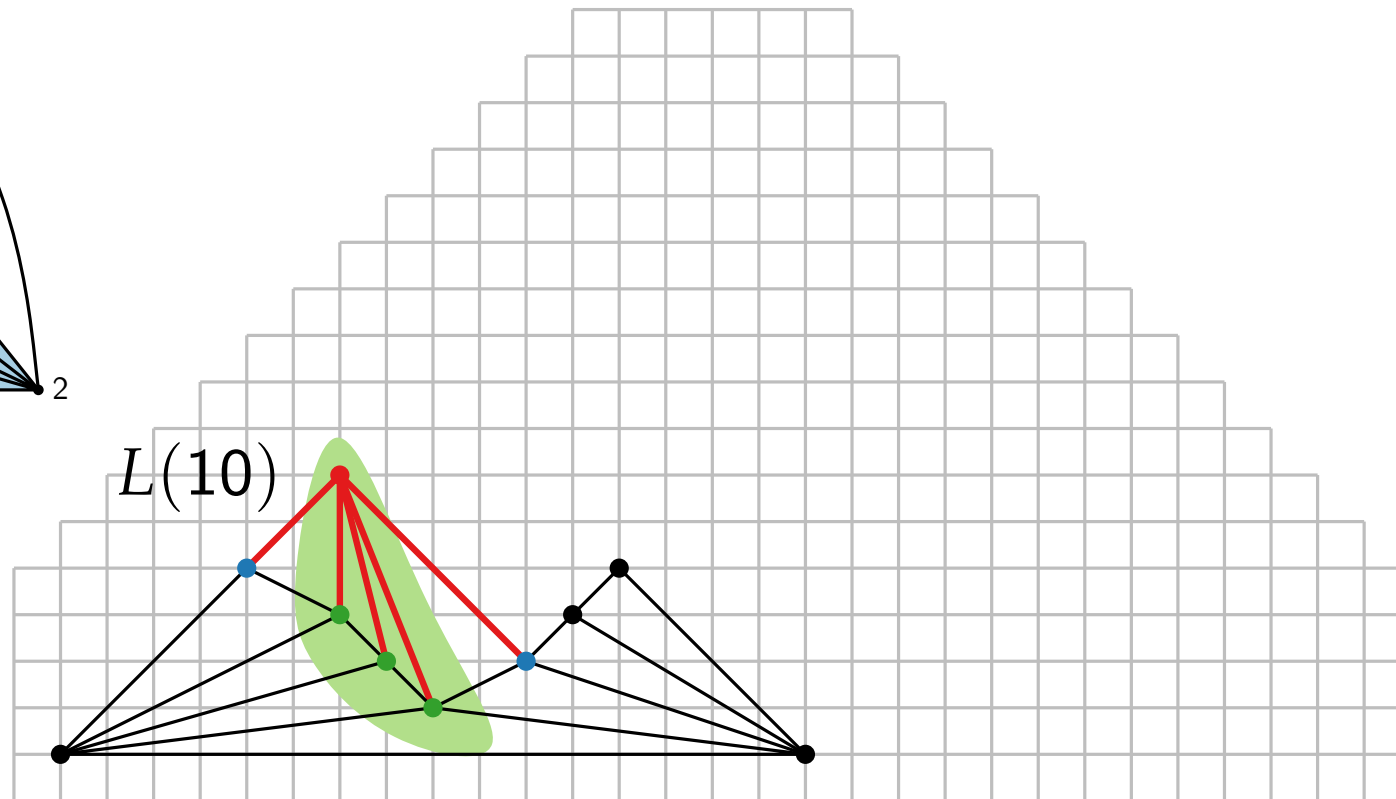
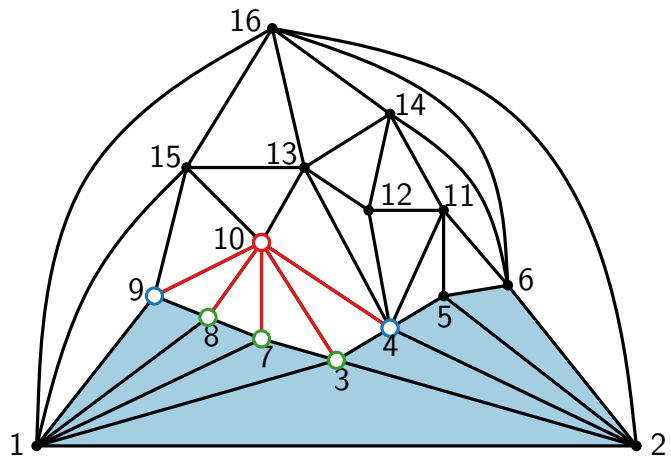
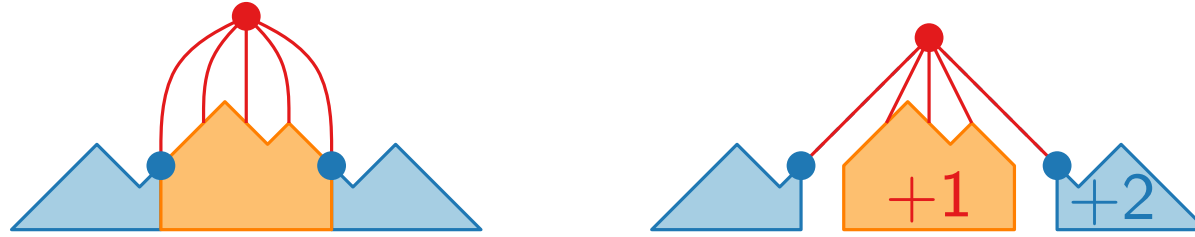
Shift method – example



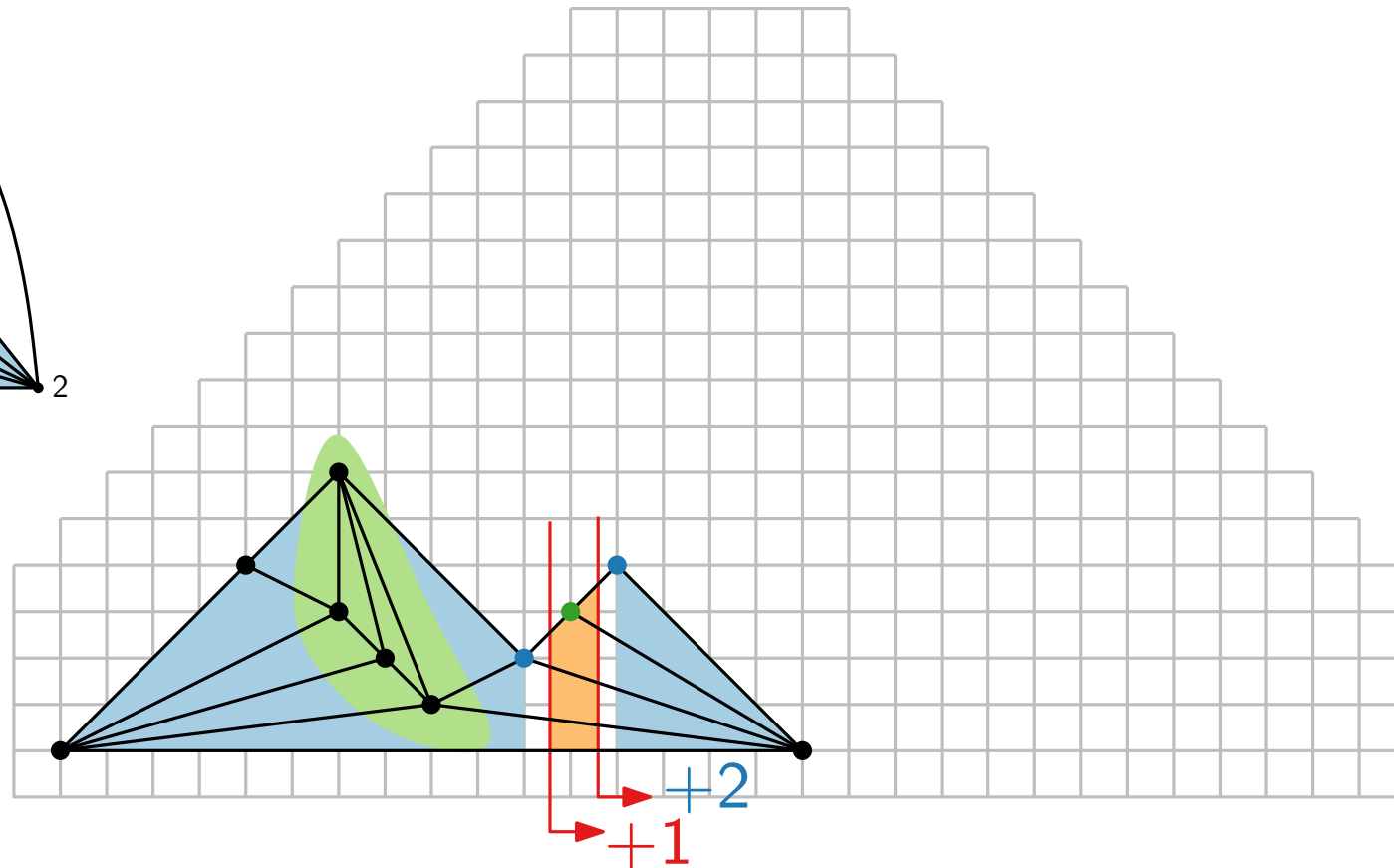
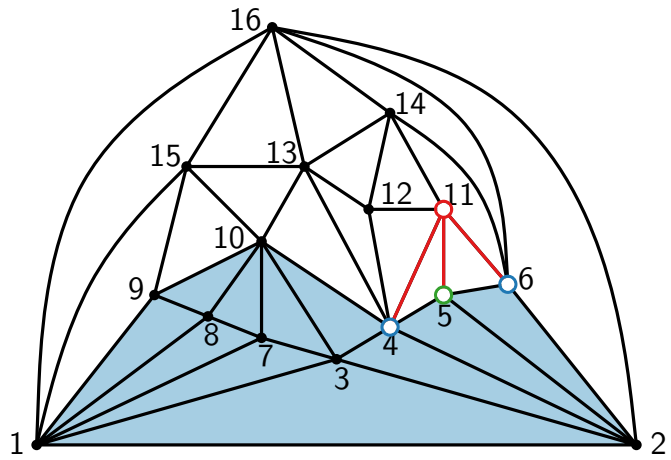
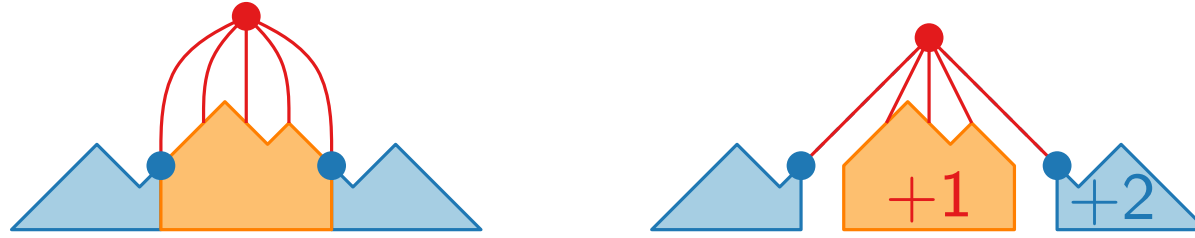
Shift method – example



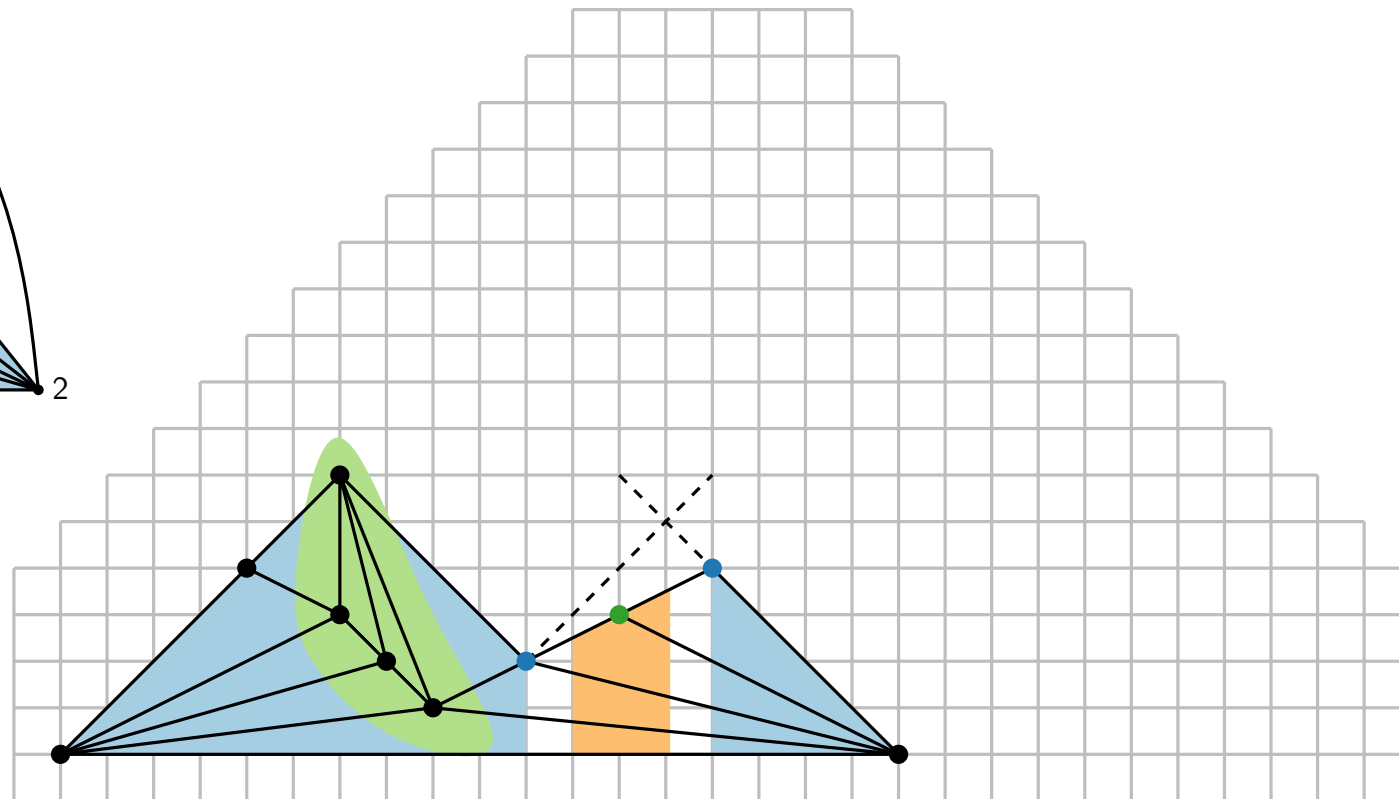
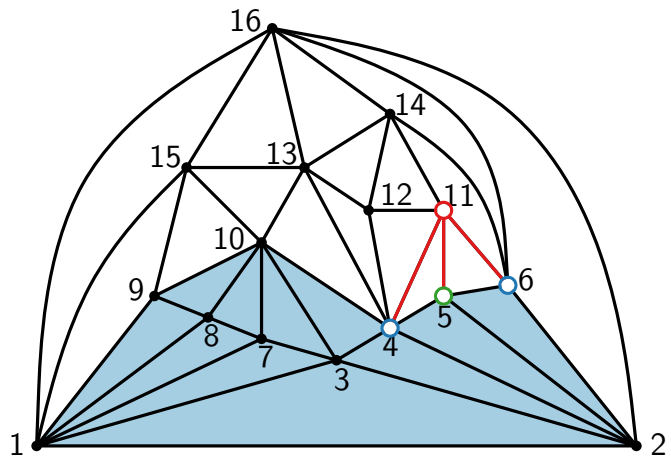
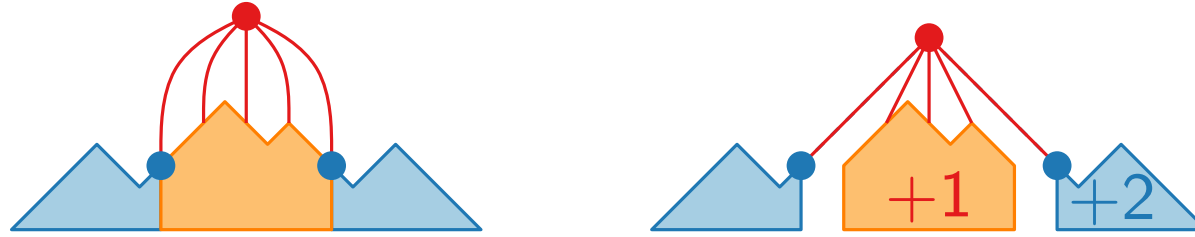
Shift method – example



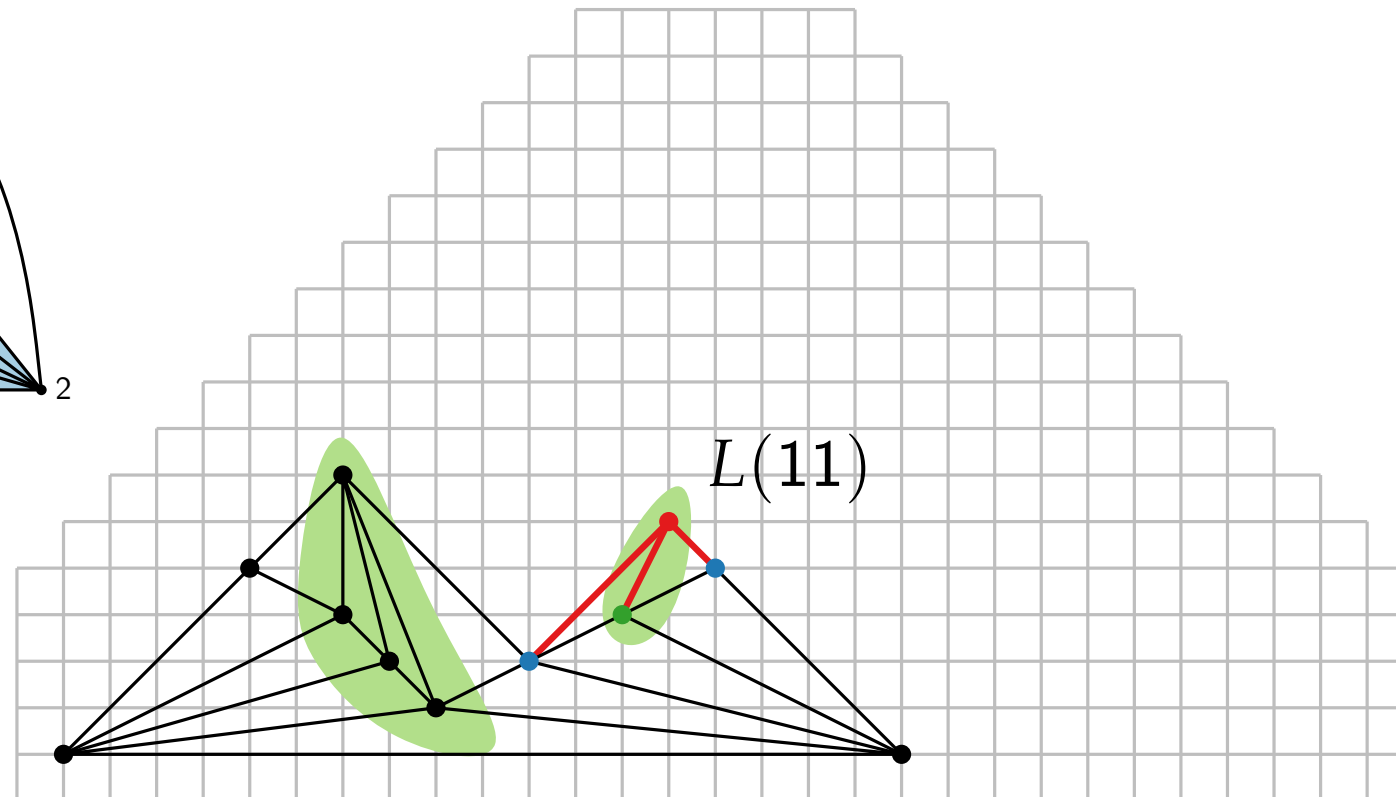
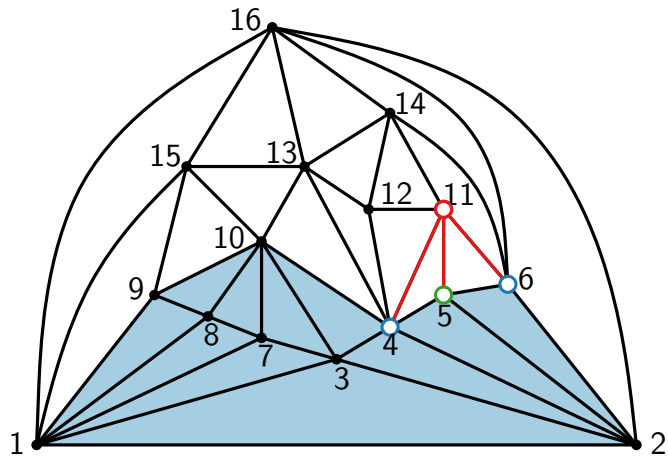
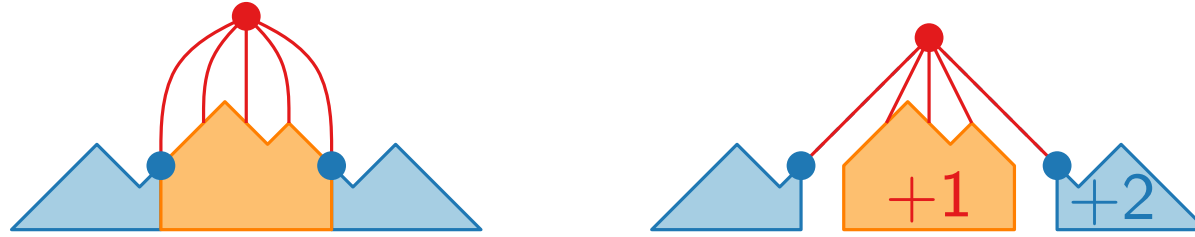
Shift method – example



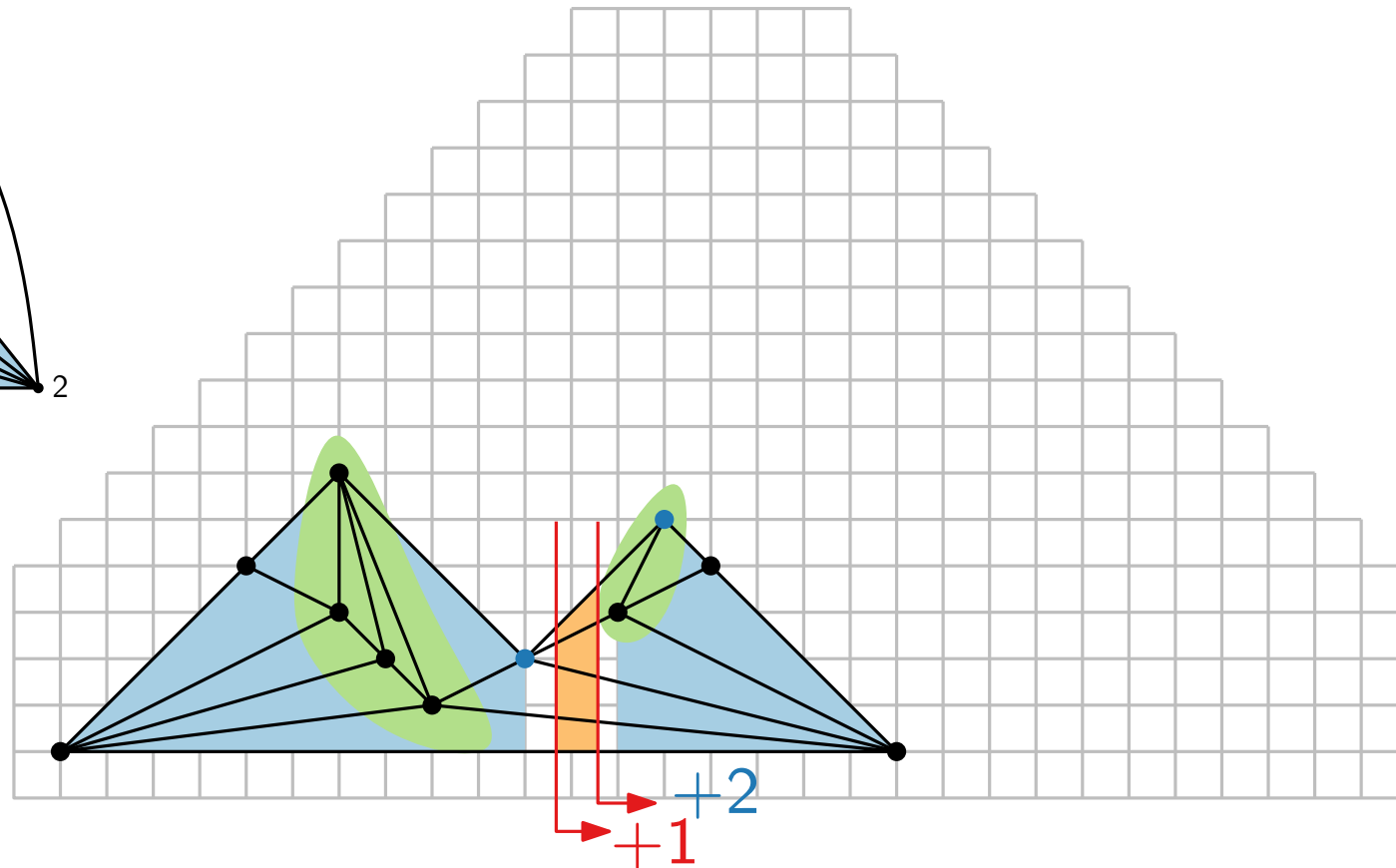
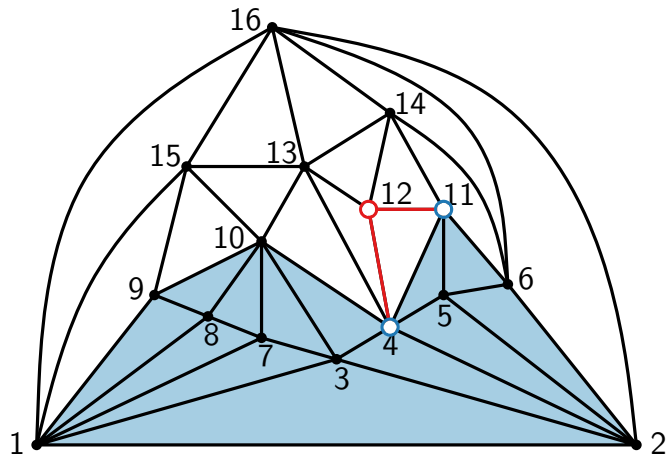
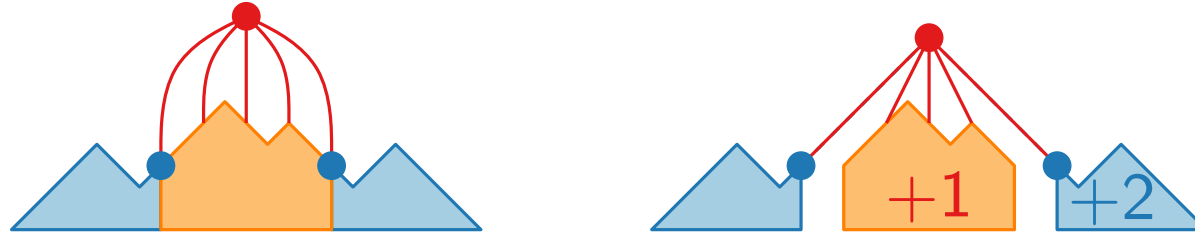
Shift method – example



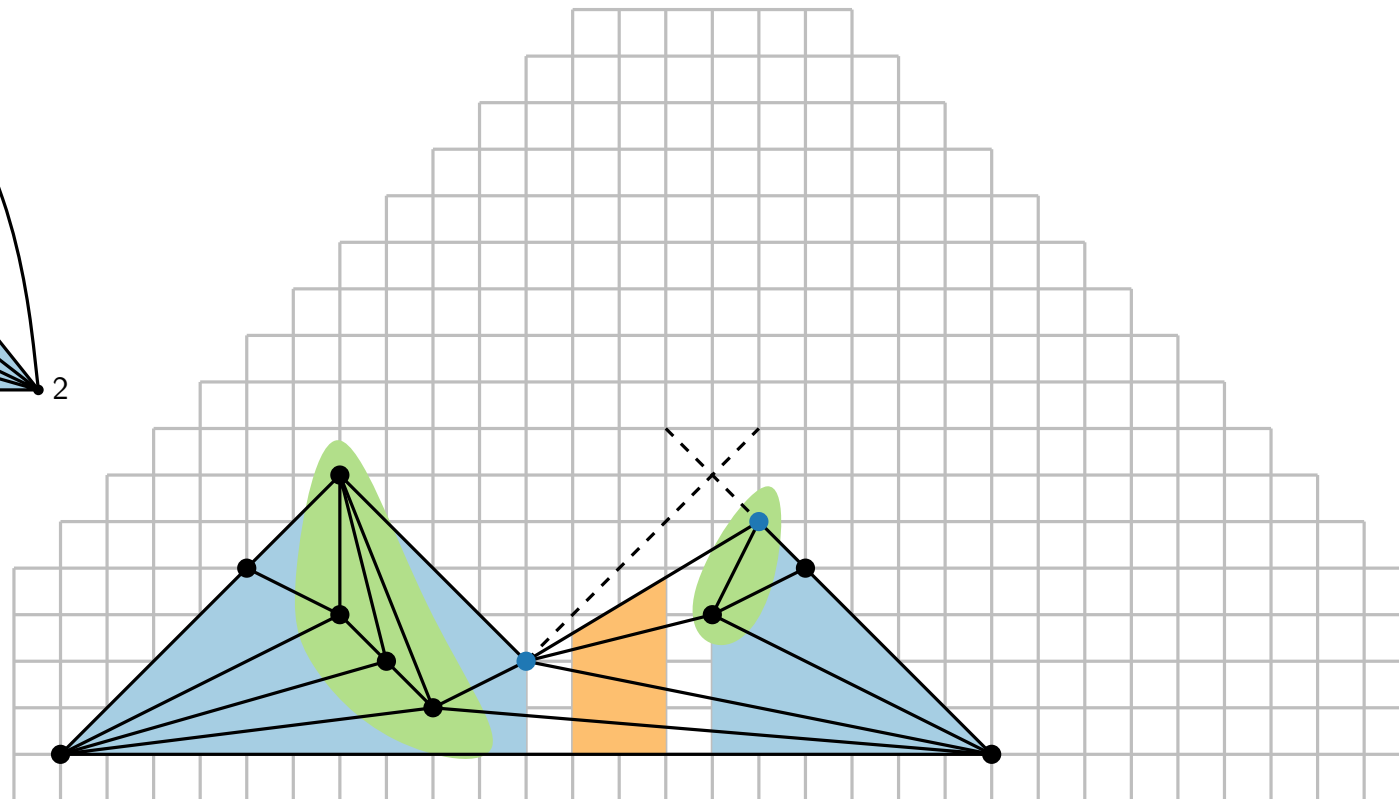
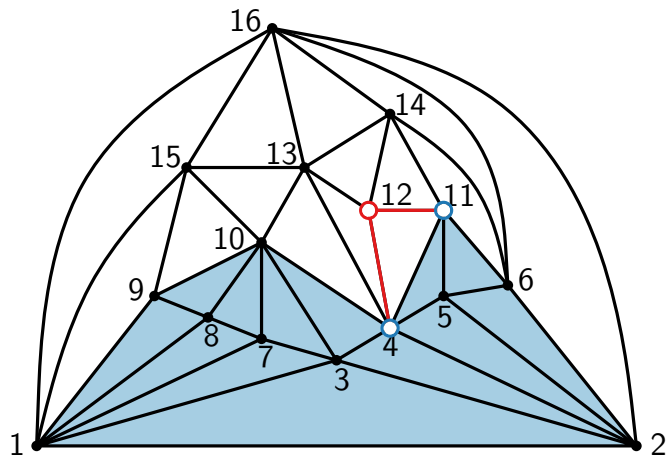
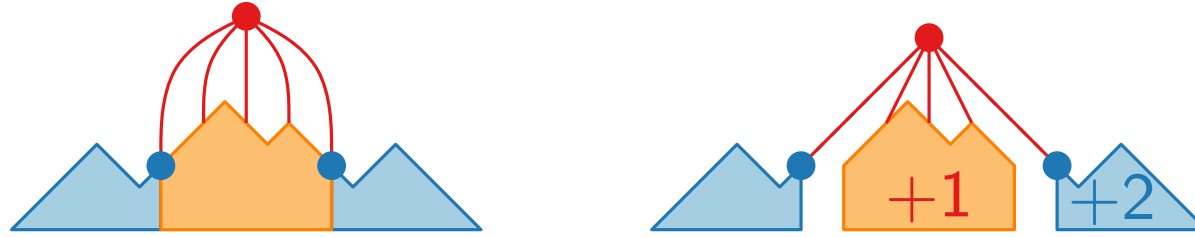
Shift method – example



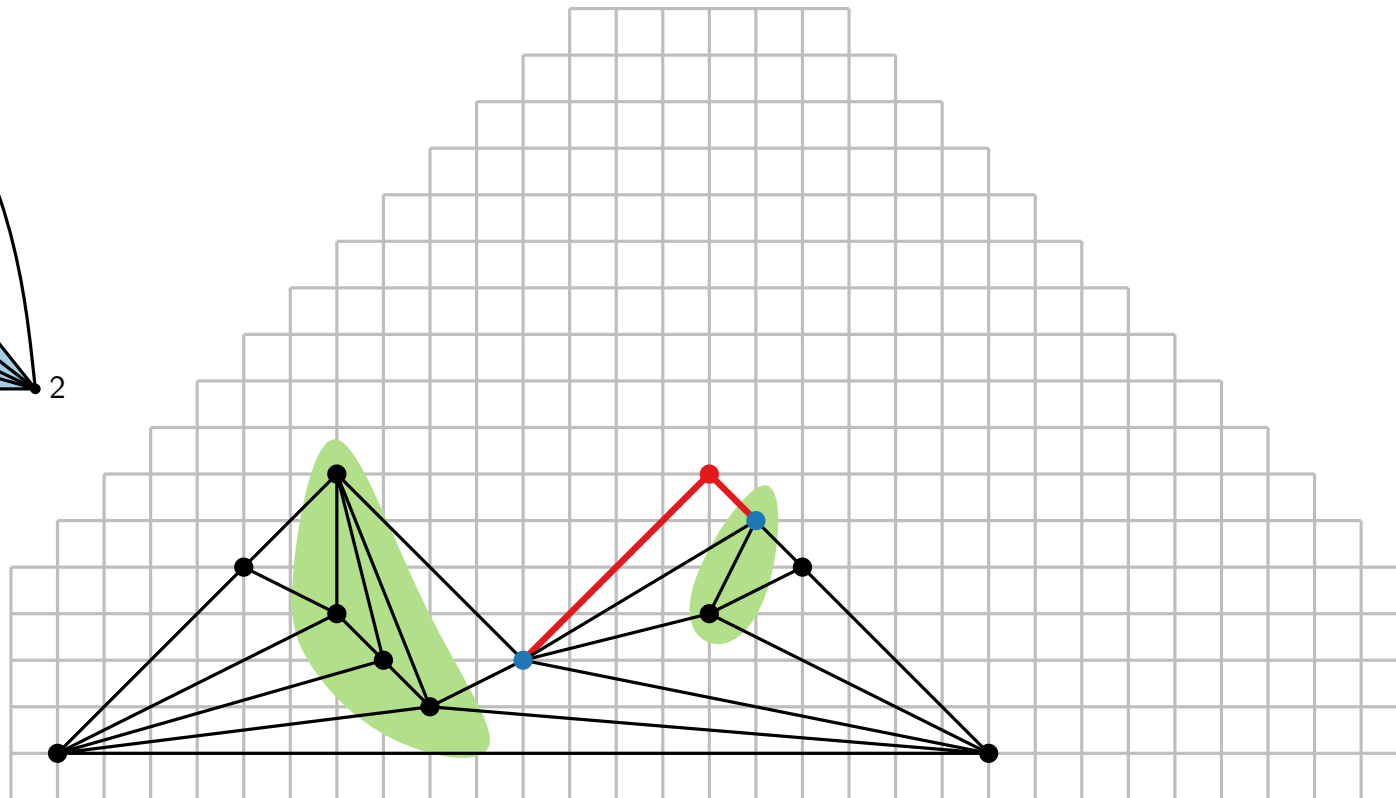
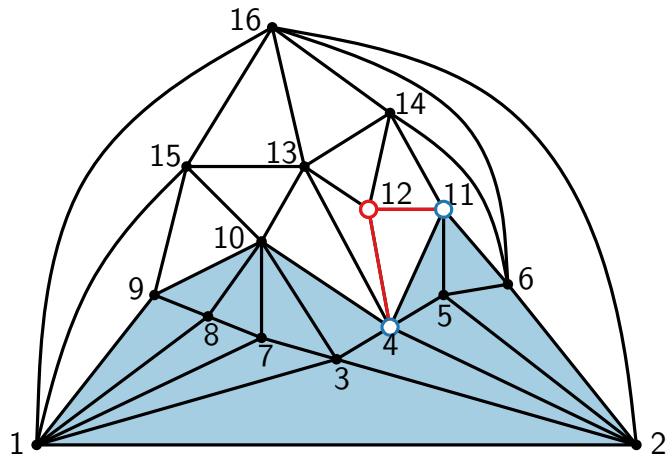
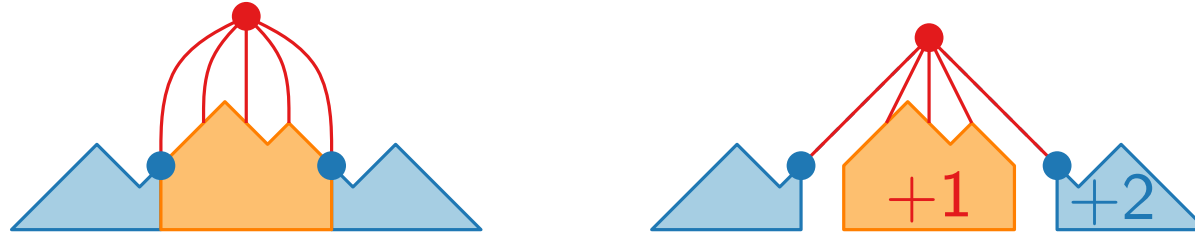
Shift method – example



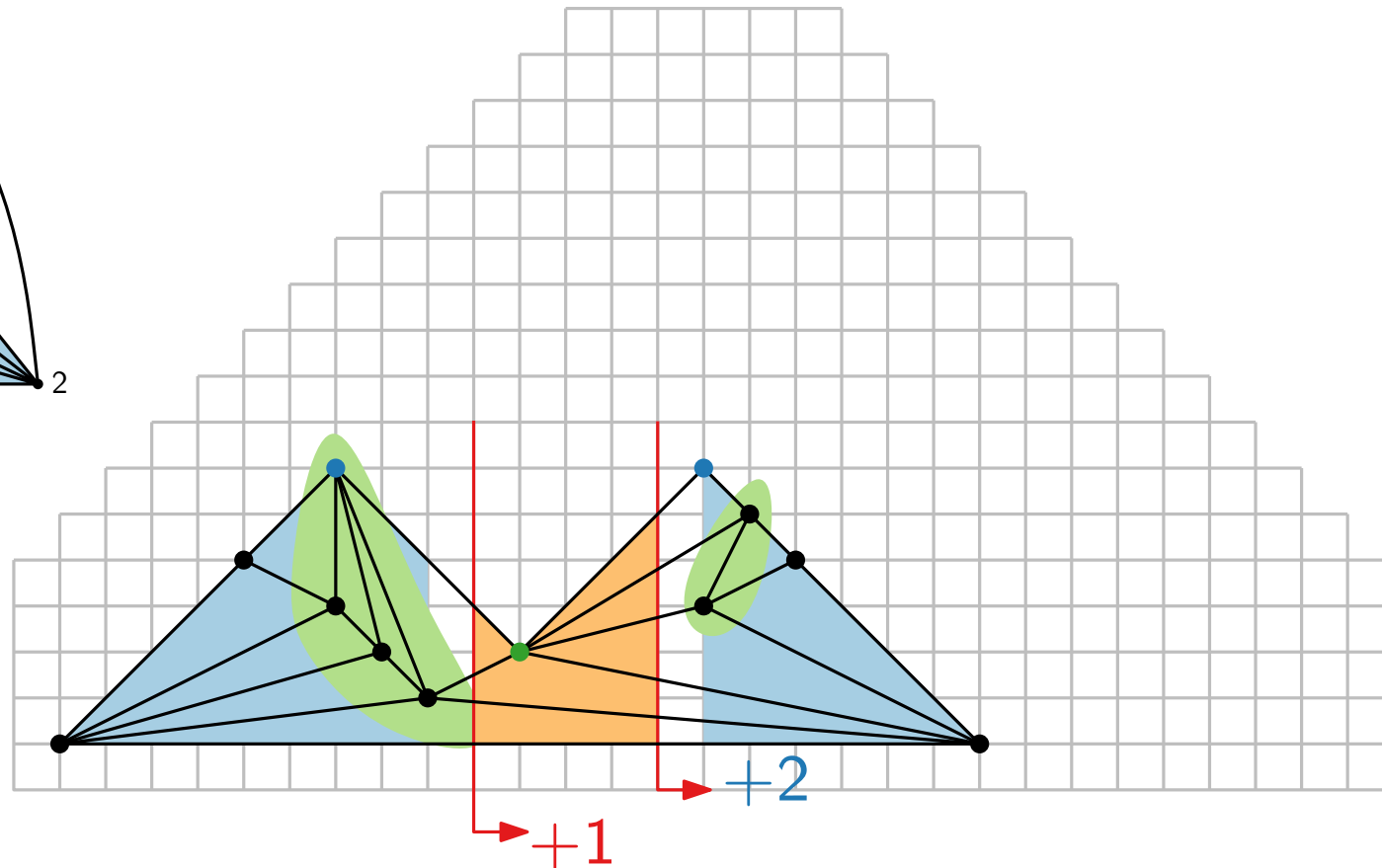
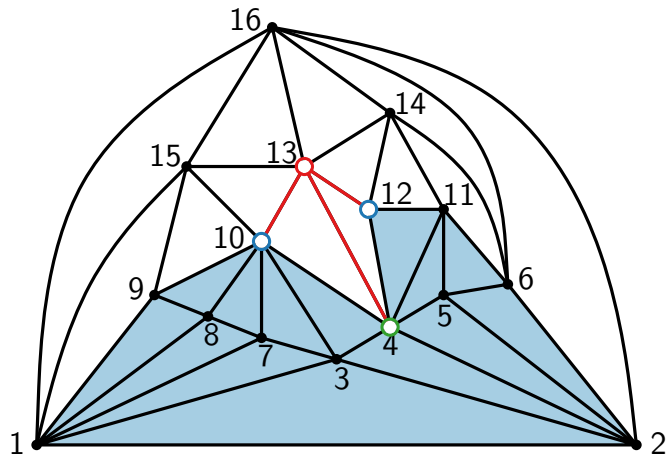
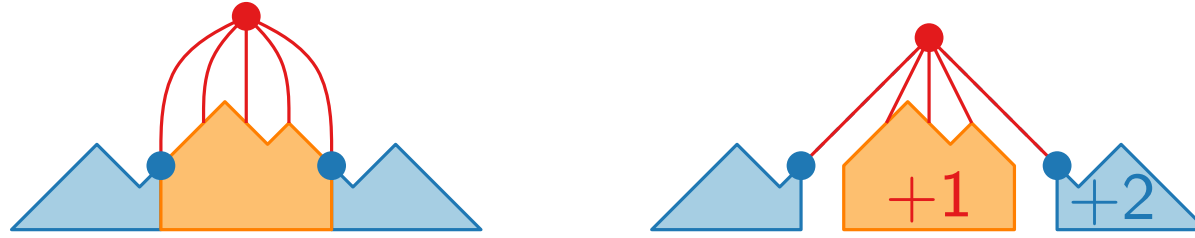
Shift method – example



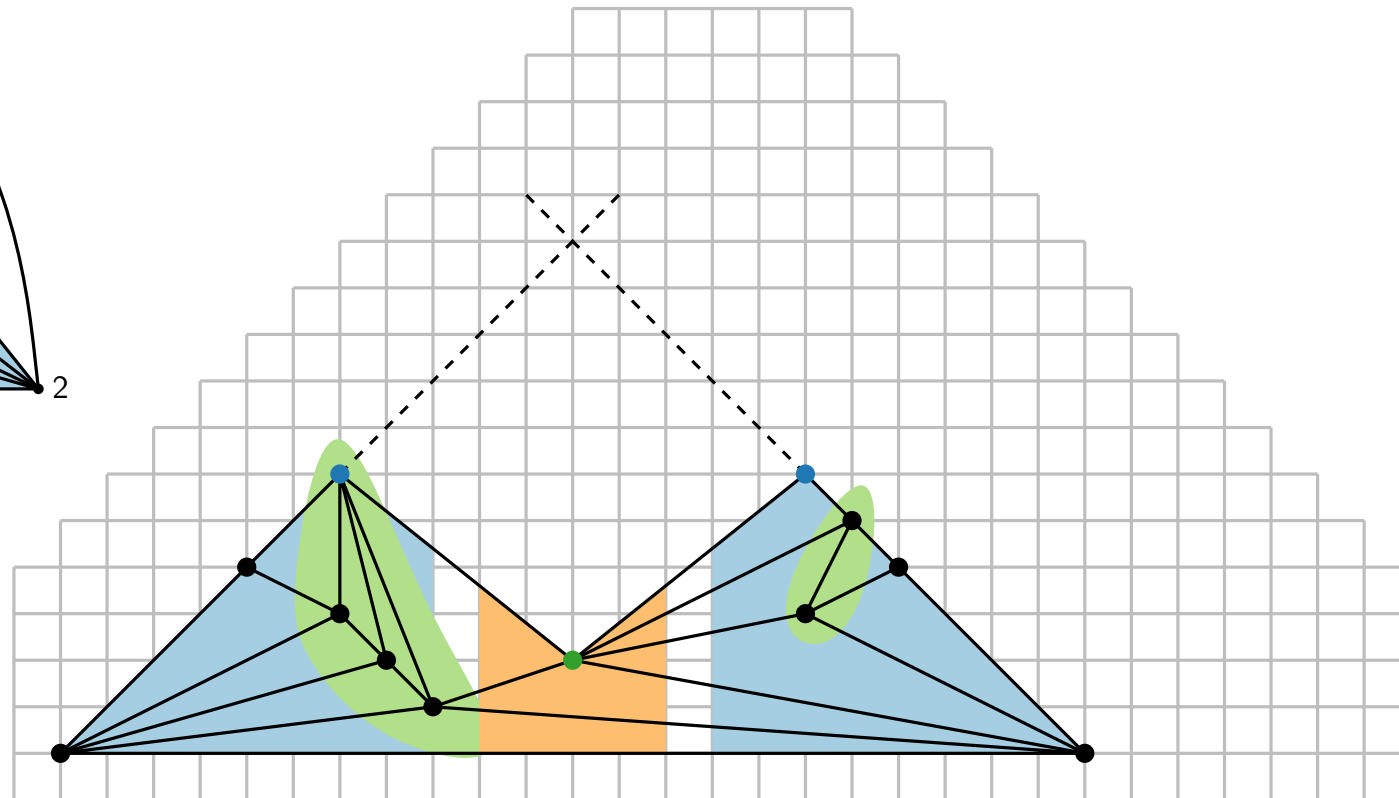
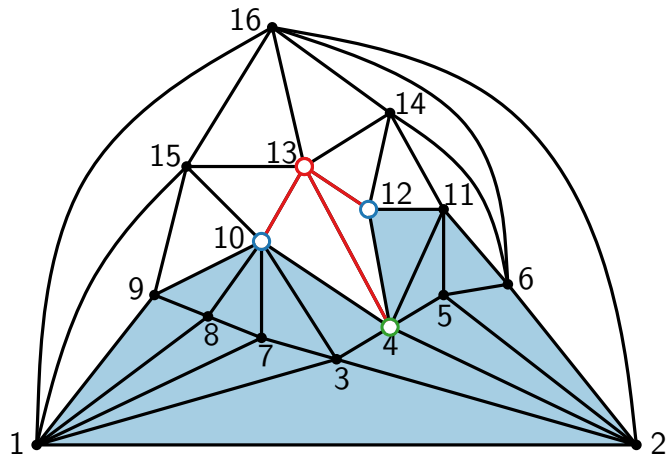
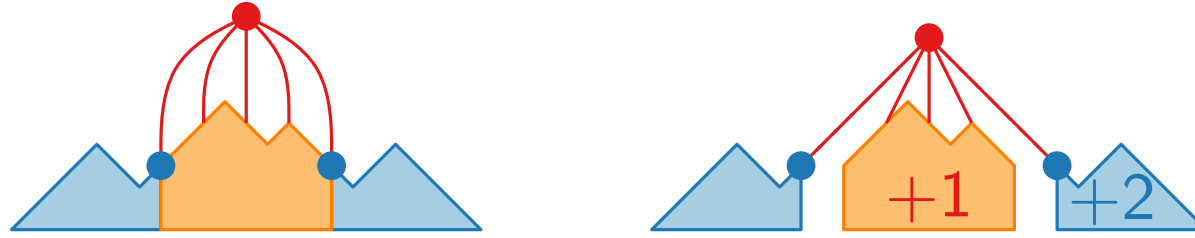
Shift method – example



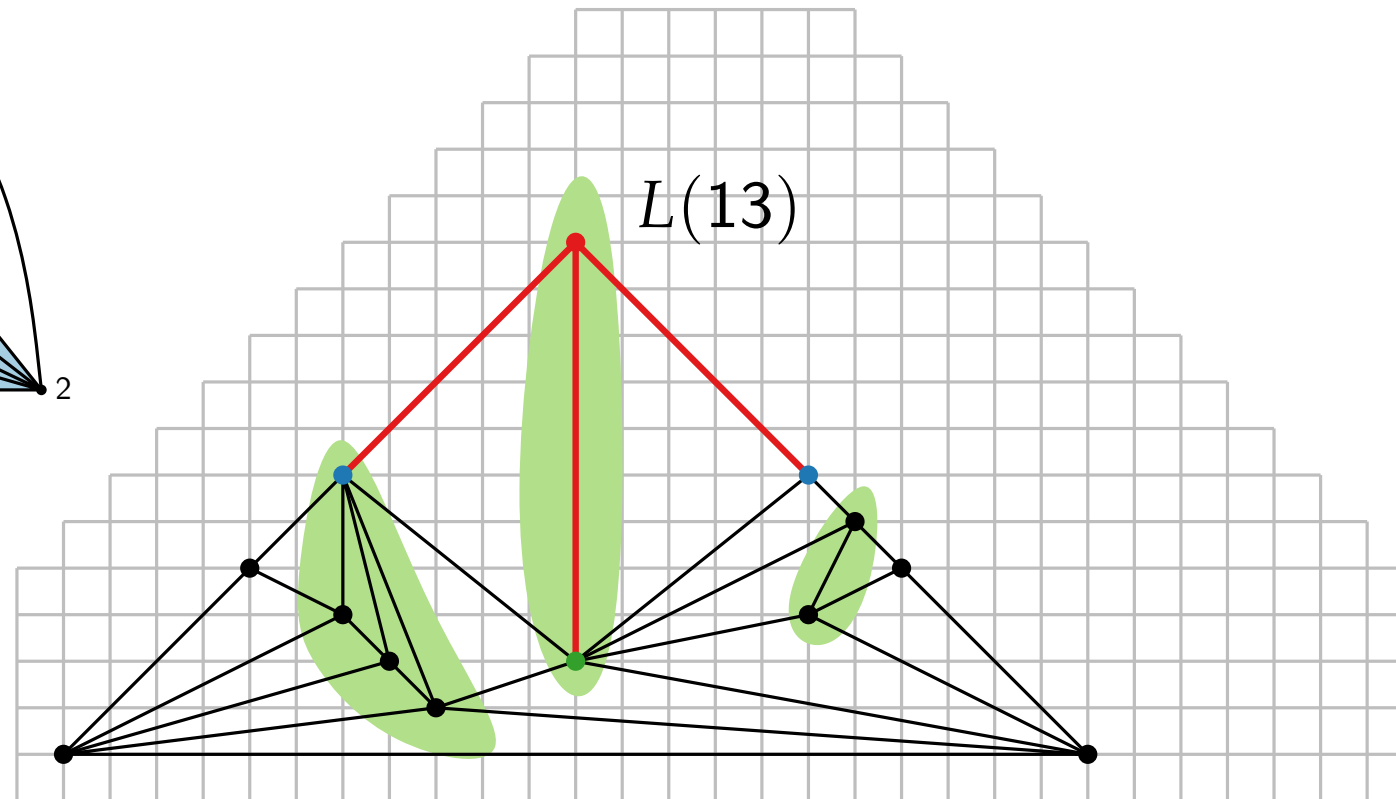
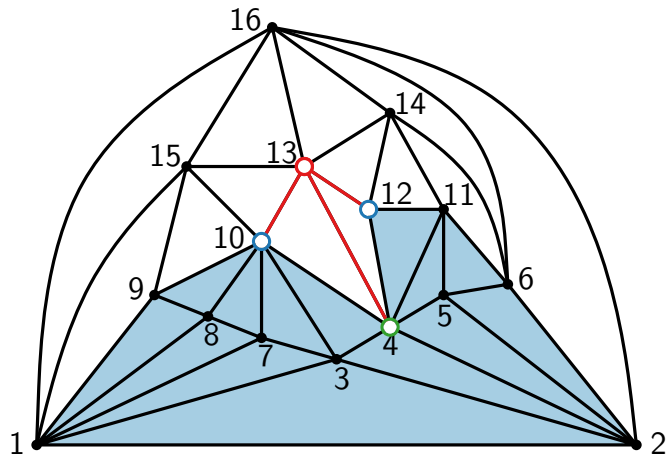
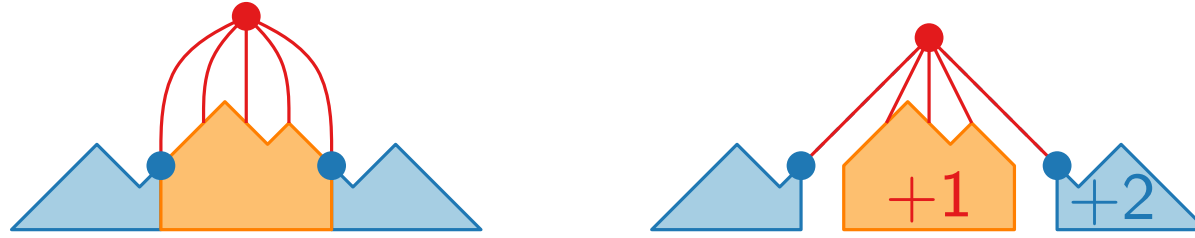
Shift method – example



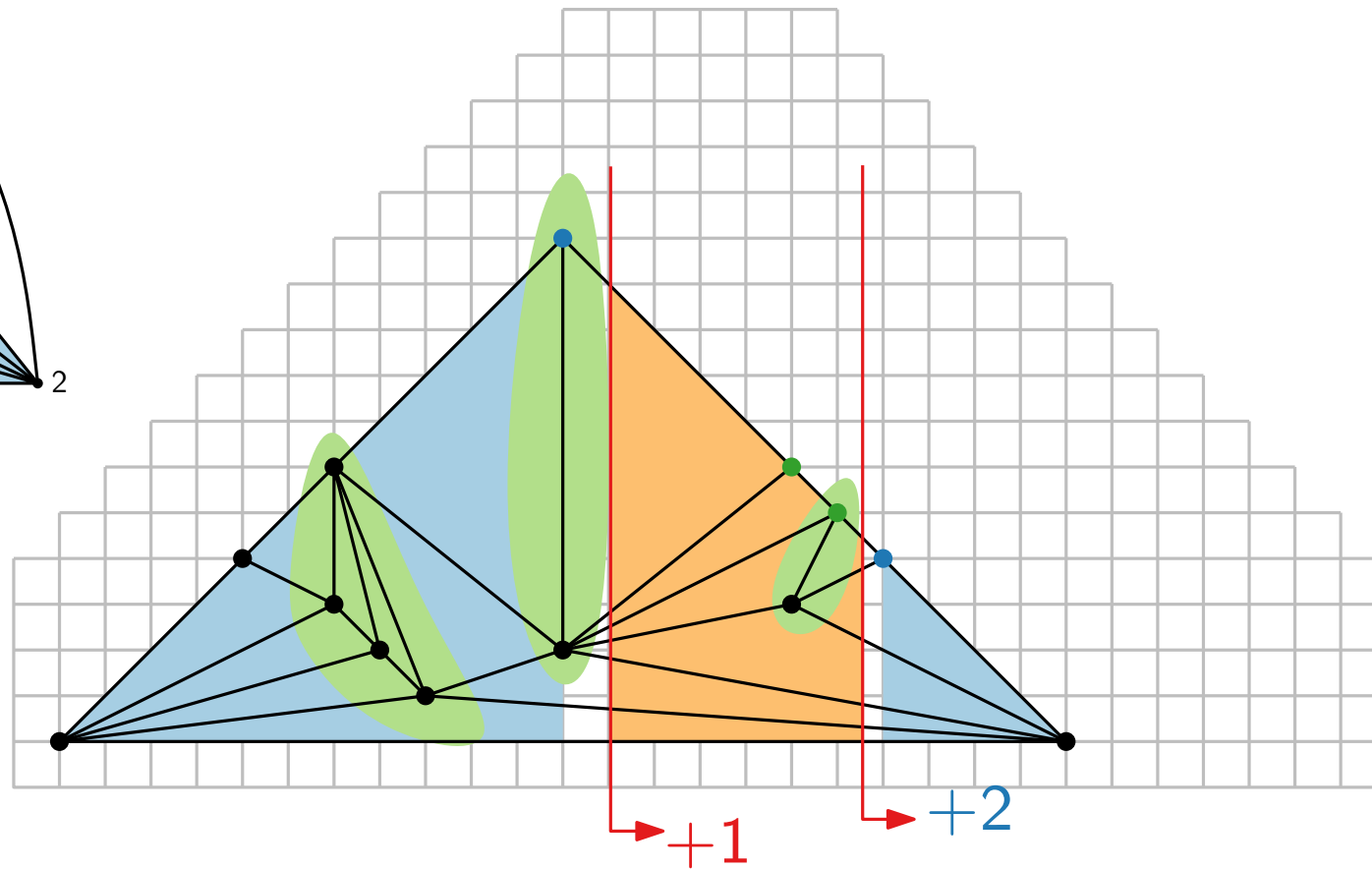
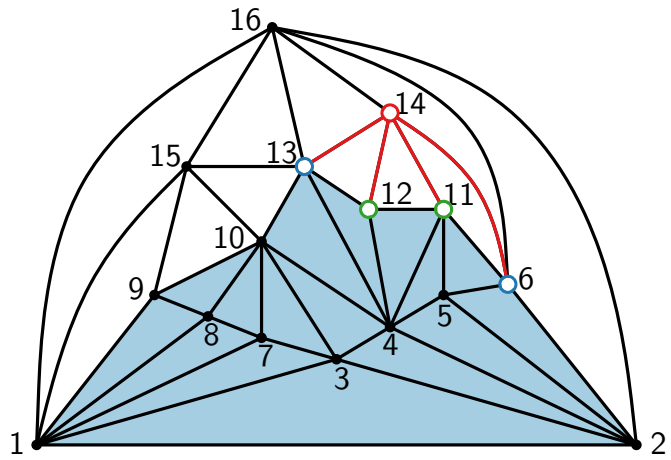
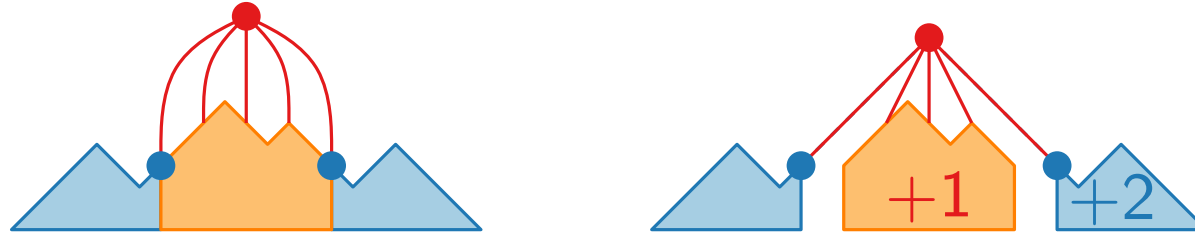
Shift method – example



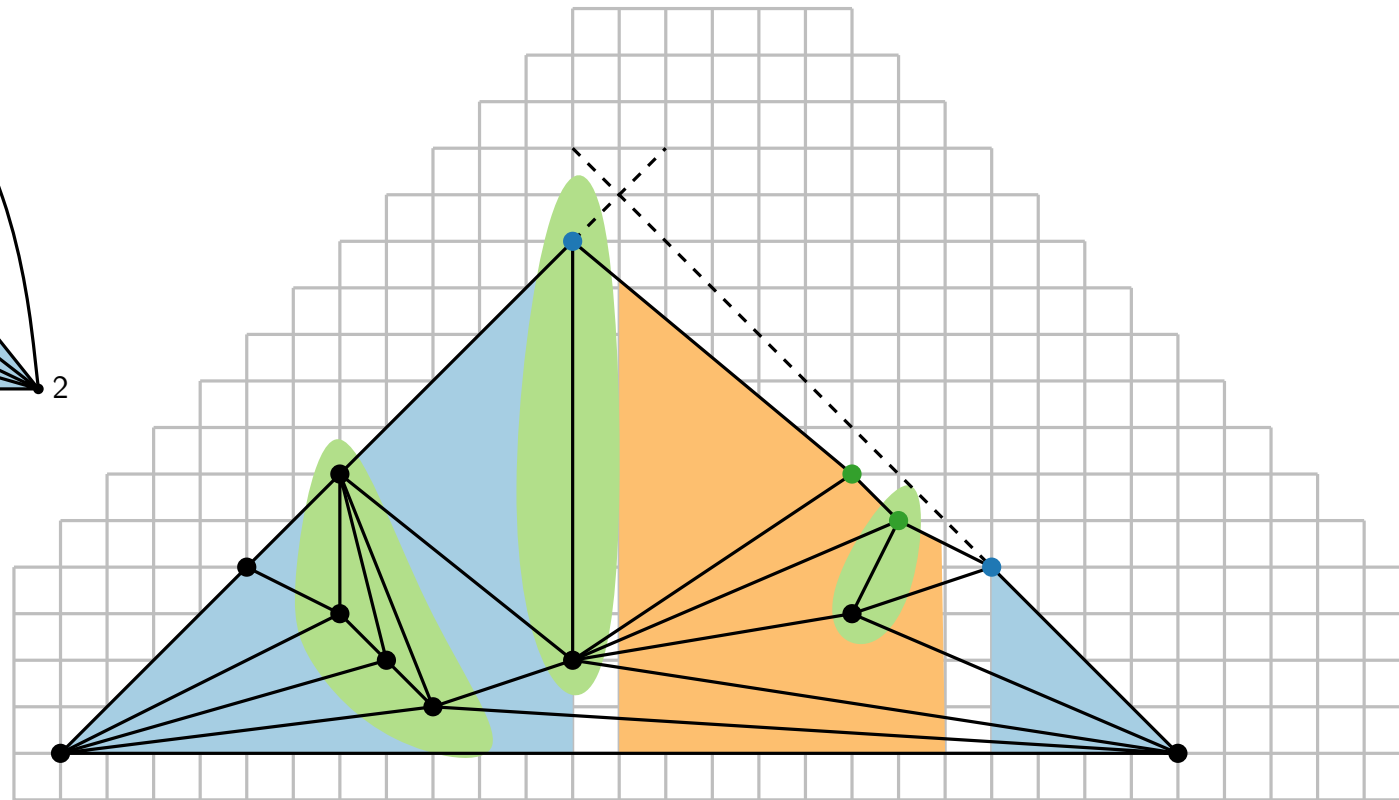
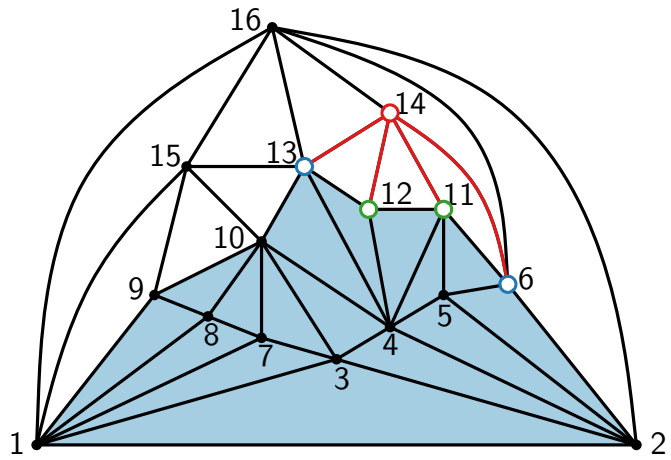
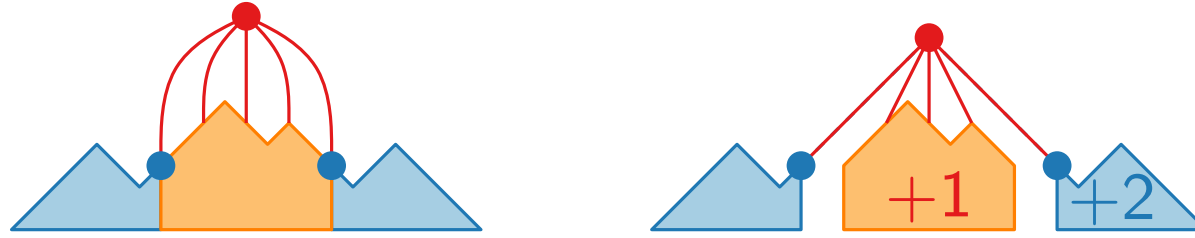
Shift method – example



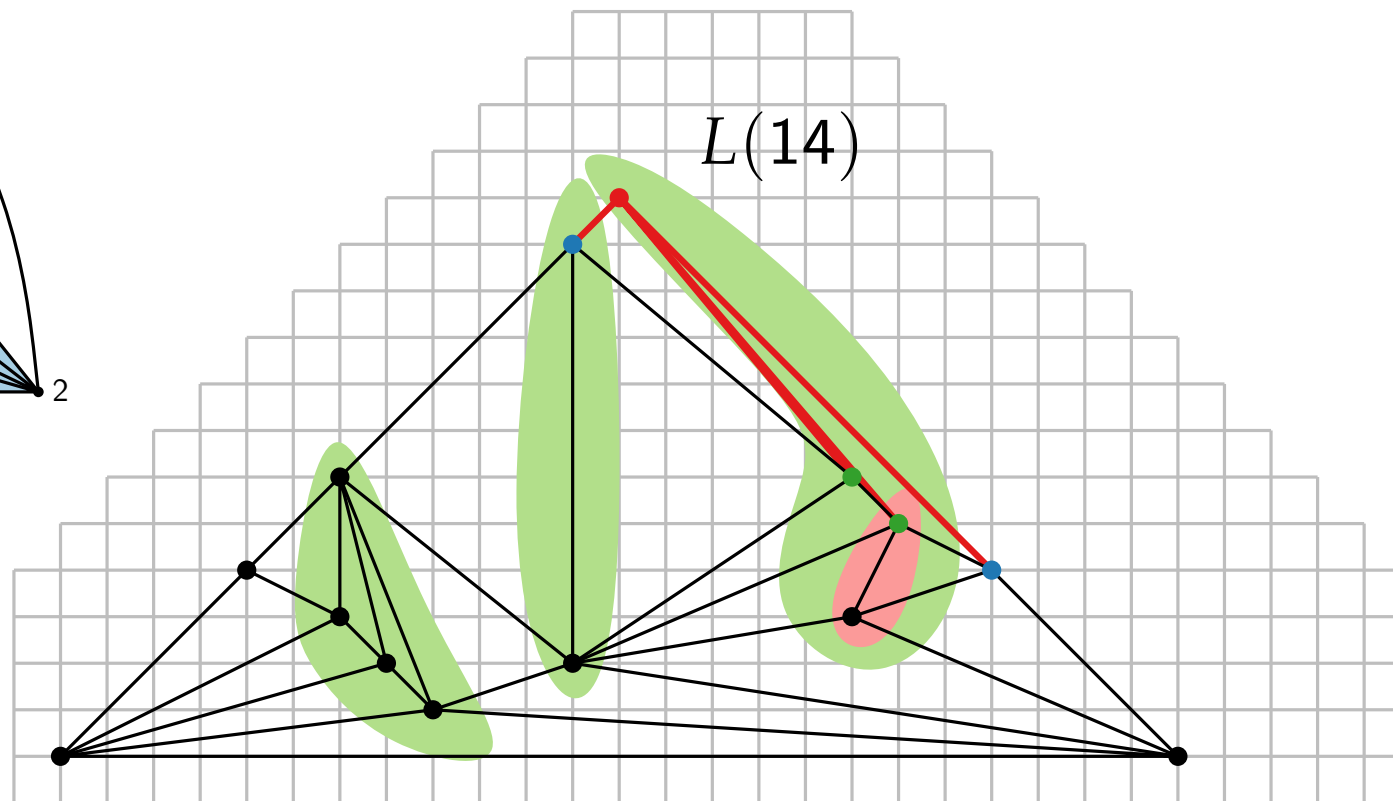
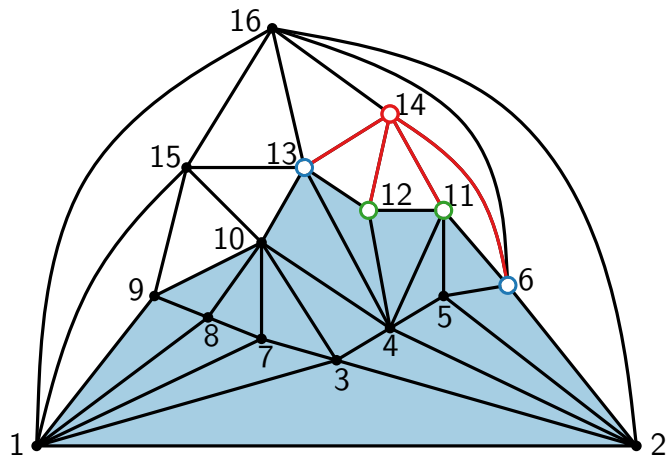
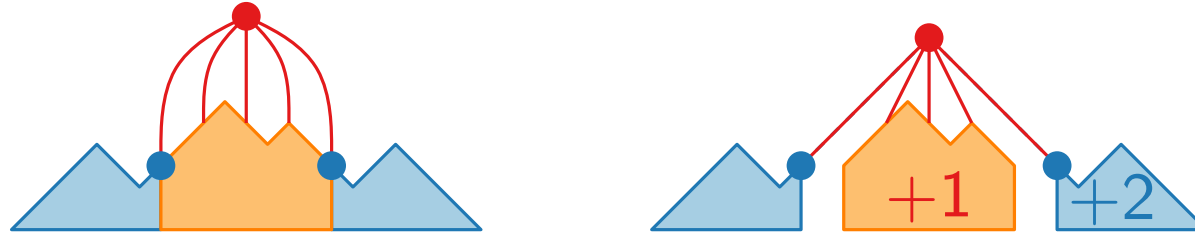
Shift method – example



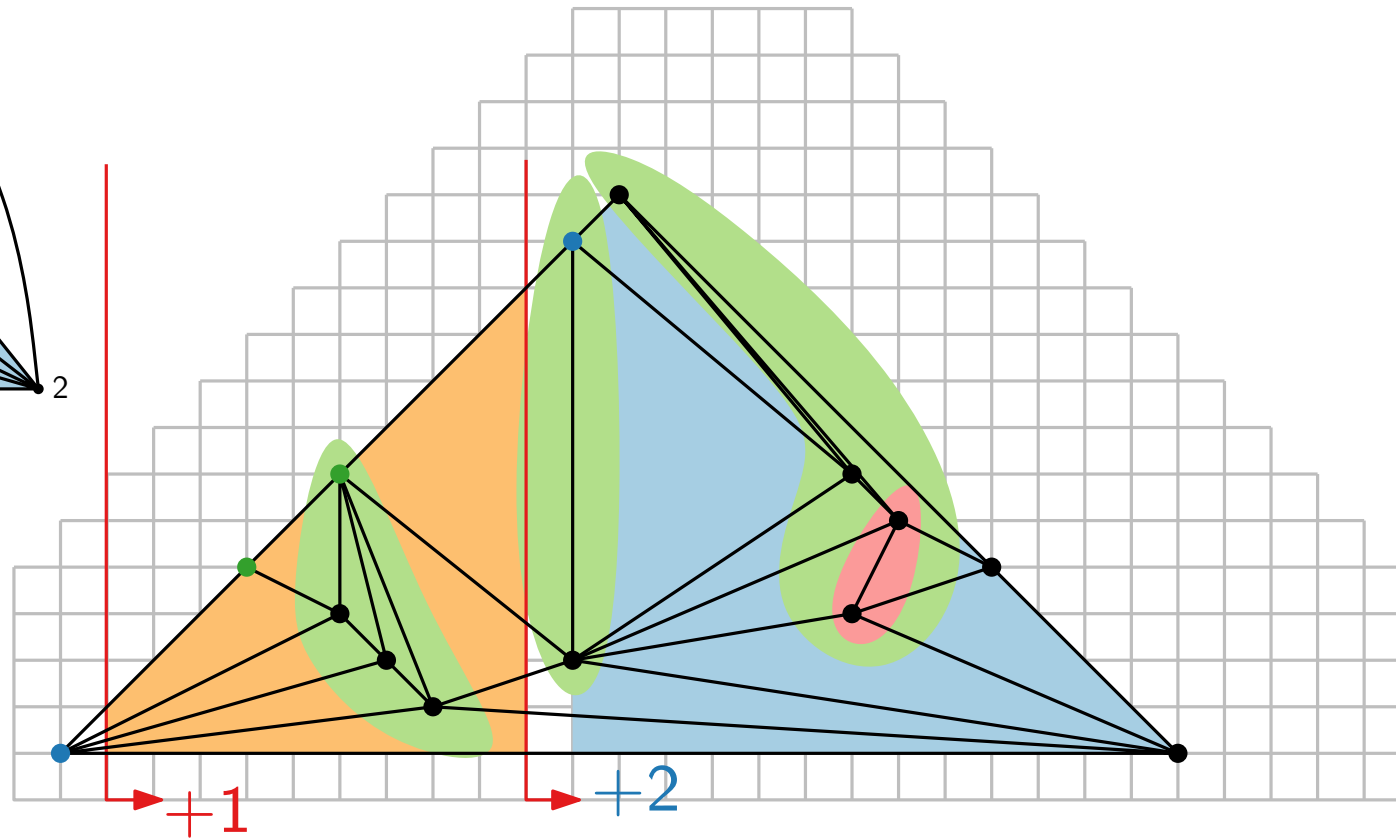
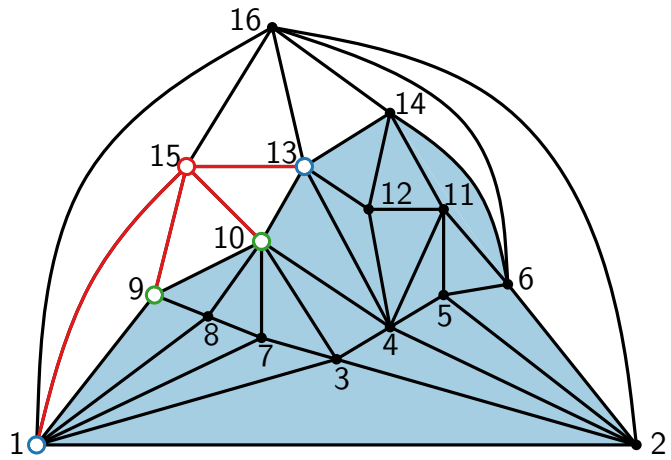
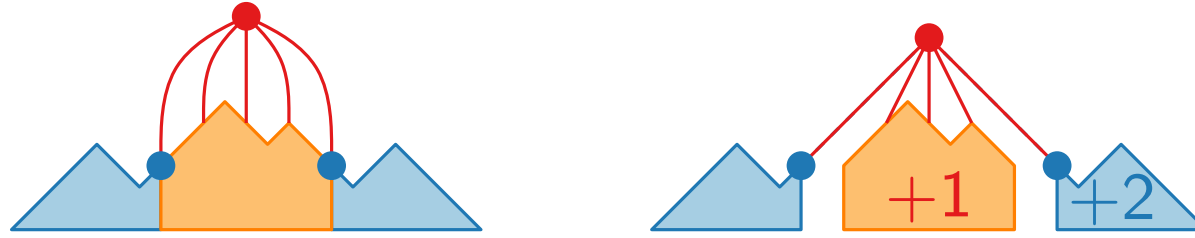
Shift method – example



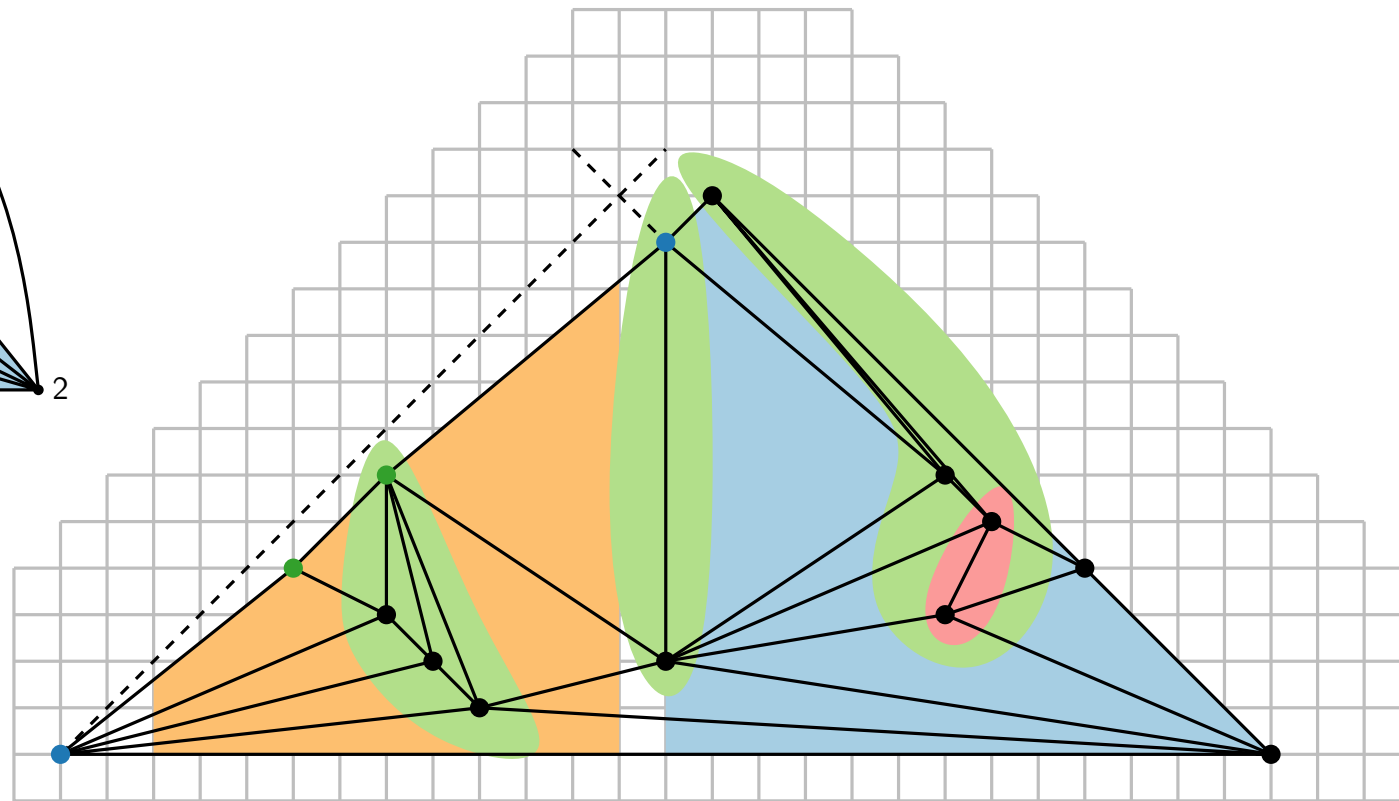
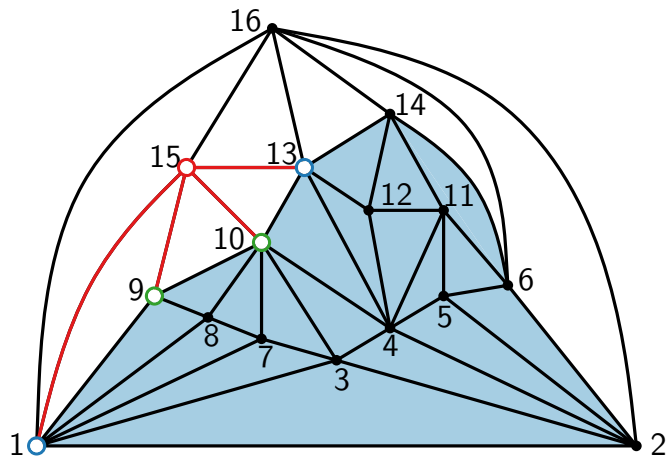
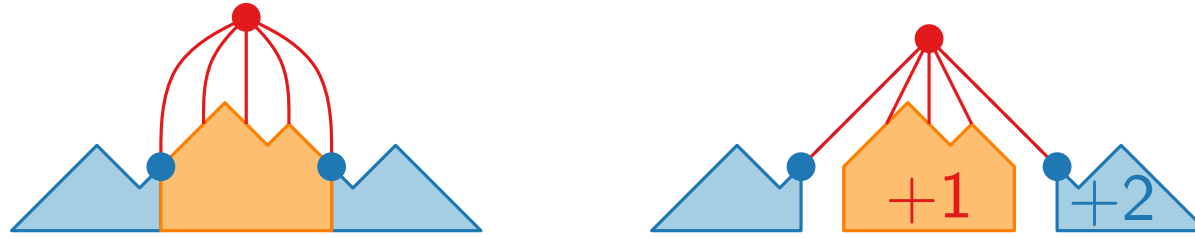
Shift method – example



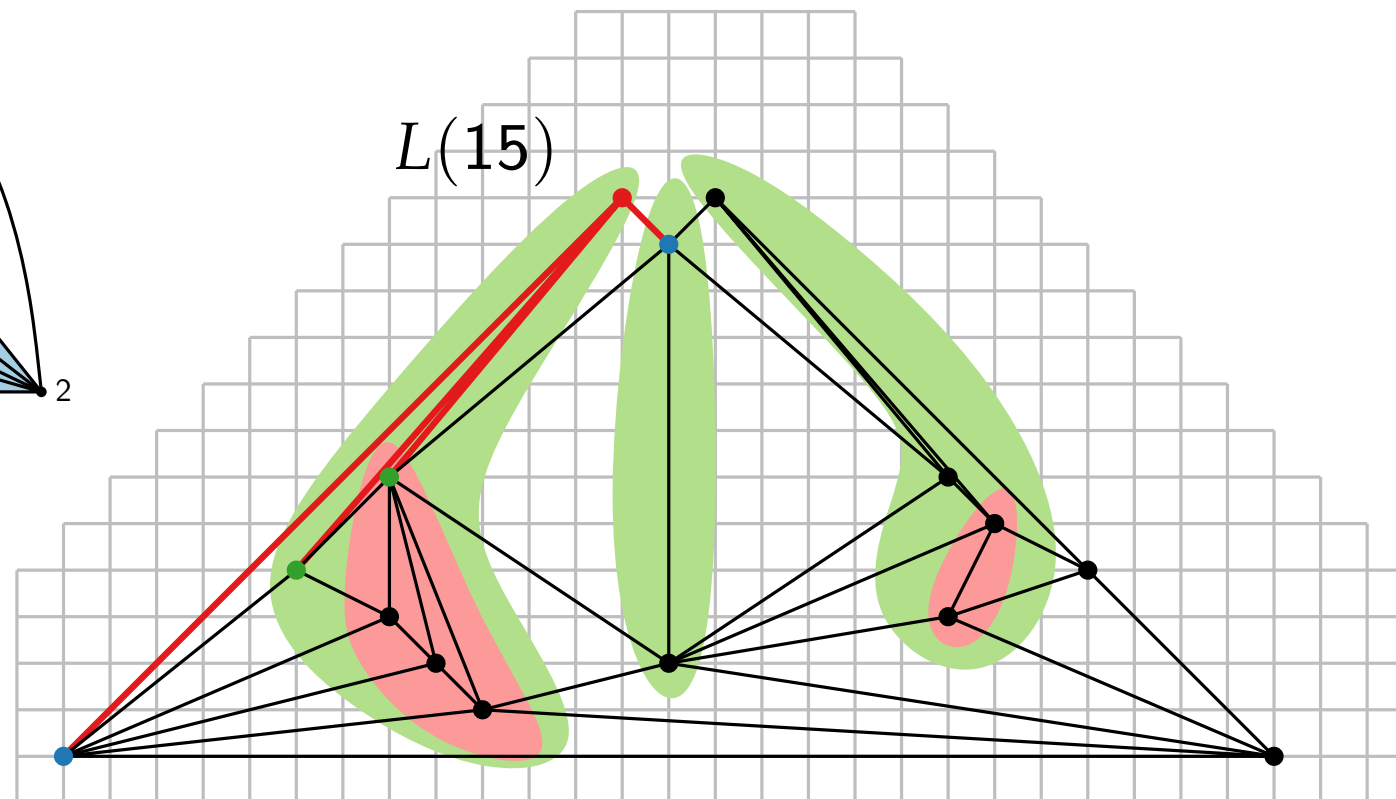
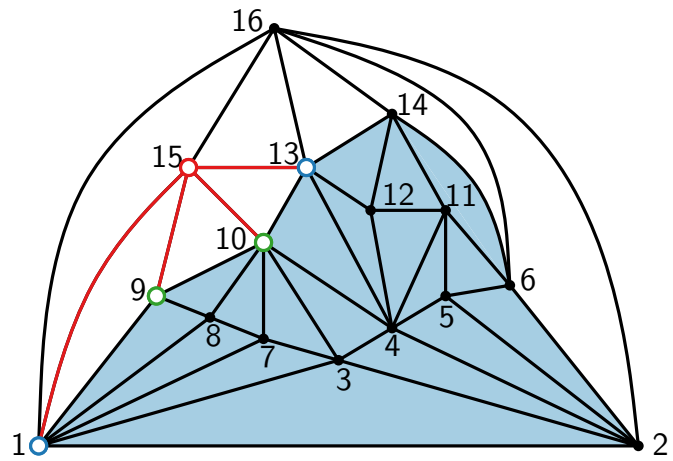
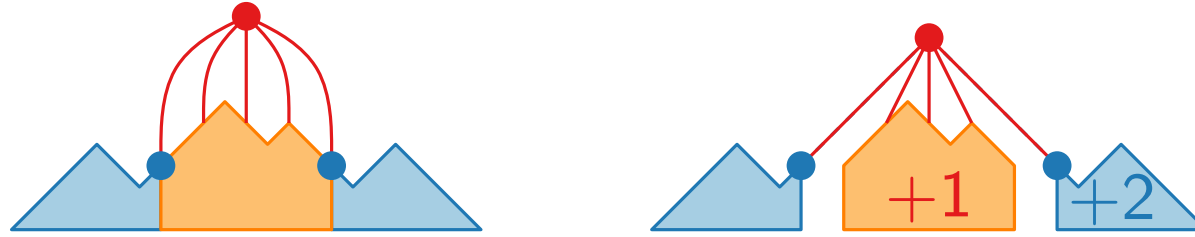
Shift method – example



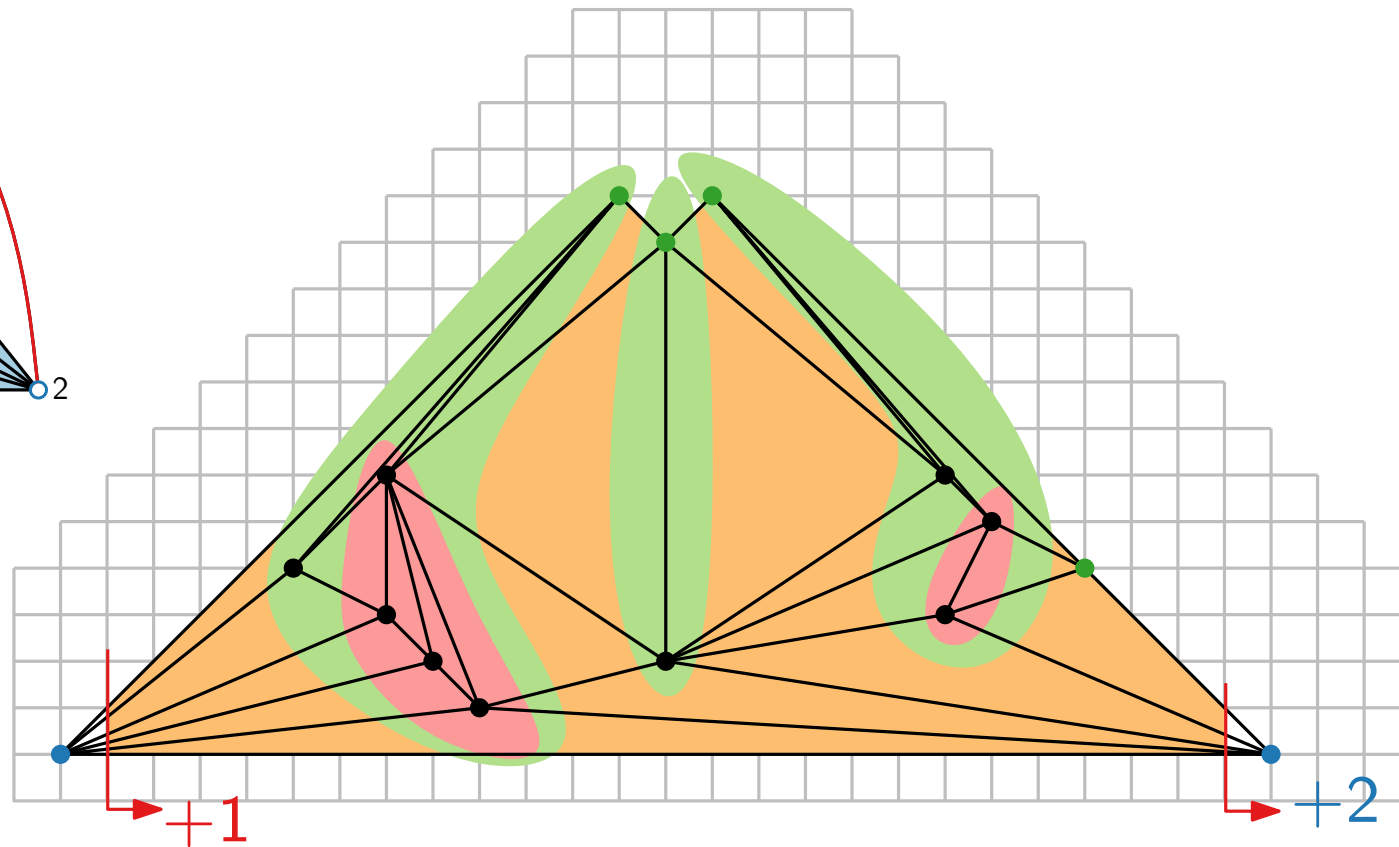
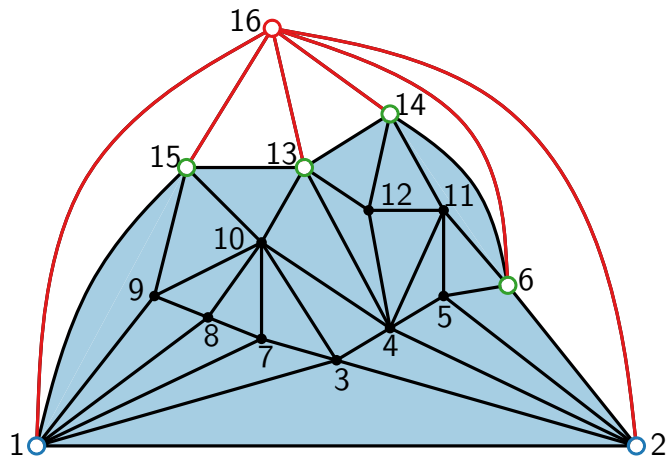
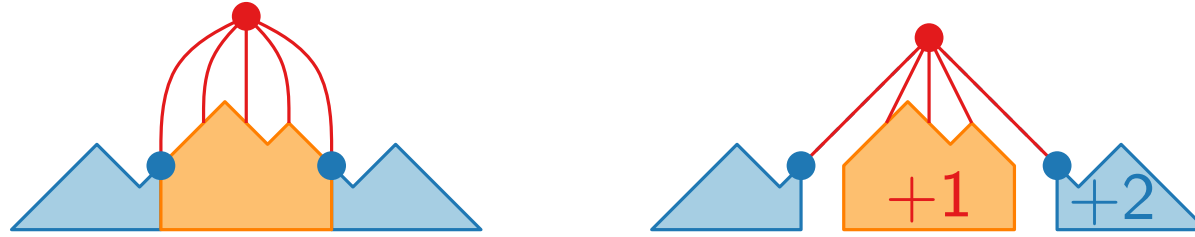
Shift method – example



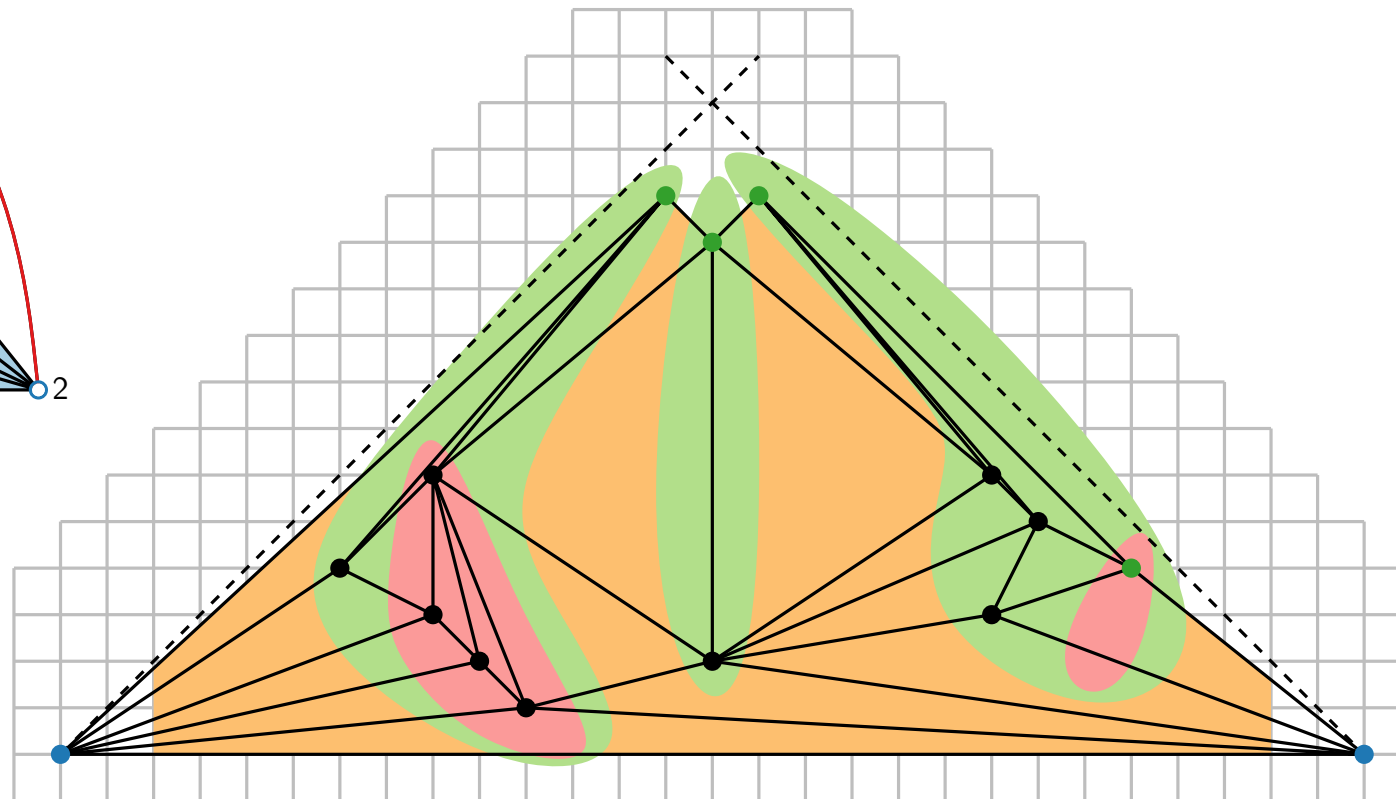
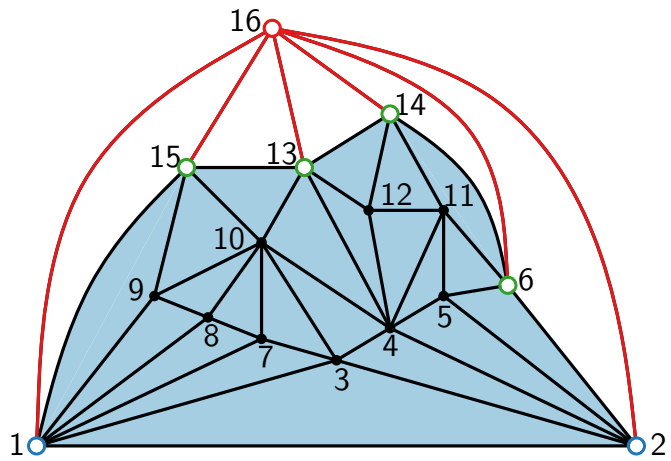
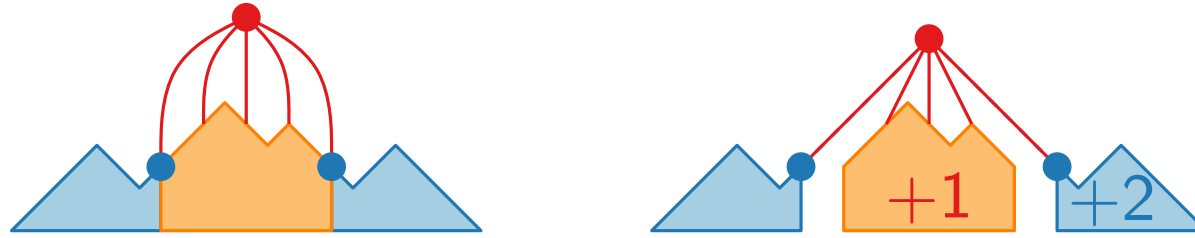
Shift method – example



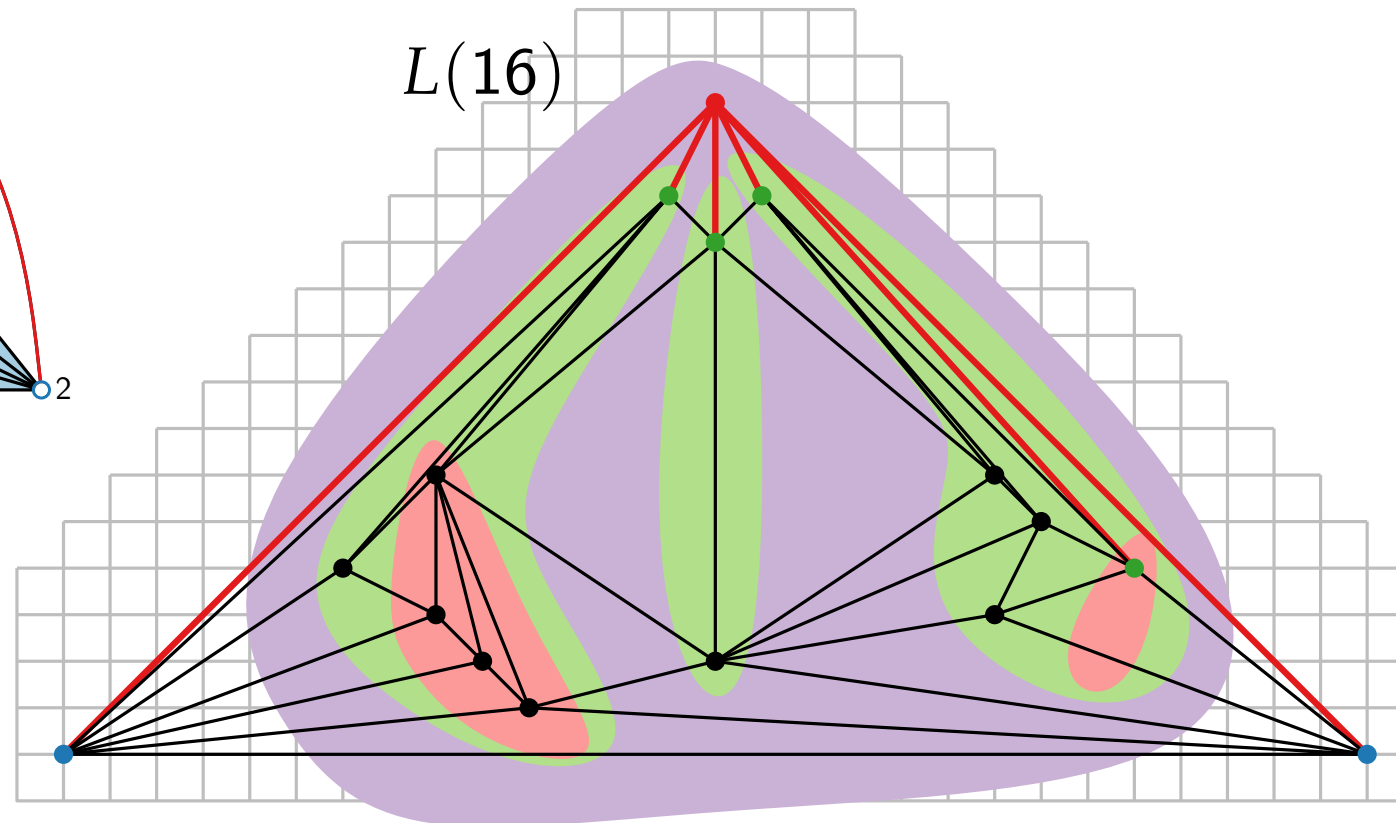
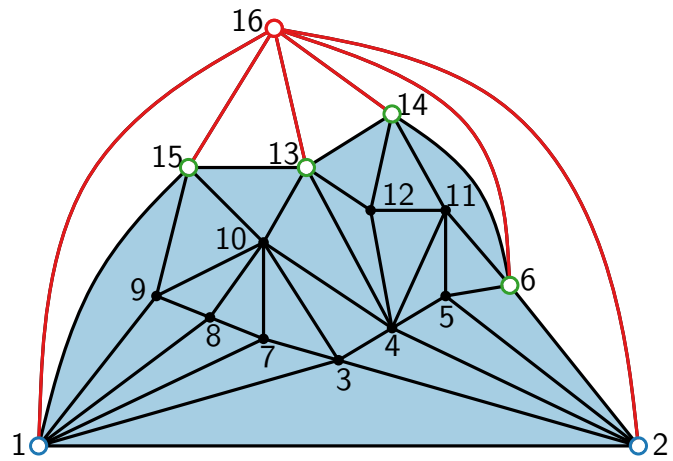
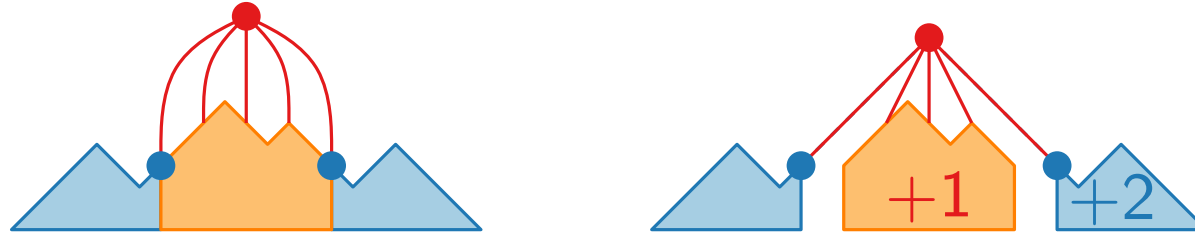
Shift method – example



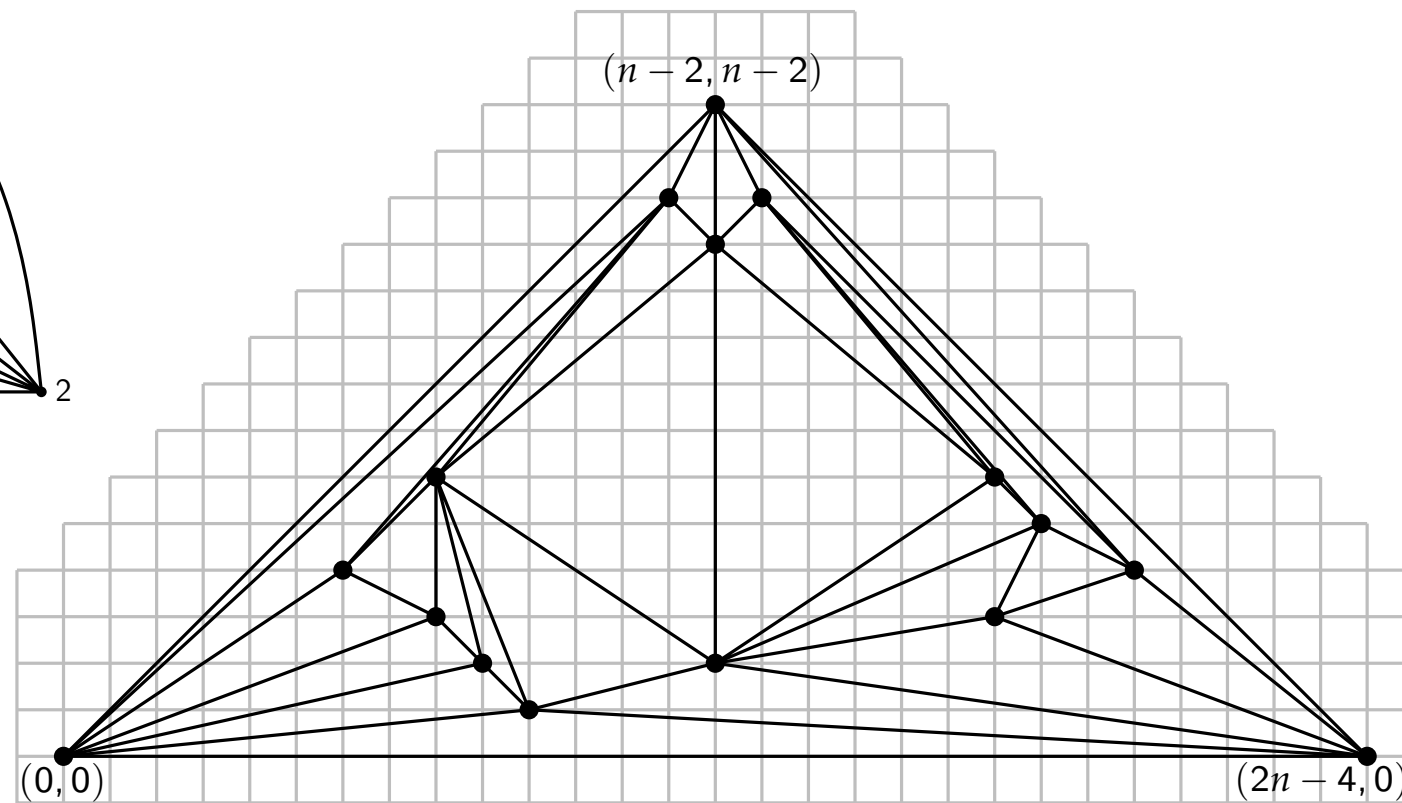
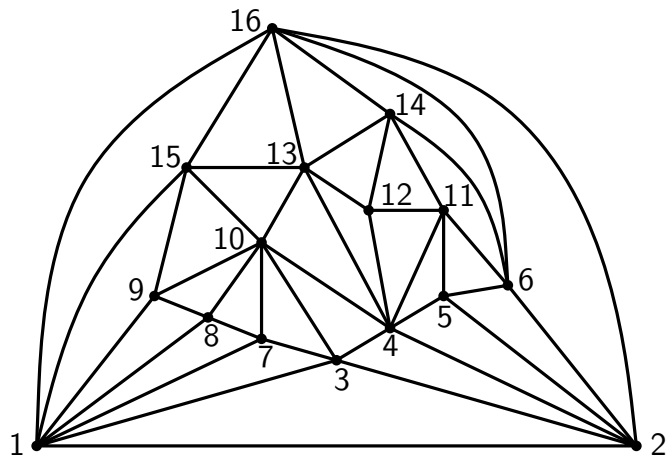
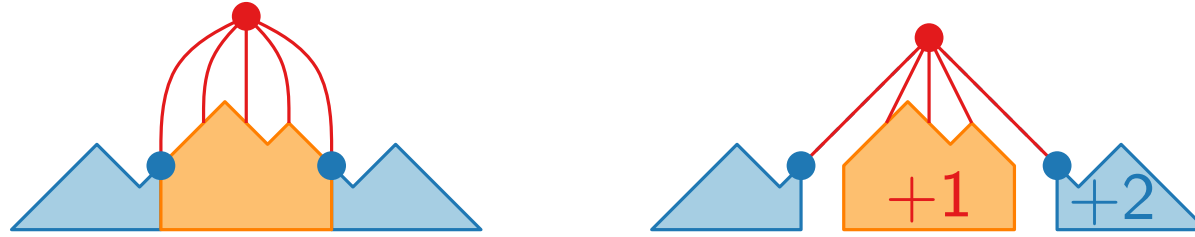
Shift method – example



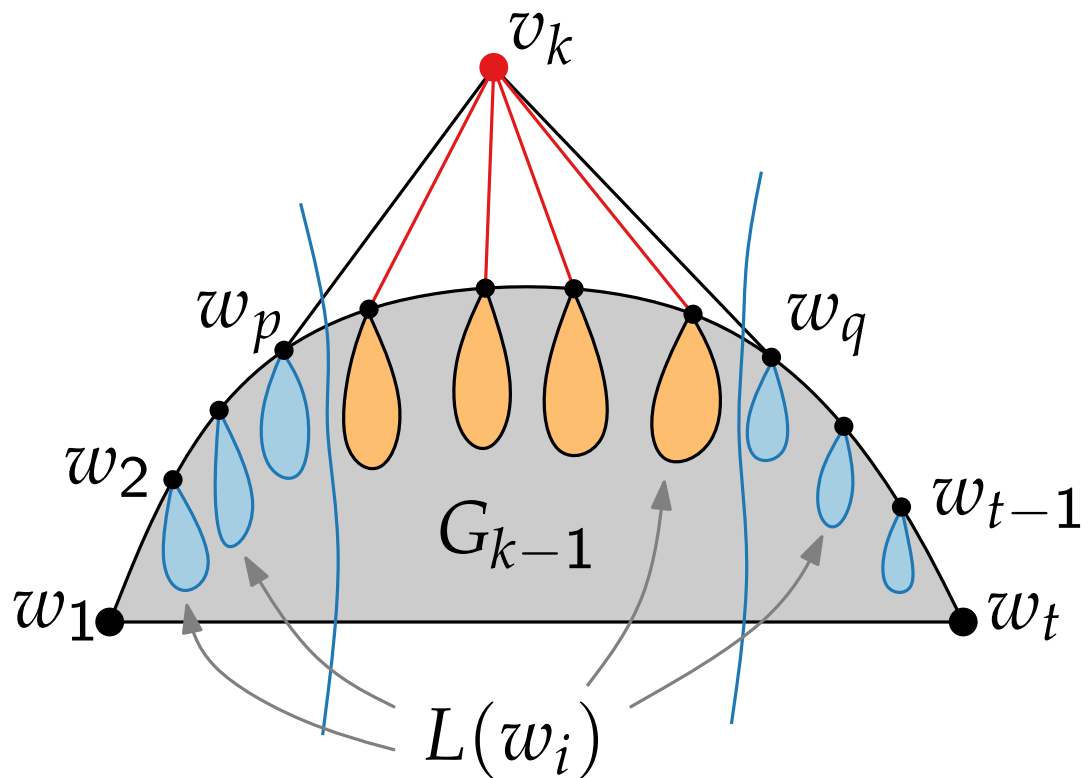
Shift method – example



Shift method – example



Shift method – planarity

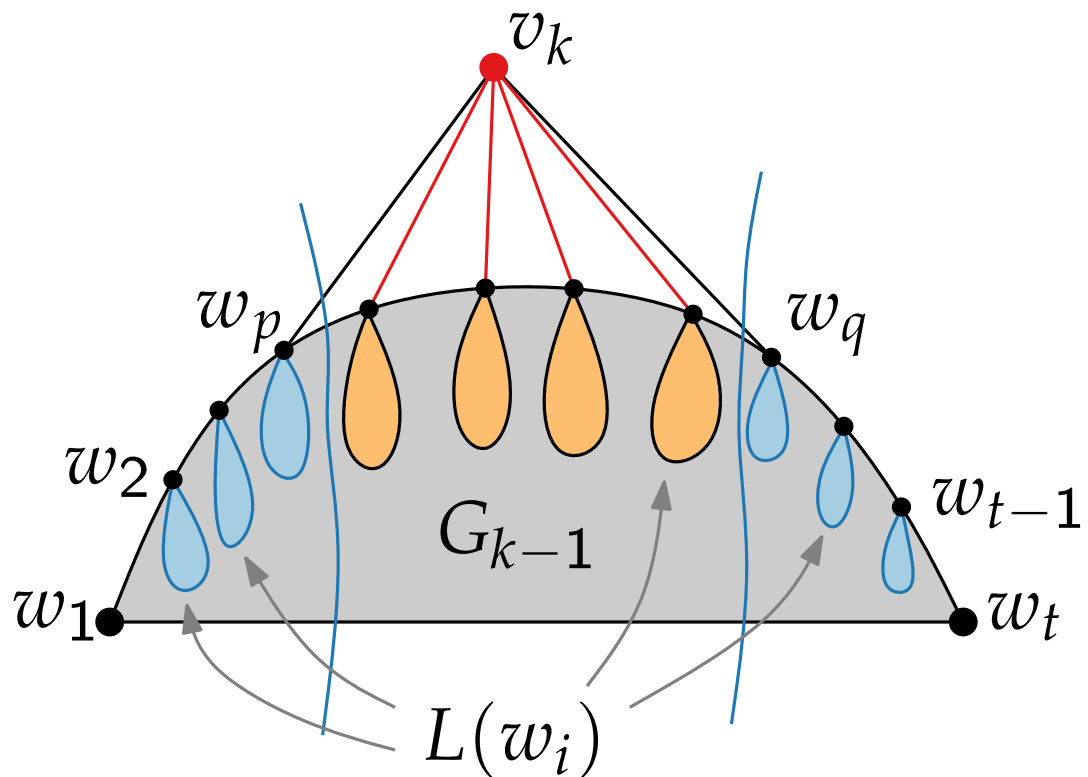


Observations.

- Each internal vertex is covered exactly once.
- Covering relation defines a tree in G
- and a forest in $G_i, 1 \leq i \leq n - 1$.

Shift method – planarity

Lemma. Let $0 < \delta_1 \leq \delta_2 \leq \dots \leq \delta_t \in \mathbb{N}$, such that $\delta_q - \delta_p \geq 2$ and even. If we shift $L(w_i)$ by δ_i to the right, we get a planar straight-line drawing.



Observations.

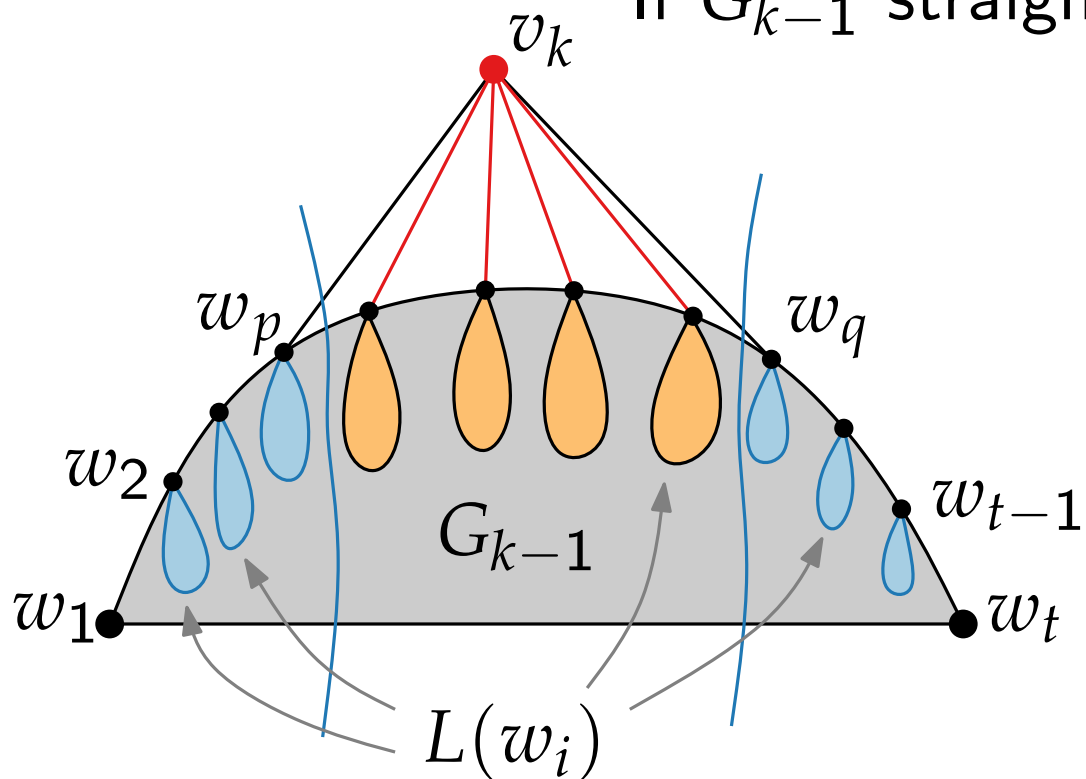
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Proof by induction:

If G_{k-1} straight-line planar, then also G_k .



Observations.

- Each internal vertex is covered exactly once.
- Covering relation defines a tree in G
- and a forest in $G_i, 1 \leq i \leq n - 1$.

Shift method – pseudocode

Let v_1, \dots, v_n be a canonical order of G

for $i = 1$ to 3 **do**

$L(v_i) \leftarrow \{v_i\}$

$P(v_1) \leftarrow (0, 0); P(v_2) \leftarrow (2, 0), P(v_3) \leftarrow (1, 1)$

for $k = 4$ to n **do**

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for $k = 4$ to n **do**

└ Let $w_1 = v_1, w_2, \dots, w_{t-1}, w_t = v_2$ denote the boundary of G_{k-1}
and let w_p, \dots, w_q be the neighbours of v_k

└ **for** $\forall v \in \cup_{j=p+1}^{q-1} L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 1$

└ **for** $\forall v \in \cup_{j=q}^t L(w_j)$ **do**

└ $x(v) \leftarrow x(v) + 2$

└ $P(v_k) \leftarrow$ intersection of $+1/-1$ edges from $P(w_p)$ and $P(w_q)$

└ $L(v_k) \leftarrow \cup_{j=p+1}^{q-k} L(w_j) \cup \{v_k\}$

Shift method – pseudocode

Let v_1, \dots, v_n be a canonical order of G

for $i = 1$ to 3 **do**

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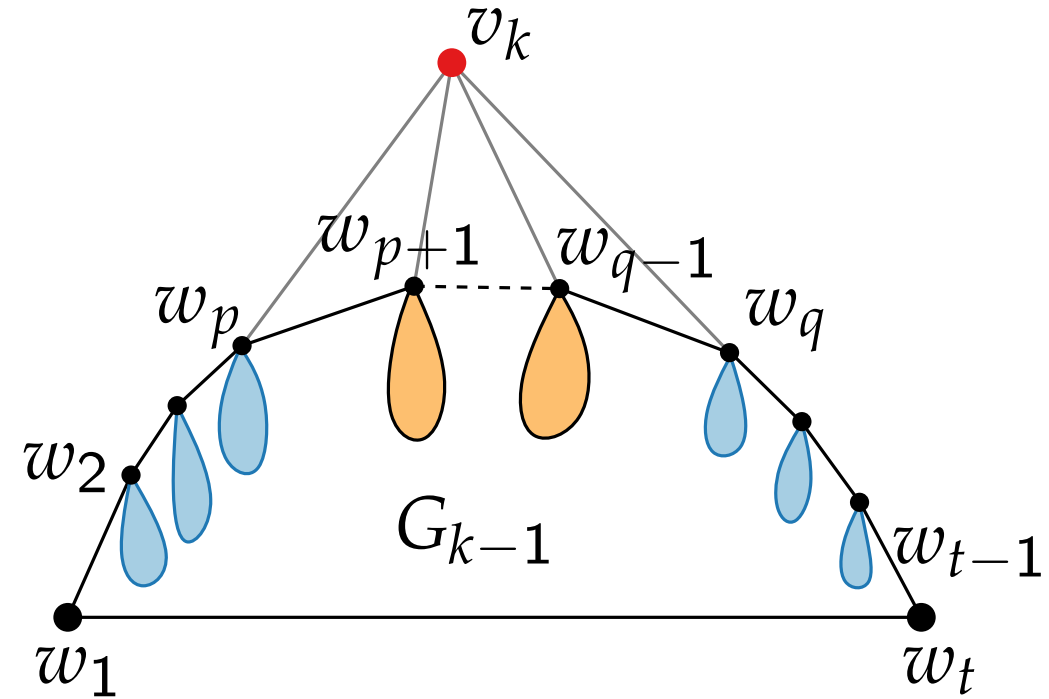
$L(v_k) \leftarrow \cup_{j=p+1}^{q-k} L(w_j) \cup \{v_k\}$

- Runtime $\mathcal{O}(n^2)$
- Can we do better?

Shift method – linear time implementation

Idea:

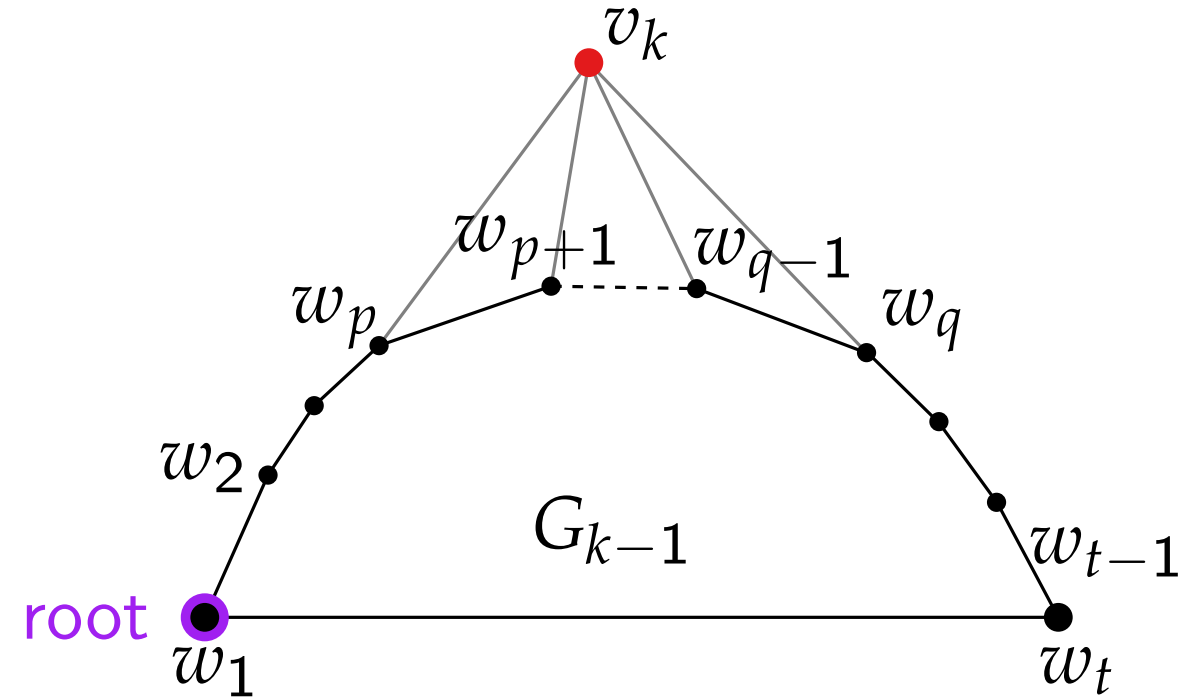
- Instead of storing explicit x -coordinates, we store x differences.
- We need a **spanning tree** rooted at v_1



Shift method – linear time implementation

Idea:

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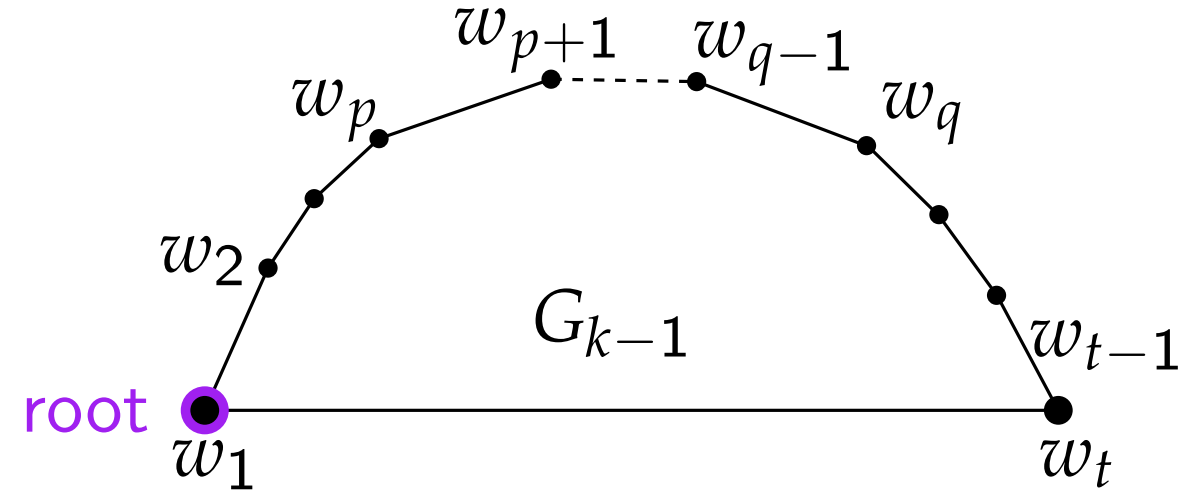
Shift method – linear time implementation

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Outface of G_{k-1}

- at w_i store $\Delta x(w_i) = x(w_i) - x(w_{i-1})$



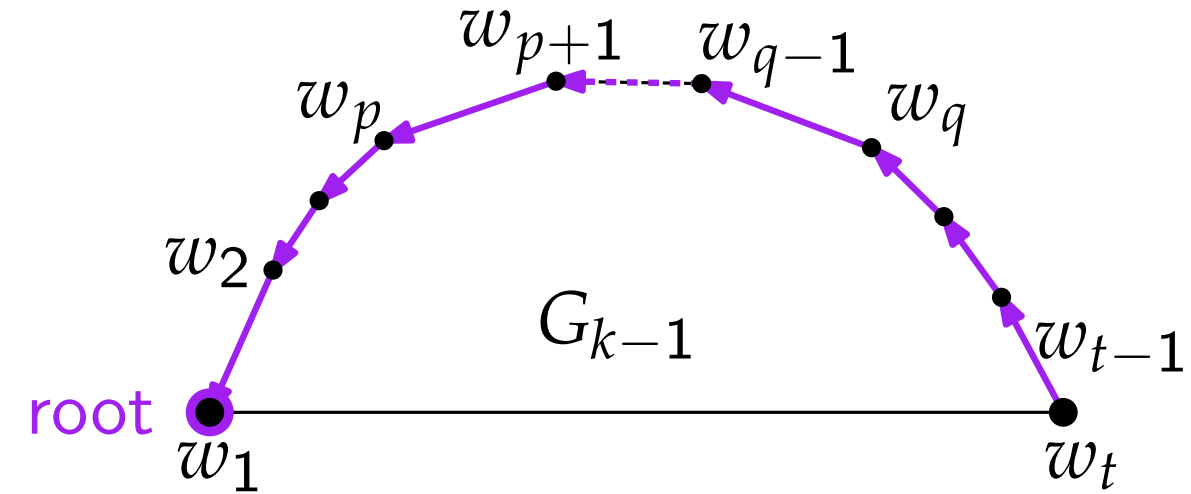
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Shift method – linear time implementation

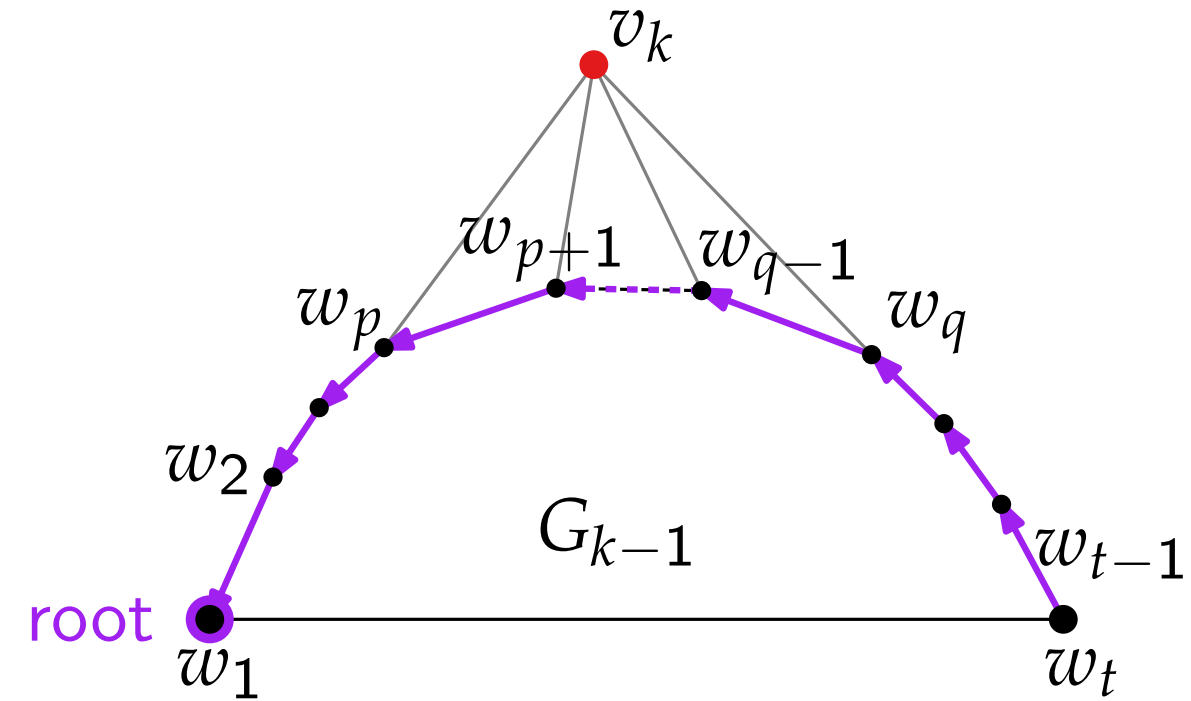
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Adding v_k



Shift method – linear time implementation

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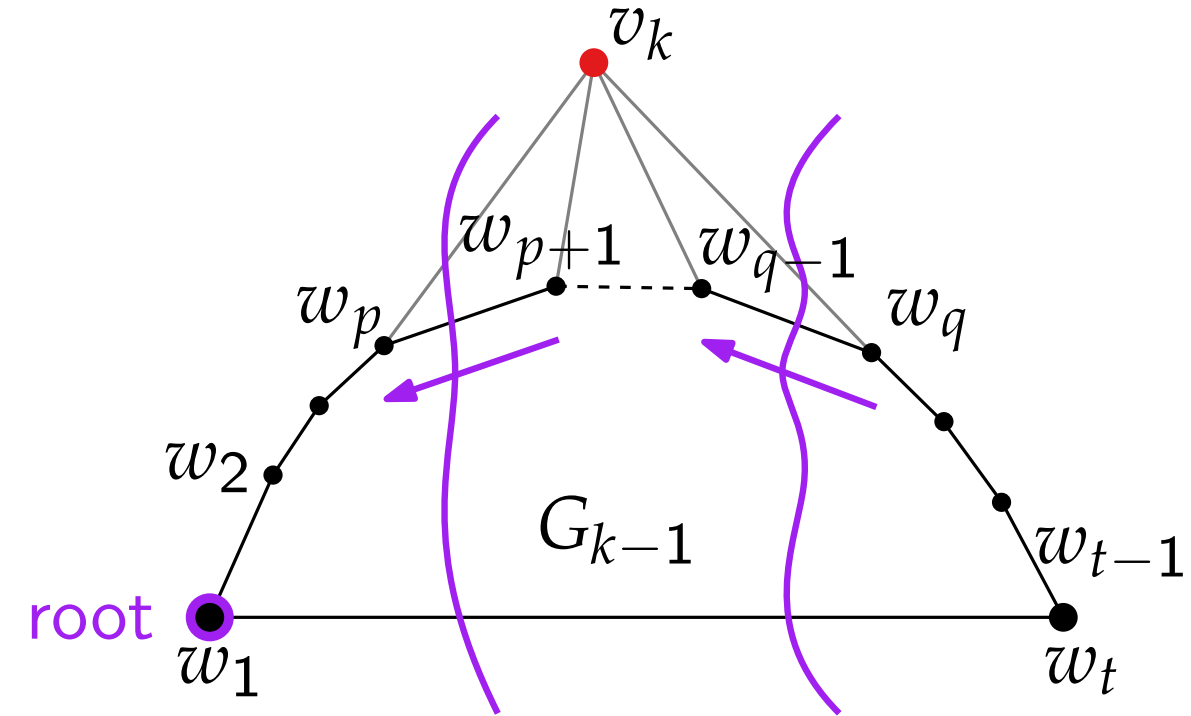
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Adding v_k

- Shifting is performed by increasing $\Delta x(w_{p+1})$ and $\Delta x(w_q)$



Shift method – linear time implementation

Idea:

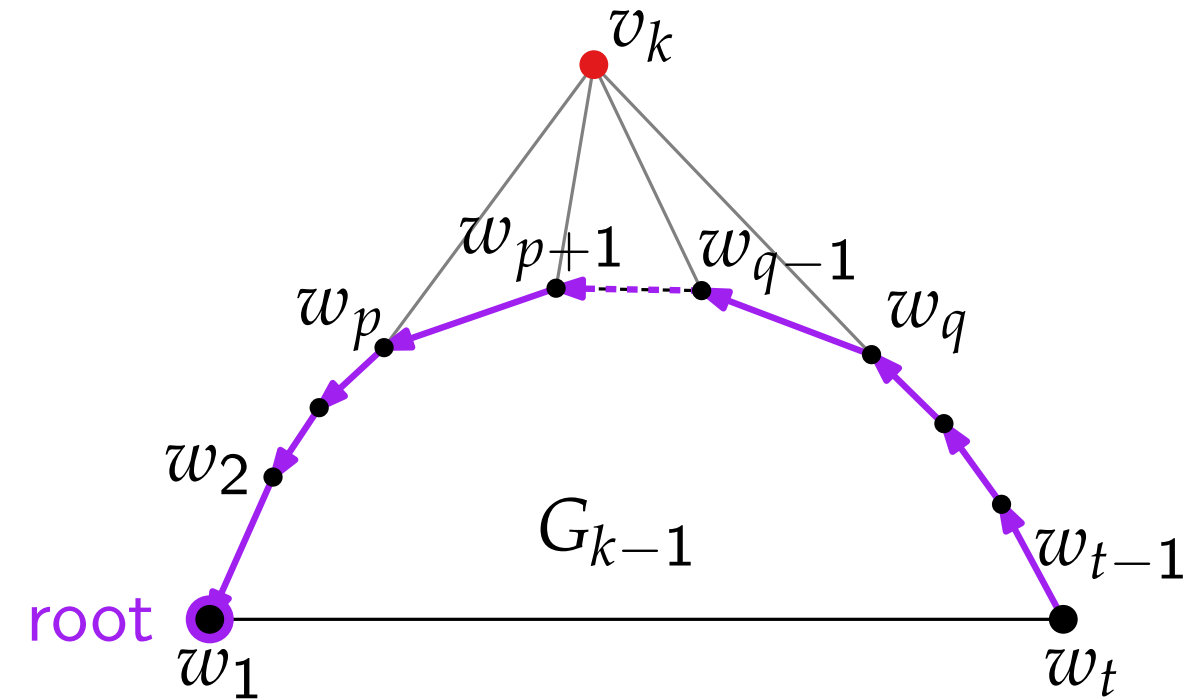
- Instead of storing explicit x -coordinates, we store x differences.
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Outerface of G_{k-1}

- at w_i store $\Delta x(w_i) = x(w_i) - x(w_{i-1})$

Adding v_k

- Shifting is performed by increasing $\Delta x(w_{p+1})$ and $\Delta x(w_q)$
- $x(v_k)$ depends on $x(w_p)$ and $x(w_q)$



Shift method – linear time implementation

Idea:

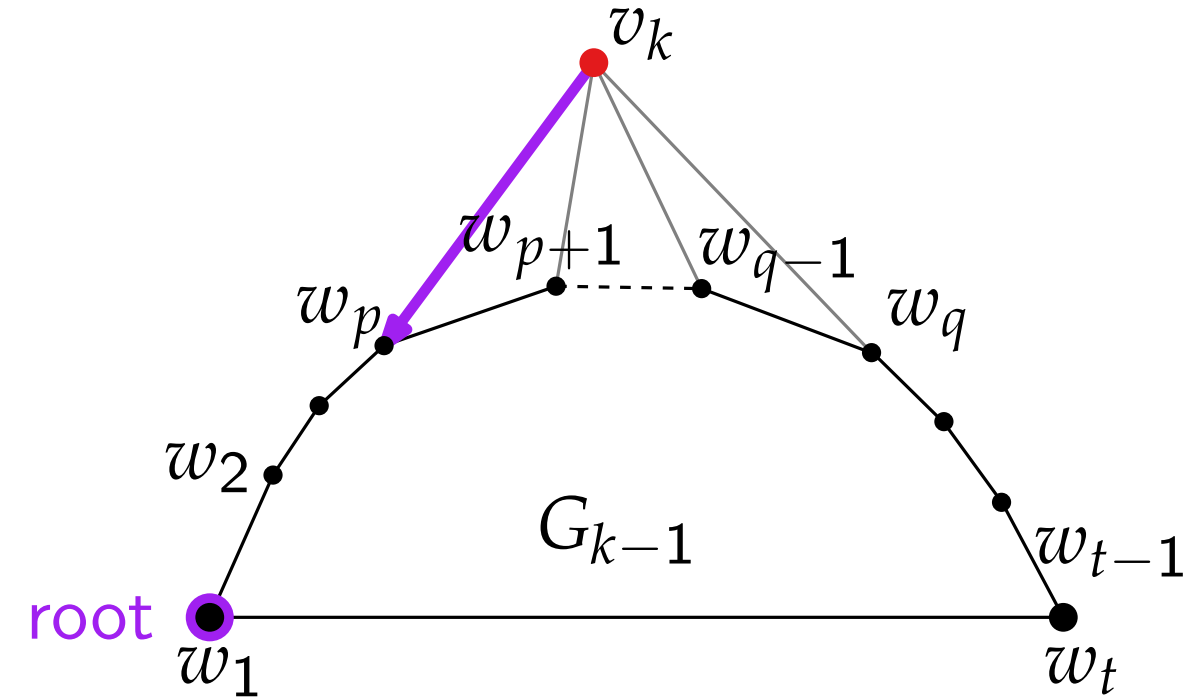
- Instead of storing explicit x -coordinates, we store x differences.
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Outerface of G_{k-1}

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Adding v_k

- Shifting is performed by increasing $\Delta x(w_{p+1})$ and $\Delta x(w_q)$
- $x(v_k)$ depends on $x(w_p)$ and $x(w_q)$
- $x(v_k)$ as x difference from w_p



Shift method – linear time implementation

Idea:

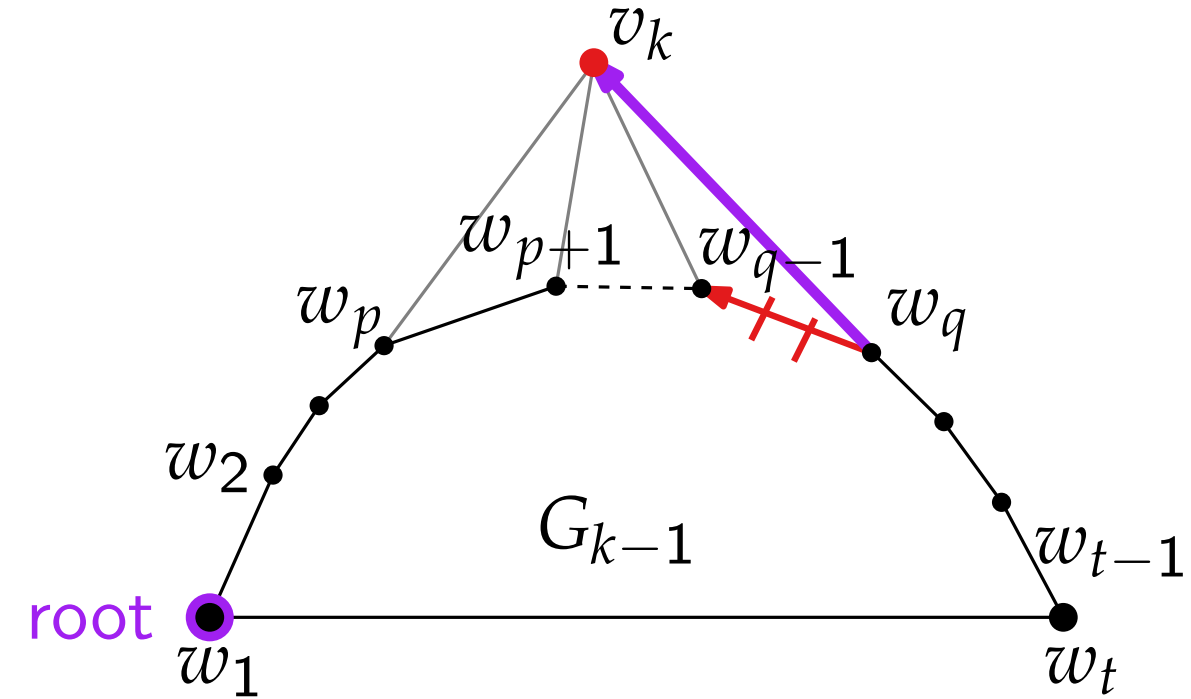
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- $x(w_q)$ as x difference from v_k



Shift method – linear time implementation

Idea:

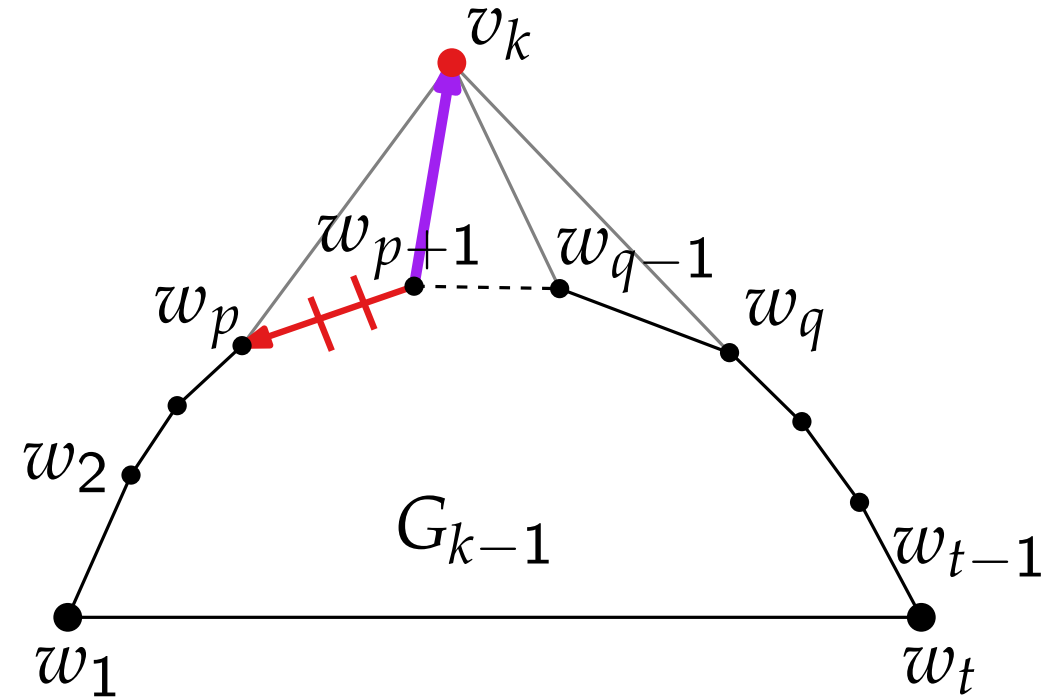
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Outerface of G_{k-1}

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Adding v_k

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- $x(v_k)$ as x difference from w_p
- $x(w_q)$ as x difference from v_k
- w_{p+1} covered by v_k
 $\rightarrow x(w_{p+1})$ as x difference from $x(v_k)$



Shift method – linear time implementation

Idea:

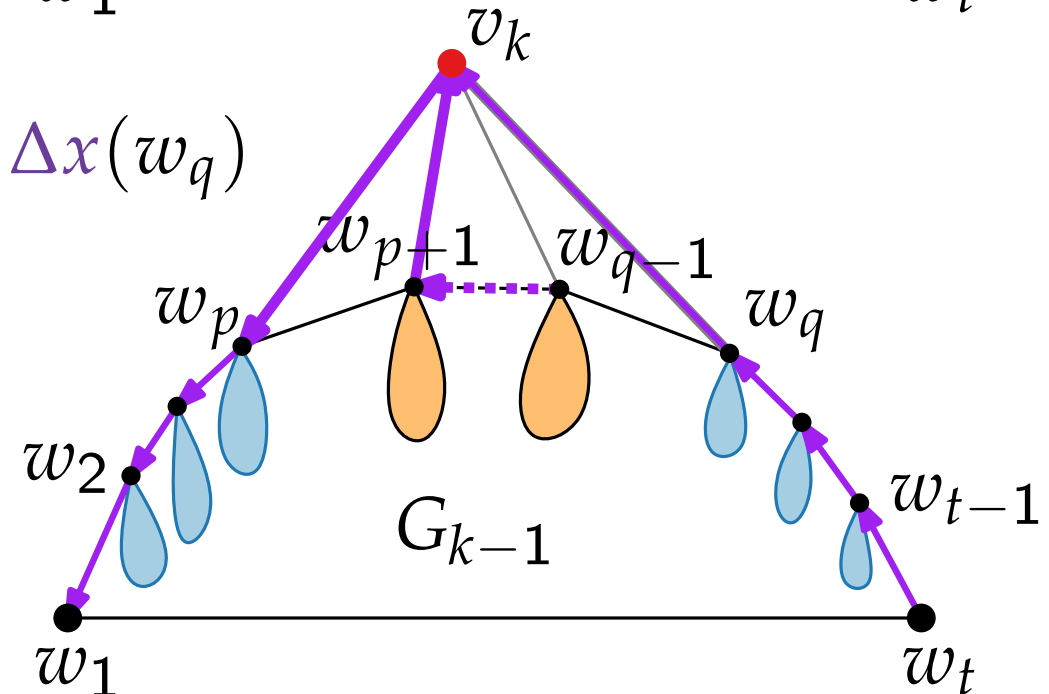
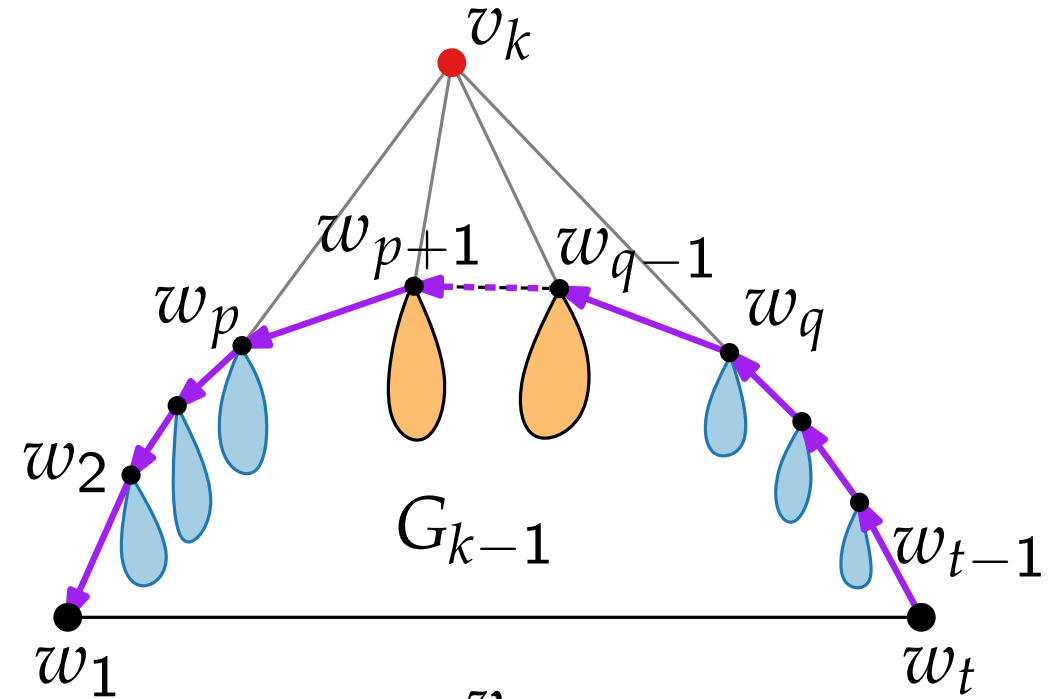
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Outerface of G_{k-1}

- at w_i store $\Delta x(w_i) = x(w_i) - x(w_{i-1})$

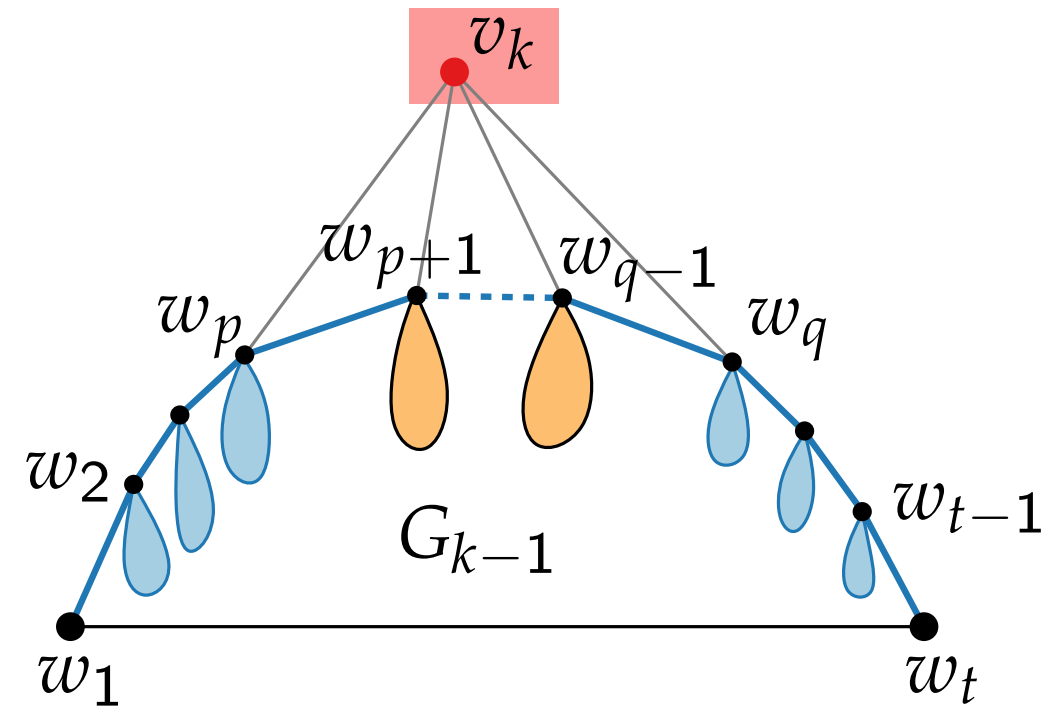
Adding v_k

- Shifting is performed by increasing $\Delta x(w_{p+1})$ and $\Delta x(w_q)$
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- $x(w_q)$ as x difference from v_k
- w_{p+1} covered by v_k
 $\rightarrow x(w_{p+1})$ as x difference from $x(v_k)$



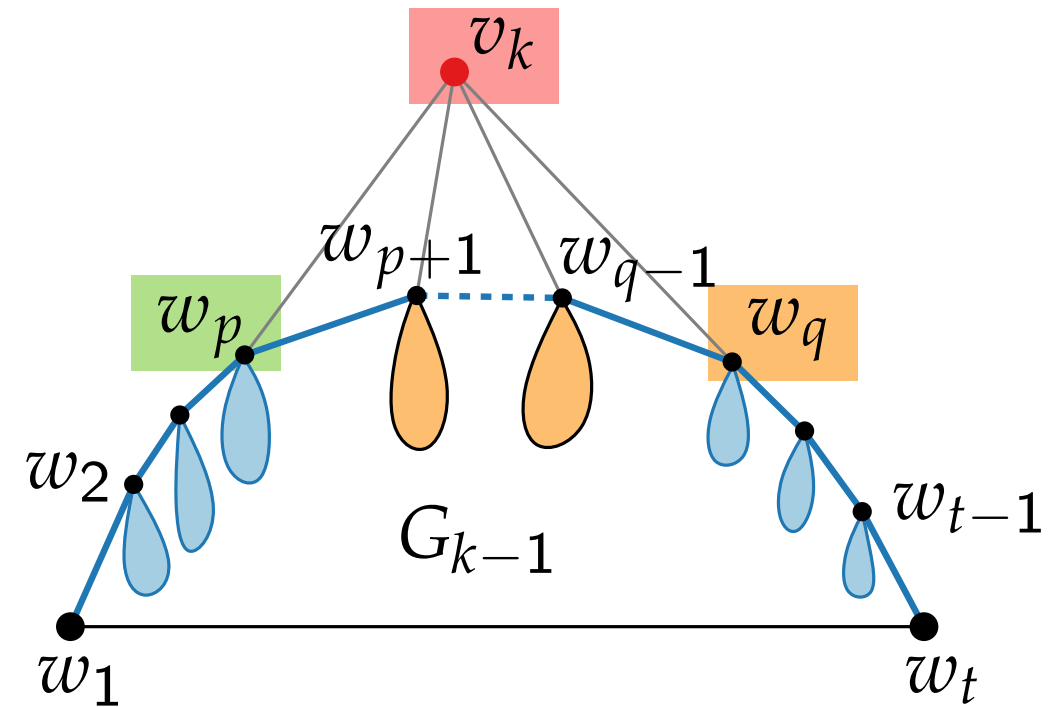
Shift method – linear time implementation

- **Step 1.** compute $x(v_k)$ and $y(v_k)$



Shift method – linear time implementation

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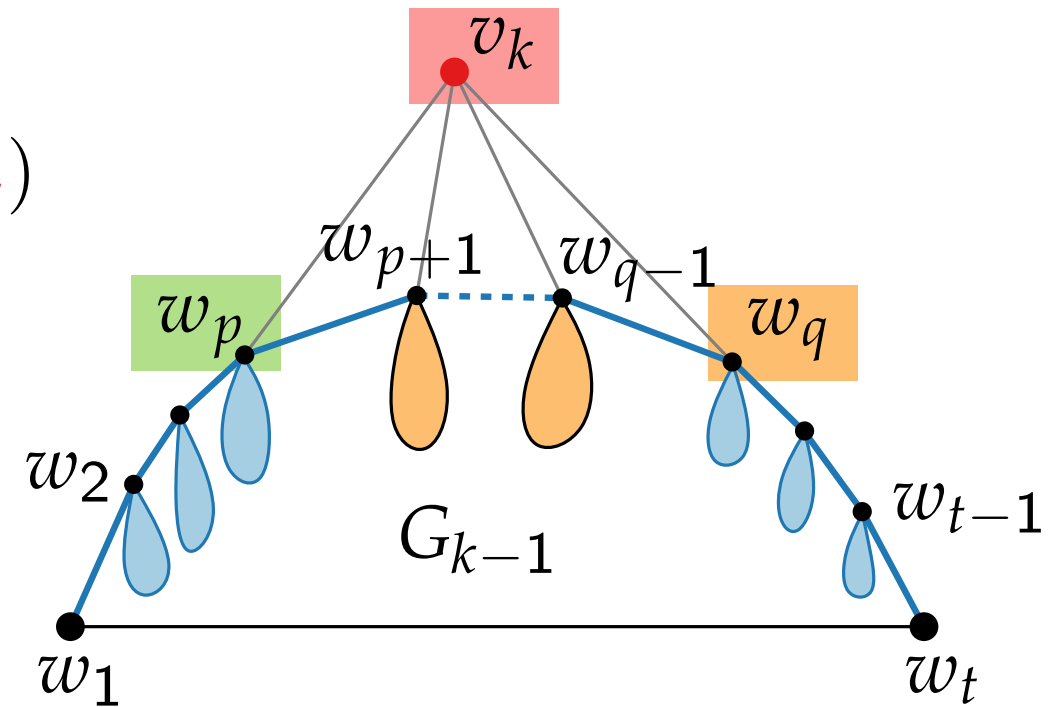


$$(1) \quad x(v_k) = \frac{1}{2} (x(w_q) + x(w_p) + y(w_q) - y(w_p))$$

$$(2) \quad y(v_k) = \frac{1}{2} (x(w_q) - x(w_p) + y(w_q) + y(w_p))$$

Shift method – linear time implementation

- **Step 1.** compute $x(v_k)$ and $y(v_k)$
- **Step 1 revised.** compute $x(v_k) - x(w_p)$ and $y(v_k)$

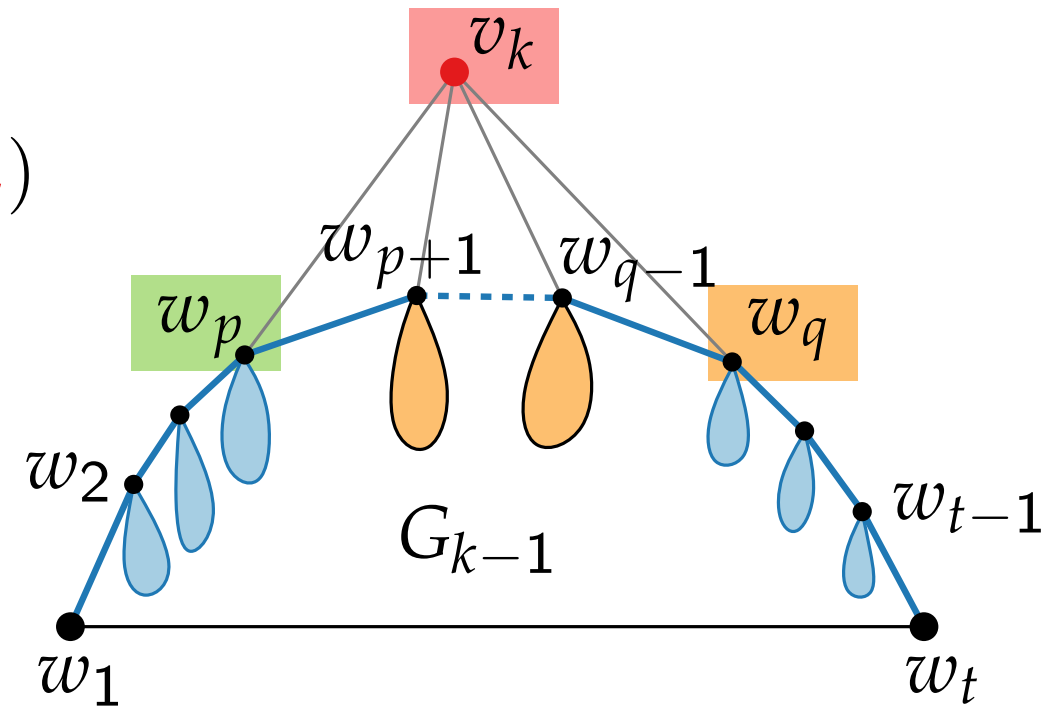


$$(1) \quad x(v_k) = \frac{1}{2} (x(w_q) + x(w_p) + y(w_q) - y(w_p))$$

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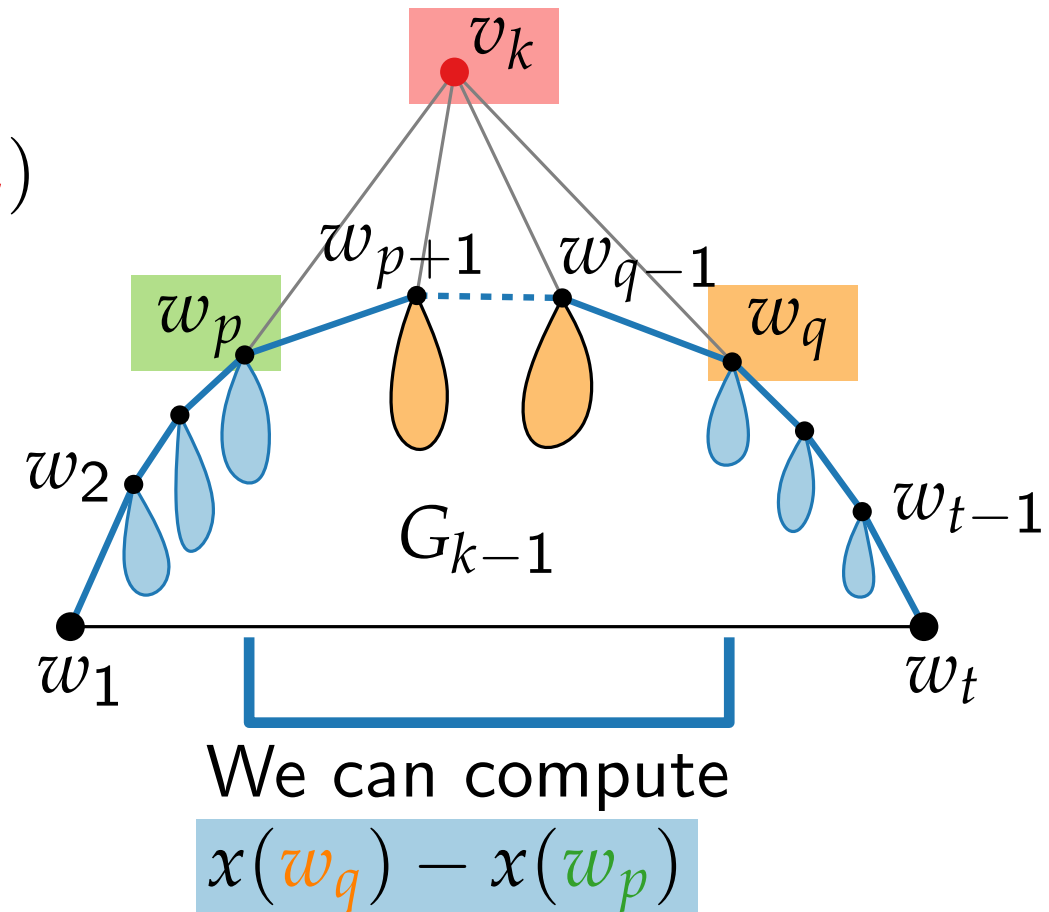
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Shift method – linear time implementation

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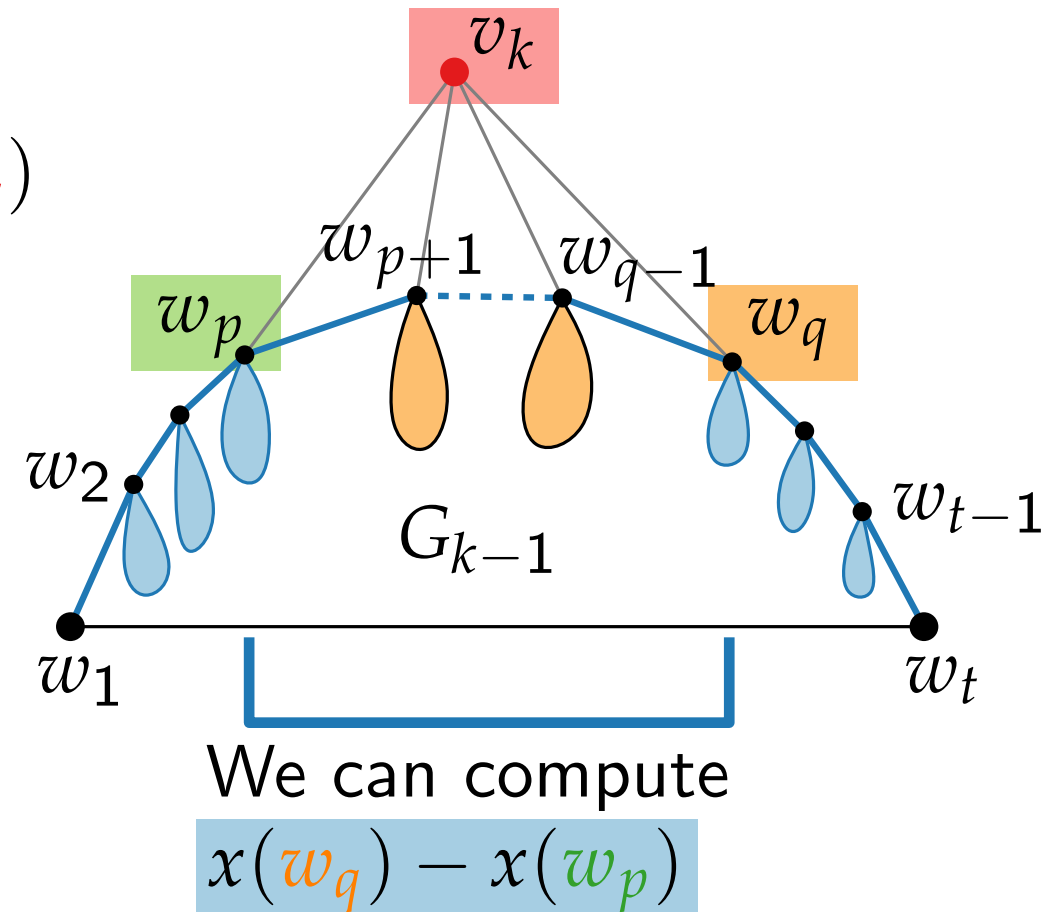
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Shift method – linear time implementation

- **Step 1.** compute $x(v_k)$ and $y(v_k)$
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Step 2- Calculations.

- $\Delta x(w_{p+1})^{++}$, $\Delta x(w_q)^{++}$



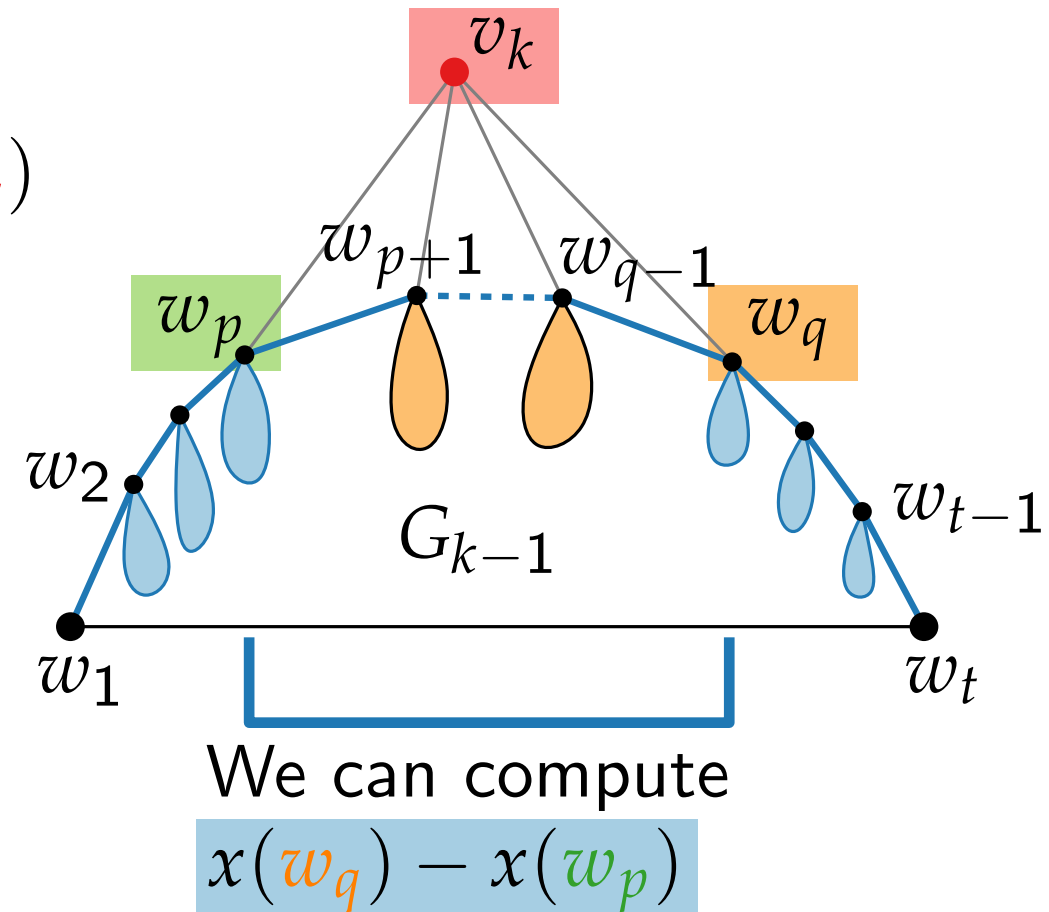
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Shift method – linear time implementation

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- **Step 1 revised.** compute $x(v_k) - x(w_p)$ and $y(v_k)$

Step 2- Calculations.

- $\Delta x(w_{p+1})$, $\Delta x(w_q)$
- $x(w_q) - x(w_p) = \Delta x(w_{p+1}) + \dots + \Delta x(w_q)$



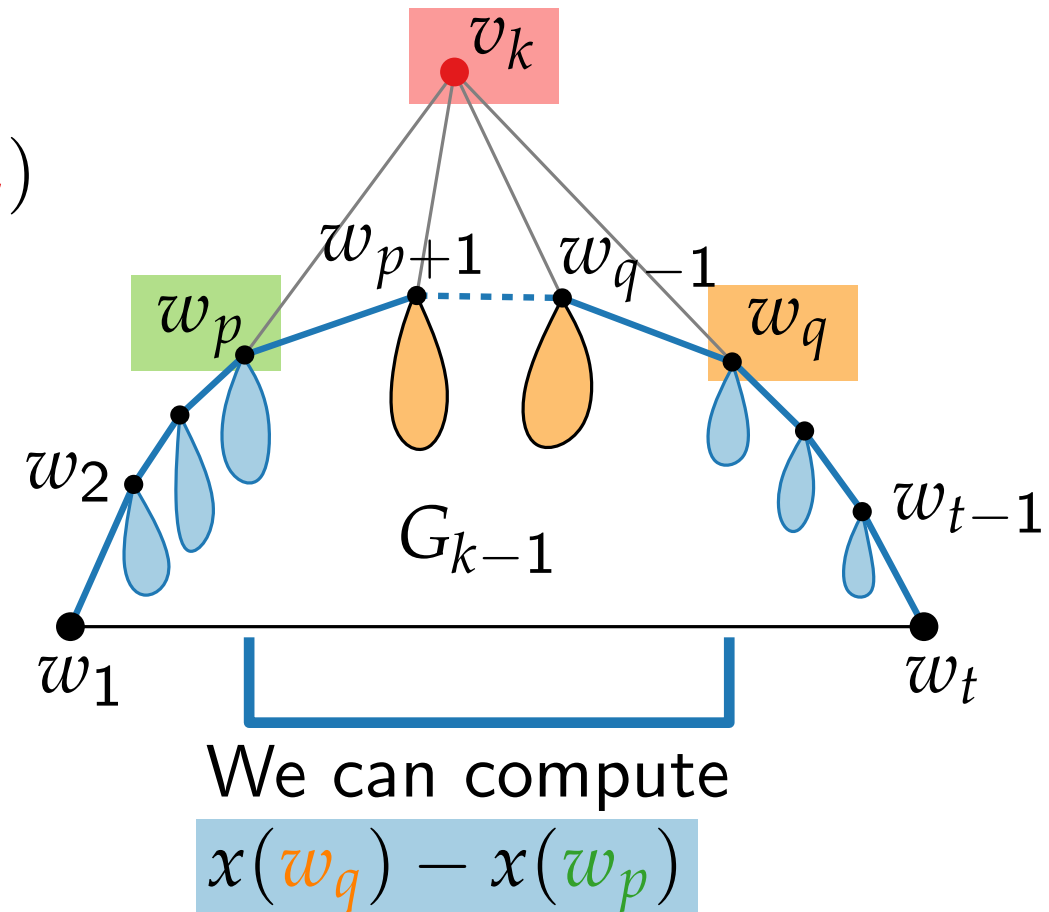
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Shift method – linear time implementation

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Step 2- Calculations.

- $\Delta x(w_{p+1})$, $\Delta x(w_q)$
- $x(w_q) - x(w_p) = \Delta x(w_{p+1}) + \dots + \Delta x(w_q)$
- $\Delta x(v_k)$ by (3)



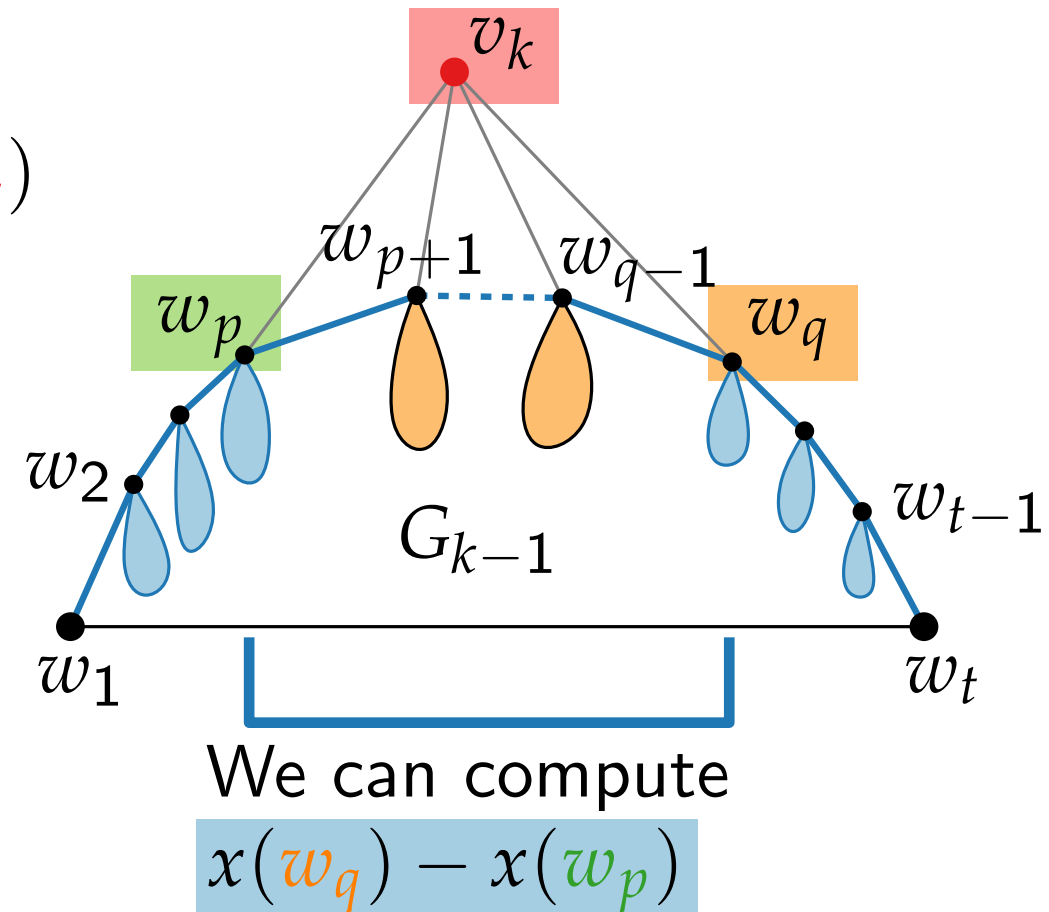
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Shift method – linear time implementation

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Step 2- Calculations.

- $\Delta x(w_{p+1})++$, $\Delta x(w_q)++$
- $x(w_q) - x(w_p) = \Delta x(w_{p+1}) + \dots + \Delta x(w_q)$
- $\Delta x(v_k)$ by (3)
- $\Delta x(w_q) = x(w_q) - x(w_p) - \Delta x(v_k)$



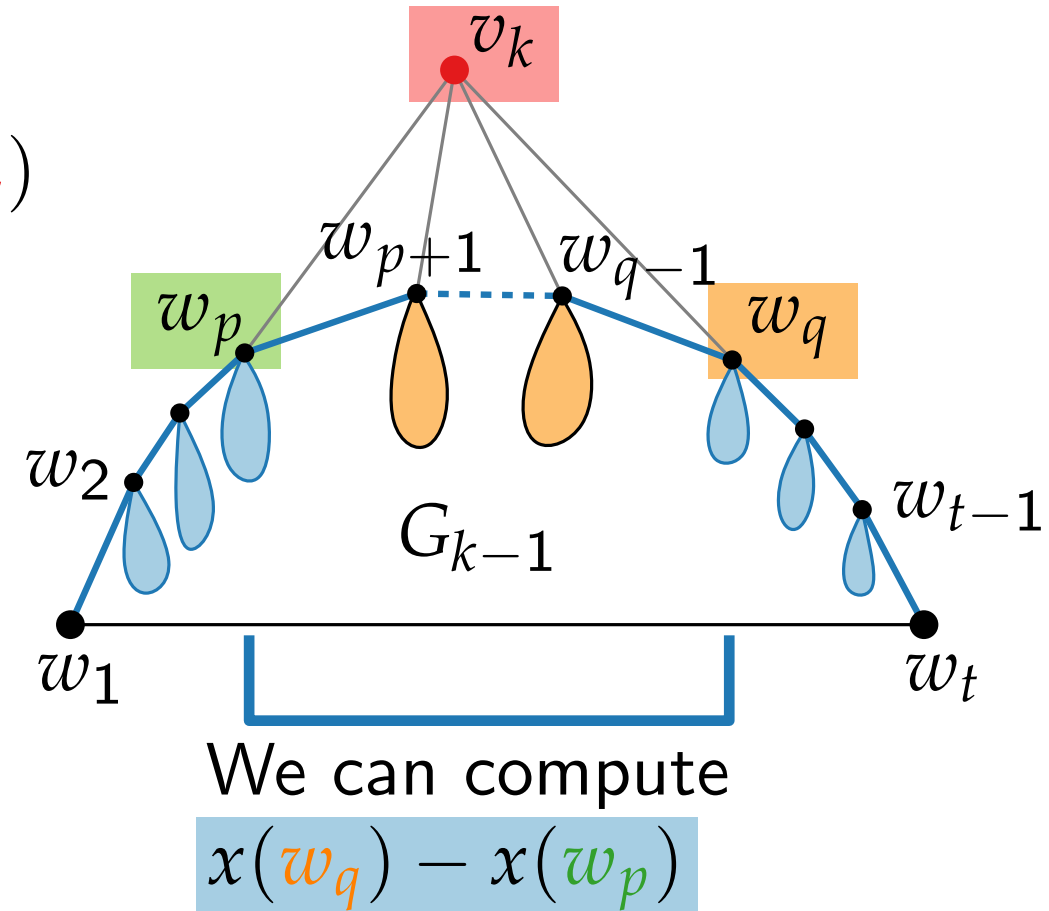
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Step 2- Calculations.

- $\Delta x(w_{p+1})$, $\Delta x(w_q)$
- $x(w_q) - x(w_p) = \Delta x(w_{p+1}) + \dots + \Delta x(w_q)$
- $\Delta x(v_k)$ by (3)
- $\Delta x(w_q) = x(w_q) - x(w_p) - \Delta x(v_k)$
- $\Delta x(w_{p+1}) = \Delta x(w_{p+1}) - \Delta x(v_k)$



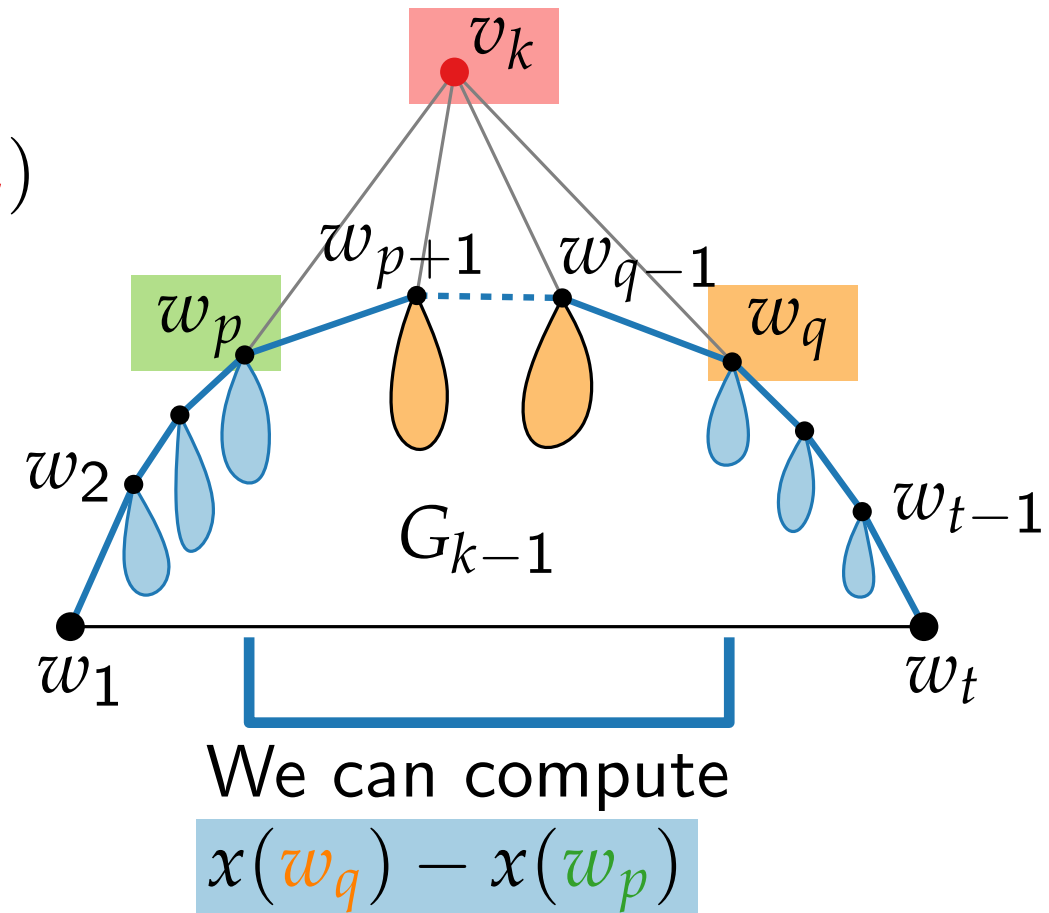
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- $x(w_q) - x(w_p) = \Delta x(w_{p+1}) + \dots + \Delta x(w_q)$
- $\Delta x(v_k)$ by (3)
- $\Delta x(w_q) = x(w_q) - x(w_p) - \Delta x(v_k)$
- $\Delta x(w_{p+1}) = \Delta x(w_{p+1}) - \Delta x(v_k)$
- $y(v_k)$ by (2)



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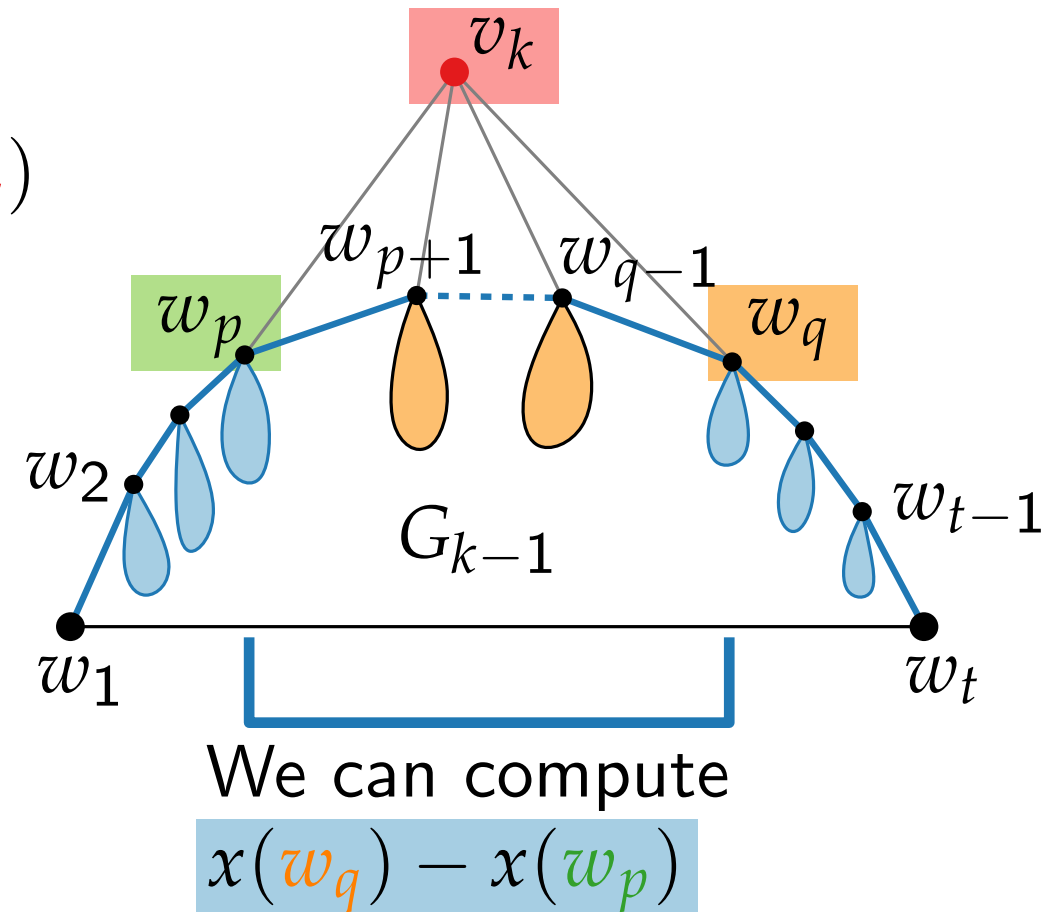
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- $\Delta x(v_k)$ by (3)
- $\Delta x(w_q) = x(w_q) - x(w_p) - \Delta x(v_k)$
- $\Delta x(w_{p+1}) = \Delta x(w_{p+1}) - \Delta x(v_k)$
- $y(v_k)$ by (2)



After v_n , use preorder traversal to compute x -coordinates

- (1) $x(v_k) = \frac{1}{2} (x(w_q) + x(w_p) + y(w_q) - y(w_p))$
- (2) $y(v_k) = \frac{1}{2} (x(w_q) - x(w_p) + y(w_q) + y(w_p))$
- (3) $x(v_k) - x(w_p) = \frac{1}{2} (x(w_q) - x(w_p) + y(w_q) - y(w_p))$

Literature

- [dFPP90] de Fraysseix, Pach, Pollack "*How to draw a planar graph on a grid*", *Combinatorica*, 1990